# Operating System Concepts

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## Chapter 1. Introduction

### Introduction

- What is an Operating System?
  - A basis for application programs
  - An intermediary between users and hardware

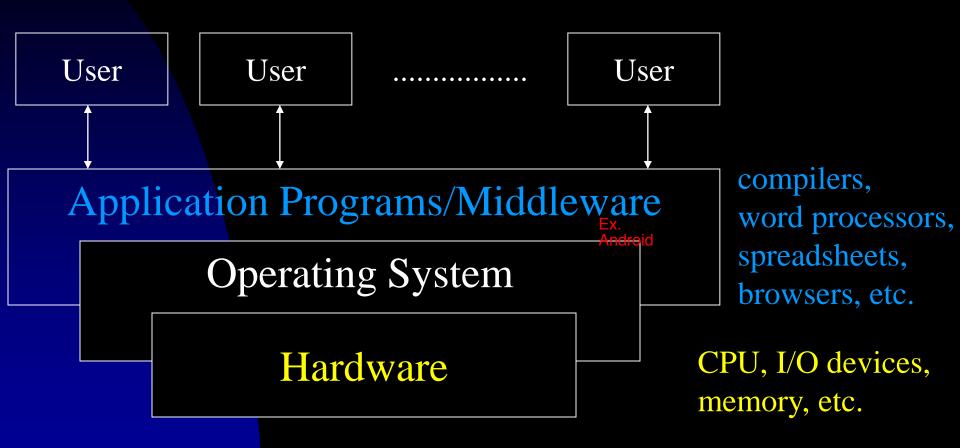
#### Amazing variety

 Mainframe, personal computer (PC), handheld computer, embedded computer without any user view

Convenient vs Efficient

大型主機

## Computer System Components



OS – a government/environment provider

#### **User View**

- The user view of the computer varies by the interface being used!
- Examples:
  - Personal Computer → Ease of use
  - Mainframe or minicomputer ->
    maximization of resource utilization
    - Efficiency and fair share
  - Workstations → compromise between individual usability & resource utilization
  - Handheld computer → individual usability
  - Embedded computer without user view -> run without user intervention

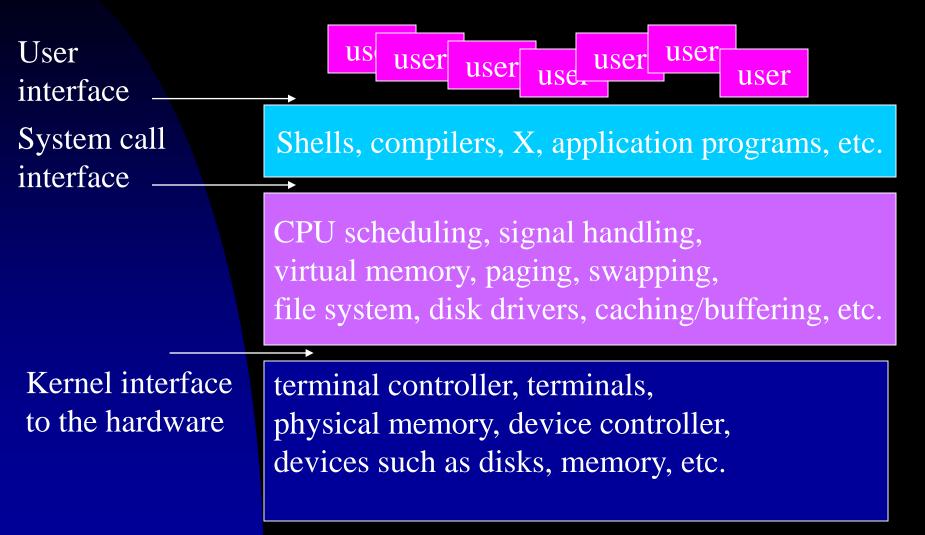
## System View

- A Resource Allocator
  - CPU time, Memory Space, File Storage, I/O Devices, Shared Code, Data Structures, and more
- A Control Program
  - Control execution of user programs
  - Prevent errors and misuse
- OS definitions US Dept.of Justice against Microsoft in 1998
  - The stuff shipped by vendors as an OS
  - Run at all time

