

March 28, 2018

1 Assignment 1

1.1 Exercise 1.1

rough sketch for ex 1.2:

1. define the positive“ subspace P in the RGB cube
2. iterate over all pixels in I and check if in P or $\sim P$
3. write result to new image
4. play around with size and shape of P and display binary image (**RESULT**)

In [14]: %matplotlib inline

```

from skimage import io, data, color
from skimage.morphology import erosion, disk, dilation, square
import numpy as np
import matplotlib.pyplot as plt
import warnings; warnings.filterwarnings('ignore')

image = io.imread('images/racecar/010.jpeg')
height, width, _ = image.shape
print(width, height)

def create_mask(image, width, height):
    mask = np.zeros_like(image[:, :, 0])

    for y in range(0, height):
        for x in range(0, width):
            rgb = [image[y, x, 0], image[y, x, 1], image[y, x, 2]]
            rgb.sort()
            color_min = rgb[1] - 40
            color_max = rgb[1] + 40

            # filter greyish color
            if (color_min < rgb[0] < color_max and color_min < rgb[2] < color_max):
                continue

            # get blue color
            mask[y, x] = 255

```

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        if image[y,x,2] > 110 and image[y,x,0:1] < 220 :
            mask[y,x] = 255

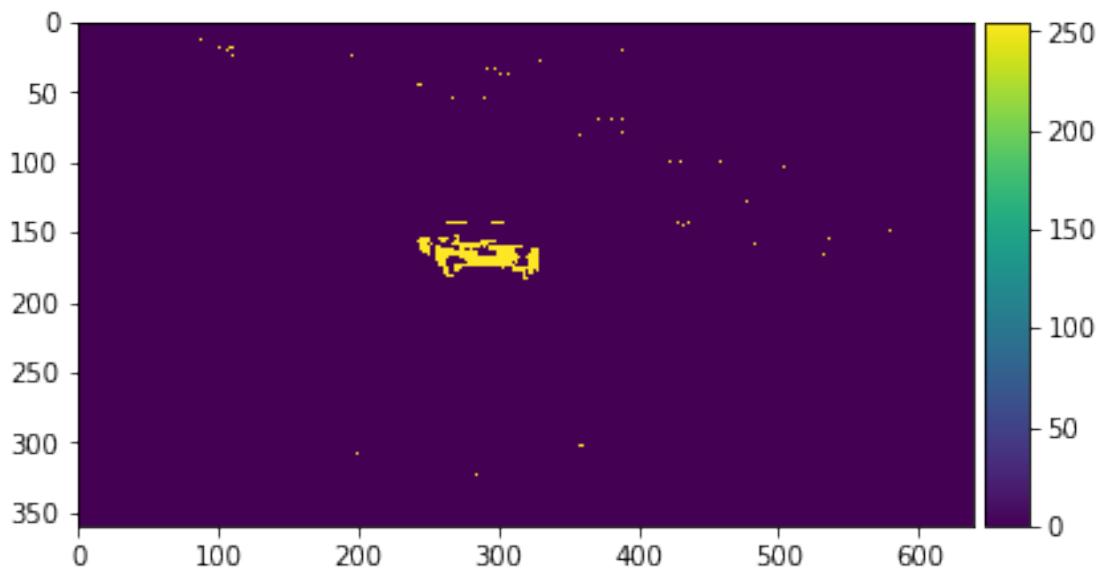
    return mask

mask = create_mask(image, width, height)

io.imshow(mask)
io.show()
# RESULT

```

640 360



1.2 Exercise 1.2

- starting from the binary color detection image
- erase noise with an erosion operation
- dilate once to get original size of object
- find connected components with one-pass algorithm
- extract bounding box on the fly
- draw bounding box on original image (**RESULT**)

In [4]: `from skimage.draw import polygon_perimeter`

```

selem = square(3)
eroded = erosion(mask, selem)
dilated = dilation(eroded, selem)

```

