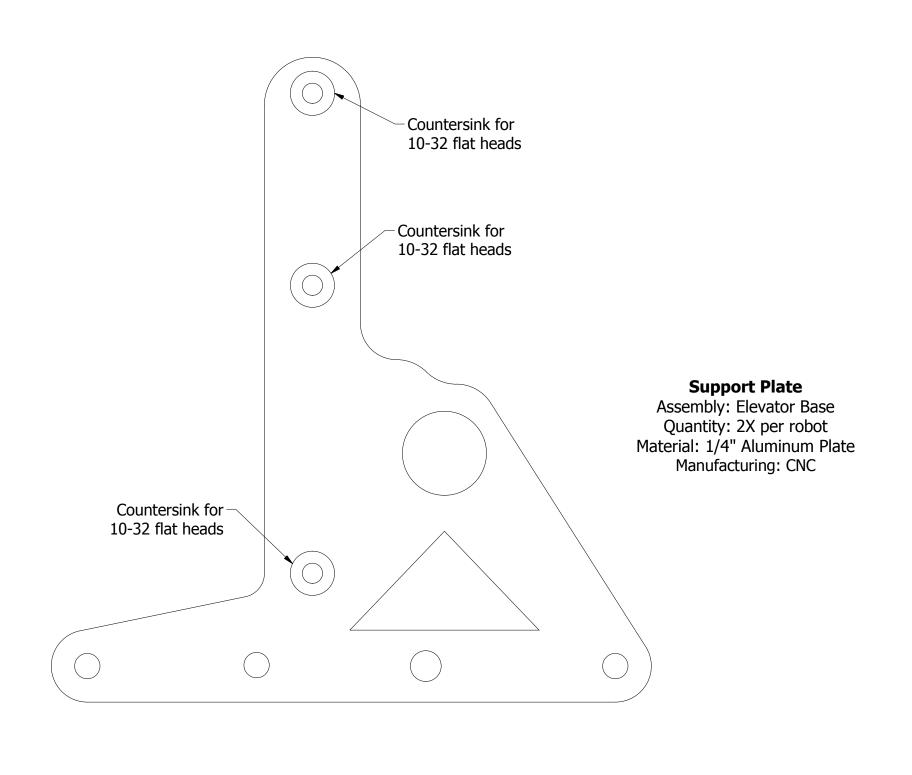
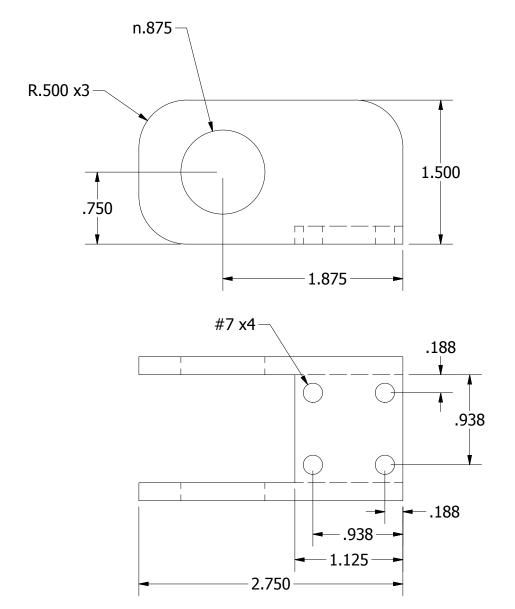
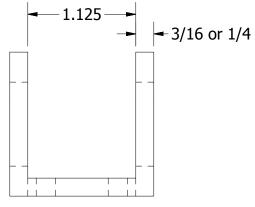
# **Elevator Base**

PARTS LIST						
ITEM	QTY	PART NUMBER	MASS	MATERIAL		
1	2	Rail	1.909 lbmass	Aluminum		
2	2	Support Plate	0.346 lbmass	Aluminum		
3	2	First Stage Pulley Bracket	0.144 lbmass	Aluminum		
4	2	15T XL Pulley	0.059 lbmass	Aluminum		
5	2	1.125" Printed Pulley	0.025 lbmass	Printed ABS		
6	2	First Stage Belt	0.077 lbmass	Purchased		
7	2	First Stage Anchor	0.110 lbmass	Aluminum		
8	1	Driveshaft	0.703 lbmass	Steel		

