

# everyday genius

# MT8183 Camera Bring Up SOP

Version: 1.0

Release date: 2019-03-21

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# **Document Revision History**

Revision	Date	Description	
1.0	2019-03-18	Initial Draft	
			2



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# 1. Introduction

In this document, we'll introduce MT8183 camera sensor porting.

# 1.1 Purpose

This document is to guide customers on how to porting camera sensor in mtk platform.

# 1.2 Definitions, Acronyms and Abbreviations

\$(project)

Take MTK's turnkey solution as an example, \$(project) correspond to tb8183m1\_64\_bsp.

### 1.3 References

N/A

#### 1.4 Overview

N/A



## 2. Camera sensor porting

## 2.1 Mipi Port Connection Customization

- -- modify the customization setting by your hw layout.
- -- cfg\_setting\_imgsensor.cpp(\custom\\$project\$\hal\imgsensor\_src\)(file Priority: project > platform > common).

```
static CUSTOM CFG gCustomCfg[] = {
        .sensorIdx
                        = IMGSENSOR SENSOR IDX MAIN,
                        = CUSTOM_CFG_MCLK_1, //main
        .mclk
                        = CUSTOM CFG CSI PORT 0,
        .port
                        = CUSTOM CFG DIR REAR,
        .dir
                        = CUSTOM CFG BITORDER 9 2,
        .bitOrder
        .orientation
        .horizontalFov = 67,
        .verticalFov
    },
                        = IMGSENSOR SENSOR IDX SUB,
        .sensorIdx
                        = CUSTOM CFG MCLK 2, //sub
        .mclk
                        = CUSTOM CFG CSI PORT 1,
        .port
                        = CUSTOM CFG DIR FRONT,
        .dir
                        = CUSTOM CFG BITORDER 9 2,
        .bitOrder
        .orientation
                        = 270,
                          63,
        .horizontalFov =
                          40
        .verticalFov
    },
typedef enum {
    CUSTOM CFG CSI PORT 0 =
    CUSTOM CFG CSI PORT 1,
                                         // 4D1C
    CUSTOM CFG CSI PORT 2,
                                         // 4D1C
    CUSTOM CFG CSI PORT OA,
                                 // 2D1C
    CUSTOM CFG CSI PORT 0B,
                                 // 2D1C
    CUSTOM CFG CSI PORT MAX NUM,
    CUSTOM CFG CSI PORT NONE
                                 //for non-MIPI sensor
 CUSTOM CFG CSI PORT;
```

#### 2.2 Mclk Connection Customization

camera\_custom\_imgsensor\_cfg.h

- -- modify the customization setting by your hw layout.
- -- cfg\_setting\_imgsensor.cpp(vendor\mediatek\proprietary\custom\\$project\$\hal\imgsensor\_src)



```
static CUSTOM CFG gCustomCfg[] = {
        .sensorIdx
                       = IMGSENSOR SENSOR IDX MAIN,
                       = CUSTOM CFG MCLK 1,
        .mclk
                                              //main
        .port
                       = CUSTOM CFG CSI PORT O,
                       = CUSTOM CFG DIR REAR,
        .dir
                       = CUSTOM CFG BITORDER 9 2,
        .bitOrder
        .orientation
        .horizontalFov = 67,
        .verticalFov
    Ъ.
                       = IMGSENSOR SENSOR IDX SUB,
        .sensorIdx
                                             ///sub
                       = CUSTOM_CFG_MCLK_2,
        .mclk
                       = CUSTOM_CFG_CSI_PORT 1,
        .port
        .dir
                       = CUSTOM_CFG_DIR_FRONT,
        .bitOrder
                       = CUSTOM CFG BITORDER 9 2,
        .orientation
        .horizontalFov = 63,
        .verticalFov
    },
typedef enum {
     CUSTOM CFG MCLK 1 = 0 \times 0
     CUSTOM CFG MCLK 2,
                             //mclk2
     CUSTOM CFG MCLK 3,
                             //mclk3
     CUSTOM CFG MCLK 4,
     CUSTOM CFG MCLK 5,
     CUSTOM CFG MCLK MAX NUM,
     CUSTOM CFG MCLK NONE
} CUSTOM CFG MCLK
camera_custom_imgsensor_cfg.h
```

