

PLC Coding Style

Variables

- ⚠ Camel case
- ✅ First letter in Lower case
- 🚫 Prohibited “_”

Example:

- ✓ ready, isUp
- ✓ run, stop, up

- ⚠ Grouped variables that cannot be in a structure can use “_”:
- ✓ motor1_run
- ✓ motor1_stop

Constants

- ⚠ Snake case
- ✅ All Upper case

Example:

- ✓ STATUS_0_DONE
- ✓ ERROR_NOT_FOUND

Structures Data Types

- ⚠ Camel case
- ⚠ 1st letter in lower case
- 🚫 Prohibited “_”

Example:

- ✓ userData, motor
- ✓ nameOfStructure

```
STRUCTURE motor
    isRunning: bool
    command: int
    error: bool
END STRUCTURE
```

Enumerations

- Definition follows Structure rules.
- Data follows Constant rules.

```
ENUMERATION status
    ID_0_NIL : int := 0
    ID_2_BUSY : int := 2
END ENUMERATION
```

Data Containers (DB/DI)

- ⚠ Snake case
- ✅ All Upper case

Example:

- ✓ DB_NAME
- ✓ MOTOR1, SYSTEM

Program Organization Units

- ⚠ Snake case
- ✅ All Upper case

Example:

- ✓ MAIN, CYCICAL, HW_INTERRUPT
- ✓ OB001_MAIN (Siemens compatibility)

Subroutines Procedures

- ⚠ Camel case
- ⚠ First letter in Upper case

Example:

- ✓ Group1
- ✓ Controllers

```
OB001_MAIN:
    └─ FC: Group1
        └─ FB: Motor1_control, DB: MOTOR1
        └─ FB: Motor2_control, DB: MOTOR2
    └─ FC: Group2
        └─ FB: Motor3_control, DB: MOTOR3
        └─ FB: Motor4_control, DB: MOTOR4
```

- ⚠ “_” can be used for semantic ordering
- 🚫 “_” Prohibited in other case

Functions

- ⚠ Camel case
- ✓ “_” Must be the first char.
- ⚠ First letter in Lower case

Example:

- ✓ _foo(), _calc(), _measure()
- ✓ _add(), _toggle()

Interfaces

- ⚠ Camel case
- ✓ “I” Must be the first char.

Example:

- ✓ IMotor, ILamp
- ✓ IAlarm, IMotion