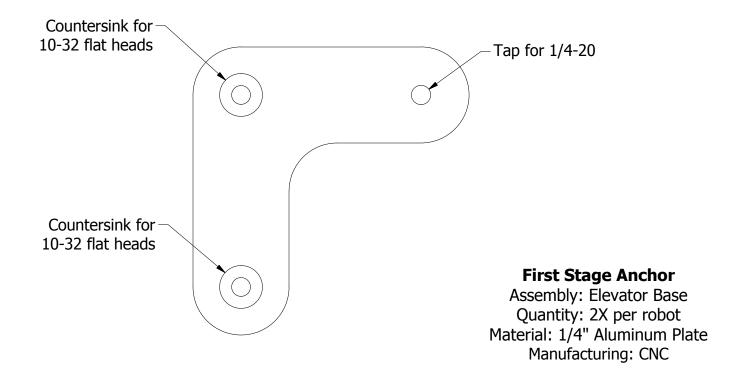


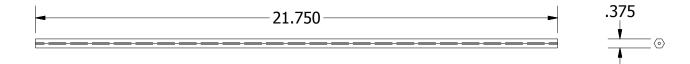




## **First Stage Pulley Bracket**

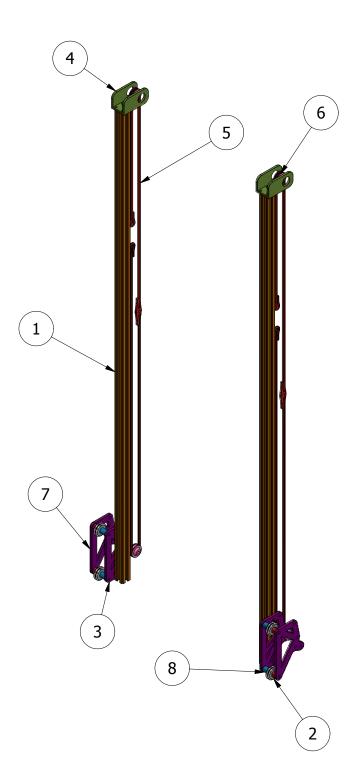
Assembly: Elevator Base
Quantity: 2X per robot
Material: 3/16" by 1.5" C Channel
or 1/4" by 1.625" C Channel
Manufacturing: Mill





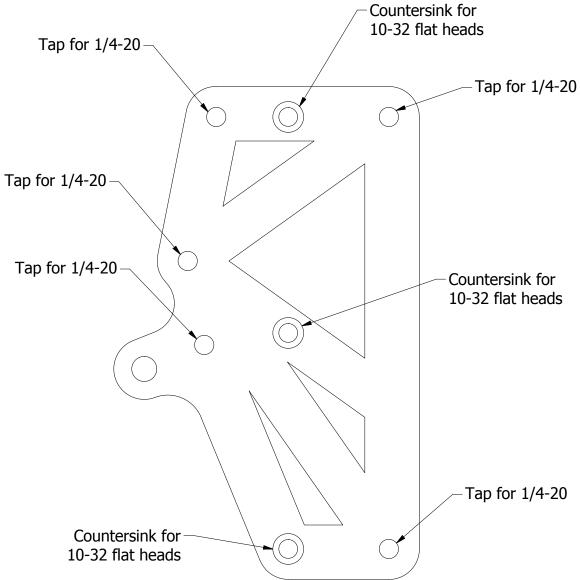
### **Driveshaft**

Assembly: Elevator Base Quantity: 2X per robot Material: 3/8" Steel Hex Shaft Manufacturing: Cut from stock



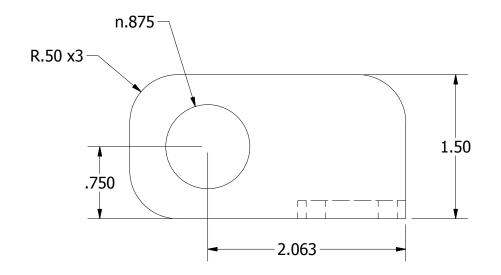
# **First Stage**

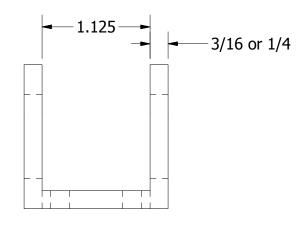
PARTS LIST						
ITEM	QTY	PART NUMBER	MASS	MATERIAL		
1	2	Rail	1.909 lbmass	Aluminum		
2	6	Roller and Bushing	0.111 lbmass	Purchased		
3	2	Middle Plate	0.240 lbmass	Aluminum		
4	2	Second Stage Pulley Bracket	0.151 lbmass	Aluminum		
5	2	Second Stage Belt	0.133 lbmass	Paracord		
6	4	Line Pulley	0.010 lbmass	Printed ABS		
7	2	Outside Plate	0.192 lbmass	Aluminum		
8	6	First Stage Roller Spacer	0.009 lbmass	Aluminum		