#### 2.3 Mclk On/Off control

#endif

-- Customization mclk on/off control in power on sequence

(kernel-4.4\drivers\misc\mediatek\imgsensor\src\mt6771\camera\_hw\imgsensor\_cfg\_table.c)

```
#if defined(OV13855_MIPI_RAW)

SENSOR_DRVNAME_OV13855_MIPI_RAW,

{SensorMCLK, Vol_High, 0},

{PDN, Vol_Low, 0},

{RST, Vol_Low, 0},

{DOVDD, Vol_1800, 1},

{AVDD, Vol_2800, 1},

{DVDD, Vol_1200, 5},

{AFVDD, Vol_12800, 1},

{PDN, Vol_High, 1},

{RST, Vol_High, 2}

},
```

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```
struct IMGSENSOR HW CFG imgsensor custom config[] = {
           IMGSENSOR SENSOR IDX MAIN,
           IMGSENSOR I2C DEV 0,
            {IMGSENSOR_HW_PIN_MCLK, IMGSENSOR_HW_ID_MCLK},
            (IMGSENSOR HW PIN AVDD, IMGSENSOR HW ID REGULATOR),
            {IMGSENSOR_HW_PIN_DOVDD, IMGSENSOR_HW_ID_REGULATOR},
            {IMGSENSOR_HW_PIN_DVDD, IMGSENSOR_HW_ID_GPIO}, {IMGSENSOR_HW_PIN_PDN, IMGSENSOR_HW_ID_GPIO},
            {IMGSENSOR_HW_PIN_RST, IMGSENSOR_HW_ID_GPIO},
            {IMGSENSOR_HW_PIN_NONE, IMGSENSOR_HW_ID_NONE},
            -},
           IMGSENSOR SENSOR IDX SUB,
           IMGSENSOR_I2C_DEV_1,
            {IMGSENSOR_HW_PIN_MCLK, IMGSENSOR_HW_ID_MCLK},
            {IMGSENSOR HW PIN AVDD, IMGSENSOR HW ID REGULATOR},
            {IMGSENSOR_HW_PIN_DOVDD, IMGSENSOR_HW_ID_REGULATOR}, 
{IMGSENSOR_HW_PIN_DVDD, IMGSENSOR_HW_ID_REGULATOR}, 
{IMGSENSOR_HW_PIN_PDN, IMGSENSOR_HW_ID_GPIO},
            {IMGSENSOR_HW_PIN_RST, IMGSENSOR_HW_ID_GPIO},
            {IMGSENSOR_HW_PIN_NONE, IMGSENSOR_HW_ID_NONE},
            },
```

#### 2.4 **Camera Driver File Path**

Kernel driver()

MEDIATEK

kernel-4.4\drivers\misc\mediatek\imgsensor\src\{platform}

kernel-4.4\drivers\misc\mediatek\imgsensor\inc\{platform}

hal driver()

vendor\mediatek\proprietary\custom\{project}\hal

#### 2.5 Add a new sensor

#### 2.5.1.1 Modify imgsensor configuration

#### 2.5.1.1.1 Step1 device\mediateksample\\$project\$\ProjectConfig.mk

Modify imgsensor configuration

