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Touch Panel Driver Bringup SOP---for Andorid O



Outline

- Key words
- CTP HW interface and Platform instruction
 - I2C interface user guide
- Mediatek Touch Driver Introduction
 - driver architecture
 - useful APIs
 - coordinate calibration method
- touch customization
 - project Config
 - kernel config
 - device tree(dts) of dts
- add a new touch driver step by step
- touch debug



Key words

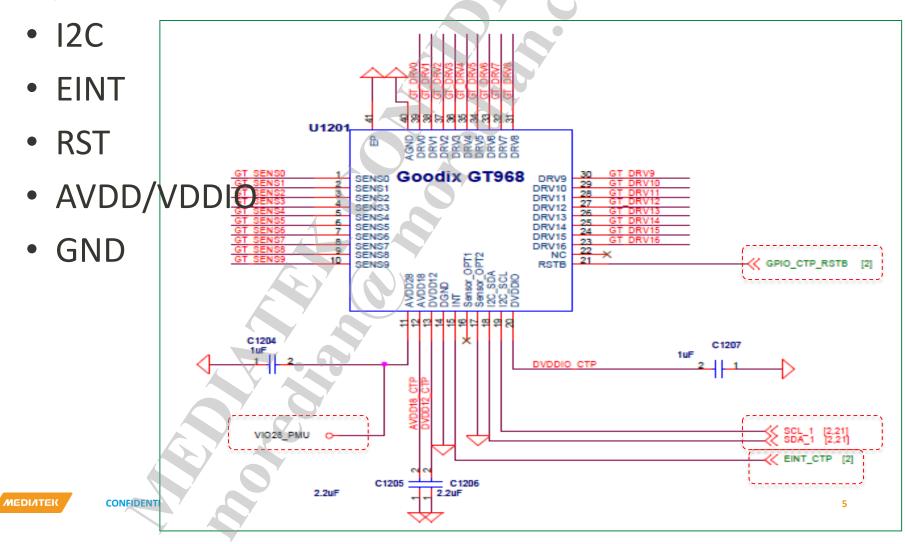
- proj>
 - project name, e.g. tb8183m1 64
- <platform>
 - platform, e.g. mt8183
- <kernel ver>
 - linux kernel version, e.g. kernel-4.4
- <arm_ver>:
 - arm or arm64
- <tp_drv>:
 - specific touch driver name, e.g. GT5688
- <cust folder>:
 - customize information folder e.g. folder for touch config file: "config_default"



CTP HW and Platform Instruction

CTP HW interface

e.g. GT968 HW pad:



Platform instruction

- GPIO /EINT/POWER
 - After got the HW information, you should apply your hardware interface to device tree(".dts"), such as EINT/RST/Power ... etc.
- 12C
 - Mediatek platform I2C support :
 - FIFO mode: read/write 8 Bytes one time
 - DMA mode: only read/write: 65532Byte;

write and read: write 255 Byte, read 31Byte

```
NOTE: For DMA 255x255Byte: The low 8-bit is "trans_len".

The high 8-bit is "trans_num"

\[ \frac{1}{\trans_{\text{lens}}} = \left( \text{msg->len} \right) \left( \text{0xFF}; \text{trans_num} = \left( \text{msg->len} \right) \left\ \text{0xFF}; \text{trans_num} = \left( \text{msg->len} \right) \right\ \text{0xFF}; \text{trans_num} = \left( \text{msg->len} \ri
```



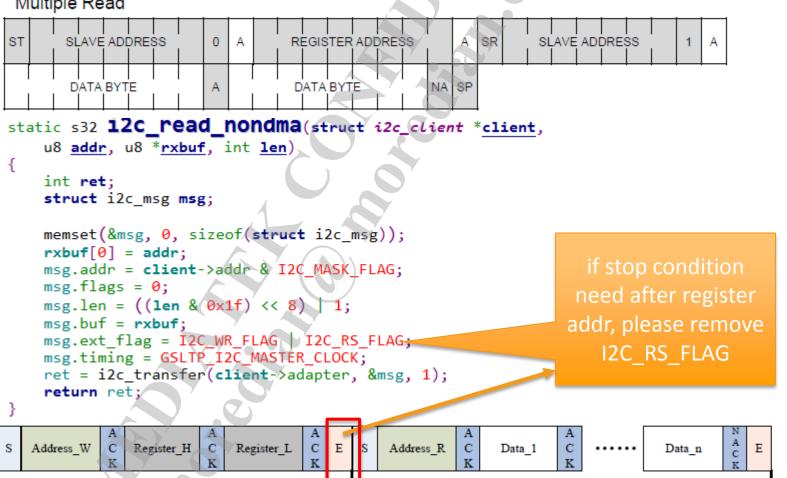
12C interface-Read with FIFO mode

- read with FIFO mode, max 8 bytes one time
 - write and read mode: I2C_WR_FLAG

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without stop condition after register address write: I2C_RS_FLAG
 Multiple Read



