

# CS 215 : Data Analysis and Interpretation

(Instructor : Suyash P. Awate)

## End-Semester Examination (Closed Book)

Roll Number: \_\_\_\_\_

Name: \_\_\_\_\_

For all questions, if you feel that some information is missing, make justifiable assumptions, state them clearly, and answer the question.

### Relevant Formulae

- Poisson:  $P(k|\lambda) := \lambda^k \exp(-\lambda)/(k!)$

- Exponential:  $P(x; \lambda) = \lambda \exp(-\lambda x); \forall x > 0$

- Gamma:

$$P(x; \alpha, \beta) = \frac{\beta^\alpha x^{\alpha-1} \exp(-\beta x)}{\Gamma(\alpha)}$$

- Gamma function:  $\Gamma(z) = \int_0^\infty x^{z-1} \exp(-x) dx$  for real-valued  $z$ .

When  $z$  is integer valued, then  $\Gamma(z) = (z-1)!$ , where  $!$  denotes factorial.

For all  $z$ ,  $\Gamma(z+1) = z\Gamma(z)$ .

- Univariate Gaussian:

$$P(x; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-0.5\frac{(x-\mu)^2}{\sigma^2}\right)$$

- Product of two univariate Gaussians:  $G(z; \mu_1, \sigma_1^2)G(z; \mu_2, \sigma_2^2) \propto G(z; \mu_3, \sigma_3^2)$

where

$$\mu_3 = \frac{\mu_1\sigma_2^2 + \mu_2\sigma_1^2}{\sigma_1^2 + \sigma_2^2}; \sigma_3^2 = \frac{\sigma_1^2\sigma_2^2}{\sigma_1^2 + \sigma_2^2}$$

- Multivariate Gaussian:

$$G(x; \mu, C) = \frac{1}{(2\pi)^{D/2}|C|^{0.5}} \exp(-0.5(x-\mu)^\top C^{-1}(x-\mu))$$

- $d(Ax) = Adx$

- $d(x^\top Ax) = x^\top (A + A^\top) dx$

- Fisher information:

$$I(\theta_{\text{true}}) := E_{P(X|\theta_{\text{true}})} \left[ \left( \frac{\partial}{\partial \theta} \log P(X|\theta) \Big|_{\theta_{\text{true}}} \right)^2 \right]$$

- Laplace:  $P(x; \mu, b) := (0.5/b) \exp(-|x-\mu|/b)$ , where  $b > 0$  and  $x \in \mathbb{R}$

- “i.i.d.” stands for “independent and identically distributed”

- “PDF” stands for “probability density function”

- “PMF” stands for “probability mass function”

1. (10 points)

Consider two real-valued continuous random variables  $X$  and  $Y$ , with a joint PDF  $P(X, Y)$ .

Suppose you repeat the following two-step experiment infinitely many times:

- (i) first, generate an independent sample point  $a$  as a random draw from  $P(Y)$ , and then
- (ii) given  $a$ , generate a sample point  $b$  as a random draw from  $P(X|Y = a)$ .

Mathematically derive the PDF underlying the set of sample points  $b$  obtained across infinite runs of the experiment.

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Answer:  $P(X)$

Let  $B$  the random variable underlying the set of observations  $b$ .

Then,  $P(B \leq c) = \int_{x=-\infty}^c P_{X|Y}(x|y) \int_{y=-\infty}^{\infty} P_Y(y) dy dx$

$$= \int_{x=-\infty}^c \int_{y=-\infty}^{\infty} P_{XY}(x, y) dy dx$$

$$= \int_{x=-\infty}^c \int_{y=-\infty}^{\infty} P_{XY}(x, y) dy dx$$

$$= \int_{x=-\infty}^c P_X(x) dx$$

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2. (15 points)

Consider a dataset  $\{x_n\}_{n=1}^N$  where each  $x_n$  is drawn independently from some (unknown) PDF.

- [5 points] Derive the bias of the sample-mean estimator  $\bar{x}$  for the mean of the PDF.

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sample mean is an unbiased estimator of the mean.

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- [7 points] Derive the bias of the sample-variance estimator for the variance of the PDF, where the estimator is defined as  $\sum_{n=1}^N (1/N)(x_n - \bar{x})^2$ .

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[https://en.wikipedia.org/wiki/Variance#Biased\\_sample\\_variance](https://en.wikipedia.org/wiki/Variance#Biased_sample_variance)

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- [3 points] Derive the bias of the sample-variance estimator for the variance of the PDF, where the estimator is defined as  $\sum_{n=1}^N (1/(N-1))(x_n - \bar{x})^2$ .

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Unbiased. Follows from proof in previous question. [https://en.wikipedia.org/wiki/Variance#Unbiased\\_sample\\_variance](https://en.wikipedia.org/wiki/Variance#Unbiased_sample_variance)

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3. (15 points)

Consider a dataset  $\{x_n \in \mathbb{R}\}_{n=1}^N$  where integer  $N > 99$ ,  $N$  is even, each datum  $x_n$  is unique (i.e., all data values are distinct), and each  $x_n$  is drawn independently from a Laplace PDF  $P(x; \mu, b)$ .

- [5 points] Formulate an optimization problem for estimating  $\mu$  and  $b$  from the dataset.
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ML estimation. Maximize log likelihood.

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- [10 points: 7 + 3] Mathematically derive the optimal estimates for both the parameters.
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1) [3 points]

log-likelihood function is differentiable in  $b$ . estimate is mean absolute deviation around the estimate for  $\mu$ .

2) [7 points]

log-likelihood function has a derivative w.r.t.  $\mu$ , which is  $\sum_n \text{sgn}(x_n - \mu)$  that is well defined at all  $x$  except at the data points  $x_n$ .