```
eg:main(rear camera) imx135_mipi_raw, sub (front camera)ov5648_mipi_raw)
```

CUSTOM HAL IMGSENSOR = imx135 mipi raw ov5648 mipi raw

CUSTOM KERNEL IMGSENSOR = imx135 mipi raw ov5648 mipi raw

CUSTOM HAL MAIN IMGSENSOR = imx135 mipi raw

CUSTOM\_HAL\_SUB\_IMGSENSOR = ov5648\_mipi\_raw

CUSTOM\_KERNEL\_MAIN\_IMGSENSOR = imx135\_mipi\_raw

CUSTOM KERNEL SUB IMGSENSOR = ov5648 mipi raw



#### Modify lens

if have no AF set it as dummy lens; YUV sensor has af set it as sensordrive; RAW sensor has af set

it as lens name (eg:fm50af,ov8825af)

imx135\_mipi\_raw has AF, sub sensor has no af

CUSTOM HAL LENS = dw9714af dummy lens

CUSTOM\_KERNEL\_LENS = dw9714af dummy\_lens

CUSTOM HAL MAIN LENS = d29714af

CUSTOM HAL SUB LENS = dummy lens

CUSTOM KERNEL MAIN LENS = dw9714af

CUSTOM KERNEL SUB LENS = dummy lens

Modify flashlight

If it has Flashlight set it as constant\_flashlight, if no set it as dummy\_flashlight

CUSTOM\_HAL\_FLASHLIGHT = constant\_flashlight

CUSTOM\_KERNEL\_FLASHLIGHT = constant\_flashlight

#### 2.5.1.1.2 Step2 \device\mediatek\common\kernel-headers\kd\_imgsensor.h

\kernel-4.4\drivers\misc\mediatek\imgsensor\inc\kd\_imgsensor.h

#define OV5648 SENSOR ID

0x5648Config sensor ID

#define SENSOR\_DRVNAME\_OV5648\_MIPI\_RAW "ov5648mipiraw" Define sensor device driver name

#### 2.5.1.1.3 Step3

\kernel-4.4\drivers\misc\mediatek\imgsensor\src\common\v1 1\imgsensor sensor list.h

UINT32 OV5648 MIPI RAW SensorInit(PSENSOR FUNCTION STRUCT \*pfFunc);

kdSensorList[]

#if defined(OV5648\_MIPI\_RAW)

{OV5648\_SENSOR\_ID,SENSOR\_DRVNAME\_OV5648\_MIPI\_RAW,OV5648\_MIPI\_RAW\_SensorInit}, #endif

\vendor\mediatek\proprietary\custom\mt6771\hal\imgsensor src\sensorlist.cpp

SensorList∏

#if defined(OV5648\_MIPI\_RAW)

RAW\_INFO(OV5648\_SENSOR\_ID, SENSOR\_DRVNAME\_OV5648\_MIPI\_RAW, NULL),

The order of the SensorList[] in sensorlist.cpp and the kdSensorList[] in imgsensor\_sensor\_list.c must be the same, otherwise the id of user space & kernel space will not be able to match.



```
MSDK_SENSOR_INIT_FUNCTION_STRUCT SensorList[] =
#if defined(OV8830 RAW)
RAW INFO (OV8830 SENSOR ID, SENSOR DRVNAME OV8830 RAW, NULL),
   defined(IMX073_MIPI_RAW)
    RAW_INFO(IMX073_SENSOR_ID, SENSOR_DRVNAME_IMX073_MIPI_RAW, EEPROMGetCalData)
#if defined(S5K4ElGA_MIPI_RAW)
    RAW_INFO(S5K4E1GA_SENSOR_ID, SENSOR_DRVNAME_S5K4E1GA_MIPI_RAW,NULL),
    defined(0V5642_RAW)
    RAW_INFO(OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_RAW, NULL),
#if defined(HI542_RAW)
    RAW_INFO(HI542_SENSOR_ID, SENSOR_DRVNAME_HI542_RAW, NULL)
   ıdi f
#if defined(0V5642_MIPI_YUV)
    YUV_INFO(OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_MIPI_YUV,
    defined(OV5642_MIPI_RGB)
    YUV_INFO(OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_MIPI_RGB, NULL)
    defined(OV5642_MIPI_JPG)
    YUV_INFO(OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_MIPI
 ndi f
#if defined(0V5642_YUV)
   YUV_INFO(0V5642_SENSOR_ID, SENSOR_DRVNAME_0V5642_YUV)
#if defined(0V5647 MIPI_RAW)
    RRW_INFO(0V5647MIPI_SENSOR_ID, SENSOR_DRVWAME_QV5647MIPI_RAW, NULL),
```

And it is recommended to arrange the resolutions in descending order.