I2C interface—Write with FIFO mode

- write with FIFO mode
 - max write 8 bytes one time

```
static s32 i2c write nondma(struct i2c client *client, u8 addr, u8 *txbuf, int len)
    int ret:
    int retry = 0;
    struct i2c msq msq;
    u8 wrBuf[RPR FIFO MAX WR SIZE + 1];
                                                           #define RPR FIFO MAX RD SIZE C I2C FIFO SIZE
                                                           #define RPR FIFO MAX WR SIZE C I2C FIFO SIZE - RPR REG ADDR LEN
    if ((txbuf == NULL) && len > 0)
        return -1:
    memset(&msq, 0, sizeof(struct i2c msq));
    memset (wrBuf, 0, RPR FIFO MAX WR SIZE +
    wrBuf[0] = addr;
    if (txbuf)
        memcpy(wrBuf + 1, txbuf, len);
    msg.flags = 0;
    msq.buf = wrBuf;
    msq.len = 1 + len;
    msq.addr = (client->addr & I2C MASK FLAG);
    msq.ext flag = (client->ext flag | I2C ENEXT FLAG);
    msq.timing = RPR I2C MASTER CLOCK;
    for (retry = 0; retry < 5; ++retry) {</pre>
        ret = i2c transfer(client->adapter, &msg, 1);
        if (ret < 0)</pre>
             continue:
        return 0;
    RPR0521 ERR ("Dma I2C Write Error: 0x%04X, %d bytes, err-code: %d\n", addr, len, ret).
    return ret;
                                                                                 Parameter of i2c write nond
3 ? end i2c write nondma?
```

I2C interface—read with DMA WRRD mode

- read with DMA mode: I2C_DMA_FLAG
 - with write and read mode: I2C_WR_FLAG, max 31bytes
 - without stop condition after register address write:
 I2C RS FLAG

```
static s32 i2c_dma_read(struct i2c_client *client, u8 addr, u8
{
  int ret;
  struct i2c_msg msg;

  memset(&msg, 0, sizeof(struct i2c_msg));
  *g_dma_buff_va = addr;
  msg.addr = client->addr & I2C_MASK_FLAG;
  msg.flags = 0;
  msg.len = ((len & 0x1f) << 8) | 1;
  msg.buf = g_dma_buff_pa;
  msg.ext_flag = I2C_WR_FLAG | I2C_RS_FLAG | I2C_DMA_FLAG;
  msg.timing = GSLTP_I2C_MASTER_CLOCK;

  ret = i2c_transfer(client->adapter, &msg, 1);
  memcpy(rxbuf, g_dma_buff_va, len);
  return ret;
}
```

I2C interface—read only with DMA mode

- read only with DMA mode: have I2C_DMA_FLAG but no I2C_WR_FLAG
- there will be a stop condition between msg[0] and msg[1]
- max read length is 65532 bytes

```
static s32 i2c_dma_non_wrrd_read (struct i2c_client *client, u)
   int ret;
   struct i2c msq msq[2];
   memset (&msq, 0, 2 * sizeof (struct i2c msq));
   msq[0].addr = client->addr & I2C MASK FLAG;
   msq[0].flags = 0;
   msg[0].len = GSLTP REG ADDR LEN;
   msq[0].buf = &addr;
   msg[0].ext flag = I2C DMA FLAG;
   msq[0].timing = GSLTP I2C MASTER CLOCK;
   msq[1].addr = client ->addr & I2C MASK FLAG;
   msq[1].flags = 0; /
   msq[1].len = len;
   msg[1].buf = g dma buff pa;
   msq[1].ext flag = I2C DMA FLAG;
   msg[1].timing = GSLTP I2C MASTER CLOCK;
   ret = i2c transfer(client->adapter, &msq, 2);
   memcpy(rxbuf, g dma buff va, len);
   return ret;
} ? end i2c_dma_non_wrrd_read ?
```