Assume data are sorted.

In the sorted sequence, assume  $x_i$  and  $x_j$  are the points numbered  $(N/2)$  and  $(N/2 + 1)$ .

Then, any  $\mu$  within  $(x_i, x_j)$  makes the derivative zero. Also, log-likelihood function value remains constant within  $[x_i, x_j]$ . Thus, any  $\mu \in [x_i, x_j]$  can be an estimate.

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4. (30 points)

Consider a Gaussian PDF  $P(x; \mu, C)$  on a 3D Euclidean domain where

(i) the mean vector  $\mu$  is of unit norm and

(ii) the covariance matrix  $C = \mathbf{I}/\alpha$  where  $\mathbf{I}$  is the  $3 \times 3$  identity matrix and  $\alpha > 0$ .

• [5 points] Consider a conditional PDF  $Q(x; \mu, \alpha) := P(X | \|x\|_2 = 1)$  that restricts the Gaussian PDF  $P(x; \mu, C)$  to the sphere  $\{x : \|x\|_2 = 1\}$ . Thus, the PDF  $Q(x)$  is a function on a domain that is the sphere where  $\|x\|_2 = 1$ . Mathematically derive the functional form of the PDF  $Q(x)$  (you don't need to find the exact functional form of the normalizing constant).

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$$Q(x; \mu, \alpha) \propto \exp(\alpha \mu^\top x)$$

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• [3 points] This family of PDFs will, of course, be represented in terms of  $\mu$  and  $\alpha$ . What will the locations  $x$  of (all possible) modes of the PDF  $Q(x; \mu, \alpha)$  be? Derive mathematically.

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Maximum at  $x = \mu$

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• [3 points] What will the location  $x$ , on the unit sphere, where the PDF  $Q(x; \mu, \alpha)$  takes its minimum value? Derive mathematically.

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Minimum at  $x = -\mu$

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• [2 points] For the family of such PDFs  $Q(x; \cdot)$ , what parameter models/captures the spread of the probability mass around the mode? Give a convincing mathematical argument ("proof" not required).

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$\mu$  decides the mode. changing  $\mu$  to  $\mu' = R\mu$  (where  $R$  is orthogonal) implies rotating the coordinate system in terms of  $R$ .

$\alpha$  parameter models spread.

$\alpha = 0$  leads to a uniform distribution on the sphere.

Increasing  $\alpha$  makes the distribution more concentrated around the mode at  $\mu$ .

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• [2 points] Give a mathematical argument ("proof" not required) for the normalizing constant of the PDF to be independent of  $\mu$ .

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the PDF is rotationally symmetric around the mode.

by a simple rotation, the PDF can be aligned in some canonical form, e.g., where the mode is at  $[1, 0, 0]$ .

the normalizing constant is simply the integral of the un-normalized function over the sphere. this integral remains the same irrespective of any rotation-based reparametrization

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• [5 points] Formulate an optimization problem for estimating  $\mu$  (of unit norm) given a data sample of size  $N$ .

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let sample be  $\{x_n\}_{n=1}^N$ .

ML estimation. Seek for the maximum of the likelihood function defined over points  $\mu$  on the sphere (i.e., with the constraint that  $\|\mu\|_2 = 1$ .)

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- [4 points] Propose a conjugate prior  $R(\mu; \theta)$ , parameterized by a parameter (or parameter set)  $\theta$ , for the parameter  $\mu$  of the PDF  $Q(x; \mu, \alpha)$  on the sphere. Mathematically justify that the proposed prior is a conjugate prior.

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$R(\mu; a, b) \propto \exp(ba^\top \mu)$ , where  $b$  is scalar non-negative.

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- [6 points: 4 + 2] For the proposed conjugate prior  $R(\mu; \theta)$ , using Bayesian inference and given a sample of size  $N$ , mathematically derive the functional form of the posterior PDF (you don't need to find the exact functional form of the normalizing constant). Derive the mode of the posterior PDF.

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posterior PDF  $\propto \exp((ba + \alpha \sum_n x_n)^\top \mu)$

posterior mode at  $(ba + \alpha \sum_n x_n) / \|ba + \alpha \sum_n x_n\|_2$

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5. (25 points)

Consider a Poisson PMF with parameter  $\lambda$ .

- [5 points] Derive the Jeffreys non-informative prior for  $\lambda$ .

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[https://en.wikipedia.org/wiki/Jeffreys\\_prior#Poisson\\_distribution\\_with\\_rate\\_parameter](https://en.wikipedia.org/wiki/Jeffreys_prior#Poisson_distribution_with_rate_parameter)

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- [3 points] Given a sample (set)  $S$  of size  $N > 1$  from the Poisson PMF, derive the formula for the maximum-likelihood estimator, say,  $T(S)$ , of  $\lambda$ .

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sample mean

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- [7 points: 6 + 1] Mathematically derive the distribution of the estimator  $T(S)$ . Is this distribution Poisson or not ?

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sample sum is distributed as  $\text{Poisson}(N\lambda)$ , as derived in class.

derive sample-mean distribution using transformation of random variables.

NOT Poisson ( $S$  isn't integer valued).

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- [10 points] Is the estimator  $T(S)$  an efficient (i.e., minimum-variance unbiased ) estimator ? Give a mathematical proof.

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[2 points] show estimator is unbiased

[3 points] find variance of estimator:  $\lambda / N$

[3 points] find Fisher information:  $N / \lambda$  [https://en.wikipedia.org/wiki/Poisson\\_distribution](https://en.wikipedia.org/wiki/Poisson_distribution)

[2 points] apply Cramer-Rao lower bound to check for the inequality/equality. this estimator is efficient.

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