```
ACDK KD SENSOR INIT FUNCTION STRUCT kdSensorList[MAX NUM OF SUPPORT SENSOR+1] =
#if defined(OV8830_RAW)
    (OV8830_SENSOR_ID, SENSOR_DRVNAME_OV8830_RAW, OV8830SensorInit),
#if defined(IMX073_MIPI_RAW)
    (IMXO73_SENSOR_ID, SENSOR_DRVNAME_IMXO73_MIPI_RAW, IMXO73_MIPI_RAW_SensorInit),
#if defined(S5K4ElGA_MIPI_RAW)
    {S5K4E1GA_SENSOR_ID, SENSOR_DRVNAME_S5K4E1GA_MIPI_RAW, S5K4E1GA_MIPI_RAW_SensorInit},
#endi f
#if defined(OV5642_RAW)
    {OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_RAW, OV5642_RAW_SensorInit},
    (HI542_SENSOR_ID, SENSOR_DRVNAME_HI542_RAW, HI542_RAW_SensorInit),
 endif
#if defined(OV5642_MIPI_YUV)
    {OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_MIPI_YUV, OV5642_MIPI_YVV_SensorInit},
#endif
#if defined(OV5642_MIPI_RGB)
    {OV5642 SENSOR ID, SENSOR DRVNAME_OV5642_MIPI_RGB, OV5642_MIPI_RGB_SensorInit},
  ndif
#if defined(OV5642_MIPI_JPG)
    (OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_MIPI_JPG, OV5642_MIPI_JPG_SensorInit),
#if defined(OV5642_YUV)
     (OV5642_SENSOR_ID, SENSOR_DRVNAME_OV5642_YUV, OV5642_YUV_SensorInit),
#if defined(OV5647 MIPI RAW)
     (OV5647MIPI_SENSOR_ID, SENSOR_DRVNAME_OV5647MIPI_RAW, OV5647MIPISensorInit),
```



## 2.6 Modify Power On/Off

\kernel-4.4\drivers\misc\mediatek\imgsensor\src\common\v1\_1\imgsensor\_hw.c

```
imgsensor hw power sequence (
                          phw,
                          sensor idx,
                          pwr status,
                          platform power sequence, imgsensor sensor idx name[sensor idx]);
  imgsensor hw power sequence (
                         phw,
                          sensor idx,
                          pwr status, sensor power sequence,
                                                                              curr_sensor
                                                                                                name);
POWER ON
static enum IMGSENSOR_RETURN imgsensor hw power sequence
                   struct IMGSENSOR_HW
                                                         *phw,
                   enum IMGSENSOR SENSOR_IDX sensor idx,
enum IMGSENSOR_HW POWER_STATUS pwr_status,
struct IMGSENSOR_HW POWER_SEQ *ppower_sequ
                                                         *ppower_sequence,
                   char *pcurr idx)
         if (pwr_status == IMGSENSOR_HW_DOWER_STATUS_ON) {
    if (ppwr_info->pin != IMGSENSOR_HW_PIN_UNDEF) {
        pdev = phw->pdev[psensor_pwr->id[ppwr_info->pin]];
}
                                            ratelimit(&ratelimit))
                                               PK_DBG
("sensor_idx %d, ppwr_info->pin %d, ppwr_info->pin_state_on %d",
sensor_idx, ppwr_info->pin, ppwr_info->pin_state_on);
                                          (pdev->set != NULL)
                                               pdev->set(pdev->pinstance,
                                                           sensor_idx,
ppwr_info->pin, ppwr_info->pin_state_on);
                             mdelay(ppwr
                                                 >pin on delay);
                   ppwr_info++;
pin_cnt++;
          } ? end while ppwr_info->pin!=IN
```



#### **POWER OFF**