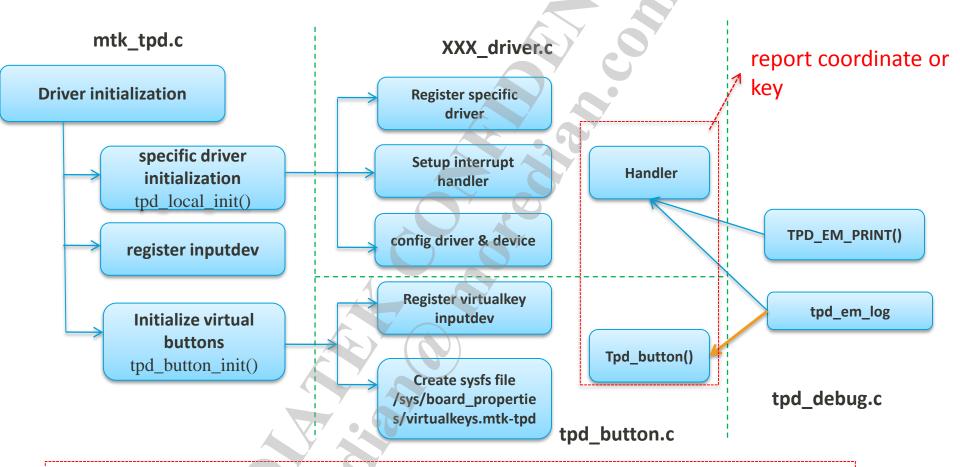
I2C interface—Write with DMA mode

write with DMA mode, max 65532 bytes

Mediatek touch driver introduction

driver architecture and useful notes

Touch Panel Driver Architecture



All specific touch driver are mounted on MTK common touch driver which named mtk_tpd,c



driver file

- path for touch common code: (e.g. mtk_tpd.c):
 - <kernel_ver>/drivers/input/touchscreen/mediatek
- driver for specific touch (e.g. gt1x_tpd.c):
 - <kernel_ver>/drivers/input/touchscreen/mediatek /<tp_drv>
- coutomized touch driver file path(e.g. gt1x_tpd_custom.h)
 - <kernel_ver>/drivers/input/touchscreen/mediatek /<tp_drv>/include/<cust_folder>
 - set customized file path in kernel config
 - <kernel_ver>/arch/<arm_ver>/configs/



APIs used in touch(1)

- Use of_find_compatible_node to get your dts node, or use the probe callback of platform drivers to get populated dts node
- please make sure that return type of interrupt handler is irqreturn_t
 and must return with IRQ_HANDLED

APIs used in touch(2)

- Use irq_of_parse_and_map() to get virtual irq
- Use request_irq() instead to register IRQ
 - interrupt flag should be IRQF_TRIGGER_NONE, since irq_of_parse_and_map() already set trigger type, you can also overwrite the trigger type here)
- Use enable_irq()/disable_irq() to enable and disable irq
 - use disable_irq_nosync() in irq context instead
 - please make sure balance of enable_irq and disable_irq
 - default irq is enabled after request_irq, don't enable_irq again
- Use irq_set_irq_type() to change irq trigger type
- use enable_irq_wake() and disable_irq_wake() for irq with wakeup request



customize --- Calibration

- SW use the matrix to make touch coordinate match with LCM coordinate
 - <kernel_ver>/drivers/input/touchscreen/mediatek/<tp_dr v>/include/<cust_folder>/ tpd_custom_gt9xx.h

#define TPD_CALIBRATION_MATRIX_ROTATION_NORMAL (1096,0,0,0,3686,0,0,0);
#define TPD_CALIBRATION_MATRIX_ROTATION_FACTORY (1096,0,0,0,3686,0,0,0); $\begin{bmatrix}
X' \\
Y'
\end{bmatrix} = \begin{bmatrix}
A & B & C \\
D & E & F
\end{bmatrix} \begin{bmatrix}
X \\
Y \\
1
\end{bmatrix}$ 4096Ax + By + C = ResX * 4096

Dx + Ey + F = ResY * 4096

(X,Y): touch point, e.g. (0,0);(0,1280)...