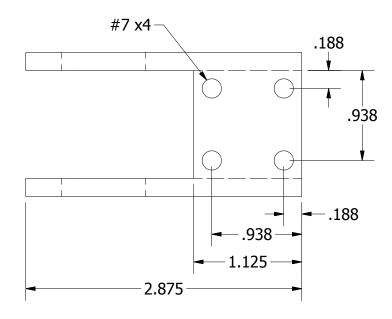


Assembly: First Stage Quantity: 2X per robot Material: 1/4" Aluminum Plate Manufacturing: CNC

**Middle Plate** 

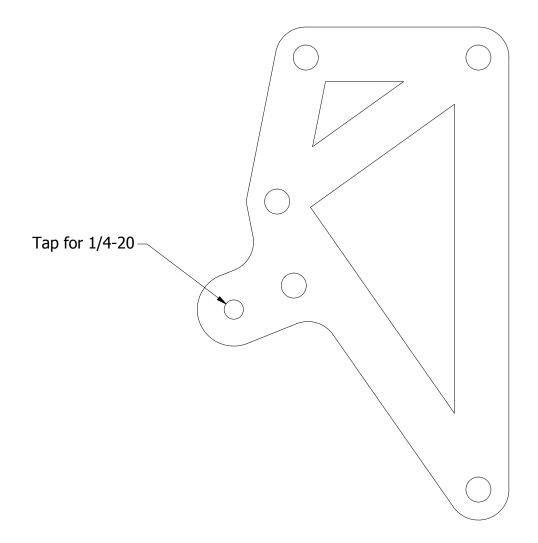






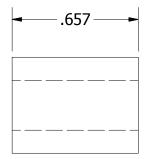
# **Second Stage Pulley Bracket**

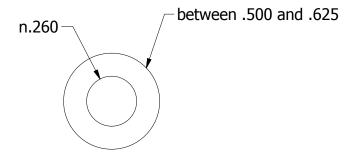
Assembly: First Stage
Quantity: 2X per robot
Material: 3/16" by 1.5" C Channel
or 1/4" by 1.625" C Channel
Manufacturing: Mill



### **Outside Plate**

Assembly: First Stage
Quantity: 2X per robot
Material: 1/4" Aluminum Plate
Manufacturing: CNC





# **First Stage Spacer**

Assembly: First Stage
Quantity: 6X per robot
Material: Aluminum Anything
Manufacturing: lathe