```
static enum IMGSENSOR_RETURN imgsensor hw power sequence(
                  struct IMGSENSOR_HW
                                                       *phw,
                         IMGSENSOR SENSOR IDX
                  enum
                                                        sensor idx.
                          IMGSENSOR HW POWER STATUS pwr status,
                  enum
                  struct IMGSENSOR HW POWER SEQ
                                                       *ppower sequence,
                  char *pcurr idx)
         while (ppwr_info->pin != IMGSENSOR_HW_PIN_NONE &&
         ppwr_info < ppwr_seq->pwr_info + IMGSENSOR_HW_POWER_INFO_MAX)
if (pwr_status == IMGSENSOR_HW_POWER_STATUS_OFF) (
                  while (pin_cnt) {
                           ppwr_info--;
                           pin_cnt--;
                           if (__ratelimit(&ratelimit))
                                    PK DBG
                                    ("sensor_idx %d, ppwr_info->pin %d, ppwr_info->pin_state_off %d",
sensor_idx, ppwr_info->pin, ppwr_info->pin_state_off);
                           if (ppwr_info->pin != IMGSENSOR_HW_PIN_UNDEF)
                                    pdev = phw->pdev[psensor_pwr->id[ppwr_info->pin]];
                                    if (pdev->set != NULL)
                                              pdev->set(pdev->pinstance,
                                                         sensor
                                                                idx,
                                                         ppwr_info->pin, ppwr_info->pin_state_off);
                           mdelay(ppwr_info->pin_on_delay)
                  } ? end while pin_cnt ?
         return IMGSENSOR_RETURN_SUCCES
} ? end while ppwr info->pin!=IMGSE... ?
```

### 2.7 Add Sensor Driver

If you have a ready-prepared sensor driver, you can directly put it in the corresponding path. The files you need to add are:

- 1. kernel driver (kernel-4.4\drivers\misc\mediatek\imgsensor\src\{platform}\)
- 2. tuning file(vendor\mediatek\proprietary\custom\{platform}\hal\imgsensor\)
- 3. ftb(vendor\mediatek\proprietary\custom\{platform}\hal\senindepfeature\)
- 4. metadata(vendor\mediatek\proprietary\custom\{platform}\hal\imgsensor\_metadata)

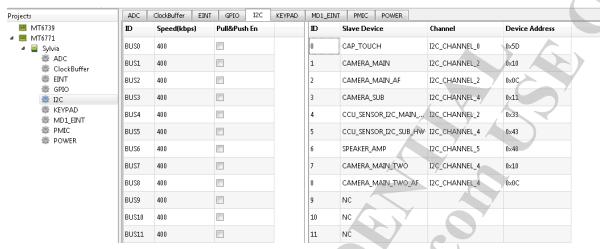
NOTE: The metadata file is not provided in the QVL download code. You can modify the name of the other sensor's metadata file to the current sensor from the metadata directory.

Currently only the facing, orientation, and flashlight configurations in metadata will be

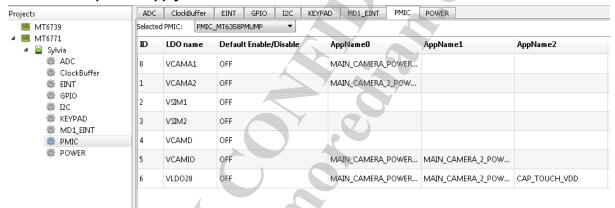
#### 2.8 DWS/DTS

Path: kernel-4.4\drivers\misc\mediatek\dws\mt6771\{project\}.dws camera I2C config





#### camera PMIC power supply



Path: kernel-4.4\arch\arm64\boot\dts\mediatek\{project}.dts

**Pinctrl configuration** 



```
/* CAMERA GPIO standardization */
&pio {
    camera_pins_cam0_rst_0: cam000 {
        pins_cmd_dat {
            pins = <PINMUX_GPIO37__FUNC_GPIO37>;
            slew-rate = <1>; /*direction 0:in, 1:out*/
            output-low;/*direction out used only. output low or high*
        } :
    };
    camera_pins_camO_rst_1: camO@1 {
        pins cmd dat {
            pins = <PINMUX_GPIO37__FUNC_GPIO37>;
            slew-rate = <1>;
            output-high;
    };
    camera pins camO pnd O: camO@2 {
        pins cmd dat {
            pins = <PINMUX GPIO35 FUNC GPIO35>;
            slew-rate = <1>;
            output-low;
        );
    );
    camera_pins_cam0_pnd_1: cam0@3 {
        pins cmd dat {
            pins = <PINMUX GPIO35 FUNC GPIO35>;
            slew-rate = <1>;
            output-high;
    };
    camera pins cam1 rst 0: cam100 {
        pins cmd dat {
            pins = <PINMUX GPIO36 FUNC GPIO36>;
            slew-rate = <1>; /*direction 0:in, 1:out*/
            output-low:/*direction out used only. output low or high*/
```



