Introduction to Network Layer Control Plane: Routing Algorithms

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Chapter 5
Network Layer: Control Plane

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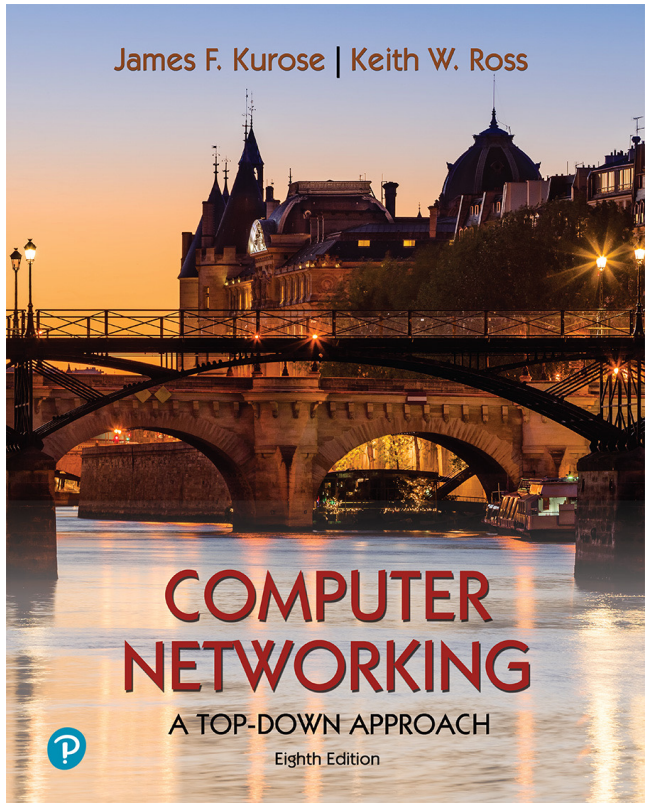


Computer Networking: A Top-Down Approach

8th edition
Jim Kurose, Keith Ross
Pearson, 2020

Network layer control plane: our goals

- understand principles behind network control plane:
  - traditional routing algorithms
  - SDN controllers
  - network management, configuration

- instantiation, implementation in the Internet:
  - OSPF, BGP
  - OpenFlow, ODL and ONOS controllers
  - Internet Control Message Protocol: ICMP
  - SNMP, YANG/NETCONF

Network layer: “control plane” roadmap

- introduction
- routing protocols
  - link state
  - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol

- Clean-slate approach to Internet routing

Network-layer functions

local

- forwarding: move packets from router's input to appropriate router output → *data plane* (fast, mostly hw, no-delay, nanosec)

- routing: determine route taken by packets from source to destination → *control plane* (slow)

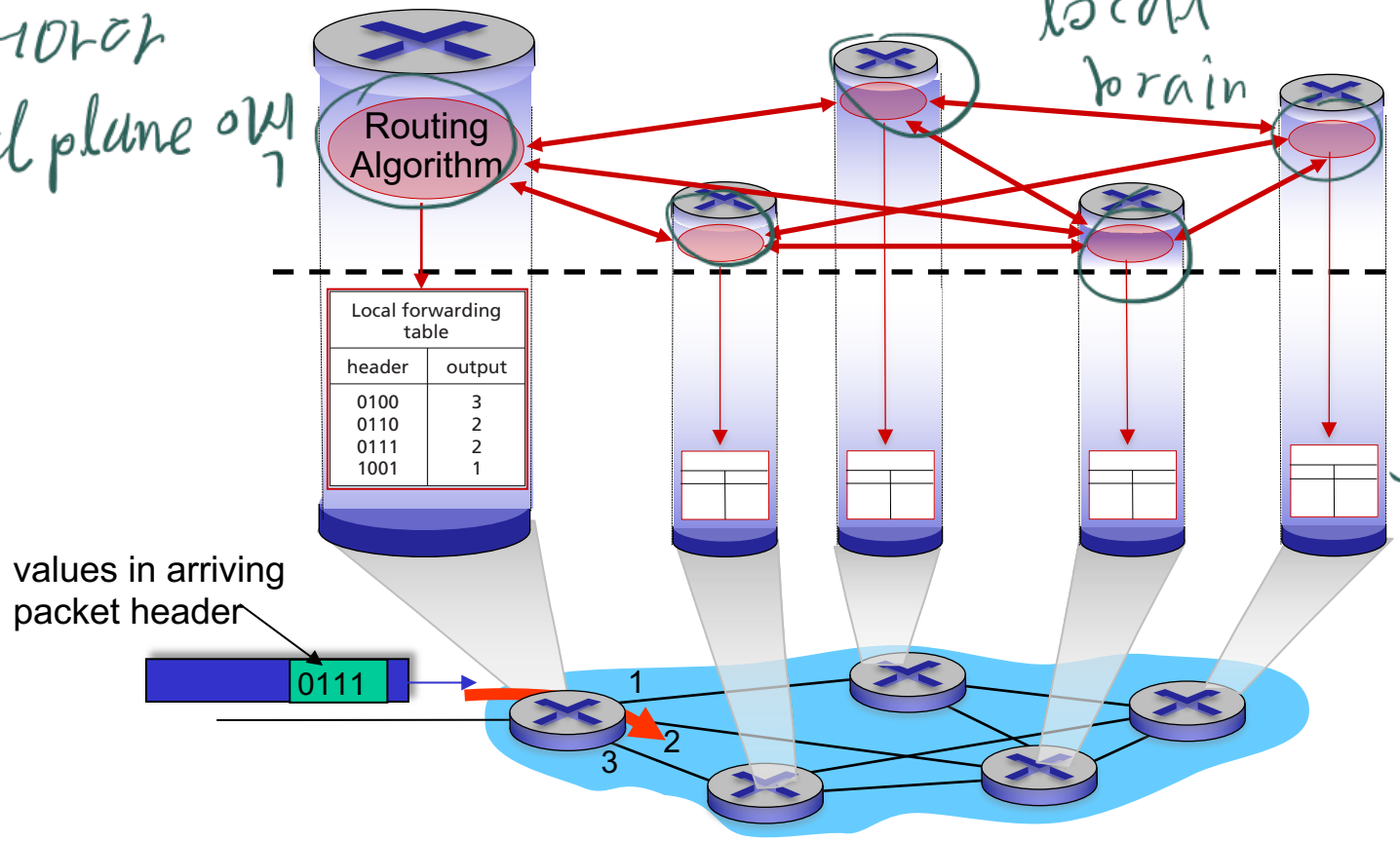
multiple routers (global)

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

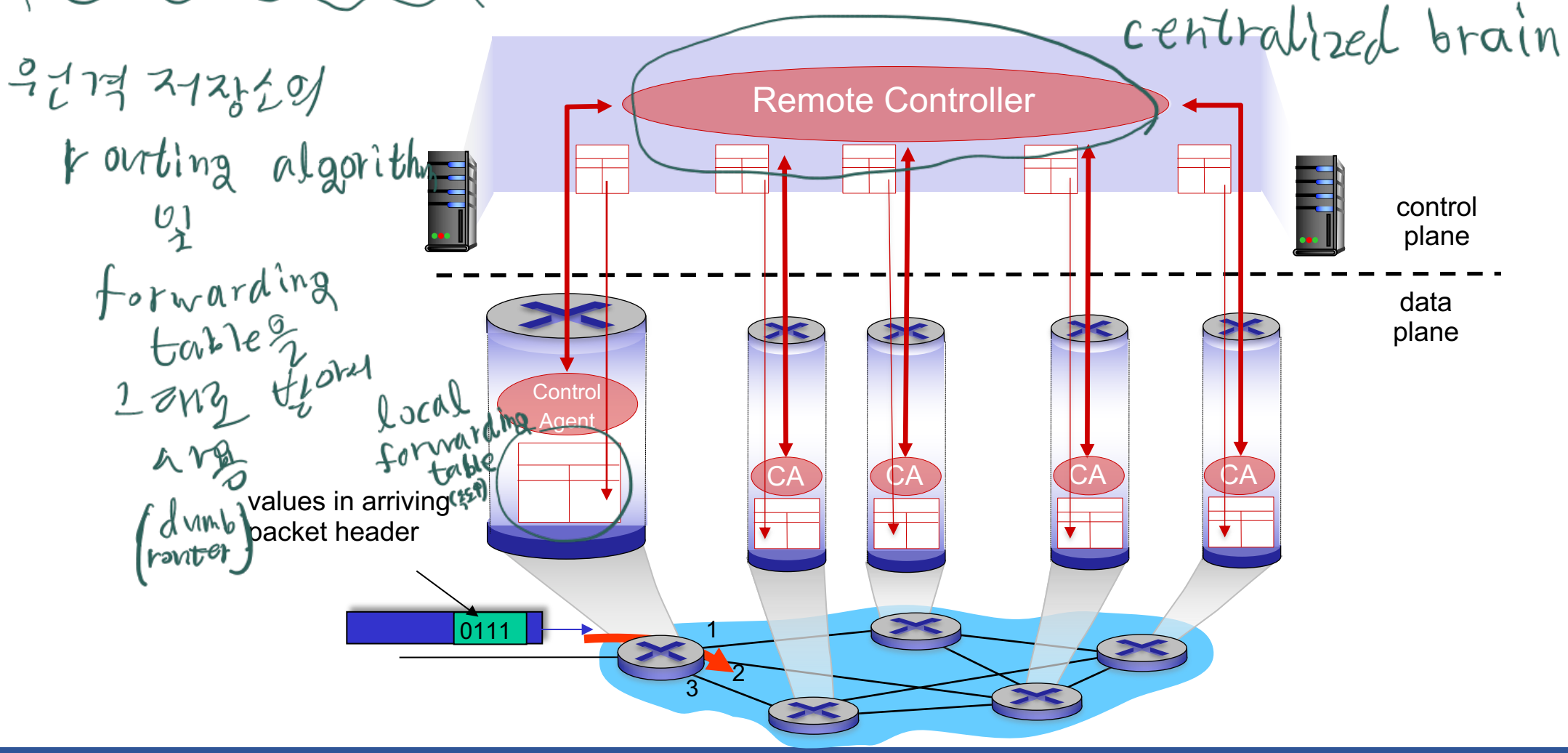
Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane



Software-Defined Networking (SDN) control plane

Remote controller computes, installs forwarding tables in routers



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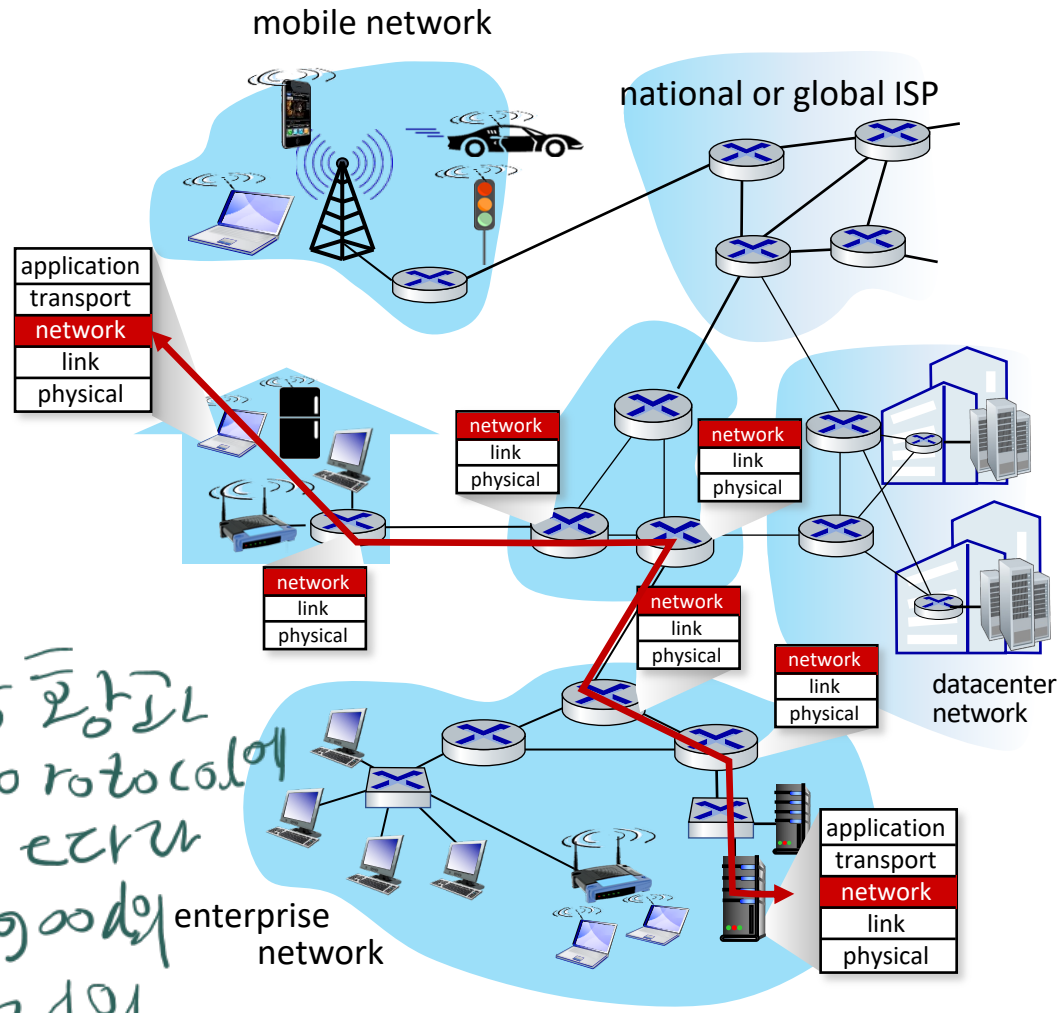
) → classic knowledge

- Clean-slate approach to Internet routing

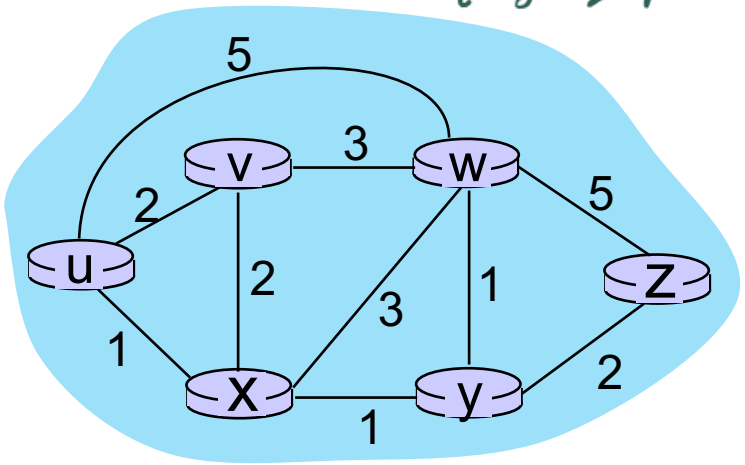
Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- **path:** sequence of routers packets traverse from given initial source host to final destination host
- **"good":** least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!



Graph abstraction: link costs



$c_{a,b}$: cost of *direct* link connecting *a* and *b*

e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

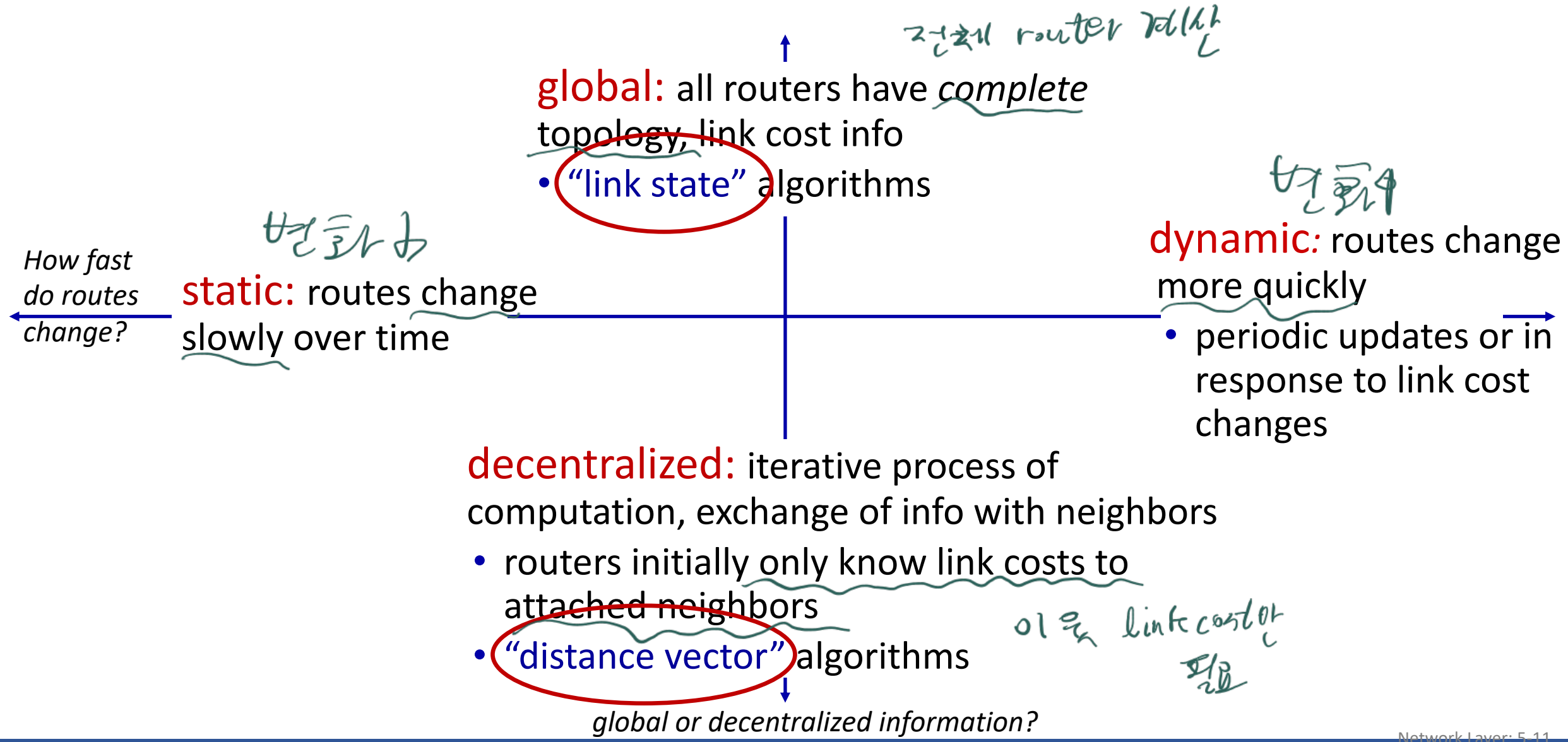
cost defined by network operator: could always be 1, or inversely related to bandwidth, or inversely related to congestion

graph: *G = (N,E)*

N: set of routers = { *u, v, w, x, y, z* }

E: set of links ={ (*u,v*), (*u,x*), (*v,x*), (*v,w*), (*x,w*), (*x,y*), (*w,y*), (*w,z*), (*y,z*) }

Routing algorithm classification



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Dijkstra's link-state routing algorithm

- centralized: network topology, link costs known to *all* nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after *k* iterations, know least cost path to *k* destinations

→ link state broadcast는 통해 전체 node 정보 획보

notation

- $c_{x,y}$: direct link cost from node *x* to *y*; = ∞ if not direct neighbors
- *D(v)*: *current* estimate of cost of least-cost-path from source to destination *v*
- *p(v)*: predecessor node (전임자) along path from source to *v*
- *N'*: set of nodes whose least-cost-path *definitively* known

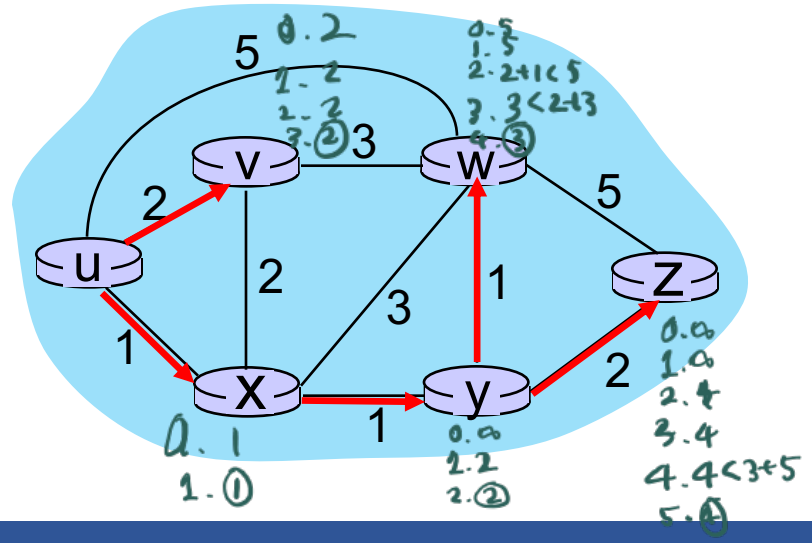
↳ least cost를 아는 node의 집합 (탐색 완료)

