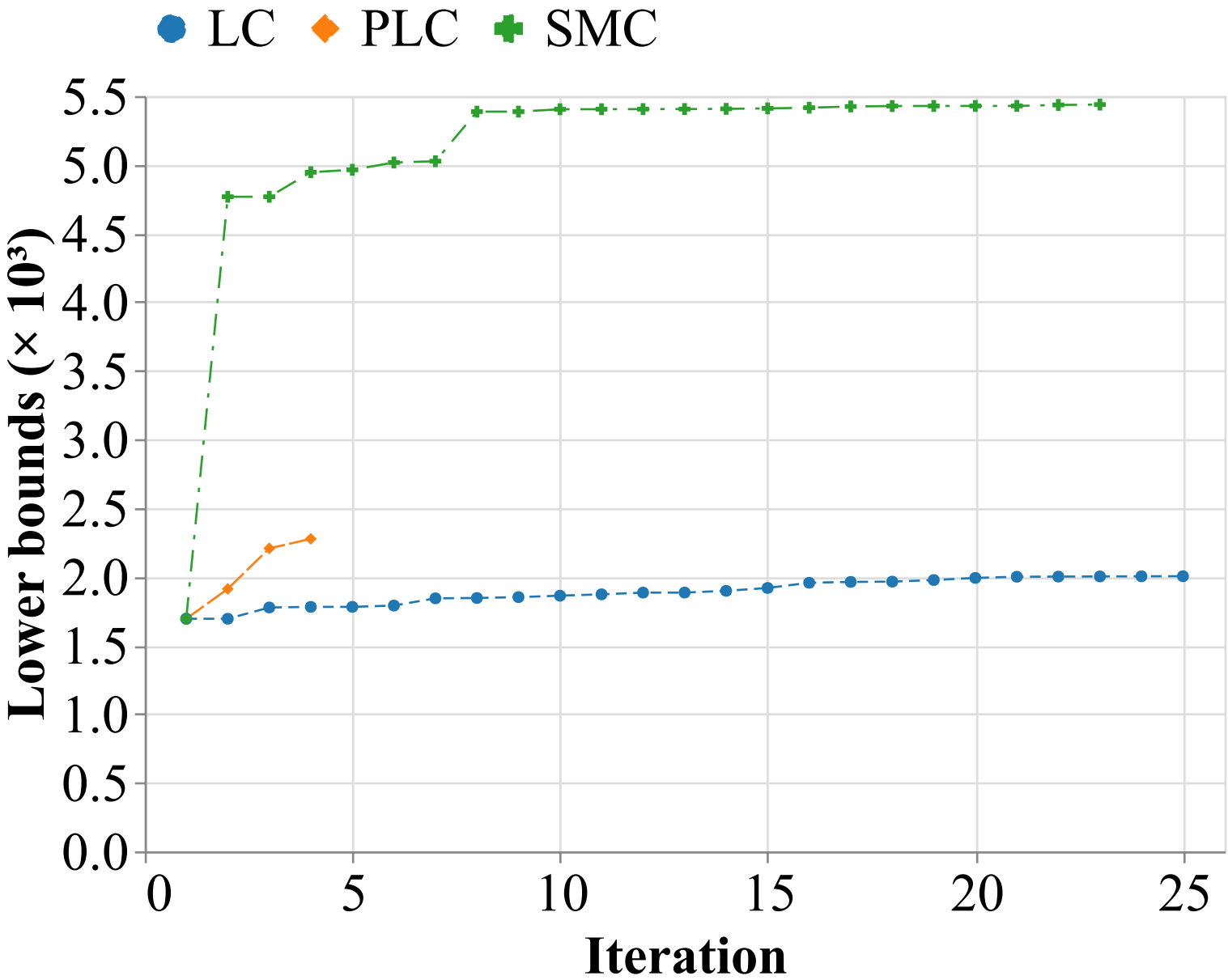
LC
PLC
SMC
Lower bounds (× 10³)
5.5
5.0
4.5
4.0
3.5
3.0
2.5
2.0
1.5
1.0
0.5
0.0
0
5
10
15
20
25
Iteration