# **Second Stage**

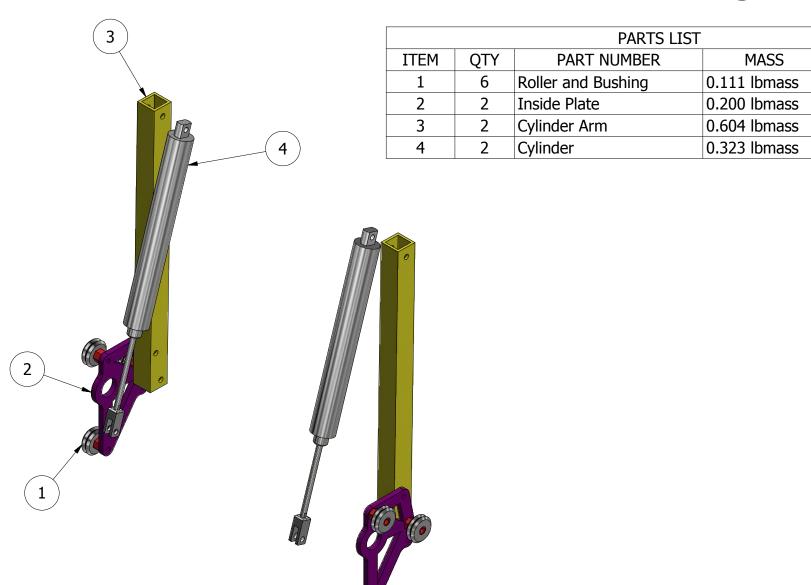
**MATERIAL** 

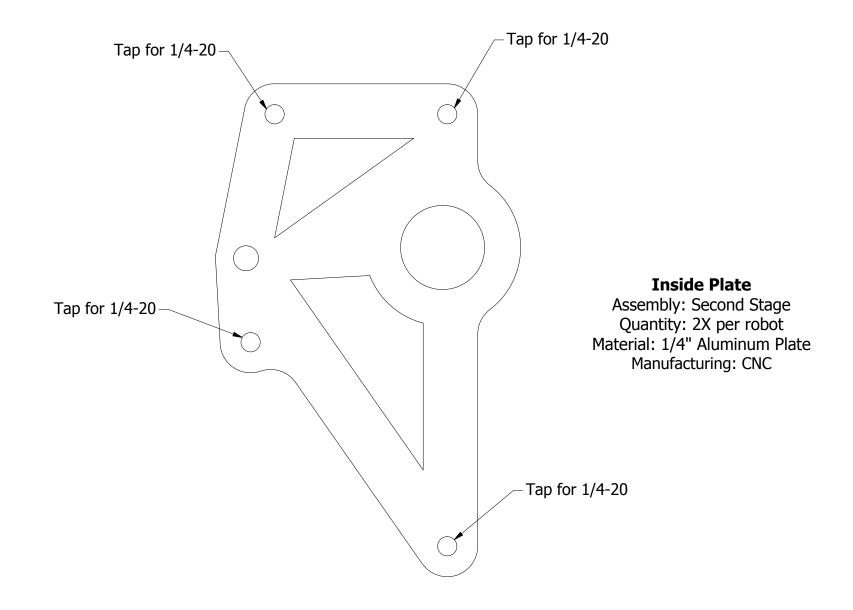
Purchased

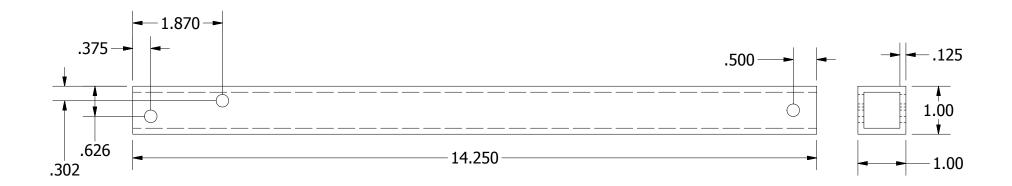
Aluminum

Aluminum

Purchased





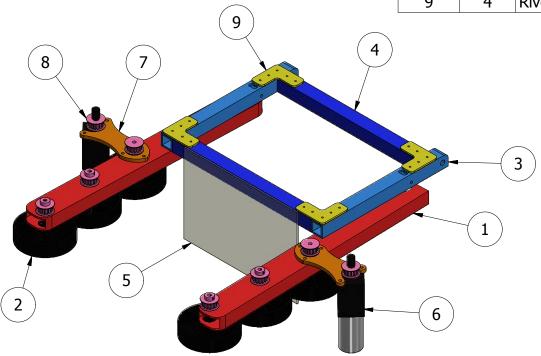


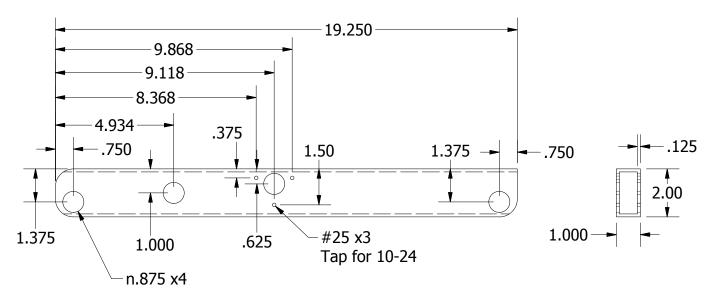
# **Cylinder Arm**

Assembly: Second Stage Quantity: 2X per robot Material: 1" Aluminum Box Manufacturing: Mill

