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1 Introduction

This document describes three commonly used Multi-Armed Bandit (MAB) strategies in reinforcement learning: the ε -Greedy algorithm, the Upper Confidence Bound (UCB) algorithm, and the Softmax (Boltzmann) algorithm. Each balances exploration and exploitation to maximize total rewards over a limited number of decisions.

2 ε -Greedy Algorithm

2.1 Algorithm Overview

The ε -Greedy algorithm is a straightforward exploration–exploitation strategy. At each decision round t:

- With probability 1ε , select the arm with the highest estimated average reward (exploitation).
- With probability ε , select an arm uniformly at random (exploration).

Here, $\varepsilon \in [0,1]$ represents the exploration rate, typically chosen between 0.01 and 0.1 based on the number of arms and total decision rounds.

2.2 Action Selection Probability

In round t, the probability of selecting arm i is given by:

$$P(a_t = i) = \begin{cases} 1 - \varepsilon + \frac{\varepsilon}{K}, & \text{if } i = \arg\max_j \hat{\mu}_j(t - 1), \\ \frac{\varepsilon}{K}, & \text{otherwise,} \end{cases}$$

where:

- K is the total number of arms.
- $\hat{\mu}_j(t-1)$ is the estimated average reward of arm j up to round t-1.

2.3 Reward Update Rule

When arm i is selected at round t and reward r_t is observed, its pull count and estimated average reward are updated as follows:

$$n_i(t) = n_i(t-1) + 1,$$
 (1)

$$\hat{\mu}_i(t) = \hat{\mu}_i(t-1) + \frac{1}{n_i(t)} (r_t - \hat{\mu}_i(t-1)).$$
 (2)

2.4 Summary of ε -Greedy

The ε -Greedy algorithm is widely used in MAB and other reinforcement learning scenarios requiring exploration–exploitation trade-offs due to its simplicity and low computational cost. Adjusting ε or using decay strategies can further improve long-term performance.

3 Upper Confidence Bound (UCB) Algorithm

3.1 Algorithm Overview

The UCB algorithm applies the principle of optimism in the face of uncertainty by constructing an upper confidence bound for each arm's estimated value. At each round t, the arm with the highest bound is selected, naturally balancing exploration and exploitation.

3.2 UCB Index Formula

For arm i at round t, the UCB index is defined as:

$$UCB_i(t) = \hat{\mu}_i(t) + \sqrt{\frac{2 \ln t}{n_i(t)}},$$

where:

- $\hat{\mu}_i(t)$ is the estimated average reward of arm i up to round t.
- $n_i(t)$ is the number of times arm i has been selected before round t.
- t is the total number of decision rounds so far.

3.3 Pseudocode

```
Initialize: for each arm i, set n_i = 0, \hat\mu_i = 0
// Ensure each arm is tried once
for i = 1 to K do
  pull arm i, observe reward r
  n_i = 1, \hat\mu_i = r
```

end for

```
for t = K+1 to T do
  for i = 1 to K do
    UCB_i = \hat\mu_i + sqrt((2*ln t)/n_i)
  end for
  select arm i* = argmax UCB_i
  pull arm i*, observe reward r
  n_{i*}++
  \hat\mu_{i*} += (r - \hat\mu_{i*})/n_{i*}
end for
```

3.4 Theoretical Guarantee

UCB achieves a logarithmic regret bound:

$$\mathbb{E}[R(T)] = O\left(\sum_{i:\Delta_i > 0} \frac{\ln T}{\Delta_i}\right),\,$$

where $\Delta_i = \mu^* - \mu_i$ is the gap between the optimal arm's mean reward and arm i's mean reward.

4 Softmax (Boltzmann) Algorithm

4.1 Algorithm Overview

The Softmax algorithm assigns a selection probability to each arm based on a Boltzmann distribution over estimated values, allowing smooth trade-off between exploration and exploitation.

4.2 Temperature Parameter

A temperature parameter $\tau > 0$ controls the randomness:

- As $\tau \to 0^+$, the selection becomes more greedy (higher-value arms get almost all probability).
- As $\tau \to \infty$, the selection becomes more uniform across arms.

4.3 Action Selection Probability

In round t, the probability of selecting arm i is:

$$P_i(t) = \frac{\exp(\hat{\mu}_i(t)/\tau)}{\sum_{j=1}^K \exp(\hat{\mu}_j(t)/\tau)}.$$

4.4 Reward Update Rule

After selecting arm i and observing reward r_t , update its estimate:

$$\hat{\mu}_i(t) = \hat{\mu}_i(t-1) + \frac{1}{n_i(t)} (r_t - \hat{\mu}_i(t-1)),$$

where $n_i(t)$ is the pull count including this round.

4.5 Summary of Softmax

Softmax exploration provides a differentiable selection mechanism that smoothly interpolates between greedy and random policies, and can be tuned via the temperature parameter for desired exploration behavior.

5 Conclusion

This document presented the ε -Greedy, UCB, and Softmax algorithms for solving the Multi-Armed Bandit problem, including their motivations, formulas, and key properties. These strategies are fundamental tools in reinforcement learning for efficient decision-making under uncertainty.