COMS 4735 Assignment 3 Write-up

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April 16th, 2018

Introduction

This assignment aims to use visual input (a map of Columbia campus) to generate textual descriptions of buildings and provide directions. There are three input files: new-campus.pgm (B/W image of the map), new-labeled.pgm (B/W image of the map with grayscale identifiers), and new-table.txt (a table of grayscale identifier values and building names).

The code listing is at: . All codes are original.

Step 0: Pre-Processing

The system will read in all three input files first, and store the two maps into 2D numpy arrays. Then the system reads in the value/name table and store them with two 1D arrays with matching indices, from 0 - 25 (26 buildings in total).

Step 1: Describing Shapes

Design Choices & Algorithms

The system will take the three input files and output 4 arrays: AREA (size of the building in pixel count), COM (center of mass in float coordinates), BBOX (max/min x and y of the building pixels), and DESC (shape descriptors). All these arrays can be inferred through matched

indices. (i.e. index 0 stands for information of Pupin for all four arrays, as it is organized in new-table.txt).

AREA is calculated through counting the pixels with color value matching the value/name table for each of the building.

COM is calculated through diving the sum of x and y coordinates by the area of the building.

BBOX is calculated through finding the maximum and minimum of all the building pixel coordinates in both x and y direction.

Three types of shape descriptors are included: size, orientation and shape. No more descriptors are selected because most of the buildings are already identifiable through these descriptors with the exception of Mudd, and buildings with exactly the same shapes.

The size descriptor is given based on the building's size in comparison with the maximum size.

Size Descriptor	Size Ratio
LARGE	(0.67, 1]
MEDIUM	(0.33, 0.67]
SMALL	(0.1, 0.33]
TINY	(0, 0.1]

The orientation descriptor is given based on the ratio of bounding box's height and width.

Orientation Descriptor	Condition
VERTICAL	bbox_height > 1.25 * bbox_width
HORIZONTAL	bbox_width > 1.25 * bbox_height
SQUARELY ORIENTED	Others

There are two sets of shape descriptors as listed below:

1) SQUARE, RECTANGULAR, NON-RECTANGULAR

And if the building is NON-RECTANGULAR, the second set of descriptor is given.

2) SYMMETRICAL, NOT SYMMETRICAL ON BOTH ORIENTATIONS

The algorithm is designed as the following:

- 1) Compute the bounding box area.
- 2) If the bounding box area is smaller than 102% of the building area (2% is introduced to include floating errors), then it is either SQUARE or RECTANGULAR, go to step 3. Else, go to step 4.
- 3) If the bounding box width is within 10% of difference with the bounding box height, it is a SQUARE (10% accounts for not human noticable differences, buildings are highly unlikely designed to be exact square-shaped), or else it is RECTANGULAR.
- 4) The building is NON-RECTANGULAR. Compute the center coordinate of the bounding box.
- 5) If the center of mass is within 0.5% of difference with the bounding box center coordinate, the building is SYMMETRICAL, else it is NOT SYMMETRICAL ON BOTH ORIENTATIONS.

Output

Note that the sequence matches the sequence in new-table.txt.

AREA

```
array([1640., 1435., 5831., 1998., 5753., 3911., 3613., 322., 1164., 1182., 1191., 3898., 1087., 759., 1307., 1085., 340., 225., 1590., 1470., 4950., 2615., 5855., 2940., 5282., 1540.])
```