## System Goals

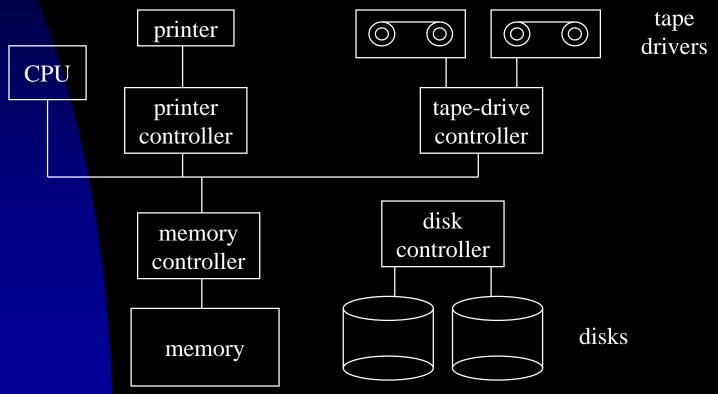
- Two Conflicting Goals:
  - Convenient for the user!
  - Efficient operation of the computer system!
- We should
  - recognize the influences of operating systems and computer architecture on each other
  - and learn why and how OS's are by tracing their evolution and predicting what they will become!

#### **UNIX Architecture**



## Computer-System Organization

Objective: General knowledge of the structure of a computer system.



Device controllers: synchronize and manage access to devices.

## **Booting**

電腦開啟時,需要跑一個initial program(bootstrap program)儲存在ROM或EEPROM,(俗稱韌體firm ware)

- Bootstrap program:
  - Initialize all aspects of the system, e.g., CPU registers, device controllers, memory, etc.
  - Load and run the OS
- Operating system: run init to initialize system processes, e.g., various daemons, login processes, after the kernel has been bootstrapped. (/etc/rc\* & init or /sbin/rc\* & init)

## Interrupt

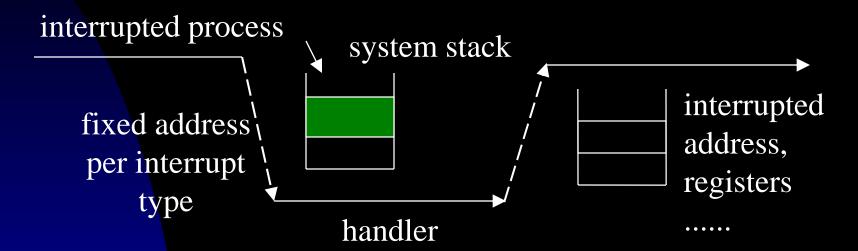
- Hardware interrupt, e.g. services requests of I/O devices
- Software interrupt, e.g. signals, invalid memory access, division by zero, system calls, etc – (trap)

process execution interrupt handler return

Procedures: generic handler or interrupt vector (MS-DOS,UNIX)



## Interrupt Handling Procedure



- Saving of the address of the interrupted instruction: fixed locations or stacks
- Interrupt disabling or enabling issues: lost interrupt?!
  - prioritized interrupts → masking

## Interrupt Handling Procedure

- Interrupt Handling
  - Save interrupt information
  - OS determine the interrupt type (by polling)
  - Call the corresponding handlers
  - Return to the interrupted job by the restoring important information (e.g., saved return addr. > program counter)

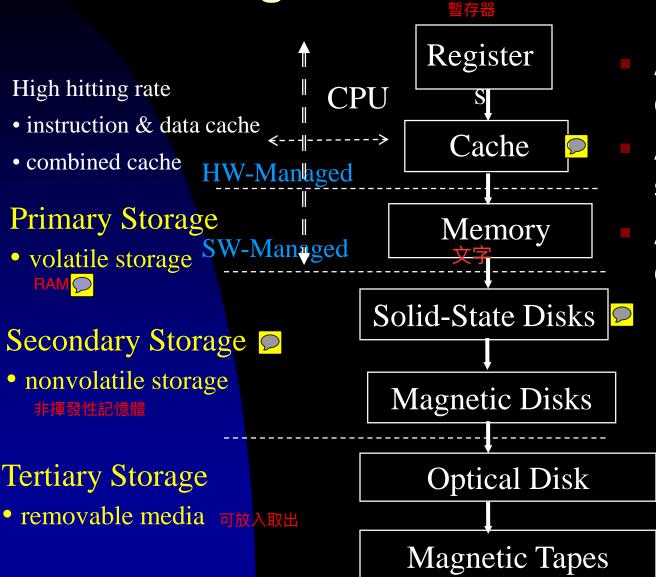
Vector

indexed by
a unique
device
number

n

Interrupt Handlers (Interrupt Service Routines)

