

Q1.1

From the correspondence relationship, we have

$$x'^T F x = 0$$

$$\Leftrightarrow \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ f_1 & f_2 & f_3 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = 0$$

$$\Leftrightarrow \begin{bmatrix} f_{13}, f_{23}, f_{33} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = 0 \Leftrightarrow f_{33} = 0.$$

Q1.2

We have  $R = I = \begin{bmatrix} 1 & & \\ & 1 & \\ & & 1 \end{bmatrix}$  and  $[t]_x = \begin{bmatrix} 0 & -t_3 & t_2 \\ t_3 & 0 & -t_1 \\ -t_2 & t_1 & 0 \end{bmatrix}$

$$\text{So } E = [t]_x R = \begin{bmatrix} 0 & -t_3 & t_2 \\ t_3 & 0 & -t_1 \\ -t_2 & t_1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & -t_1 \\ 0 & t_1 & 0 \end{bmatrix} \quad (t_2 = t_3 = 0).$$

$$\text{So } l_1 = E^T x_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & t_1 \\ 0 & -t_1 & 0 \end{bmatrix} \begin{bmatrix} x_2 \\ y_2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ t_1 \\ -t_1 y_2 \end{bmatrix}$$

$$l_2 = E x_1 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & -t_1 \\ 0 & t_1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -t_1 \\ t_1 y_1 \end{bmatrix}$$

both  $l_1$  and  $l_2$  are parallel to the  $x$ -axis.

Q1.3

$$p_i = K[R_i | t_i] \cdot \begin{bmatrix} P \\ 1 \end{bmatrix} = K \cdot (R_i P + t_i)$$

$$p_1 = K(R_1 P + t_1) \quad p_2 = K(R_2 P + t_2) \Rightarrow P = R_1^{-1}(K^{-1} p_1 - t_1)$$

$$\Rightarrow p_1 = K(R_1 R_2^{-1}(K^{-1} p_2 - t_2) + t_1) = K R_1 R_2^{-1} K^{-1} p_2 - K R_1 R_2^{-1} t_2 + K t_1$$

$$= R_{rel} p_2 + t_{rel}$$

$$\text{So } \begin{cases} R_{rel} = K R_1 R_2^{-1} K^{-1} \\ t_{rel} = -K R_1 R_2^{-1} t_2 + K t_1 \end{cases}$$

$$\begin{cases} E = [t_{rel}]_x R_{rel} \\ F = K^{-1} [t_{rel}]_x R_{rel} K^{-1} \end{cases}$$

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Q 1.4.

Let  $P$  and  $P'$  be a point and its reflection in real world and  $d$  and  $d'$  be the image of them.

The translation between  $P$  and  $P'$  is

$$R = I, T = \begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix}$$

$$\text{We have } \begin{cases} d = KP \text{ ① and } \lambda d' = KP' \text{ ②} \\ P' = RP + T = P + T \text{ ③} \end{cases}$$

from ① ② ③. We get

$$K^{-1} \lambda d' = K^{-1} d + T$$

$$\Leftrightarrow \lambda d' = d + KT$$

$$\Leftrightarrow \cancel{\lambda [T]_x d'} = \cancel{[T]_x d} + K$$

$$\lambda d' [T]_x = d [T]_x + K T [T]_x$$

$$\Leftrightarrow \lambda d' [T]_x = d [T]_x$$

$$\Leftrightarrow \lambda d' [T]_x d'^T = d [T]_x d^T \text{ ④}$$

left side of equation ④ is 0.

$$\text{So } d [T]_x d^T = 0.$$

We can view  $[T]_x$  as a fundamental matrix  $F$ .

$$[T]_x^T = -[T]_x.$$

$$\text{So } F^T = -F. \text{ (skew-symmetric).}$$