```

dilated = dilation(dilated, selem)

mask = dilated
height, width = mask.shape

#test3color = io.imread('images/test3.png')
#test3 = color.rgb2gray(test3color)
#height, width = test3.shape

class BBox:
    # static var - can be accessed by BBox.bboxes - clear this before use again
    bboxes = dict()      # todo: rename

    minX = 9999
    minY = 9999

    maxX = 0
    maxY = 0

    def add(self, x, y):
        BBox.bboxes[(x,y)] = self
        if self.minX > x:
            self.minX = x
        if self.maxX < x:
            self.maxX = x
        if self.minY > y:
            self.minY = y
        if self.maxY < y:
            self.maxY = y

    def join(self, other_bbox):
        for k,v in BBox.bboxes.items():
            if v == other_bbox:
                self.add(k[0], k[1])

    def get_size(self):
        width = self.maxX - self.minX
        height = self.maxY - self.minY
        return width * height

    @staticmethod
    def add_create_bbox(x, y):
        if (x-1,y) in BBox.bboxes and not (x,y-1) in BBox.bboxes:
            # add
            BBox.bboxes[(x-1,y)].add(x,y)
        elif (x,y-1) in BBox.bboxes and not (x-1,y) in BBox.bboxes:
            # add
            BBox.bboxes[(x,y-1)].add(x,y)

```

```

        elif (x,y-1) in BBox.bboxes and (x-1,y) in BBox.bboxes:
            # join
            BBox.bboxes[(x-1,y)].add(x,y)
            BBox.bboxes[(x-1,y)].join(BBox.bboxes[(x,y-1)])
    else:
        # create new
        box = BBox()
        BBox.bboxes[(x,y)] = box

def compute_bounding_boxes(mask, img, draw_boxes = True):
    BBox.bboxes.clear()
    height, width = mask.shape

    # calculate bboxes
    for y in range(0,height):
        for x in range (0,width):
            if mask[y, x] == 255: # use 1.0 for test3
                BBox.add_create_bbox(x, y)

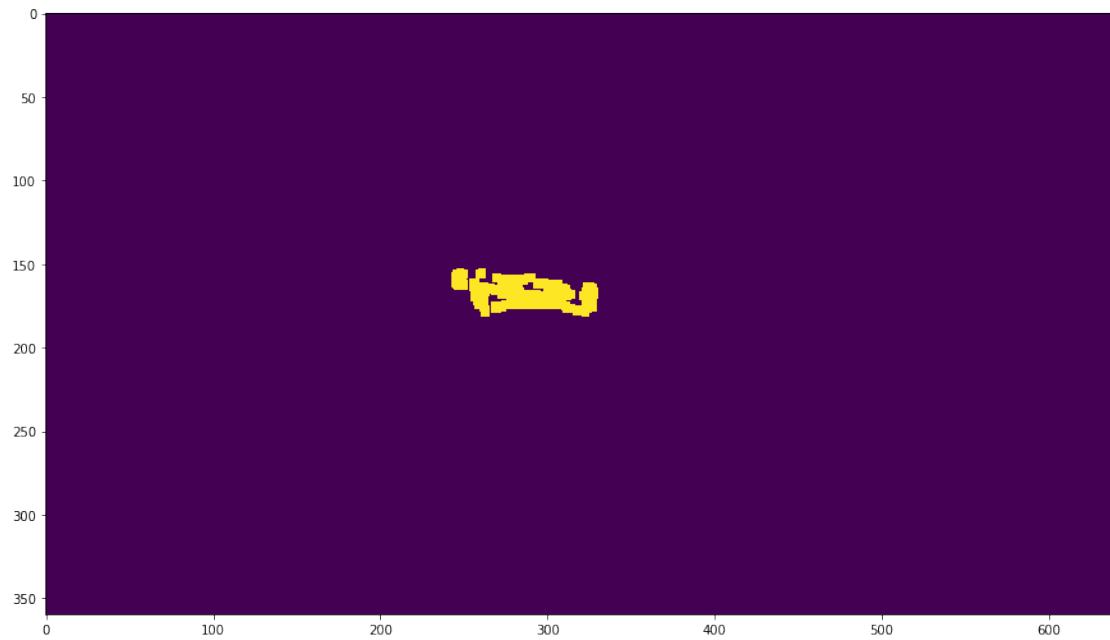
    # draw bboxes
    if draw_boxes:
        for box in set(BBox.bboxes.values()):
            rr, cc = polygon_perimeter([box.minY, box.maxY, box.maxY, box.maxY, box.maxY,
                                         [box.minX, box.minX, box.minX, box.maxX, box.maxX, box.maxX, box.maxX],
                                         img.shape])
            img[rr, cc] = [255,255,255] # use [0,0,255,255] for test 3