Dijkstra's link-state routing algorithm

```
1  Initialization:
2    N' = {u}                    /* compute least cost path from u to all other nodes */
3    for all nodes v
4      if v adjacent to u        /* u initially knows direct-path-cost only to direct neighbors */
5        then D(v) = c_u,v       /* but may not be minimum cost! */
6      else D(v) = ∞
7
8    Loop
9      find w not in N' such that D(w) is a minimum
10     add w to N'
11     update D(v) for all v adjacent to w and not in N' :
12       D(v) = min ( D(v), D(w) + c_w,v )
13     /* new least-path-cost to v is either old least-cost-path to v or known
14     least-cost-path to w plus direct-cost from w to v */
15   until all nodes in N'
```

Dijkstra's algorithm: an example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

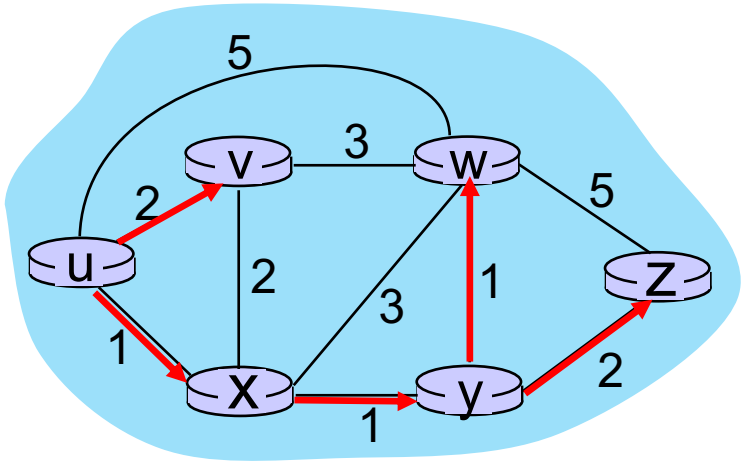


Initialization (step 0): For all a: if *a* adjacent to then $D(a) = c_{u,a}$

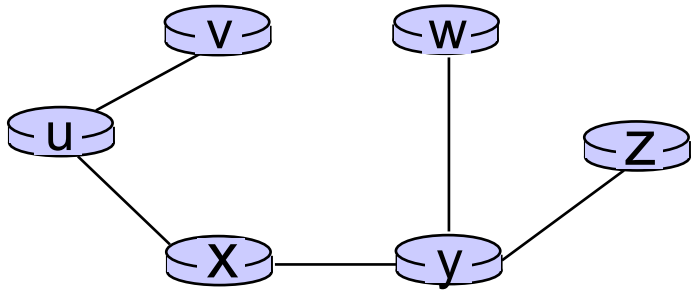
find *a* not in *N'* such that *D(a)* is a minimum
add *a* to *N'*
update *D(b)* for all *b* adjacent to *a* and not in *N'* :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



resulting forwarding table in u:

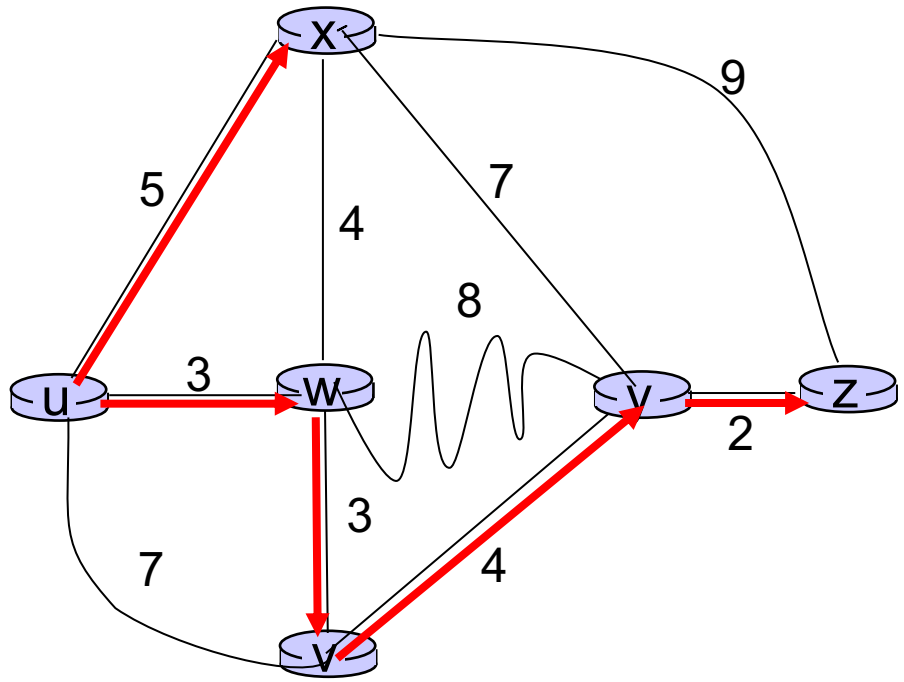
destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
x	(u,x)

route from *u* to *v* directly

route from u to all other destinations via *x*

Dijkstra's algorithm: another example

Step	N′	v D(v), p(v)	w D(w), p(w)	x D(x), p(x)	y D(y), p(y)	z D(z), p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					



notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: *n* nodes

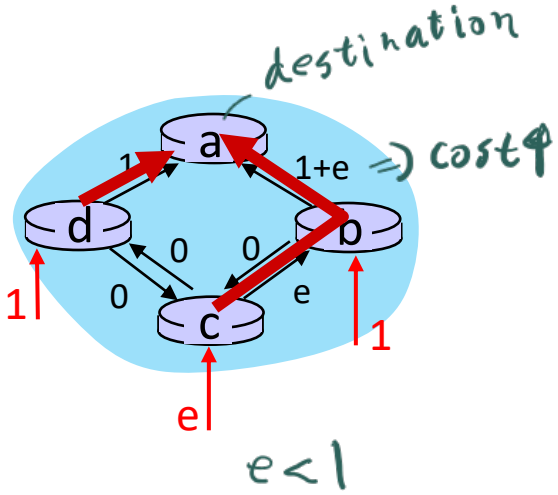
- each of *n* iteration: need to check all nodes, *w*, not in *N*
- $n(n+1)/2$ comparisons: $O(n^2)$ complexity
- more efficient implementations possible: $O(n\log n)$

message complexity:

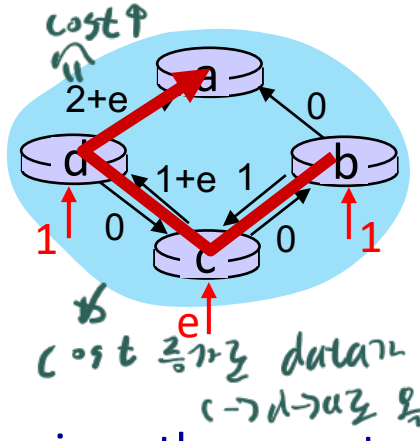
- each router must *broadcast* its link state information to other *n* routers
- efficient (and interesting!) broadcast algorithms: $O(n)$ link crossings to disseminate a broadcast message from one source
- each router's message crosses $O(n)$ links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

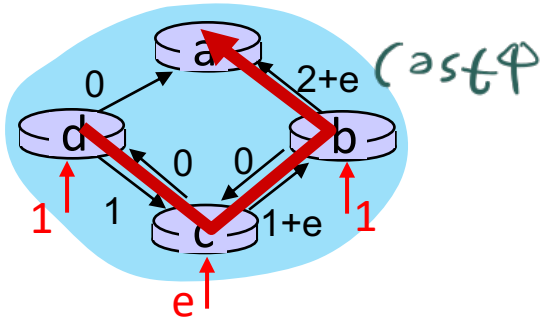
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
  - routing to destination a, traffic entering at d, c, e with rates 1, e (<1), 1
  - link costs are directional, and volume-dependent



initially



given these costs,
find new routing....
resulting in new costs



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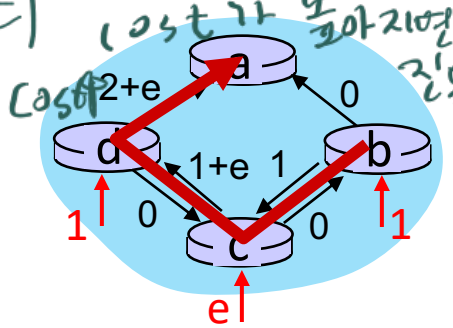

given these costs,
find new routing....
resulting in new costs

Network layer: “control plane” roadmap

네트워크 학과 intern

- introduction
- routing protocols
  - link state = Dijkstra
  - distance vector
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Distance vector algorithm

Based on *Bellman-Ford* (BF) equation (dynamic programming):

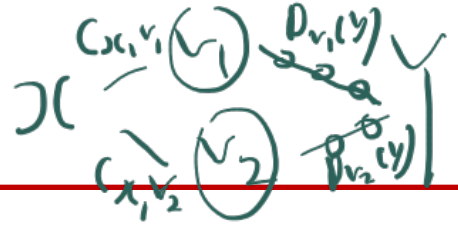
Bellman-Ford equation

최소 비용 거리

Let $D_x(y)$: cost of least-cost path from x to y.