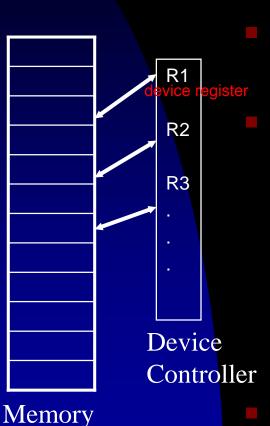
## **Storage Structure**



- Access time: a cycle
- Access time: several cycles
- Access time: many cycles

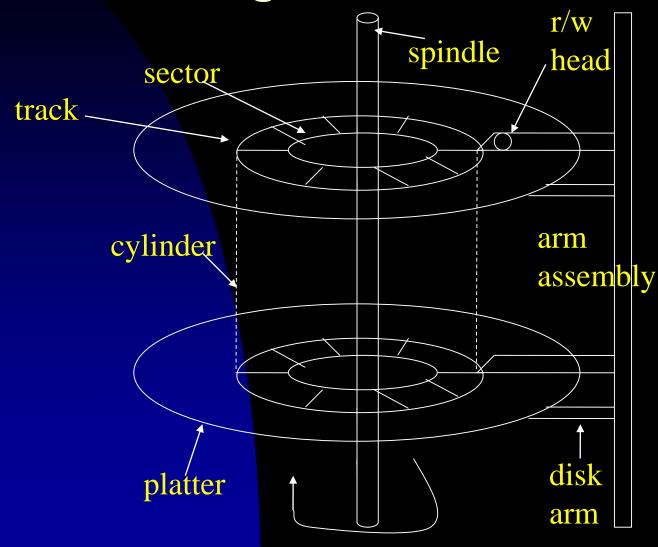
\* Differences: Size, Cost, Speed, Volatility

### Memory



- Processor can have direct access!
  - Intermediate storage for data in the registers of device controllers
  - Memory-Mapped I/O (PC & Mac)
  - (1) Frequently used devices
  - (2) Devices must be fast, such as video controller, or special I/O instructions is used to move data between memory & device controller registers
  - Programmed I/O polling
    - or interrupt-driven handling

### Magnetic disks



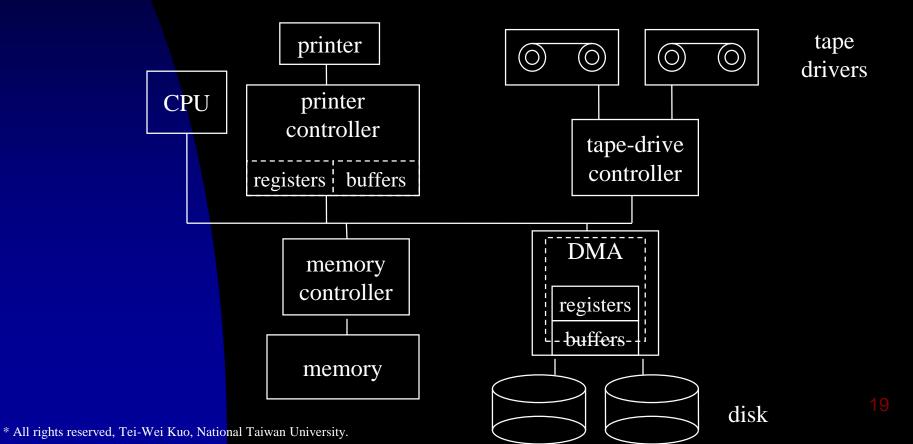
- Transfer Rate
- Random-Access Time
  - Seek time in x ms
  - Rotational latency in y ms
    - 60~200 times/sec

## **Magnetic Disks**

- Disks
  - Fixed-head disks:
    - More r/w heads v.s. fast track switching
  - Moving-head disks (hard disk)
  - Primary concerns:
    - Cost, Size, Speed
  - Computer → host controller → disk controller
     → disk drives (cache ← → disks)
- Floppy disk
  - slow rotation, low capacity, low density, but less expensive
- Tapes: backup or data transfer bet machines

### I/O Structure

Device controllers are responsible of moving data between the peripheral devices and their local buffer storages.