# **Cube Intake**

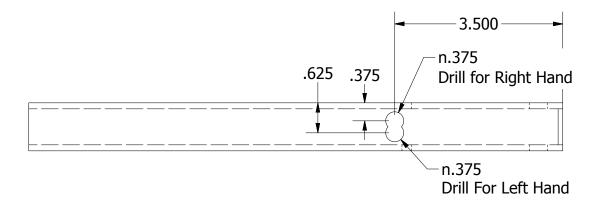
PARTS LIST						
ITEM	QTY	PART NUMBER	MASS	MATERIAL		
1	2	Intake Arm	1.209 lbmass	Aluminum		
2	6	Compliant Wheels	0.150 lbmass	Purchased		
3	2	Pivot Arm	0.464 lbmass	Aluminum		
4	2	Cross Brace	0.280 lbmass	Aluminum		
5	1	Rest Plate	0.379 lbmass	Polycarbonate		
6	2	Bag Motor and Gearbox	0.436 lbmass	Purchased		
7	2	Motor Mount	0.150 lbmass	Aluminum		
8	12	15T XL Pulley	0.043 lbmass	Purchased or		
				Printed		
9	4	Rivet Plate	0.046 lbmass	Aluminum		

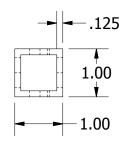


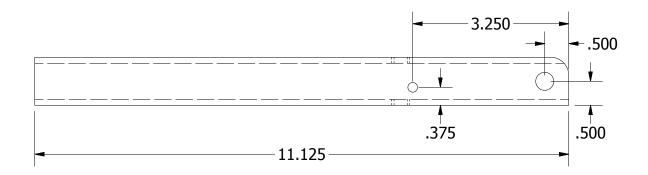


### **Intake Arm**

Assembly: Cube Intake Quantity: 2X per robot Material: 2" x 1" Aluminum Box Manufacturing: Mill

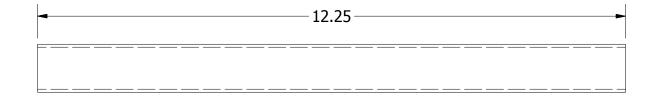


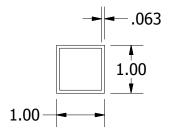




#### **Pivot Arm**

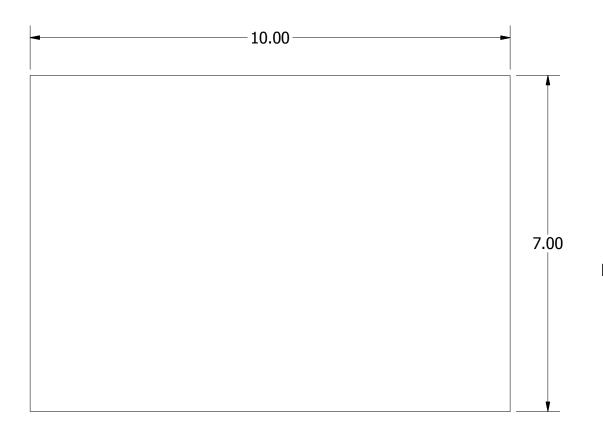
Assembly: Cube Intake Quantity: One each RH, LH Material: 1" Aluminum Box Manufacturing: Mill





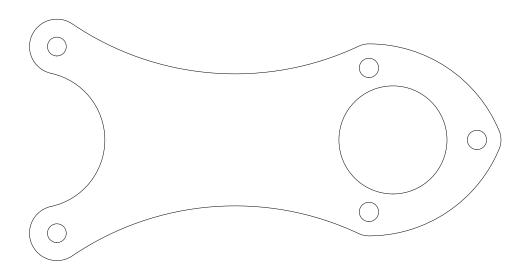
### **Cross Brace**

Assembly: Cube Intake Quantity: 2X per robot Material: 1" Aluminum Box Manufacturing: Mill



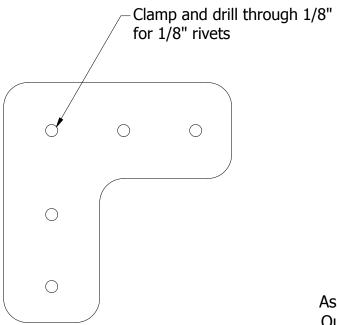
### **Rest Plate**

Assembly: Cube Intake
Quantity: 1X per robot
Material: 1/8" Polycarbonate Plate
Manufacturing: CNC



# **Motor Mount**

Assembly: Cube Intake Quantity: 2X per robot Material: 1/4" Aluminum Plate Manufacturing: CNC



#### **Rivet Plate**

Assembly: Cube Intake Quantity: 4X per robot Material: 1/8" Aluminum Plate Manufacturing: CNC