图像特征练习

补充并完成本练习。

我们已经看到,通过在输入图像的像素上训练线性分类器,从而在图像分类任务上达到一个合理的性能。在本练习中,我们将展示我们可以通过对线性分类器(不是在原始像素上,而是在根据原始像素计算出的特征上)进行训练来改善分类性能。

你将在此notebook中完成本练习的所有工作。

```
In [1]: import random
   import numpy as np
   from daseCV.data_utils import load_CIFAR10
   import matplotlib.pyplot as plt

%matplotlib inline
   plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
   plt.rcParams['image.interpolation'] = 'nearest'
   plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading extenrnal modules
   # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

数据加载

与之前的练习类似,我们将从磁盘加载CIFAR-10数据。

```
In [2]: from daseCV.features import color histogram hsv, hog feature
        def get CIFAR10 data(num training=49000, num validation=1000, num test=1000):
            # Load the raw CIFAR-10 data
            cifar10 dir = 'daseCV/datasets/cifar-10-batches-py'
            # Cleaning up variables to prevent loading data multiple times (which may cause memo
            try:
               del X train, y train
               del X test, y test
               print('Clear previously loaded data.')
            except:
               pass
            X train, y train, X test, y test = load CIFAR10(cifar10 dir)
            # Subsample the data
            mask = list(range(num training, num training + num validation))
            X_val = X_train[mask]
            y val = y train[mask]
            mask = list(range(num training))
            X train = X train[mask]
            y train = y train[mask]
            mask = list(range(num test))
            X test = X test[mask]
            y test = y test[mask]
```

```
return X_train, y_train, X_val, y_val, X_test, y_test

X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
```

特征提取

对于每一张图片我们将会计算它的方向梯度直方图(英語: Histogram of oriented gradient,简称HOG)以及在HSV颜色空间使用色相通道的颜色直方图。

简单来讲,HOG能提取图片的纹理信息而忽略颜色信息,颜色直方图则提取出颜色信息而忽略纹理信息。 因此,我们希望将两者结合使用而不是单独使用任一个。去实现这个设想是一个十分有趣的事情。

hog_feature 和 color_histogram_hsv 两个函数都可以对单个图像进行运算并返回改图像的一个特征向量。 extract_features函数输入一个图像集合和一个特征函数列表然后对每张图片运行每个特征函数, 然后将结果存储在一个矩阵中,矩阵的每一列是单个图像的所有特征向量的串联。