BBOX (max_y, max_x, min_y, min_x)

```
array([[ 76.15304878, 14.97621951],
                                                                            array([[ 27., 115., 3., 39.],
         [143. , 20. ],
[223.24181101, 35.27954039],
                                                                                       37., 163.,
                                                                                                        3., 123.],
                                                                                     [ 86., 272., 3., 166.],
         [ 16. , 40.5 ],
[142.5256388 , 99.46532244],
                                                                                     [ 77., 29., 4., 3.], [147., 175., 48., 110.],
                                                                                     [147., 173., 46., 110.],

[147., 273., 77., 181.],

[147., 80., 81., 3.],

[147., 103., 125., 90.],

[201., 215., 151., 191.],
         [233.44694452, 120.51009972],
         [ 37.53086078, 119.54248547],
         [ 96.5 , 136. ],
[204.04896907, 175.98195876],
         [259.61505922, 176.
                                                                                      [201., 272., 151., 247.],
                                                                                     [206., 31., 158., 3.],
[256., 169., 187., 101.],
         [ 17. , 182.
         [135. , 221.5 ], [226.55381785, 222.02115915],
                                                                                      [234., 251., 210., 201.],
                                                                                     [233., 68., 211., 31.],
[285., 31., 233., 3.],
         [ 49.59947299, 221.8629776 ],
         [ 17. , 259. [258.33548387, 263.
                                                                                      [286., 272., 240., 245.],
                       , 253.5
         ſ208.
                                                                                     [261., 220., 246., 196.],
[283., 143., 269., 129.],
         [136.
                          , 276.
                        , 301.09056604],
                                                                                      [311., 80., 289.,
         [ 41.5
                        , 300.9
         [233.
                                                                                      [310., 272., 290., 194.],
         [137.
                           322.5
                                                                                      [331., 274., 314., 0.],
         [137. , 322.5 ],
[ 30.58699809, 363.94416826],
                                                                                     [414., 81., 338., 4.],
[490., 270., 338., 191.],
         [240.33885568, 416.94722459],
                    , 446.5
         [ 38.5
                                                                                      [467., 73., 426., 4.],
         [132.
                         , 460.41461568],
                                                                                      [490., 179., 431., 85.],
                          , 479.5
         [ 38.5
                                                                                     [490., 73., 469., 4.]])
```

DESC

```
[['SMALL',
     'HORTZONTAL'
     'NON-RECTANGULAR',
     'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['SMALL', 'SYMMETRICALLY ORIENTED', 'RECTANGULAR'],
  ['LARGE',
     'HORIZONTAL'
    'NON-RECTANGULAR'
    'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['MEDIUM', 'VERTICAL', 'RECTANGULAR'],
    'VERTICAL',
    'NON-RECTANGULAR'
     'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['MEDIUM',
    'HORIZONTAL'
     'NON-RECTANGULAR',
    'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['MEDIUM',
     'SYMMETRICALLY ORIENTED'.
    'NON-RECTANGULAR',
    'NOT SYMMETRICAL ON BOTH ORIENTATION'],
 ['TINY', 'VERTICAL', 'RECTANGULAR'],
['SMALL',
     'VERTICAL',
    'NON-RECTANGULAR'
   'NOT SYMMETRICAL ON BOTH ORIENTATION'],

'SMALL', 'VERTICAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'VERTICAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'MEDIUM', 'SYMMETRICALLY ORIENTED', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'VERTICAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'VERTICAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'TINY', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'SMALL', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],

'LARGE', 'HORIZONTAL', 'RECTANGULAR', 'SYMMETRICAL'],

'MEDIUM',
     'NOT SYMMETRICAL ON BOTH ORIENTATION'],
    'MEDTUM'
     'SYMMETRICALLY ORIENTED',
     'NON-RECTANGULAR',
    'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['LARGE',
'LARGEST',
    'NON-RECTANGULAR',
     'NOT SYMMETRICAL ON BOTH ORIENTATION'],
  ['MEDIUM', 'HORIZONTAL', 'RECTANGULAR'],
['LARGE', 'HORIZONTAL', 'NON-RECTANGULAR', 'SYMMETRICAL'],
['SMALL', 'HORIZONTAL', 'RECTANGULAR']]
```

Step 2: Describing Absolute Space

Design Choices & Algorithms

To describe the absolute position of the buildings, two sets of descriptors are introduced.

- 1) NORTHWEST, NORTH, NORTHEAST, WEST, CENTER, EAST, SOUTHWEST, SOUTH, SOUTHEAST
- 2) UPPER, LOWER

The map is divided into a equally spaced 3x3 grid with the descriptor names. The first set of descriptor is based on the center of mass position of the building with regard to the grid, and assign the descriptor name to the building. The second set of descriptor is based on the center of mass position of the building within its grid - if it is above the grid center, it is UPPER, otherwise it is LOWER.

The reason for such design is to make the absolute space descriptors not too complicated while remain as distinct as possible for relative space computation purposes. It is not hard to notice that by observing the map, the center position of the buildings roughly fits into a 3x3 grid with the exception of the College Walk. The second set of descriptor will help to limit the maximum number of buildings with the same absolute space descriptors to 3 - which will make relative space computation much easier.