#### I/O Structure

- I/O operation
  - a. CPU sets up specific controller registers within the controller.
  - b. Read: devices → controller buffers → memory
    - Write: memory → controller buffers → devices
  - Notify the completion of the operation by triggering an interrupt





- Goal: Release CPU from handling excessive interrupts!
  - E.g. 9600-baud terminal
    - 2-microsecond service / 1000 microseconds High-speed device:

50%時間處理中 2-microsecond service / 4 microseconds

- Procedure
  - Execute the device driver to set up the registers of the DMA controller.
  - DMA moves blocks of data between the memory and its own buffers.
  - Transfer from its buffers to its devices.
  - Interrupt the CPU when the job is done.

## Single-Processor Systems

- Characteristics: One Main CPU
  - Special-Purpose Processors, e.g., Disk-Controller Microprocessors.
- Examples:
  - Personal Computers (Since 1970's), Mainframes.
- Operating Systems
  - Batching → Multiprogramming → Time-Sharing

# Multiprocessor/Parallel Systems

- Tightly coupled: have more than one processor in close communication sharing computer bus, clock, and sometimes memory and peripheral devices 外報報
- Loosely coupled: otherwise
- Advantages
  - Speedup Throughput
  - Lower cost Economy of Scale
  - More reliable Graceful Degradation → Fail Soft (detection, diagnosis, correction)
  - A Tandem or HP-NonStop fault-tolerance solution

# Multiprocessor/Parallel Systems

- Symmetric multiprocessing model: each processor runs an identical copy of the OS
- Asymmetric multiprocessing model: a masterslave relationship
  - Dynamically allocate or pre-allocate tasks
  - Commonly seen in extremely large systems
  - Hardware and software make a difference?
- Trend: the dropping of microporcessor cost
  - → OS functions are offloaded to slave processors (back-ends)

# Multiprocessor/Parallel Systems

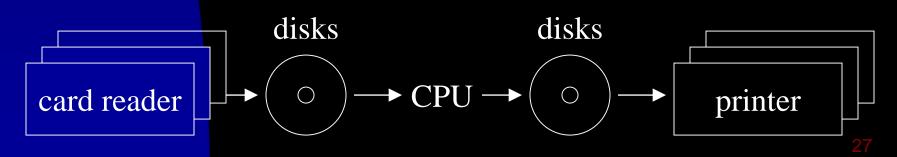
- The Recent Trend:
  - Hyperthreading Processors
  - Multiple Cores over a Single Chip
    - N Standard Processors!
- Loosely-Coupled Systems
  - Processors do not share memory or a clock
  - Blade Servers
    - Each blade-processor board boots independently and runs its own OS.

## **Clustered Systems**

- Definition: Clustered computers which share storage and are closely linked via LAN networking.
- Advantages: high availability, performance improvement, etc.
- Types
  - Asymmetric/symmetric clustering
  - Parallel clustering multiple hosts that access the same data on the shared storage.
- Distributed Lock Manager (DLM)
  - Oracle

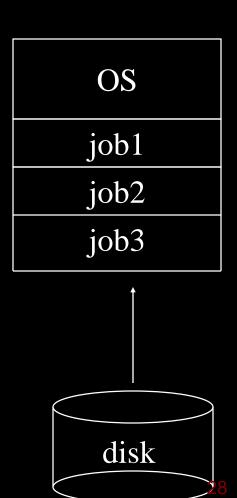
## Operating-System Structure

- Simple batch systems
  - Resident monitor Automatically transfer control from one job to the next 工作做完後搬下一個進去
- Spooling (Simultaneous Peripheral Operation On-Line)
  - Replace sequential-access devices with random-access device



## Operating-System Structure

- Multiprogramming increases CPU utilization by organizing jobs so that the CPU always has one to execute Early 1960
  - Job scheduling and CPU scheduling
  - Goal : efficient use of scare resources



## **Operating-System Structure**

Time sharing (or multitasking) is a logical extension of multiprogramming!

 Started in 1960s and become common in 1970s.