```
In [3]:
        from daseCV.features import *
        num color bins = 20 # Number of bins in the color histogram <- modified
        feature fns = [hog feature, lambda img: color histogram hsv(img, nbin=num color bins)]
        X train feats = extract features (X train, feature fns, verbose=True)
        X val feats = extract features(X val, feature fns)
        X test feats = extract features(X test, feature fns)
        # Preprocessing: Subtract the mean feature
        mean feat = np.mean(X train feats, axis=0, keepdims=True)
        X train feats -= mean feat
        X val feats -= mean feat
        X test feats -= mean feat
        # Preprocessing: Divide by standard deviation. This ensures that each feature
        # has roughly the same scale.
        std feat = np.std(X train feats, axis=0, keepdims=True)
        X train feats /= std feat
        X val feats /= std feat
        X test feats /= std feat
        # Preprocessing: Add a bias dimension
        X train feats = np.hstack([X train feats, np.ones((X train feats.shape[0], 1))])
        X val feats = np.hstack([X val feats, np.ones((X val feats.shape[0], 1))])
        X test feats = np.hstack([X test feats, np.ones((X test feats.shape[0], 1))])
        Done extracting features for 1000 / 49000 images
        Done extracting features for 2000 / 49000 images
        Done extracting features for 3000 / 49000 images
        Done extracting features for 4000 / 49000 images
        Done extracting features for 5000 / 49000 images
        Done extracting features for 6000 / 49000 images
        Done extracting features for 7000 / 49000 images
        Done extracting features for 8000 / 49000 images
        Done extracting features for 9000 / 49000 images
        Done extracting features for 10000 / 49000 images
        Done extracting features for 11000 / 49000 images
        Done extracting features for 12000 / 49000 images
        Done extracting features for 13000 / 49000 images
        Done extracting features for 14000 / 49000 images
        Done extracting features for 15000 / 49000 images
        Done extracting features for 16000 / 49000 images
```

Done extracting features for 17000 / 49000 images Done extracting features for 18000 / 49000 images Done extracting features for 19000 / 49000 images

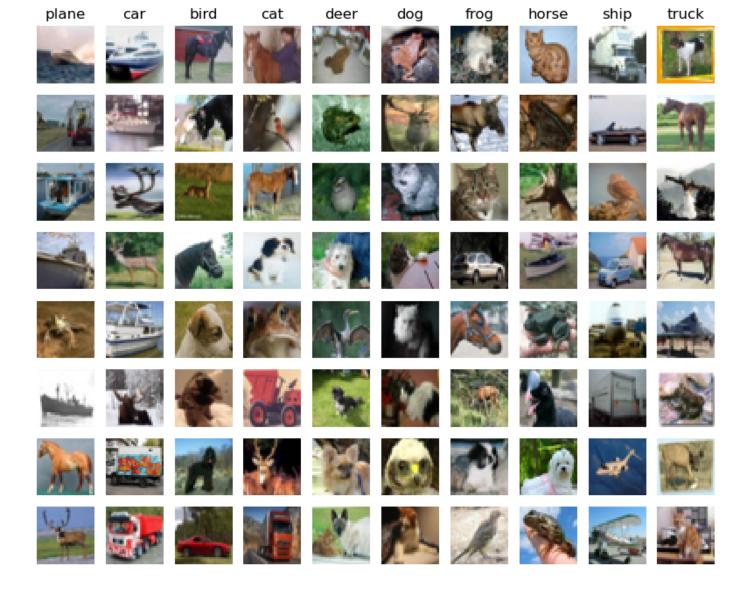
```
Done extracting features for 20000 / 49000 images
Done extracting features for 21000 / 49000 images
Done extracting features for 22000 / 49000 images
Done extracting features for 23000 / 49000 images
Done extracting features for 24000 / 49000 images
Done extracting features for 25000 / 49000 images
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Done extracting features for 47000 / 49000 images
Done extracting features for 48000 / 49000 images
Done extracting features for 49000 / 49000 images
```

使用特征训练SVM

使用之前作业完成的多分类SVM代码来训练上面提取的特征。这应该比原始数据直接在SVM上训练会去的更好的效果。

```
In [4]: # 使用验证集调整学习率和正则化强度
     from daseCV.classifiers.linear classifier import LinearSVM
     from itertools import product
     learning rates = [1e-8, 5e-8]
     regularization strengths = [1e6]
     results = {}
     best val = -1
     best svm = None
     # 你需要做的:
     # 使用验证集设置学习率和正则化强度。
     # 这应该与你对SVM所做的验证相同;
     # 将训练最好的的分类器保存在best svm中。
     # 你可能还想在颜色直方图中使用不同数量的bins。
     # 如果你细心一点应该能够在验证集上获得接近0.44的准确性。
     # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) *****
     while True:
        # 我并不想通过手动反复运行来测试我的运气,因此直接用循环来完成这件事会更好
        for lr, reg in list(product(learning rates, regularization strengths)):
           svm = LinearSVM()
           svm.train(X train feats, y train, learning rate=lr, reg=reg, num iters=2000)
```