Output

```
[['NORTHWEST', 'UPPER'],
['NORTH', 'UPPER'],
['NORTHEAST', 'UPPER'],
['NORTHWEST', 'UPPER'],
['NORTH', 'LOWER'],
['NORTHEAST', 'LOWER'],
['NORTHWEST', 'LOWER'],
 ['NORTH', 'LOWER'],
 ['EAST', 'UPPER'],
['EAST', 'UPPER'],
 ['WEST', 'UPPER'],
 ['CENTER', 'UPPER'],
['EAST', 'UPPER'],
['WEST', 'UPPER'],
 ['WEST', 'LOWER'],
 ['EAST', 'LOWER'],
 ['EAST', 'LOWER'],
 ['CENTER', 'LOWER'],
['WEST', 'LOWER'],
['EAST', 'LOWER'],
 ['CENTER', 'LOWER'],
 ['SOUTHWEST', 'UPPER'],
 ['SOUTHEAST', 'LOWER'],
 ['SOUTHWEST', 'LOWER'],
 ['SOUTH', 'LOWER'],
 ['SOUTHWEST', 'LOWER']]
```

Step 3: Describing Relative Space

Design Choices

For compass-directed spatial relationships (North, South, West, East) for (S, T), the relationship is marked true only when every pixel of S is in the same direction of every pixel of T, and it is determined through the max and min values of bounding box coordinates.

However, this might not be enough - for a pair of (S, T) that do not overlap each other at all with their bounding boxes, T could be, for example, both South and West of S. A test of their centers of mass is performed: if the line between the two centers are more vertical than horizontal, keep South and erase West, and vice versa. This would help to reduce every pair of (S, T) to only one compass-directed relationship, and it is more intuitive to human as well as easier to determine the path in later steps.

For Near relationships, I determined that the descriptor in Step 2 will first override any size considerations, simply because the grid is well-defined and very intuitive for near relationships, plus the fact that only considering size relationships would neglect some necessary ones - for example, alma mater is really near to the college walk; however, it is hard to determine that solely through the same numerical method applied to all buildings. After the override, a size relationship test is performed and is explained in the Algorithm part.

Algorithm

Given two buildings, the relative compass-directed spatial relationship (North, South, West, East) between the two is determined through the following way:

 Check the COM of S and T: if the y difference is larger than x difference, then T is either North or South of S; otherwise, T is either East or West of S.

- 2) Check the max/min BBOX values of S and T: if T is North or South of S, when min_y_T > max_y_S, T is South of S, otherwise T is North of S; if T is East or West of S, when min_x_T > max_x_S, T is East of S, otherwise T is West of S.
- 3) Perform transitive reduction in the matrix. For any (i, j, k), if North(i, j) and North(j, k), set North(i, k) = false. Same goes for the other three matrices.
- 4) Perform reflective reduction in the matrices. For any (i, j), if North(i, j) = South(j, i) = True, set South(j, i) = False; if East(i, j) = West(j, i) = True, set West(j, i) = False.

The Near relationship is determined through the following way:

- 1) For every pair of buildings (i, j), if their descriptor in Step 2 is exactly the same, Near(i, j) = True.
- 2) For every other pair of buildings (i, j) that is not marked as true in 1), check the area within twice the scale of the bounding box of (i) around the center of mass of (i). If j appears in the area, Near(i, j) = True.
- 3) For all other unmarked (i, j) pairs, Near(i, j) = False.

Output

```
Pupin
--East-->SchapiroCEPSR

Pupin
--Near-->SchapiroCEPSR

Pupin
--Near-->NorthwestCorner

Pupin
--East-->Schermerhorn

Pupin
--East-->Fayerweather

SchapiroCEPSR
--Near-->Pupin

SchapiroCEPSR
--East-->Mudd&EngTerrace&Fairchild&CS

SchapiroCEPSR
--Near-->Mudd&EngTerrace&Fairchild&CS
```

```
SchapiroCEPSR
--Near-->Uris
Mudd&EngTerrace&Fairchild&CS
--Near-->SchapiroCEPSR
Mudd&EngTerrace&Fairchild&CS
--Near-->Uris
Mudd&EngTerrace&Fairchild&CS
--Near-->Schermerhorn
NorthwestCorner
--East-->Pupin
NorthwestCorner
--Near-->Pupin
NorthwestCorner
--East-->Uris
NorthwestCorner
--Near-->Chandler&Havemeyer
NorthwestCorner
--East-->Avery
{\tt NorthwestCorner}
--East-->StPaulChapel
NorthwestCorner
--East-->Philosophy
Uris
--North-->Pupin
Uris
--Near-->Pupin
--North-->SchapiroCEPSR
Uris
--Near-->SchapiroCEPSR
--Near-->Mudd&EngTerrace&Fairchild&CS
Uris
--East-->Schermerhorn
Uris
--Near-->Schermerhorn
--Near-->Chandler&Havemeyer
--Near-->ComputerCenter
Uris
--Near-->Avery
```