 An <u>interactive</u> (or <u>hand-on</u>) computer system

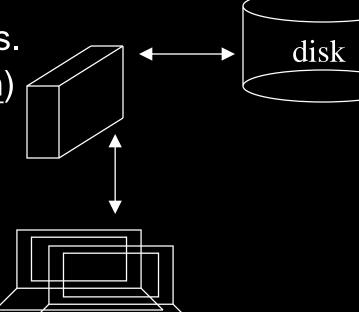
Multics, IBM OS/360

Virtual Memory

Physical Address

on-line file system virtual memory sophisticated CPU scheduling job synchronization protection & security

and so on



## **Operating-System Operations**

- An Interrupt-Driven Architecture for Modern OS's
  - Events are almost always signaled by the occurrence of an interrupt or a trap (or an exception).
- Protection of User Programs and OS
  - Multiprogramming
  - Sharing of Hardware and Software

- Goal:
  - Prevent errors and misuse!
    - E.g., input errors of a program in a simple batch operating system
    - E.g., the modifications of data and code segments of another process or OS
- Dual-Mode Operations a mode bit
  - User-mode executions except those after a trap or an interrupt occurs.
  - Monitor-mode (system mode, privileged mode, supervisor mode)
    - Privileged instruction: Machine instructions that may cause harm

#### More Modes:

- One for the Virtual Machine Manager It provides an interface that is identical to the underlying bare hardware.
- More for different kernel components

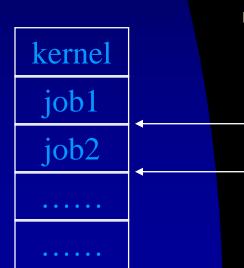
virtual user mode	processes	processes	processes
virtual monitor mode	kernel 1	kernel 2	kernel 3
monitor	virtual machine software		
mode	hardware		

- System Calls trap to OS for executing privileged instructions.
- Resources to protect
  - I/O devices, Memory, CPU
- I/O Protection (I/O devices are scare resources!)
  - I/O instructions are privileged.
    - User programs must issue I/O through OS
    - User programs can never gain control over the computer in the system mode.

- Memory Protection
  - Goal: Prevent a user program from modifying the code or data structures of either the OS or other users!
    - Instructions to modify the memory space for a process are privileged.

Base register Limit register

⇔ Check for every memory address by hardware



- CPU Protection
  - Goal
    - Prevent user programs from sucking up CPU power!
  - Use a timer to implement time-sharing or to compute the current time.
    - Instructions that modify timers are privileged.
  - Computer control is turned over to OS for every time-slice of time!
    - Terms: time-sharing, context switch

某個桯式執行的狀態

## System Components – Process Management

- Process Management
  - Process: An Active Entity
    - Physical and Logical Resources
      - Memory, I/O buffers, data, etc.
    - Data Structures Representing Current Activities:

+ Program Counter 記錄執行到哪一行

Stack

**Data Section** 

**CPU Registers** 

. . . .

And More

Passive entity

Program (code)

## System Components – Process Management

#### Services

- Process creation and deletion
- Process suspension and resumption
- Process synchronization
- Process communication
- Deadlock handling

## System Components – Memory Management

- Memory: a large array of words or bytes, where each has its own address
- OS must keep several programs in memory to improve CPU utilization and user response time
- Management algorithms depend on the hardware support
- Services
  - Memory usage and availability
  - Decision of memory assignment
  - Memory allocation and deallocation

# System Components – File-System Management

- Goal:
  - A uniform logical view of information storage
  - Each medium controlled by a device
    - Magnetic tapes, magnetic disks, optical disks, etc.
- OS provides a logical storage unit: File
  - Formats:
    - Free form or being formatted rigidly.
  - General Views:
    - A sequence of bits, bytes, lines, records

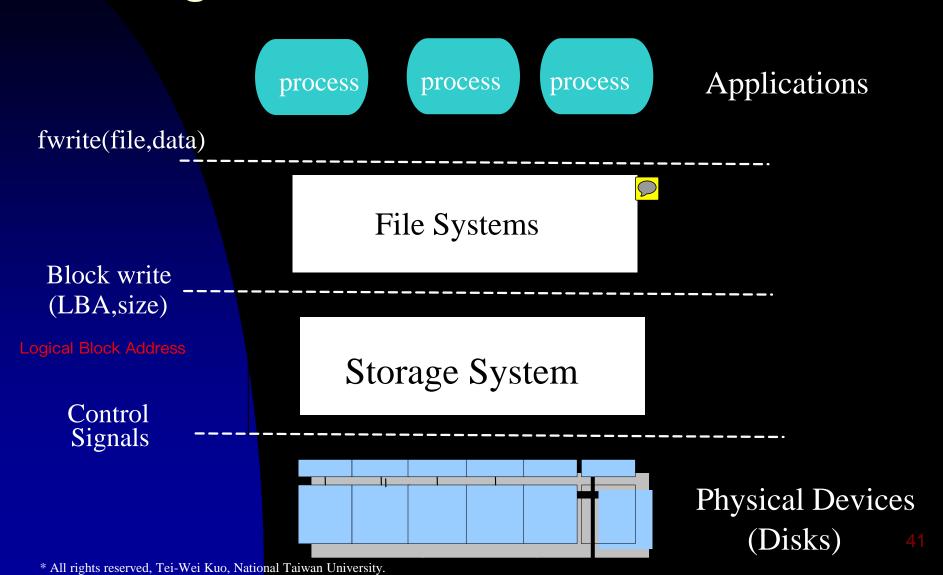
# System Components – File-System Management