(X',Y')=(ResX,ResY): LCM point

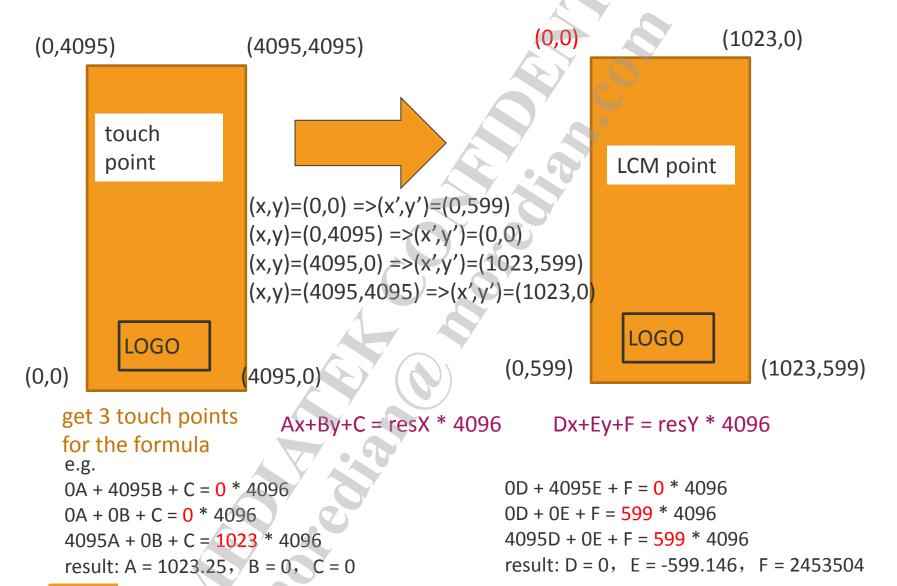


[63:mtk-tpd]<<-GTP-DEBUG->> [2284]Original touch coordinate: [X:0001, Y:0595]

[63:mtk-tpd]<<-GTP-DEBUG->> [2290] Touch coordinate after calibration: [X:0001, Y:0494]

 (x_{2}, y_{2})

customize—coordinate calibration





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earyly suspend

- there is no early suspend, please use fb_notifier instead
- touch should wakelock itself when it want to wakeup the system
- code of fb_notifier is in mtk_tpd.c, it's not need to modify

```
static struct notifier_block tpd_fb_notifier;
/* use fb_notifier */
static void touch_resume_workqueue_callback(struct work_st

{
   TPD_DEBUG("GTP touch_resume_workqueue_callback\n");
   g_tpd_drv->resume(NULL);
   tpd_suspend_flag = 0;
}
static int tpd_fb_notifier_callback(struct notifier_block *self,
```



touch customization

configuration items

project configuration

- ProjectConfig.mk (device/mediatek/<proj>)
- check information:
 - CUSTOM_KERNEL_TOUCHPANEL = <tp_drv>
 - for Goodix hotknot supported touch, please set <tp_drv> as "GT9XX" for GT9XX series touch, and please set as "GT1XX" for GT1XX series touch

```
CUSTOM_KERNEL_SUB_LENS = dummy_lens
CUSTOM_KERNEL_TOUCHPANEL = GT9XX
```

GT9XX for GT9XX series that support hotknot



- kernel config file:
 - <proj>_debug_defconfig
 - <proj>_defconfig
- config file path:
 - 32 bits : <kernel_ver>/arch/arm/configs
 - 64 bits : <kernel_ver>/arch/arm64/configs
- check contents in config file
 - CONFIG_MTK_TOUCHPANEL=y
 - CONFIG_INPUT_TOUCHSCREEN=y
 - CONFIG_TOUCH_SCREEN_<tp_drv>=y
 - _<tp_drv> : shows the real touch driver you used, please refer to Kconfig file (<kernel ver>/drivers/input/touchscreen/mediatek/Kconfig)



- Kconfig: shows which real touch driver is match to your config
 - <kernel_ver>/drivers/input/touchscreen/mediatek/Kc onfig
 - e.g. CONFIG_TOUCHSCREEN_MTK_GT9XXTB_HOTKNOT=y, means the real touch driver is GT9XXTB_hotknot

```
bool "GT9XXTB hotknot for Mediatek package"
default n
help
Say Y here if you have GT9xx touch panel.

To compile this dirver as a module, choose M here: the module will be called.

Touch Driver
path

To compile this dirver as a module, choose M here: the module will be called.
```



- you should config customized file path in kernel config, please refer to Kconfig for add and update customized file
- step1: kernel config
 - CONFIG_<tp_drv>_FIRMWARE="<cust_folder>"
 - CONFIG_<tp_drv>_CONFIG ="<cust_folder >"
 - e.g.:

 CONFIG GT9XXTB_FIRMWARE="firmware_default" | config GT9XXTB_CONFIG="config_default" | config file
- step2: check Kconfig
 - path: <kernel_ver>/drivers/input/touchscreen/mediatek/<tp_dr v>/Kconfig

```
string "GT9XXTB_FIRMWARE string "GT9XXTB_hotknot for Mediatek firmware"

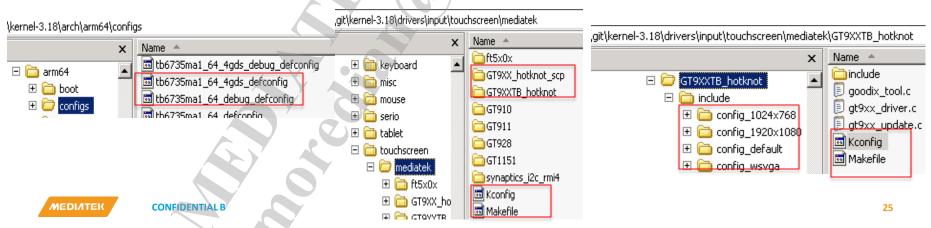
config GT9XXTB_CONFIG string "GT9XXTB_hotknot for Mediate Kconfig file
```

kernel config match with Kconfig

- Make file: check and add your customized file path
- path: <kernel_ver>/drivers/input/touchscreen/mediatek/<tp_drv>/makefile

```
ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/GT9XXTB_hotknot/
ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/
ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/GT9XXTB_hotknot/include/$(CONFIG_GT9XXTB_FIRMWARE)/
ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/GT9XXTB_hotknot/include/$(CONFIG_GT9XXTB_CONFIG)/
ccflags-y += -I$(srctree)/drivers/misc/mediatek/include/mt-plat/
ccflags-y += -I$(srctree)/drivers/misc/mediatek/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/mt-plat/$(MTK_PLATFORM)/include/**
```

file and folder examples:



config for specific touch driver

```
#define GTP_CUSTOM_CFG
#define GTP_DRIVER_SEND_CFG
#define GTP_HAVE_TOUCH_KEY

#config_GTP_DRIVER_SEND_CFG
1
CONFIG_GTP_DRIVER_SEND_CFG
1
CONFIG_GTP_AUTO_UPDATE=y
CONFIG_GTP_HEADER_FW_UPDATE=y
CONFIG_GTP_CREATE_WR_NODE=y
```

kernel config

```
Kconfig also need relative settings
```

```
config GTP_DRIVER_SEND_CFG

bool "GTP_DRIVER_SEND_CFG"

default n

help

Say Y here if you have GT9XXTB_hotknot touch panel GTP_DEBUG_FUNC_ON.

If unsure, say N.

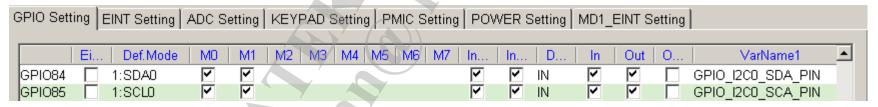
To compile this dirver as a module, choose M here: the module will be called.
```

touch customization

dws and dts

DWS file- I2C

- check i2c setting in dws file
 - <kernel_ver>/drivers/misc/mediatek/dws/<platfrom >/<proj>.dws
 - e.g. touch panel uses 12C id0
 - VarName1 should be
 - GPIO_I2CO_SDA_PIN
 - GPIO_I2CO_SDA_PIN



I2C address config





DWS file - CTP RST/EINT Pin

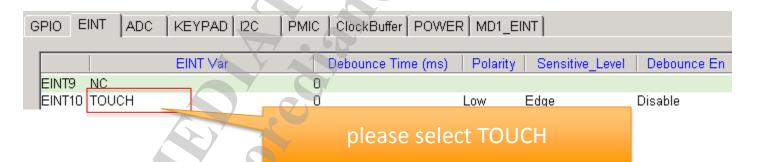
- RST Pin
 - VarName1 should be GPIO CTP RST PIN



- EINT Pin
 - check EINT mode
 - VarName1 should be GPIO_CTP_EINT_PIN



- EINT setting: please refer to CTP spec for setting EINT setting,
- note: please select TOUCH for EINT Var



dts file

- file path: <kernel_ver>/arch/<arm_ver>/boot/dts/<proj>.dts
 - please include platform dts file (< platform >.dtsi)
 - please include cust.dtsi (maybe had included in < platform >.dtsi , if so, doesn't need to include again in proj>.dts) #include "mt6735m.dtsi"
 #include "tb6735ma1 64 bat setting.dtsi"
- touch node:
 - root node: <kernel_ver>/arch/<arm_ver>/boot/dts/<platform>.dtsi
 - compatible string should match with software, SW use of_find_matching_node() read device tree information from dts file (mtk_tpd.c)
- note: device tree node name and compatible string should be lowercase