Uris

```
--East-->Fayerweather
--Near-->LowLibrary
Schermerhorn
--North-->SchapiroCEPSR
{\tt Schermerhorn}
--Near-->Mudd&EngTerrace&Fairchild&CS
Schermerhorn
--Near-->Uris
Schermerhorn
--Near-->Avery
{\tt Schermerhorn}
--Near-->Fayerweather
Schermerhorn
--Near-->LowLibrary
{\tt Chandler\&Have meyer}
--North-->Pupin
Chandler&Havemeyer
--East-->SchapiroCEPSR
Chandler&Havemeyer
--North-->NorthwestCorner
Chandler&Havemeyer
--Near-->NorthwestCorner
Chandler&Havemeyer
--Near-->Uris
Chandler&Havemeyer
--East-->ComputerCenter
Chandler&Havemeyer
--Near-->ComputerCenter
Chandler&Havemeyer
--Near-->Mathematics
Chandler&Havemeyer
--East-->Buell
Chandler&Havemeyer
--East-->Kent
ComputerCenter
--North-->Pupin
{\tt ComputerCenter}
--North-->SchapiroCEPSR
ComputerCenter
--East-->Mudd&EngTerrace&Fairchild&CS
ComputerCenter
--North-->NorthwestCorner
```

```
ComputerCenter
--East-->Uris
ComputerCenter
--Near-->Uris
ComputerCenter
--East-->Avery
ComputerCenter
--East-->StPaulChapel
{\tt ComputerCenter}
--East-->Philosophy
Avery
--North-->Mudd&EngTerrace&Fairchild&CS
Avery
--North-->Uris
Avery
--North-->Schermerhorn
Avery
--Near-->Schermerhorn
Avery
--East-->Fayerweather
Avery
--Near-->Fayerweather
Avery
--Near-->StPaulChapel
Fayerweather
--North-->Mudd&EngTerrace&Fairchild&CS
Fayerweather
--North-->Schermerhorn
Fayerweather
--Near-->Schermerhorn
Fayerweather
--Near-->Avery
Fayerweather
--Near-->StPaulChapel
Mathematics
--North-->SchapiroCEPSR
Mathematics
-- \verb|North--> Chandler&Havemeyer|
Mathematics
--Near-->Chandler&Havemeyer
Mathematics
```