```
МЕДІЛТЕК
```

```
&kd_camera_hw1 {
    pinctrl-names = "default",
            "cam0_rst0", "cam0_rst1",
            "cam0_pnd0", "cam0_pnd1",
            "cam1 rst0", "cam1 rst1",
            "cam1 pnd0", "cam1 pnd1",
            "cam2 rst0", "cam2 rst1",
            "cam2 pnd0", "cam2 pnd1",
            "cam ldo vcamd O", "cam ldo vcamd 1",
            "cam ldo main2 vcamd O", "cam ldo main2 vcamd 1"
            "camO mclk off", "camO mclk on",
            "cam1 mclk off", "cam1 mclk on",
            "cam2 mclk off", "cam2 mclk on";
    pinctrl-0 = <&camera pins default>;
    pinctrl-1 = <&camera pins camO rst 0>;
    pinctr1-2 = <&camera pins camO rst 1>;
    pinctrl-3 = <&camera pins camO pnd O>;
    pinctrl-4 = <&camera pins camO pnd 1>;
    pinctrl-5 = <&camera pins cam1 rst 0>;
    pinctrl-6 = <&camera pins cam1 rst 1>;
    pinctrl-7 = <&camera pins cam1 pnd 0>;
    pinctrl-8 = <&camera pins cam1 pnd 1>;
    pinctr1-9 = <&camera_pins_cam2_rst_0>;
    pinctrl-10 = <&camera pins cam2 rst 1>;
    pinctrl-11 = <&camera pins cam2 pnd 0>;
    pinctrl-12 = <&camera pins cam2 pnd 1>;
    pinctrl-13 = <&camera pins cam0 vcamd 0>;
    pinctrl-14 = <&camera pins camO vcamd 1>;
    pinctrl-15 = <&camera pins cam2 vcamd 0>;
    pinctrl-16 = <&camera_pins_cam2_vcamd_1>;
    pinctrl-17 = <&camera_pins_camO_mclk_off>;
    pinctrl-18 = <&camera pins camO mclk on>;
    pinctrl-19 = <@camera pins cam1 mclk off>;
    pinctrl-20 = <&camera pins cam1 mclk on>;
    pinctrl-21 = <&camera pins cam2 mclk off>;
    pinctr1-22 = <&camera pins_cam2_mclk_on>;
    status = "okay";
};
```

#### 2.9 **MOL**

http://online.mediatek.inc/Pages/eCourse.aspx?Tags=camera+driver

#### 2.10 Feature Table

#### **Related size determination**

(1) The maximum value of picture-size-values (max(width\*height)), the aspect ratio is as close as possible to the sensor resolution, and the width and height need 16 align

Note: In picture, if the resolution of the current sensor is greater than 1080P, be sure to include the size in picture size. ("1920x1080").

(2) The maximum value in preview-size-values and the maximum value in picture-size-values should be consistent or controlled within 0.01. It is recommended that the maximum preview-size should not exceed the resolution of the screen.



#### Note: ratio is also the aspect ratio of the scale.

(3) Video-size-values should include the following resolution as much as possible:

QCIF 176X144, QVGA 320X240 CIF 352X288,

480p 720x480, 720p 1280x720, 1080p 1920x1088

Specifically check /system/etc/permissions/media profile.xml

If the above file does not exist, please find the answer at framworks/av/media/libmedia/MediaProfiles.cpp

And the preview-size-values must contain the values in video-size-values.

#### **AF** function determination

device/mediatek/<project>/android.hardware.camera.xml

if the platform has no lens, no auto focus, please delete it:

<feature name="android.hardware.camera.autofocus" />

KEY\_FOCUS\_MODE default set it as FOCUS\_MODE\_FIXED, Values set it as FOCUS\_MODE\_FIXED

#### Flashlight function determination

If the platform does not support flash, please delete:

<feature name="android.hardware.camera.flash" />

And configure KEY\_FLASH\_MODE as a null string in the feature table"

note: flashlight feature table (hal/../../hal/flashlight/config.flashlight\*\*\*)

#### Other function determination

- (1) KEY\_ANTIBANDING must have ANTIBANDING\_AUTO mode
- (2) Front camera does not support continuous shooting. Capture mode is removed.
- (3) Fps range:

If the Sensor can support it, please modify the range in the feature table as follows:FTABLE\_CONFIG\_AS\_TYPE\_OF\_USER( KEY\_AS\_(MtkCameraParameters::KEY\_PREVIE W\_FPS\_RANGE),

SCENE\_AS\_DEFAULT\_SCENE(

ITEM\_AS\_DEFAULT\_( "5000,30000"),

ITEM\_AS\_USER\_LIST\_(

"(15000,15000)",

"(20000,20000)",

"(5000,30000)",

"(30000,30000)",



# 2.11 FAQ required to see

FAQ12869 KK to L, sensor driver modify

The FAQ has instructions to convert to the 64 bit chip sensor driver that needs to be modified.

FAQ18079 Analysis of common black screen problems

Change direction in FAQ14558 metadata

FAQ19451 pass1 deque fail

FAQ17668 camera feature table fps-range configuration