#include "cust.dtsi"

device tree node

attach node for touch, <proj>.dts

```
&touch {
 tpd-resolution = <800 1280>;
 use-tpd-button = <0>;
                                          touch that have keys
 tpd-key-num = <3>;
 tpd-key-local= <139 172 158 0>;
 tpd-key-dim-local = <90 883 100 40 230 883 100 40 370 883 100 40 0 0 0 0>;
 tpd-max-touch-num = <5>;
 tpd-filter-enable = <1>;
 tpd-filter-pixel-density = <93>;
 tpd-filter-custom-prameters = <0 0 0 0 0 0 0 0 0 0 0 >:
 tpd-filter-custom-speed = <0 0 0>;
 pinctrl-names = "default", "state eint as int",
                                               "state eint output0",
                                                                   "state_eint_output1",
   "state rst output0", "state rst output1";
 pinctrl-0 = <&CTP pins default>;
                                             GPIO info, use pinctri lookup state()to
 pinctrl-1 = <&CTP pins eint as int>:
                                           get the info, and use pinctal select state()
 pinctr1-2 = <&CTP pins eint output0>;
 pinctrl-3 = <&CTP pins eint output1>;
                                                          do GPIO setting
 pinctrl-4 = <&CTP pins rst output0>;
 pinctrl-5 = < \&CTP pins rst output1>;
 status = "okay";
);
                    int tpd_get_gpio_info(struct platform_device *pdev)
                         eint output0 = pinctrl lookup state(pinctrl1, "state eint output0")
                     void tpd_gpio_output(int pin, int level
                         pinctrl select state(pinctrl1, eint output0);
```

dts node--Parameters Introduction

Parameter	Introduction	Comments	
tpd_resolution[2]	touch panel resolution info for x and y axis	tpd_resolution[0]: LCM resolution of x axis tpd_resolution[1]: LCM resolution of y axis	
use_tpd_button	define whether the touch panel use virtual key	1 stands for touch panel use touch virtual key 0 stands for touch panel not use touch virtual key	
tpd_key_num	The number of the touch virtual key. you can not set this parameter if use_tpd_button is 0.	The max of the key number is 4.	
tpd_key_local[4]	the Linux key value if touch virtual key is used, you can not set this parameter if use_tpd_button is 0.	fill in Linux key code which will use for virtual key on touch panel, layout from left to right corresponding to array value tpd_key_local[0], tpd_key_local[1], tpd_key_local[2], tpd_key_local[3]	
tpd_key_dim_local[4] (include 4 parameters tpd_key_dim_local[4].key_x, tpd_key_dim_local[4].key_y, tpd_key_dim_local[4].key_width, tpd_key_dim_local[4].key_high)	the key layout info if touch virtual key is used, you can not set this parameter if use_tpd_button is 0.	every tpd_key_dim_local[i] corresponding to tpd_key_local[i] tpd_key_dim_local[i].key_x: location on x axis of tpd_key_local[i] tpd_key_dim_local[i].key_y: location on y axis of tpd_key_local[i] tpd_key_local[i] tpd_key_dim_local[i].key_width: width of tpd_key_local[i] tpd_key_local[i] tpd_key_local[i].key_high: height of tpd_key_local[i]	

device tree node

- attach node of touch--pinctrl
 - mainly check reset pin and EINT pin

```
&pio {
 CTP pins default: eintOdefault {
 };
CTP pins eint as int: eint@O {
  pins cmd dat {
    pins = <PINMUX GPIO10 FUNC GPIO10>;
     slew-rate = <0>;
    bias-disable:
  };
};
CTP pins eint outputO: eintoutputO
  pins cmd dat {
                            FUNC GPI010>;
     pins = <PINMUX GPIO10
     slew-rate = <1>;
     output-low;
  );
};
```

mode is output and output High, please refer to pinctrl SOP

```
CTP pins eint output1: eintoutput1 {
    pins cmd dat {
      pins = <PINMUX GPIO10
                             FUNC GPIO10>;
      slew-rate = <1>;
      output-high;
   );
  };
 CTP pins rst outputO: rstoutputO {
    pins cmd dat {
      pins = <PINMUX GPIO62 FUNC GPIO62>;
      slew-rate = <1>;
      output-low;
   );
 };
 CTP pins rst output1: rstoutput1 {
    pins cmd dat {
      pins = <PINMUX GPIO62
                             FUNC GPIO62>;
      slew-rate = <1>;
     output-high;
   };
/* TOUCH end */
```