--East-->ComputerCenter

```
Mathematics
--East-->LowLibrary
Mathematics
--Near-->EarlHall
Mathematics
--East-->AlmaMater
LowLibrary
--North-->Mudd&EngTerrace&Fairchild&CS
LowLibrary
--North-->Uris
LowLibrary
--North-->Schermerhorn
LowLibrary
--North-->Chandler&Havemeyer
LowLibrary
--North-->ComputerCenter
LowLibrary
--East-->Avery
LowLibrary
--Near-->Avery
LowLibrary
--East-->StPaulChapel
LowLibrary
--Near-->StPaulChapel
LowLibrary
--Near-->EarlHall
LowLibrary
--East-->Buell
LowLibrary
--Near-->Buell
LowLibrary
--Near-->AlmaMater
LowLibrary
--Near-->Dodge
LowLibrary
--East-->Kent
StPaulChapel
--North-->Avery
StPaulChapel
--Near-->Avery
StPaulChapel
--North-->Fayerweather
StPaulChapel
```

```
--Near-->Fayerweather
StPaulChapel
--Near-->Philosophy
EarlHall
--North-->Mudd&EngTerrace&Fairchild&CS
EarlHall
--North-->Uris
EarlHall
--East-->Schermerhorn
EarlHall
--North-->ComputerCenter
--North-->Mathematics
EarlHall
--Near-->Mathematics
EarlHall
--East-->LowLibrary
EarlHall
--Near-->Lewisohn
EarlHall
--East-->AlmaMater
Lewisohn
--North-->Mudd&EngTerrace&Fairchild&CS
Lewisohn
--North-->Uris
Lewisohn
--East-->Schermerhorn
Lewisohn
--North-->ComputerCenter
Lewisohn
--North-->Mathematics
Lewisohn
--East-->LowLibrary
Lewisohn
--Near-->EarlHall
Lewisohn
--East-->AlmaMater
Lewisohn
--Near-->Dodge
--East-->Hamilton&Hartley&Wallach&JohnJay
Philosophy
--North-->StPaulChapel
```

```
Philosophy
--Near-->StPaulChapel
Philosophy
--Near-->Buell
Philosophy
--Near-->Kent
Buell
--North-->ComputerCenter
Buell
--North-->StPaulChapel
Buell
--East-->Philosophy
Buell
--Near-->Philosophy
Buell
--Near-->Kent
AlmaMater
--North-->Avery
{\tt AlmaMater}
--East-->Fayerweather
AlmaMater
--North-->LowLibrary
AlmaMater
--East-->StPaulChapel
AlmaMater
--East-->Buell
{\tt AlmaMater}
--East-->Kent
{\tt AlmaMater}
--Near-->CollegeWalk
Dodge
--East-->Schermerhorn
Dodge
--East-->LowLibrary
Dodge
--North-->EarlHall
Dodge
--North-->Lewisohn
Dodge
--Near-->Lewisohn
Dodge
--East-->AlmaMater
```

```
Dodge
--Near-->CollegeWalk
--East-->Hamilton&Hartley&Wallach&JohnJay
Kent
--North-->Philosophy
Kent
--Near-->Philosophy
Kent
--North-->Buell
Kent
--Near-->Buell
Kent
--Near-->CollegeWalk
CollegeWalk
--North-->StPaulChapel
CollegeWalk
--North-->EarlHall
CollegeWalk
--North-->AlmaMater
CollegeWalk
--Near-->AlmaMater
CollegeWalk
--Near-->Dodge
CollegeWalk
--Near-->Kent
CollegeWalk
--Near-->Journalism&Fourfold
CollegeWalk
--Near-->Hamilton&Hartley&Wallach&JohnJay
Journalism&Fourfold
--North-->Avery
Journalism&Fourfold
--North-->LowLibrary
Journalism&Fourfold
--East-->AlmaMater
Journalism&Fourfold
--North-->Dodge
Journalism&Fourfold
--Near-->Dodge
Journalism&Fourfold
--Near-->CollegeWalk
Journalism&Fourfold
```

```
--Near-->Lerner
Journalism&Fourfold
--East-->ButlerLibrary
Journalism&Fourfold
--Near-->ButlerLibrary
Hamilton&Hartley&Wallach&JohnJay
--North-->EarlHall
Hamilton&Hartley&Wallach&JohnJay
--Near-->Philosophy
Hamilton&Hartley&Wallach&JohnJay
--North-->AlmaMater
Hamilton&Hartley&Wallach&JohnJay
--North-->Kent
Hamilton&Hartley&Wallach&JohnJay
--Near-->Kent
Hamilton&Hartley&Wallach&JohnJay
--Near-->CollegeWalk
Hamilton&Hartley&Wallach&JohnJay
--Near-->ButlerLibrary
Lerner
--East-->Philosophy
Lerner
--North-->Buell
Lerner
--East-->Kent
Lerner
--North-->CollegeWalk
Lerner
--North-->Journalism&Fourfold
Lerner
--Near-->Journalism&Fourfold
Lerner
--East-->ButlerLibrary
Lerner
--Near-->ButlerLibrary
Lerner
--Near-->Carman
ButlerLibrary
--North-->Dodge
ButlerLibrary
--North-->Kent
ButlerLibrary
```

--North-->CollegeWalk

```
ButlerLibrary
--East-->Hamilton&Hartley&Wallach&JohnJay
{\tt ButlerLibrary}
--Near-->Hamilton&Hartley&Wallach&JohnJay
ButlerLibrary
--Near-->Lerner
ButlerLibrary
--Near-->Carman
Carman
--East-->Philosophy
Carman
--East-->Kent
Carman
--North-->Lerner
Carman
--Near-->Lerner
Carman
--East-->ButlerLibrary
Carman
--Near-->ButlerLibrary
```