

everyday genius

# **eMMC Customization Bring-up SOP**

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## **Document Revision History**

Revision	Date	Description	
1.0	2019-09-12	Initial Draft	
			20



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## 1. Introduction

The purpose of this document is eMMC boot programming guild, for example eMMC IO driving strength,pull-down/pull-up.

## 1.1 Purpose

The purpose of this document is eMMC boot programming guild. It will contain four parts, eMMC GPIO setting , eMMC IO strength setting

## 1.2 Definitions, Acronyms and Abbreviations

N/A

### 1.3 References

N/A

### 1.4 Overview

Section 1 is mt8788 supported feature

Section 2 introduce eMMC framework.

Section 3 is eMMC GPIO seting.

Section 4 is how to handle eMMC error during bring-up.



## 2. eMMC bring-up Contents

## 2.1 mt8788 support eMMC Feature

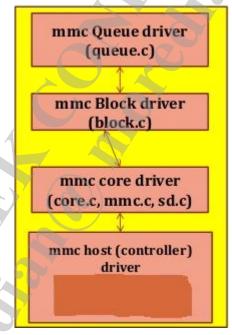
Support 1bit/4bit/8bit Bus mode
Support HS200 mode, data rate up to 200\*8Mbps
Support HS400 mode, data rate up to 200\*8\*2MBps
Support eMMC5.1 CQ
Support eMMC Boot up mode

#### 2.2 eMMC Linux Framework

Linux eMMC driver locate in kernel-4.14/drivers/mmc, It contains two directory.

Core/ bus.c core.c mmc.c mmc\_ops.c host.c queue.c block.c

Host/ mediatek/ComboA/



- mmc queue receives block read/write/erase requests from the generic core block layer.
- mmc queue driver picks up one request from its queue and assign it to mmc block driver.
- mmc block driver analyze the type of request and forwards the request to mmc core driver.
- mmc core driver has the protocol implementation for eMMC device detection, enumeration and data transfers to communicated with the actual hardware device.
- mmc core driver receives the request from block driver, prepares a mmc\_request and forwards it to the mmc host driver.
- mmc host driver initiates the transfer to device by programming Hardware controller register.
- Once the request get processed by the hardware controller, an interrupt gets generated.
- \_\_ mmc host driver receives request complete interrupt, analyzes it and pass the response to block driver.

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This process continues for all block requests.

## 2.3 eMMC GPIO setting

#### 2.3.1 DCT tool and .dws file.

We use DCT tool to set gpio property in .dws file. These properties are GPIO mode, pull-pu/pull-down, direction and so on.

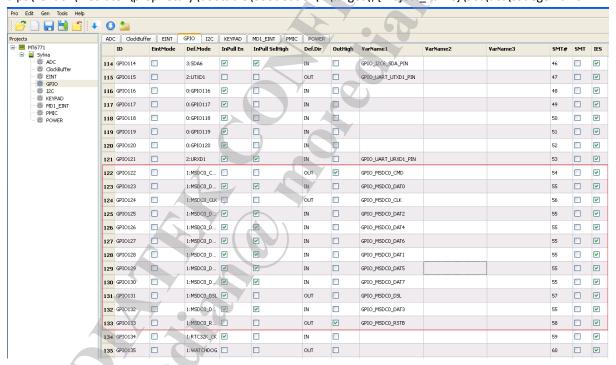
The DCT tool located in alps\vendor\mediatek\proprietary\scripts\dct\DrvGen.exe

There are three .dws files and eMMC gpio setting should be same.

alps\kernel-4.14\drivers\misc\mediatek\dws\mt6771\{Project}.dws

alps\vendor\mediatek\proprietary\bootable\bootloader\preloader\custom\\${Project\_name}\dct\dct\codegen
.dws

alps\vendor\mediatek\proprietary\bootable\bootloader\lk\target\\${Project\_name}\dct\dct\codegen.dws



#### 2.3.2 10 driving strength in .dtsi file.

We can not set GPIO IO driving strength in dws file. IO driving strength is set in cust\_mt6771\_msdc.dtsi. It located kernel-4.14/arch/arm64/boot/dts/mediatek/cust\_mt6771\_msdc.dtsi.





#### 2.4 eMMC crc error.

If you meet the issue that board cannot boot-up, due to many eMMC error from uart log. You can disable eMMC HS200 and HS400 mode, only run high-speed mode with lower frequency.

The setting is also in cust\_mt6771\_msdc.dtsi

```
clk_src = /bits/
bus-width =
max-frequency
cap-mmc-highspeed;
msdc-sys-suspend;
mmc-ddr-1_8v;
mmc-hs200-1 89
   -hs400-1
pinctl =
register setting
host function =
status =
vmmc-supply
clocks =
clock-names
hw dvfs =
```

Then feedback the issue to mediatek. We will analysis it and check root cause.