```
trn acc = (svm.predict(X train feats) == y train).sum() / y train.size
               val acc = (svm.predict(X val feats) == y val).sum() / y val.size
               results[(lr, reg)] = (trn acc, val acc)
               if val acc > best val:
                   best svm = svm
                   best val = val acc
                   print(f'new best {best val}')
            if best val >= 0.44:
               print('ok')
               break
        # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
        # Print out results.
        for lr, reg in sorted(results):
           train accuracy, val accuracy = results[(lr, reg)]
           print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
                       lr, reg, train accuracy, val accuracy))
       print('best validation accuracy achieved during cross-validation: %f' % best val)
       new best 0.421
       new best 0.423
       new best 0.428
       new best 0.443
       ok
       lr 1.000000e-08 reg 1.000000e+06 train accuracy: 0.423306 val accuracy: 0.443000
       lr 5.000000e-08 reg 1.000000e+06 train accuracy: 0.409776 val accuracy: 0.412000
       best validation accuracy achieved during cross-validation: 0.443000
In [5]: # Evaluate your trained SVM on the test set
        y test pred = best svm.predict(X test feats)
        test accuracy = np.mean(y test == y test pred)
       print(test accuracy)
       0.424
In [6]: # 直观了解算法工作原理的一种重要方法是可视化它所犯的错误。
        # 在此可视化中,我们显示了当前系统未正确分类的图像示例。
        # 第一列显示的图像是我们的系统标记为" plane",但其真实标记不是" plane"。
        examples per class = 8
        classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck
        for cls, cls name in enumerate(classes):
           idxs = np.where((y test != cls) & (y test pred == cls))[0]
           idxs = np.random.choice(idxs, examples per class, replace=False)
           for i, idx in enumerate(idxs):
               plt.subplot(examples per class, len(classes), i * len(classes) + cls + 1)
               plt.imshow(X test[idx].astype('uint8'))
               plt.axis('off')
               if i == 0:
                   plt.title(cls name)
       plt.show()
```



问题 1:

描述你看到的错误分类结果。你认为他们有道理吗?

答:

错误分类是有规律的,将一张图片的颜色和纹理信息分开考虑时,这些样本的颜色和纹理信息各自和该类别相似,这导致它在该类别上的得分很高. 出现这个问题的原因是SVM无法考虑颜色和纹理信息的共同作用,而只是简单将它们线性加和.

图像特征神经网络

在之前的练习中,我们看到在原始像素上训练两层神经网络比线性分类器具有更好的分类精度。在这里,我们已经看到使用图像特征的线性分类器优于使用原始像素的线性分类器。为了完整起见,我们还应该尝试在图像特征上训练神经网络。这种方法应优于以前所有的方法:你应该能够轻松地在测试集上达到55%以上的分类精度;我们最好的模型可达到约60%的精度。

```
In [7]: # Preprocessing: Remove the bias dimension
# Make sure to run this cell only ONCE
print(X_train_feats.shape)
X_train_feats = X_train_feats[:, :-1]
X_val_feats = X_val_feats[:, :-1]
X_test_feats = X_test_feats[:, :-1]
```

```
(49000, 165)
      (49000, 164)
In [10]: from daseCV.classifiers.neural net import TwoLayerNet
      input dim = X train feats.shape[1]
      hidden dim = 500
      num classes = 10
      best acc = 0.0
      net = TwoLayerNet(input dim, hidden dim, num classes)
      best net = None
      # TODO: 使用图像特征训练两层神经网络。
       # 您可能希望像上一节中那样对各种参数进行交叉验证。
       # 将最佳的模型存储在best net变量中。
      # ****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
       # 只尝试一次就达到了要求, 可以归因为运气好
      net.train(X train feats, y train, X val feats, y val, learning rate=le-1, num iters=1000
      print((net.predict(X val feats) == y val).sum()/y val.size)
      best net=net
      # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE) ****
```

0.609

print(X train feats.shape)

```
In [11]: # 在测试集上运行得到的最好的神经网络分类器,应该能够获得55%以上的准确性。

test_acc = (best_net.predict(X_test_feats) == y_test).mean()
print(test_acc)
```

0.594