device tree node—I2C & EINT

- i2c and interrupt info for touch
 - modify dws, nodes as below in cust.dtsi will be generated by dws file
 - note: interrupt trigger type (e.g. IRQ_TYPE_EDGE_FALLING)should be the ones that defined int the following files
 - <kernel_ver>/include/dt-bindings/interrupt-controller/arm-gic.h
 - <kernel_ver>/include/dt-bindings/interrupt-controller/irq.h

```
&i2c0 {
                                                     Touch use I2CO, and slave address
             pinctrl-names = "default";
                                                     is 0x38
             pinctrl-0 = <&i2c0 pins a>>
             status = "okav";
                                                      compatible info, SW use it to find
             cap touch@38
                                                      the touch node in dts file, should
               compatible = "mediatek, cap touch";
                                                      same with SW.
               req = <0x38>;
               interrupt-parent = <&pio>;
               interrupts = <46 IRQ TYPE EDGE FALLING>:
               int-qpio = \langle \&pio 35 0 \rangle;
               rst-gpio = <500 45 0>;
                                                   static const struct of device id tpd of match[] = {
                                                     {.compatible = "mediatek, cap touch"},
EINT pin info, IRQ_TYPE_EDGE_FALLING
                                                     {},
can't be wrong
                                                   };
```

device tree node—I2C & EINT

- modify dws file is needed, nodes as below will be generated by dws file (cust.dtsi)
 - e.g. attach nodes in cust.dtsi("&touch" means this is attach information of "touch" node)

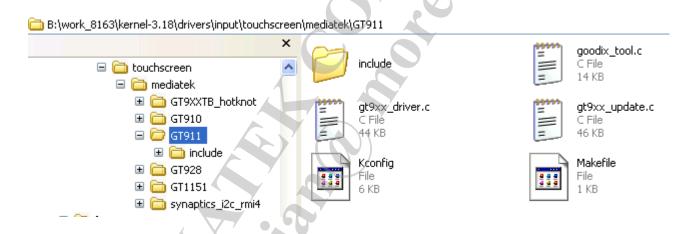
```
&touch {
   interrupt-parent = <&eintc>;
   interrupts = <10 IRQ TYPE EDGE FALLING>;
   debounce = <10 \text{ 0}>;
   status = "okav";
gtouch {
   vtouch-supply = <&mt pmic vgp1 ldo reg>;
   status = "okay";
5 };
 &i2c1 {
   #address-cells = <1>;
   #size-cells = <0>;
   cap touch@5d {
     compatible = "mediatek, cap touch";
     reg = \langle 0x5d \rangle;
     status = "okay";
   };
```

i2c info and compatible info of touch

Add a New Touch **Driver**

Touch Screen – Add New Driver (1/5)

- How to add a new touch driver in codebase
 - Path: ./<kernel_ver>/drivers/input/touchscreen/mediatek/
 - Add your driver source code.





Touch Screen – Add New Driver (2/5)

• Add the Makefile and Kconfig file driver needs, can be modeled on the other driver. Some customizable option defined here, too.

```
B:\work_8163\kernel-3.18\drivers\input\touchscreen\mediatek\GT911\Makefile
 4 ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/
5 ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/GT911/include/$(CONFIG GT911 FIRMWARE)/
6 ccflags-y += -I$(srctree)/drivers/input/touchscreen/mediatek/GT911/include/$(CONFIG GT911 CONFIG)/
7 ccflags-y += -I$(srctree)/drivers/misc/mediatek/include/mt-plat/
8 ccflags-y += -I$(srctree)/drivers/misc/mediatek/include/mt-plat/$(MTK PLATFORM)/include/
10 obj−y +=
          goodix tool.o
11 obj-v +=
          gt9xx driver.o
12 obj-y += gt9xx update.o
B:\work 8163\kernel-3.18\drivers\input\touchscreen\mediatek\GT911\Kconfig
  2 # Touchscreen driver configuration
     TOUCHSCREEN MTK GT911
 6 config GT911 FIRMWARE
    string "GT911 for Mediatek firmware"
 9 config GT911 CONFIG
    string "GT911 for Mediatek config"
12 config GTP DRIVER SEND CFG
    bool "GT911 for Mediatek package"
    default n
```



Touch Screen – Add New Driver (3/5)

Modify /<kernel_ver>/drivers/input/touchscreen/mediatek/Makefile.
 Add specific driver build option in Makefile.

```
■ B:\work_8163\kernel-3.18\drivers\input\touchscreen\mediatek\Makefile
 4 obj-y
             mtk tpd.o
 5 obj-y
             tpd button.o
             tpd calibrate.o
6 obj-y
             tpd debug.o
7 obj-y
             tpd default.o
 8 obj-y
             tpd init.o
9 obj-y
10 obj-y
             tpd misc.o
11 obj-y
             tpd setting.o
12
13 obj-$(CONFIG TOUCHSCREEN MTK GT1151)
14 obj-$ (CONFIG TOUCHSCREEN MTK GT910) +=
15 obj-$(CONFIG TOUCHSCREEN MTK GT9XXTB HOTKNOT) +=
                                                 GT9XXTB hotknot/
16 obj-$ (CONFIG TOUCHSCREEN MTK SYNAPTICS 12C RM14)
                                                    synaptics i2c rmi4/
17 obj-$ (CONFIG TOUCHSCREEN MTK GT928)
18 bbj-$ (CONFIG TOUCHSCREEN MTK GT911)
```