Then:

$$D_x(y) = \min_v \{ c_{x,v} + D_v(y) \}$$



v's estimated least-cost-path cost to y

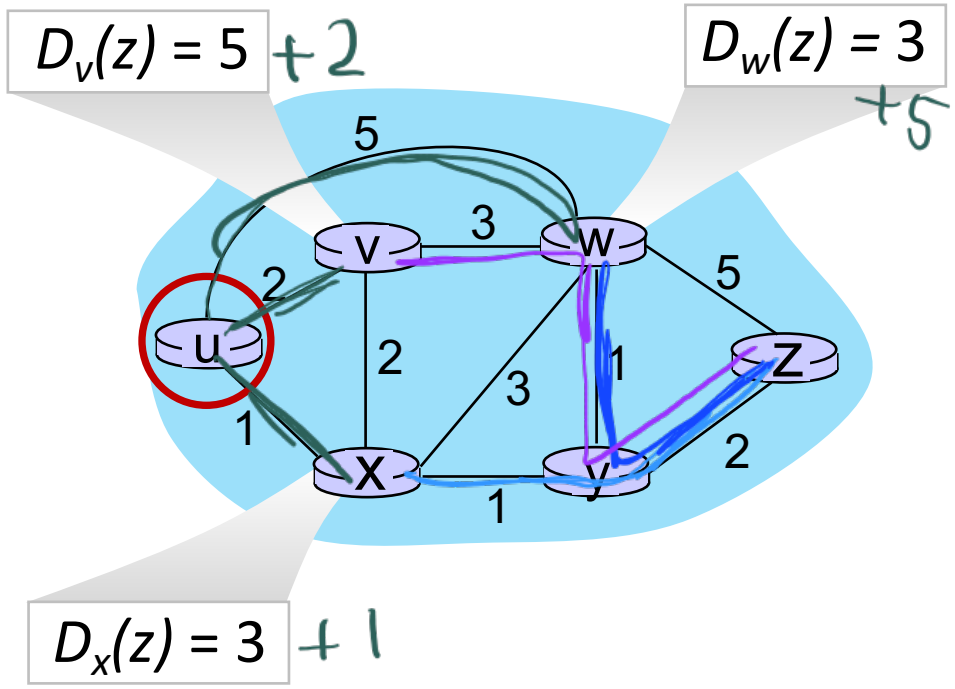
min taken over all neighbors v of x

direct cost of link from x to v

최소 비용 거리를 얻으려면 neighbor 선택 및 거리비교해 best hop 선택

Bellman-Ford Example

Suppose that *u*'s neighboring nodes, *x,v,w,* know that for destination *z*:



Bellman-Ford equation says:

$$D_u(z) = \min \{ c_{u,v} + D_v(z), \; c_{u,x} + D_x(z), \; c_{u,w} + D_w(z) \}$$

$$= \min \{2 + 5, \; 1 + 3, \; 5 + 3\} = 4$$

node achieving minimum (x) is next hop on estimated least-cost path to destination (z)

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when *x* receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c_{x,v} + D_v(y)\} \text{ for each node } y \in N$$

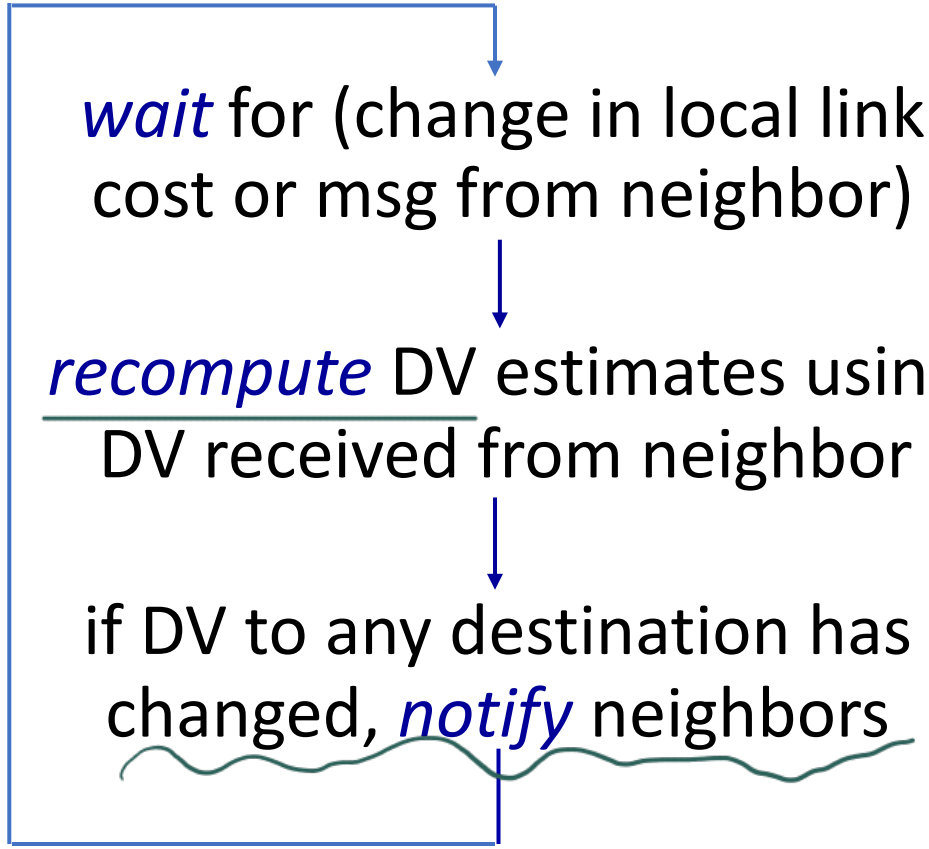
$D_x(y)$ update

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance vector algorithm:

Dijkstra의 경우, 전체 link 정보를 알아야 계산 가능 ⇒ centralize algorithm (모든 router들)
DV는 최소 거리만 알면 나머지 정보 불필요

each node:



iterative, asynchronous: each local iteration caused by: 비동기적

- local link cost change
- DV update message from neighbor

→ link cost change 및 이웃의 DV 업데이트 시

distributed, self-stopping: each node notifies neighbors *only* when its DV changes

비동기적으로 update (동시처리)

- neighbors then notify their neighbors – *only if necessary*
- no notification received, no actions taken!

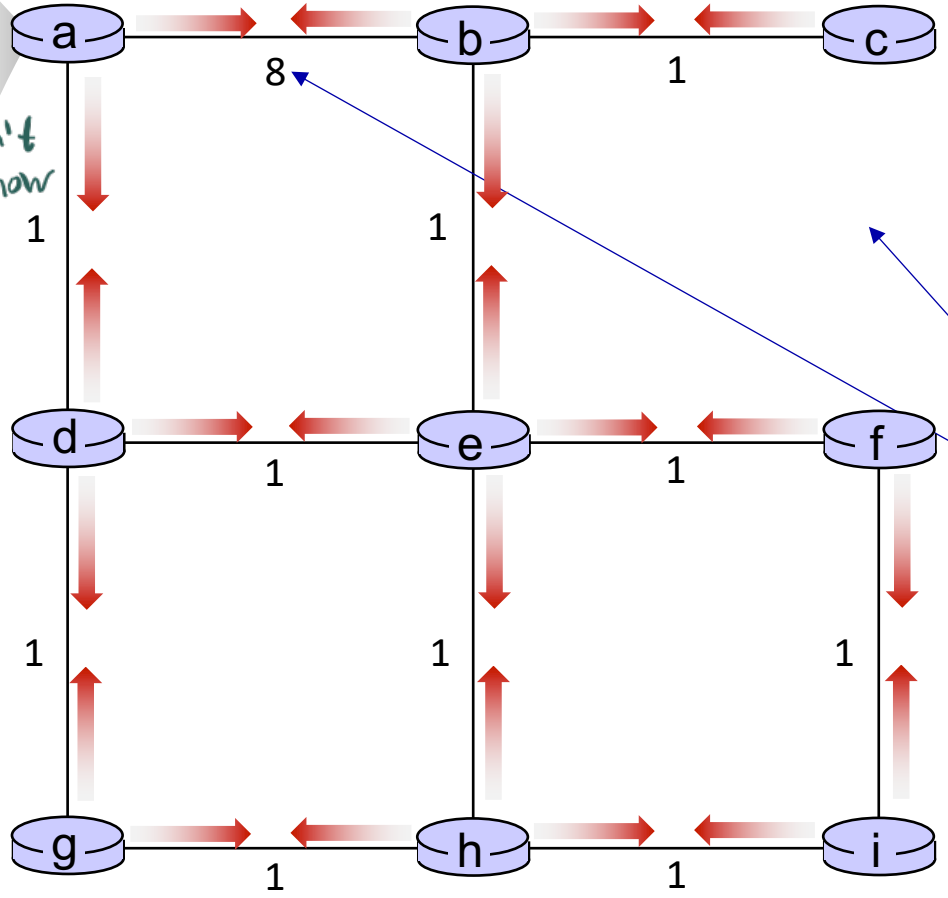
Distance vector: example

t=0

DV in a:
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

don't know

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors



A few asymmetries:

- missing link
- larger cost

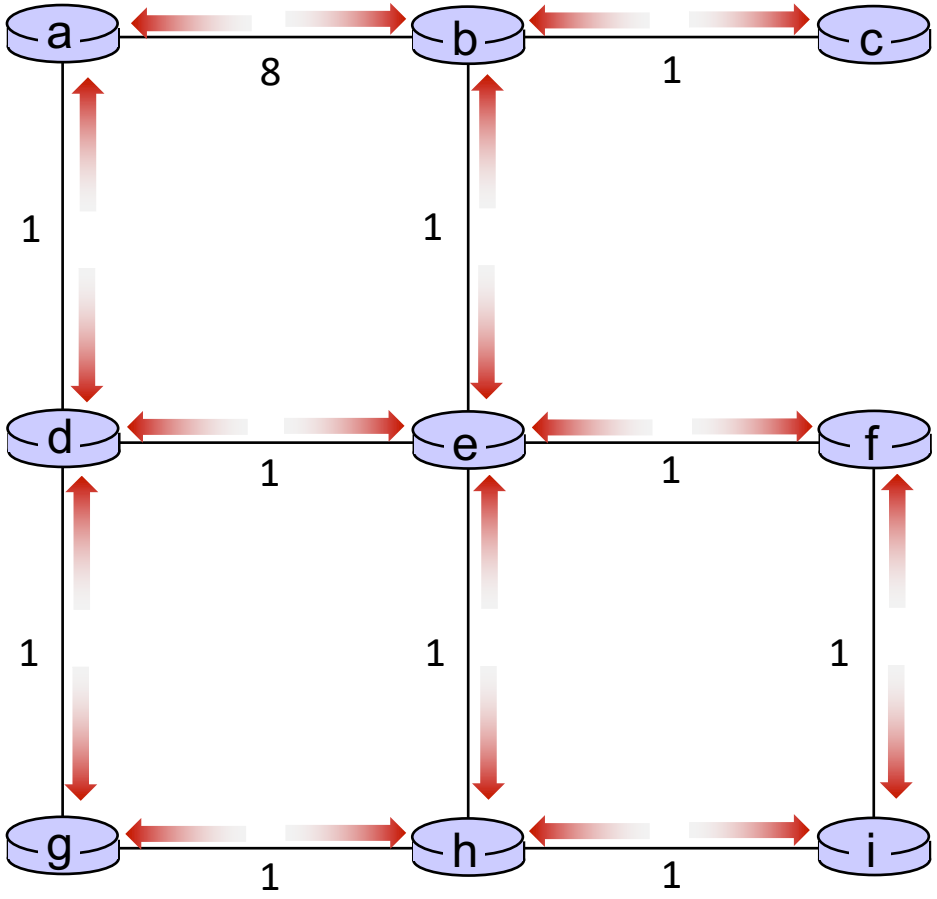
Distance vector example: iteration

t=1

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors

이웃에게 D_x(y) 전달



Distance vector example: iteration

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All nodes:

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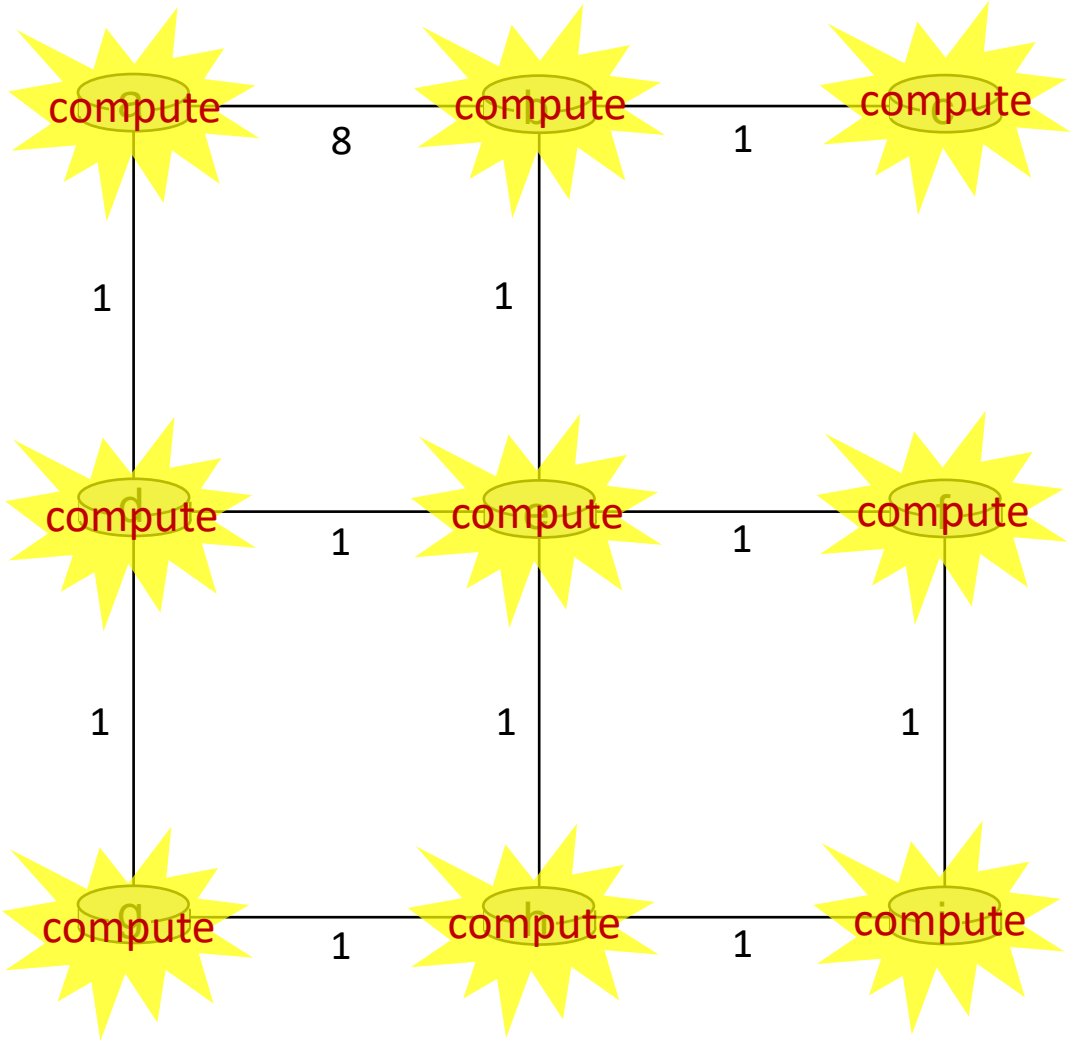

Distance vector example: iteration

t=1

All nodes:

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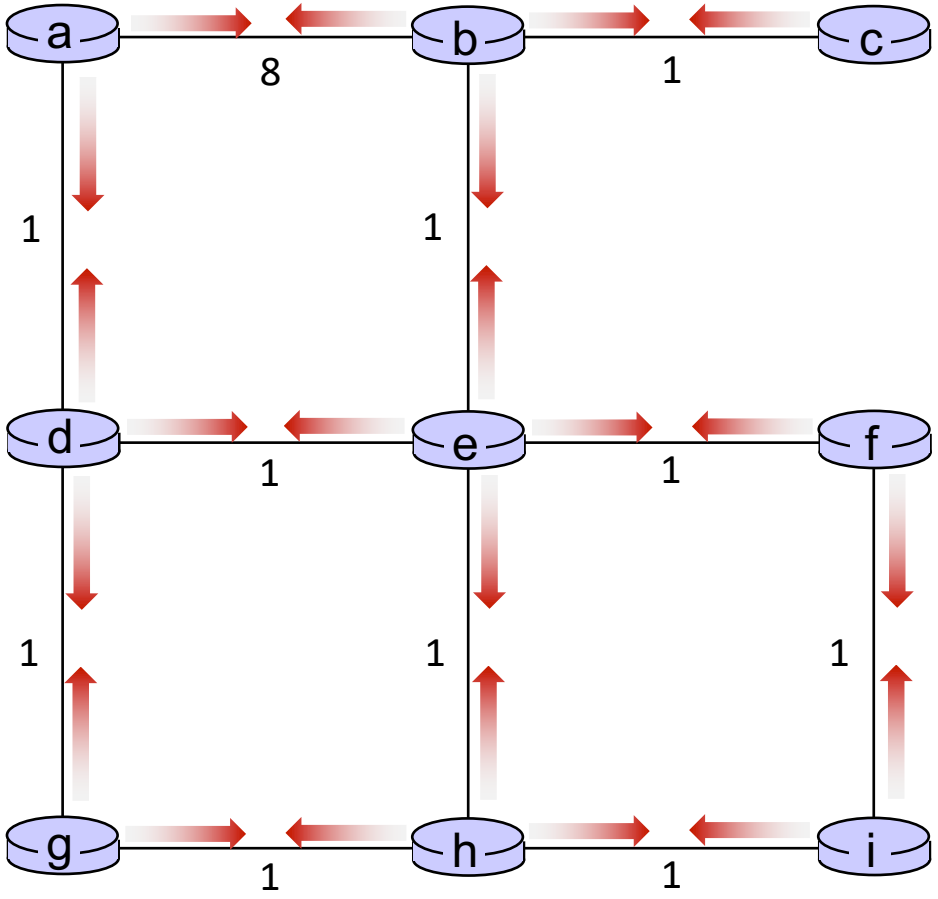
$D_a(x)$ 2 벡터