#### Services

- File creation and deletion
- Directory creation and deletion
- Primitives for file and directory manipulation
- Mapping of files onto secondary storage
- File Backup

<sup>\*</sup> Privileges for file access control

## System Components – File-System Management



### System Components – Mass-Storage Management

- Goal:
  - On-line storage medium for programs & data
    - Backup of main memory
- Services for Disk Management
  - Free-space management
  - Storage allocation, e.g., continuous allocation
  - Disk scheduling, e.g., FCFS

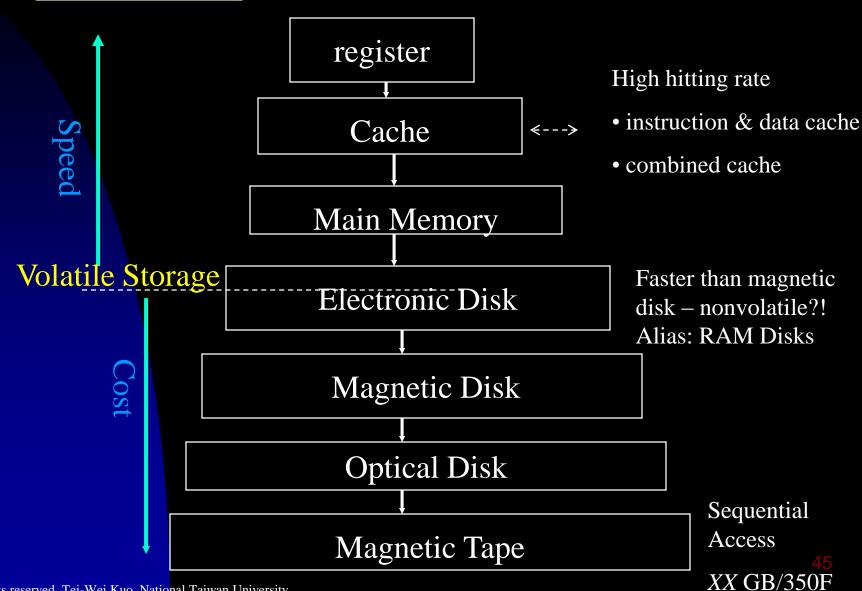
## System Components –Tertiary Storage Devices

#### Goals:

- Backups of disk data, seldom-used data, and long-term archival storage
- Examples:
  - Magnetic tape drives and their tapes, CD & DVD drives and platters.
- Services OS Supports or Applications' Duty
  - Device mounting and unmounting
  - Exclusive allocation and freeing
  - Data transfers from tertiary devices to secondary storage devices.

# System Components – I/O System Management

- Goal:
  - Hide the peculiarities of specific hardware devices from users
- Components of an I/O System
  - A buffering, caching, and spooling system
  - A general device-driver interface
  - Drivers

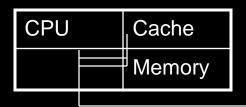




Level	1	2	3	4
Name	Registers	Cache	Memory	Disk
Typical Size	< 1KB	> 16MB	> 16GB	> 100GB
Implementat ion Strategy	Custom memory with multiple ports, CMOS	On-chip or off- chip CMOS SRAM	CMOS DRAM	Magnetic Disks
Access Time (ns)	0.25 – 0.5	0.5 – 2.5	80 – 250	5,000,000
Bandwidth (MB/s)	20,000 — 100,000	5000 — 10,000	1000 – 5000	20 – 150
Managed by	Compiler	Hardware	os	os
Backup by	Cache	Memory	Disk	CD/Tape

- Caching
  - Information is copied to a faster storage system on a temporary basis
  - Assumption: Data will be used again soon.
    - Programmable registers, instr. cache, etc.
- Cache Management
  - Cache Size and the Replacement Policy
- Movement of Information Between Hierarchy
  - Hardware Design & Controlling Operating Systems

- Coherency and Consistency
  - Among several storage levels (vertical)
    - Multitasking vs unitasking
  - Among units of the same storage level, (horizontal), e.g. cache coherency
    - Multiprocessor or distributed systems



CPU -	cache
	Memory

#### **Protection and Security**

#### Goal

 Resources are only allowed to be accessed by authorized processes.