Touch Screen – Add New Driver (4/5)

Modify /<kernel_ver>/drivers/input/touchscreen/mediatek/Kconfig.
 Add real driver config option in Kconfig.

```
B:\work_8163\kernel-3.18\drivers\input\touchscreen\mediatek\Kconfig
   81
82 source "drivers/input/touchscreen/mediatek/GT910/Kconfig"
83
  config TOUCHSCREEN MTK GT911
    bool "GT1151 for Mediatek package"
    default n
86
87
    help
    Say Y here if you have GT911 touch panel.
89
    If unsure, say N.
90
91
    To compile this dirver as a module, choose M here: the
92
    module will be called.
95 source "drivers/input/touchscreen/mediatek/GT911/Kconfig"
96 endif
```



Touch Screen – Add New Driver (5/5)

- Modify <kernel_ver>/arch/<arm_ver>/configs/<proj>_defconfig
- Modify

 kernel_ver>/arch/<arm_ver>/configs/<proj>_debug_defconfig)





- confirm touch driver has been build in load
 - if no, check project config, kernel config, Makefile and Kconfig file
- check touch log
 - enable touch log: use "pr_err" for all log macro in driver, e.g.
 - #define GTP_DEBUG(fmt, arg...) pr_err("<<-GTP-DEBUG->>
 [%d]"fmt"\n", __LINE__, ##arg)
- check touch input event
 - use "adb shell getevent -i" to get input event number of "mtk-tpd".
 - e.g. if "mtk-tpd" is event3, use "adb shell getevent /dev/input/event3" get touch input event.

```
[tpd em log] raw x = 300, raw y = 656, cal x = 190, cal y = 306, z1 = 154, z2 = 681, state = down (+10 ms [tpd em log] raw x = 317, raw y = 623, cal x = 187, cal y = 300, z1 = 162, z2 = 653, state = down (+10 ms
```



 touch input event type/code are shown as below table.

type	code		value
1=EV_KEY	0x14a (330)	= BTN_TOUCH	Down=1, Up=0
3=EV_ABS	0x30 (48)	= ABS_MT_TOUCH_MAJOR	1
3=EV_ABS	0x35 (53)	= ABS_MT_POSITION_X	x=284
3=EV_ABS	0x36 (54)	= ABS_MT_POSITION_Y	y=366
3=EV_ABS	0x39 (57)	= ABS_MT_TRACKING_ID	point index=1
O=EV_SYN	0x2(2)	= SYN_MT_REPORT	0
O=EV_SYN	0x0(0)	= SYN_REPORT	0



- check dws and dts setting with schematics
 - AVDD regulator configuration
 - check dws & dts for I2C info and interrupt information

```
cap_touch@38 {
  compatible = "mediatek,cap_touch";
  reg = <0x38>;
  interrupt-parent = <&pio>;
  interrupts = <46 IRQ_TYPE_EDGE_FALLING>;
  int-gpio = <&pio 35 0>;
  rst-gpio = <&pio 45 0>;
};

interrupt and GPIO info
touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  power supply: regulator
  int-gpio = <&pio 35 0>;
  interrupt and GPIO info

touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
}

**Touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
}

**Touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
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  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
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  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
}

**Touch: touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
}

**Touch: touch: touch {
  compatible = "mediatek,mt6735-touch";
  vtouch-supply = <&mt_pmic_vgp1_ldo_reg>;
  interrupt and GPIO info
}

**Touch: touch: touch:
```

- software check
 - regulator control should balance bwtween enable and disable
 - regulator_set_voltage(), regulator_enable()......
 - use irq_of_parse_and_map() to get virtual irq
 - use request_irq() to register IRQ
 - enable_irq() should balance with disable_irq()



- check the waveform of VDD/SCL/SDA/RESET/INT pins by scope to make sure touch IC works normally.
- For coordinate not match with LCM coordinate issue
 - check touch FW and customization table
 - check TPD_CALIBRATION_MATRIX
 - #define TPD_CALIBRATION_MATRIX_ROTATION_NORMAL
 - #define
 TPD CALIBRATION MATRIX ROTATION FACTORY



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