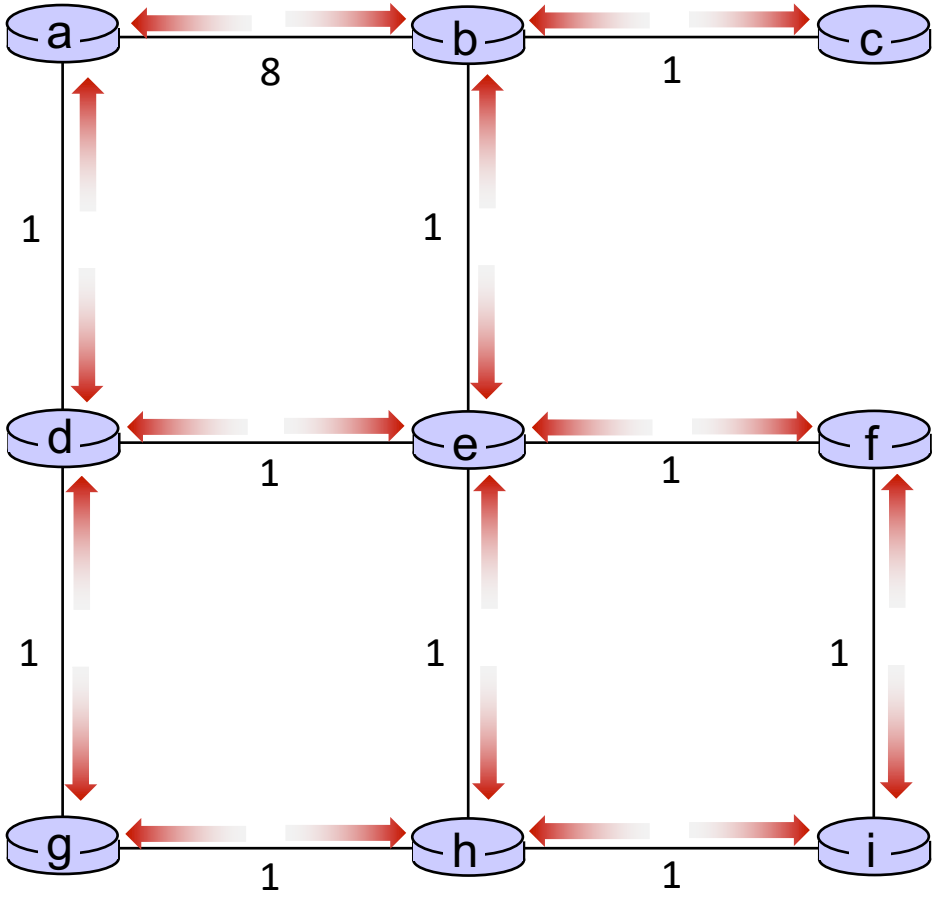


Distance vector example: iteration

t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



Distance vector example: iteration

t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
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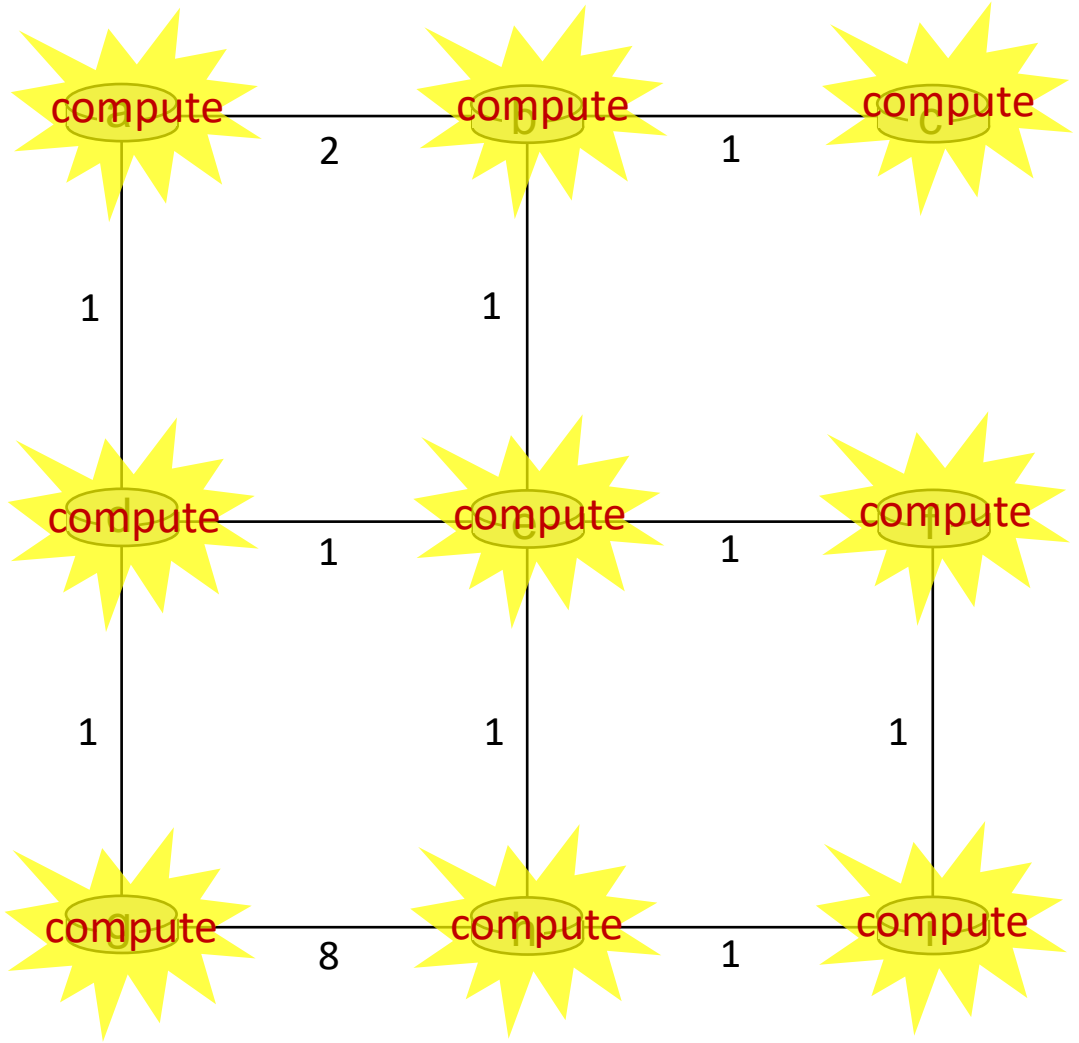

Distance vector example: iteration

t=2

All nodes:

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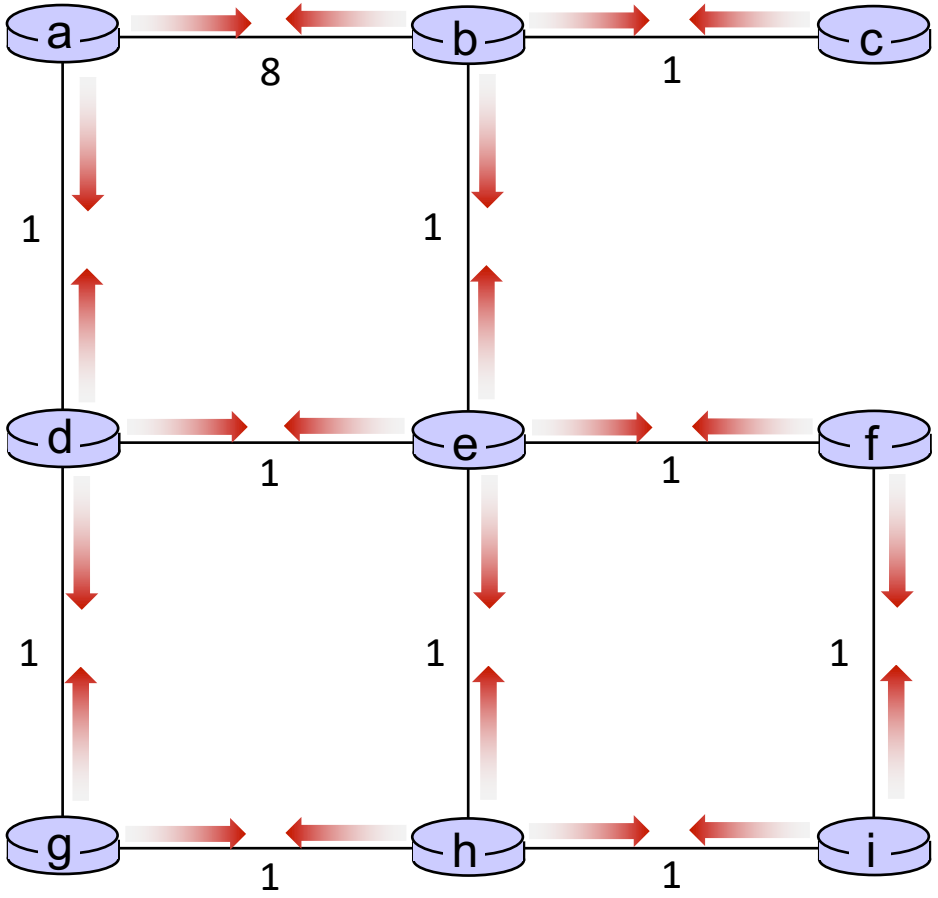


Distance vector example: iteration

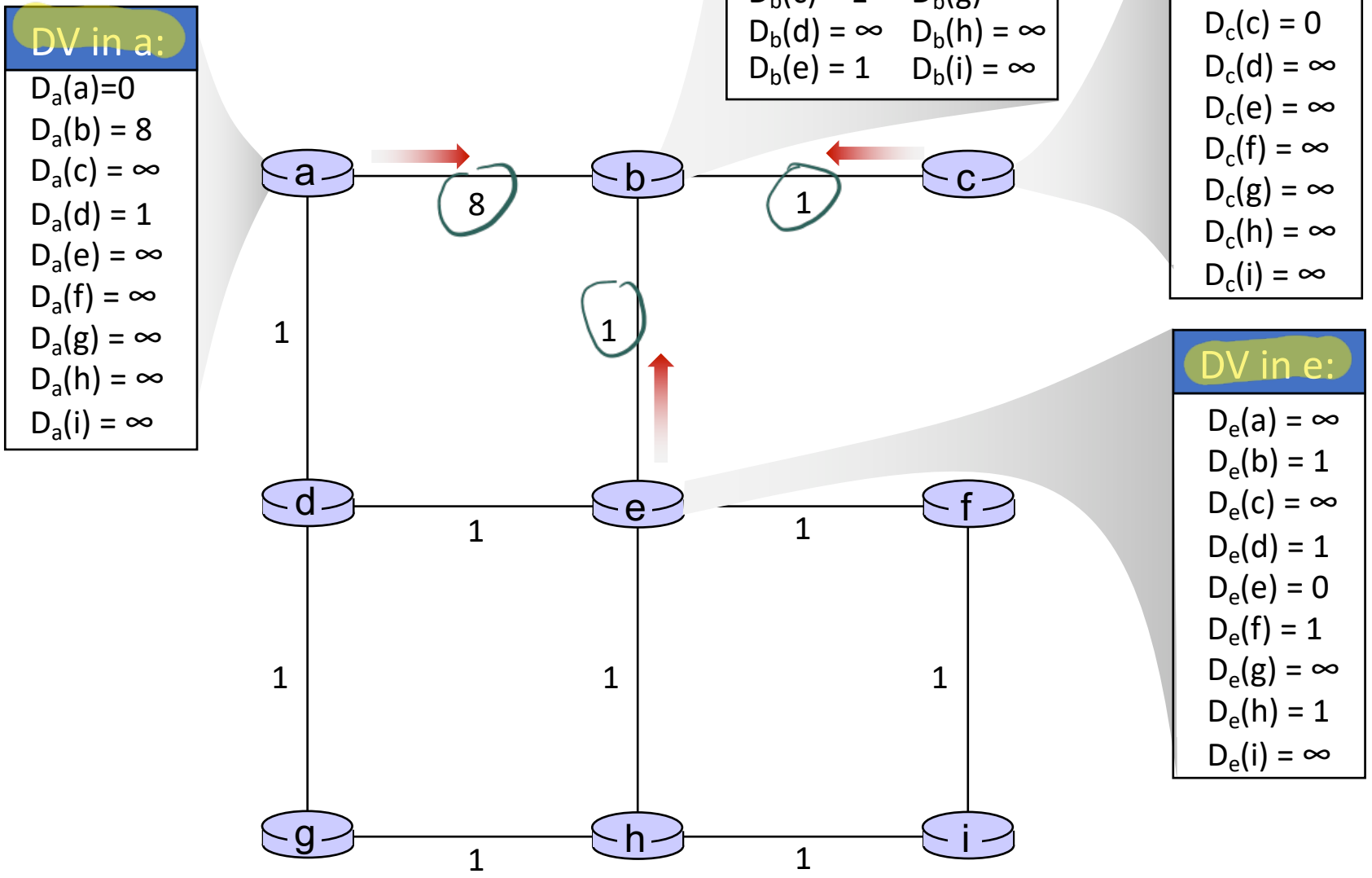
…. and so on

Let’s next take a look at the iterative *computations* at nodes

Distance vector example:

t=1

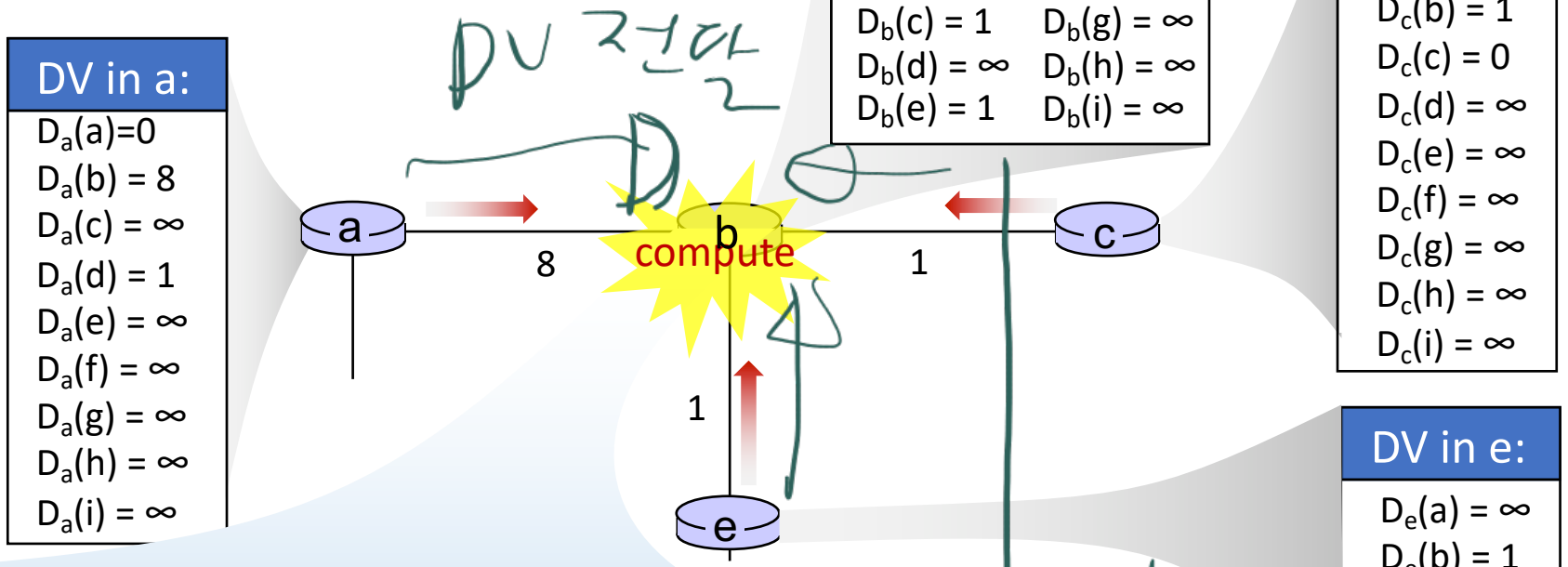
- b receives DVs from a, c, e



Distance vector example:

t=1

- b receives DVs from a, c, e, computes:



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$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

DV in b:

$D_b(a) = 8$ $D_b(f) = \infty$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = \infty$ $D_b(h) = \infty$
$D_b(e) = 1$ $D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

$D_b(a) = \min\{c_{b,a}+D_a(a), c_{b,c}+D_c(a), c_{b,e}+D_e(a)\} = \min\{8,\infty,\infty\} = 8$

$D_b(c) = \min\{c_{b,a}+D_a(c), c_{b,c}+D_c(c), c_{b,e}+D_e(c)\} = \min\{\infty,1,\infty\} = 1$

$D_b(d) = \min\{c_{b,a}+D_a(d), c_{b,c}+D_c(d), c_{b,e}+D_e(d)\} = \min\{9,2,\infty\} = 2$

$D_b(e) = \min\{c_{b,a}+D_a(e), c_{b,c}+D_c(e), c_{b,e}+D_e(e)\} = \min\{\infty,\infty,1\} = 1$

$D_b(f) = \min\{c_{b,a}+D_a(f), c_{b,c}+D_c(f), c_{b,e}+D_e(f)\} = \min\{\infty,\infty,2\} = 2$

$D_b(g) = \min\{c_{b,a}+D_a(g), c_{b,c}+D_c(g), c_{b,e}+D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty$

$D_b(h) = \min\{c_{b,a}+D_a(h), c_{b,c}+D_c(h), c_{b,e}+D_e(h)\} = \min\{\infty, \infty, 2\} = 2$

$D_b(i) = \min\{c_{b,a}+D_a(i), c_{b,c}+D_c(i), c_{b,e}+D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty$

DV in b:

$D_b(a) = 8$ $D_b(f) = 2$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = 2$ $D_b(h) = 2$
$D_b(e) = 1$ $D_b(i) = \infty$

Distance vector example:

t=1

- c receives DVs from b

DV in a:

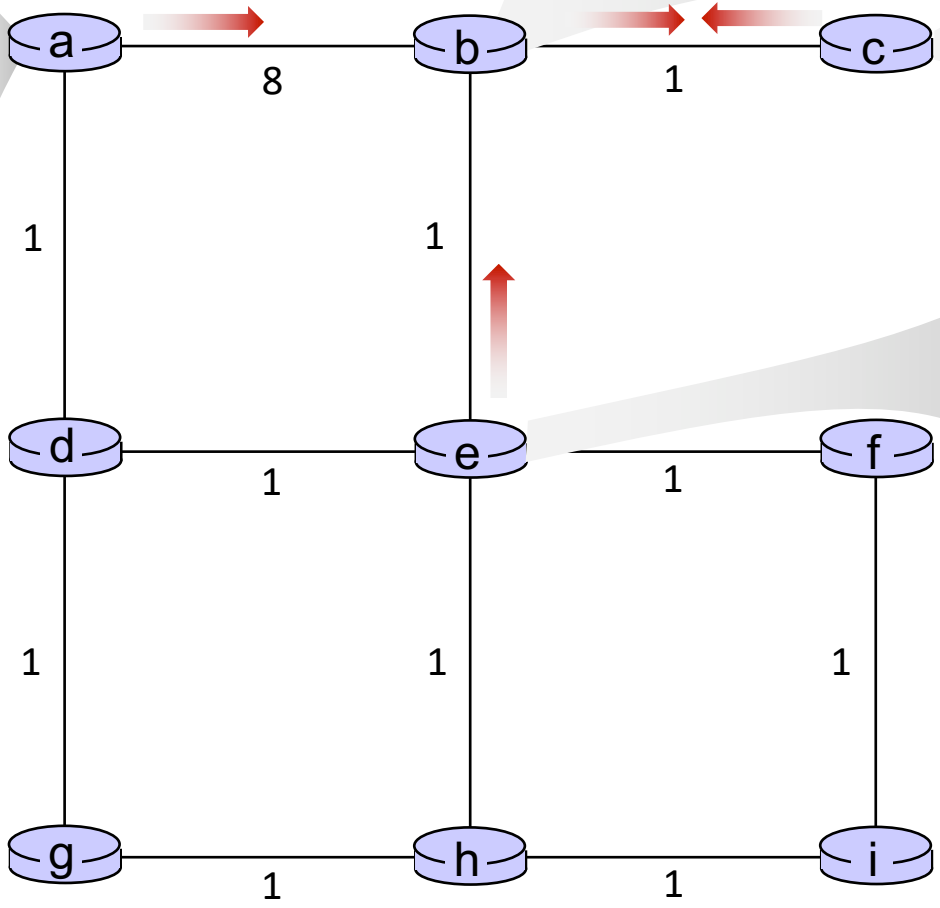
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

DV in b:

$D_b(a) = 8$ $D_b(f) = \infty$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = \infty$ $D_b(h) = \infty$
$D_b(e) = 1$ $D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$



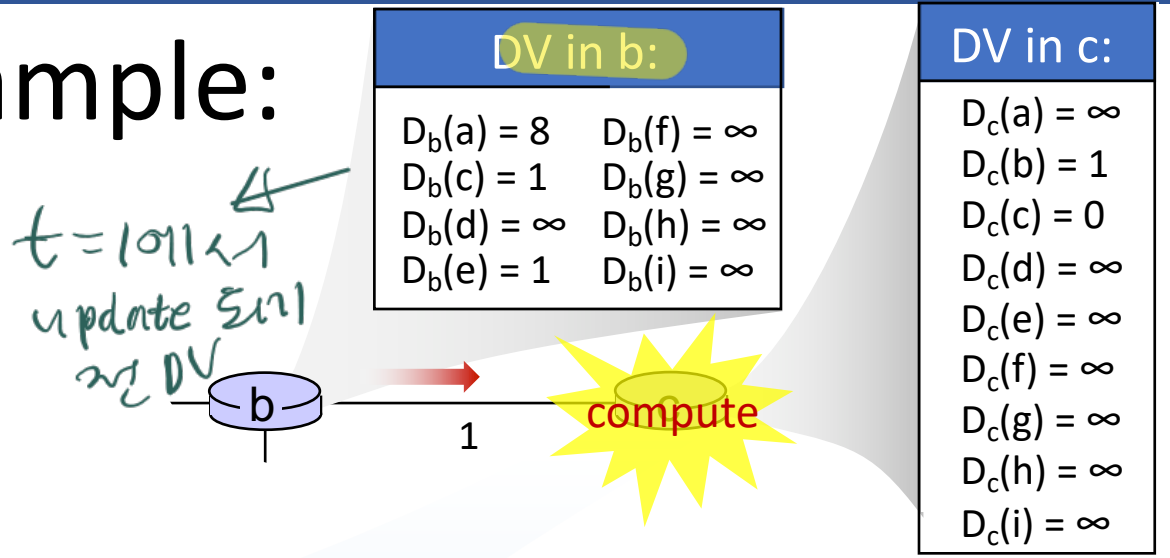
DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

Distance vector example:

t=1

- c receives DVs from b computes:



$D_c(a) = \min\{c_{c,b}+D_b(a)\} = 1 + 8 = 9$

$D_c(b) = \min\{c_{c,b}+D_b(b)\} = 1 + 0 = 1$

$D_c(d) = \min\{c_{c,b}+D_b(d)\} = 1+ \infty = \infty$

$D_c(e) = \min\{c_{c,b}+D_b(e)\} = 1 + 1 = 2$

$D_c(f) = \min\{c_{c,b}+D_b(f)\} = 1+ \infty = \infty$

$D_c(g) = \min\{c_{c,b}+D_b(g)\} = 1+ \infty = \infty$

$D_c(h) = \min\{c_{bc,b}+D_b(h)\} = 1+ \infty = \infty$

$D_c(i) = \min\{c_{c,b}+D_b(i)\} = 1+ \infty = \infty$

DV in c:

$D_c(a) = 9$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = 2$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

* Check out the online interactive exercises for more examples: http://gaia.cs.umass.edu/kurose_ross/interactive/

Distance vector example:

t=1

- e receives DVs from b, d, f, h

DV in b:

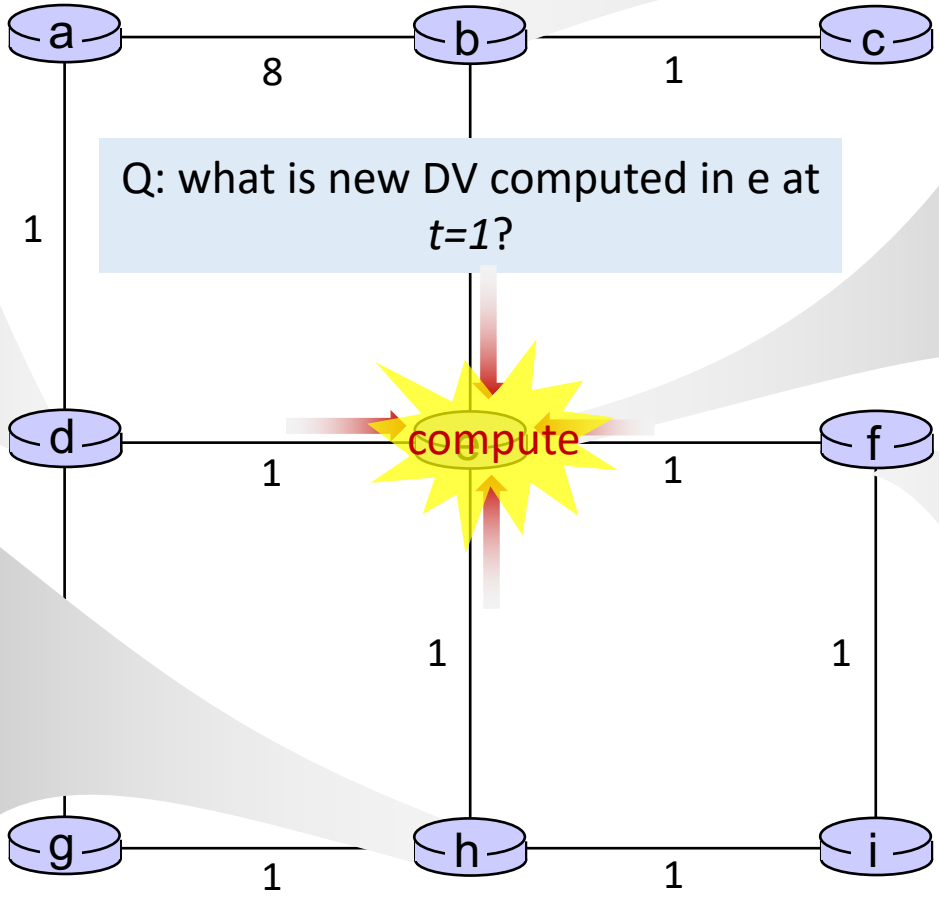
$D_b(a) = 8$ $D_b(f) = \infty$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = \infty$ $D_b(h) = \infty$
$D_b(e) = 1$ $D_b(i) = \infty$

DV in d:

$D_c(a) = 1$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = 0$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$



DV in h:

$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = 0$
$D_c(i) = 1$

DV in f:

$D_f(a) = \infty$
$D_f(b) = \infty$
$D_f(c) = \infty$
$D_f(d) = \infty$
$D_f(e) = 1$
$D_f(f) = 0$
$D_f(g) = \infty$
$D_f(h) = \infty$
$D_f(i) = 1$

Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

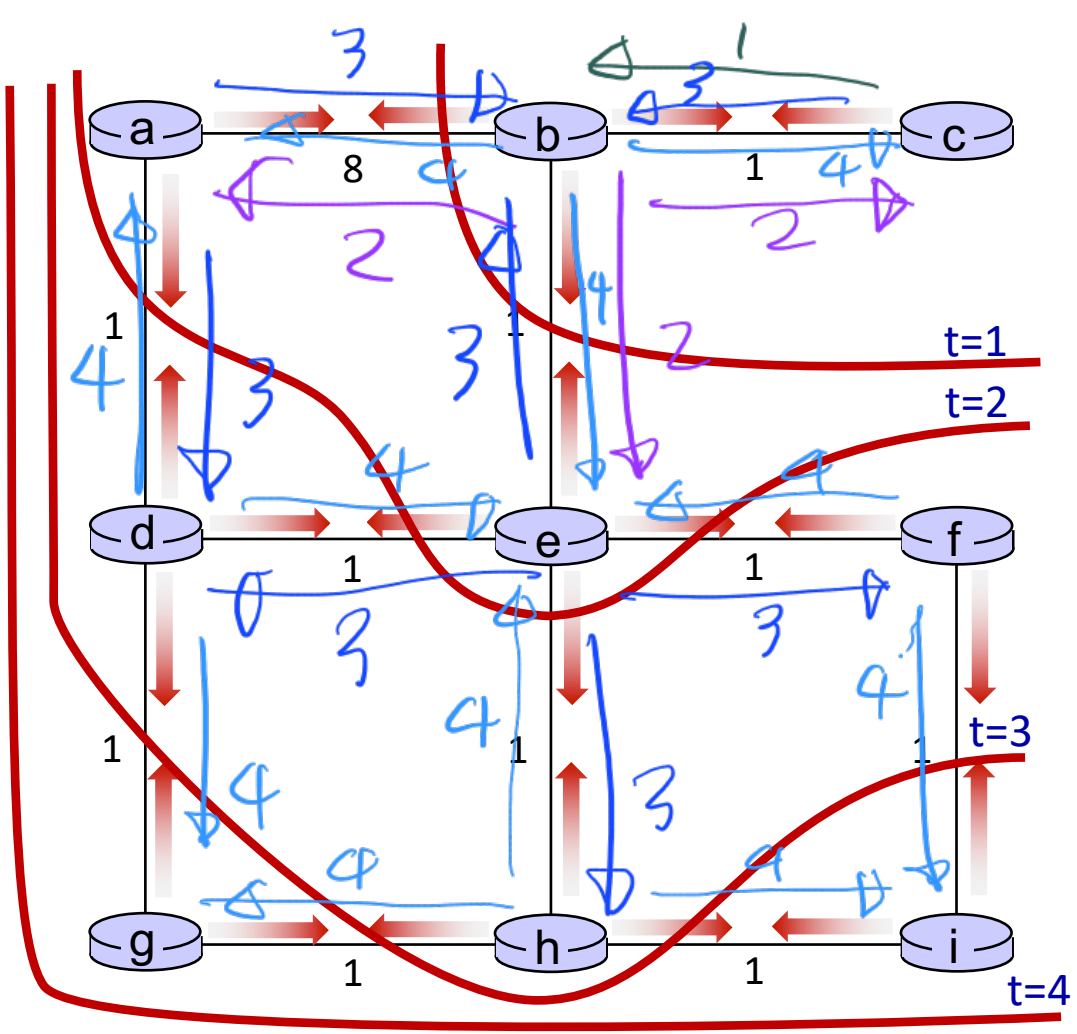
t=0 c's state at t=0 is at c only

t=1 c's state at t=0 has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b

t=2 c's state at t=0 may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well

t=3 c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at b,a,e and now at c,f,h as well

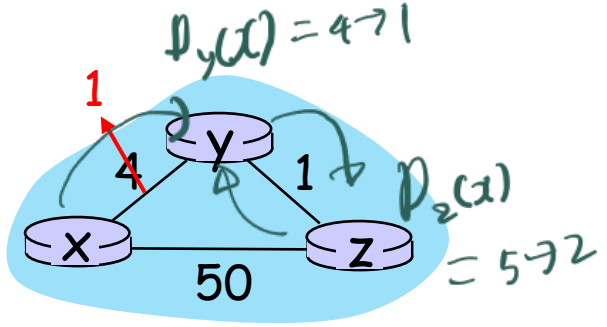
t=4 c's state at t=0 may influence distance vector computations up to **4** hops away, i.e., at b,a,e, c, f, h and now at g,i as well



Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors



cost 감소 시, 전파 속도 빠름

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors. (전파→업데이트)

"good news travels fast"

t_1 : *z* receives update from *y*, updates its table, computes new least cost to *x* , sends its neighbors its DV.

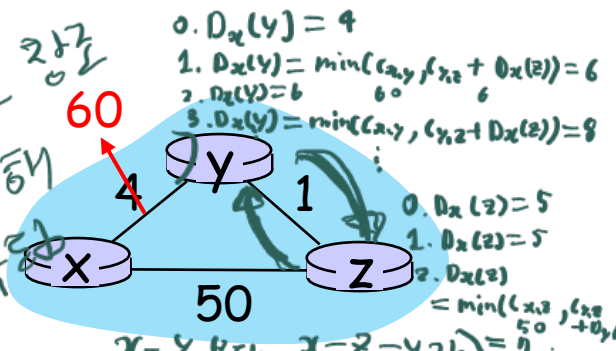
t_2 : *y* receives *z*'s update, updates its distance table. *y*'s least costs do *not* change, so *y* does *not* send a message to *z*.

Distance vector: link cost changes

link cost changes:

- node detects local link cost change
- "bad news travels slow" – count-to-infinity problem:
  - *y* sees direct link to *x* has new cost 60, but z has said it has a path at cost of 5. So *y* computes "my new cost to x will be 6, via z"; notifies *z* of new cost of 6 to *x*.
  - *z* learns that path to *x* via *y* has new cost 6, so *z* computes "my new cost to *x* will be 7 via y", notifies *y* of new cost of 7 to *x*.
  - *y* learns that path to *x* via *z* has new cost 7, so *y* computes "my new cost to *x* will be 8 via y", notifies *z* of new cost of 8 to *x*.
  - *z* learns that path to *x* via *y* has new cost 8, so *z* computes "my new cost to *x* will be 9 via y", notifies *y* of new cost of 9 to *x*.

    …
- see text for solutions. *Distributed algorithms are tricky!*



Comparison of LS and DV algorithms

message complexity

LS: n routers, $O(n^2)$ messages sent

DV: exchange between neighbors; convergence time varies

speed of convergence

LS: $O(n^2)$ algorithm, $O(n^2)$ messages

- may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

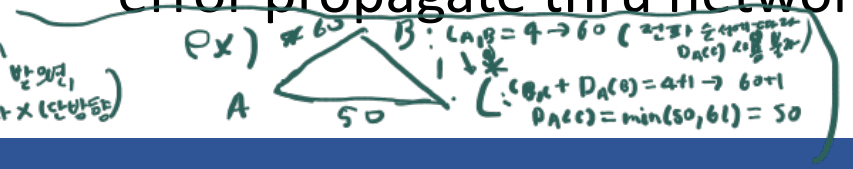
robustness: what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect *link* cost
- each router computes only its *own* table

DV:

- DV router can advertise incorrect *path* cost ("I have a *really* low cost path to everywhere"): black-holing
- each router's table used by others: error propagate thru network



Next…

- *Chapter 5.3 Intra-AS Routing in the Internet: OSPF*