#### **Definitions:**

- Protection any mechanism for controlling the access of processes or users to the resources defined by the computer system.
- Security Defense of a system from external and internal attacks, e.g., viruses, denial of services, etc.

#### **Protection and Security**

- Protected Resources
  - Files, CPU, memory space, etc.
- Protection Services
  - Detection & controlling mechanisms
  - Specification mechanisms
- Distinguishing of Users
  - User names and ID's
  - Group names and GID's
  - Privilege Escalating, e.g., Setuid in Unix
    - To gain extra permissions for an activity.
- Remark: Reliability!

#### **Kernel Data Structures**

- Frequently Used Data Structures
  - Array, List, Stack, Queue, Tree, Hash
  - Bitmaps A string of n binary digits to represent the status of n items.
    - Advantage: Space Efficiency
    - An example is the availability status of disk blocks.

- Evolving Environments
  - Transition from the period of scarce resources to the period of ubiquitous access!
  - In the past, portability is achieved by laptops!
    - Remote access is supported in a limited way. Mainframes are prevalent!
  - Now, PC's, mobile devices, and various equipments are connected!
    - High speed networks are available at home and office! Web-computing is popular (e.g., portals).

- Mobile Computing
  - Trends: Computing on handheld smartphones and tablets now offers tremendous growth in the wide range of applications, such as email and GPS, augmented-reality applications, but with limitation on screen size, memory/storage capacity, and power/energy consumption.

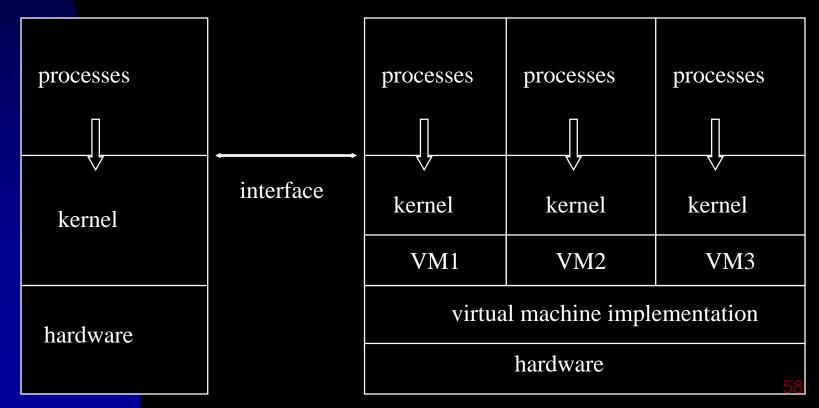
- Distributed/Loosely-Coupled Systems:
   Heterogeneous or homogeneous computer
   systems that are networked to provide
   access to various resources
  - Depend on networking for their functionality
    - Networks vary by the protocols used: TCP/IP, ATM, etc.
  - Be characterized by their node distances
    - Local-area network (LAN)
    - Wide-area network (WAN)
    - Metropolitan-area network (MAN)
    - Personal-area network distance of few feet

- Media copper wires, fiber strands, satellite wireless transmission, infrared communication, etc.
- Network Operating Systems
  - Autonomous computers
  - A distributed operating system a single
     OS controlling the network.

- Peer-to-Peer Systems
  - Characteristics: Client and server roles depend on who is requesting or providing a service.
  - Network connectivity is an essential component.
  - Service Availability and Discovery
    - Registration of services: a centralized lookup service or not
    - A discovery protocol
  - Issues:
    - Legal problems in exchanging files.

- Client-Server Systems
  - Trend: The functionality of clients is improved in the past decades.
  - Categories:
    - Compute-server systems
    - File-server systems

 Virtual Machines: provide an interface that is identical to the underlying bare hardware



<sup>\*</sup> All rights reserved, Tei-Wei Kuo, National Taiwan University.

- Implementation Issues of Virtual Machines:
  - Emulation of Physical Devices
    - E.g., Disk Systems
      - An IBM minidisk approach
  - User/Monitor Modes
    - (Physical) Monitor Mode
      - Virtual machine software
    - (Physical) User Mode
      - Virtual monitor mode & Virtual user mode

How a Virtual Machine works:

P1/VM1 system call virtual processes processes processes user Finish mode Trap service virtual kernel 2 kernel 1 monitor kernel 3 Service for the system call mode Restart VM1 monitor virtual machine software mode Simulate the Set program counter hardware & register contents, effect of the I/O instruction & then restart VM1 time

- Disadvantages of Virtual Machines:
  - Slow!
    - Execute most instructions directly on the hardware
    - Emulation is slow but is needed for obsolete hardware.
  - No direct sharing of resources
    - Physical devices and communications
    - \* I/O could be slow (interpreted) or fast (spooling)

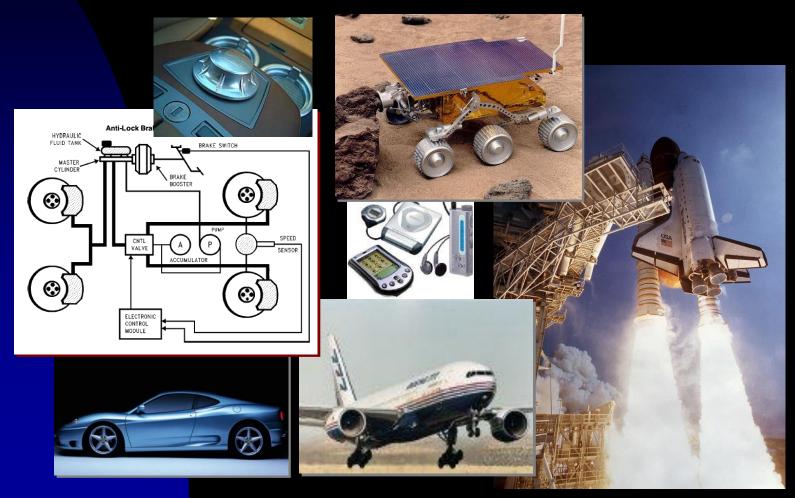
- Advantages of Virtual Machines:
  - Complete Protection Complete Isolation!
  - OS Research & Development
    - System Development Time
  - Extensions to Multiple Personalities, such as Mach (software emulation)
    - Emulations of Machines and OS's, e.g.,
       Windows over Linux
  - System Consolidation
- \* Simulation: Programs of a guest system are run on an emulator that translate each of the guest system instructions into the native instruction set of the host system.

- Cloud Computing Delivers computing, storage, and even applications as a service across a network
- Types
  - Public, Private and Hybrid Clouds
  - Software as a service (SaaS), e.g.,
     Gmail.
  - Platform as a service (PaaS), e.g., database server.
  - Infrastructure as a service (laaS), e.g., storage for backup.

- Web-Based Computing
  - Web Technology
    - Portals, network computers, etc.
  - Network connectivity
  - New categories of devices
    - Load balancers
- Embedded Computing
  - Car engines, robots, VCR's, home automation
  - Embedded OS's often have limited features.

- Embedded Computers Most Prevalent Form of Computers
  - Have a wide variety ranged from car engines to VCR's.
    - General-purpose computers with standard OS's, HW devices with or without embedded OS's
    - Standalone units or members of networks and the Web
  - Tend to have specific tasks and almost always run real-time operating systems.

Real-Time Embedded Computers



- Definition: A real-time system is a computer system where a timely response by the computer to external stimuli is vital!
- Hard real-time system: The system has failed if a timing constraint, e.g. deadline, is not met.
  - All delays in the system must be bounded.
  - Many advanced features are absent.

- Soft real-time system: Missing a timing constraint is serious but does not necessarily result in a failure unless it is excessive!
  - A critical task has a higher priority.
  - Supported in most commercial OS.
- Real-time means on-time instead of fast

#### **Open-Source Operating Systems**

- Definitions: OS with available source code.
  - Closed-source OS, e.g., MS Widows, or hybrid OS, e.g., iOS.
  - Arguably issues on bugs, security, support, etc.
  - Examples: GNU/Linux, BSD UNIX, and Solaris (up to 2005 versions).