    return set(BBox.bboxes.values())

bboxes = compute_bounding_boxes(mask, image)
print(len(bboxes))

plt.figure(1, figsize=(15, 20))
plt.imshow(mask)
plt.figure(2, figsize=(15, 20))
plt.imshow(image)
plt.show()

```



1.2.1 Number of component

```
In [5]: from skimage import measure  
import numpy as np
```

```
print(len(bboxes))
```

2

1.2.2 Bounding Box

In [6]: `from skimage.measure import regionprops`

```
import math
import cv2

# draw bboxes
for box in set(BBox.bboxes.values()):
    rr, cc = polygon_perimeter([box.minY, box.maxY, box.maxY, box.maxY, box.maxY, box.maxY, box.maxY, box.maxY, box.minX, box.minX, box.minX, box.maxX, box.maxX, box.maxX, box.maxX, box.maxX])
    image[rr, cc] = [255,255,0] # use [0,0,255,255] for test 3

plt.figure(figsize=(15, 20))
plt.imshow(image)
plt.show()
```



1.3 Exercise 1.3

- use your color detection and connected components algorithm

- implement simplest tracking algorithm
- draw history of all previous points on frame (**RESULT**)

```
In [8]: def get_file_name(i):
    if i < 10:
        return "images/racecar/00" + str(i) + ".jpeg"
    if i < 100:
        return "images/racecar/0" + str(i) + ".jpeg"
    return "images/racecar/" + str(i) + ".jpeg"

def draw_line(img, coord_list):
    coords = list(map(list, zip(*coord_list)))
    rr, cc = polygon_perimeter(coords[0], coords[1], img.shape, clip=False)
    img[cc,rr] = [0,0,255] # use [0,0,255,255] for test 3
    return img

In [11]: tracking_points = []

for i in range(0 ,150, 1):
    print(i)
    tmp_image = io.imread(get_file_name(i))
    height, width, _ = tmp_image.shape
    tmp_mask = create_mask(tmp_image, width, height)

    eroded = erosion(tmp_mask, selem)
    dilated = dilation(eroded, selem)

    tmp_box = compute_bounding_boxes(dilated, tmp_image, draw_boxes = False)
    print("Ammount of bboxes: " + str(len(tmp_box)))

    l = list(tmp_box)

    # use greatest bounding box
    largest = None
    size = 0
    for b in l:
        if b.get_size() > size:
            largest = b
            size = b.get_size()

    if largest:
        tracking_points.append( (largest minX, largest minY) )
        rr, cc = polygon_perimeter([largest minY, largest maxY, largest maxY, largest
                                    largest maxY, largest minY, largest minY],
                                    [largest minX, largest minX, largest minX, largest
                                    largest maxX, largest maxX, largest minX],
                                    tmp_image.shape)
        tmp_image[rr, cc] = [255,255,255] # use [0,0,255,255] for test 3
```

```
if (len(tracking_points) > 2):
    tmp_image = draw_line(tmp_image, tracking_points)

plt.figure(i, figsize=(15,20))
plt.imshow(tmp_image)

# plt.figure(8, figsize=(15,20))
# tmp_image = io.imread(get_file_name(151))
# tmp_image = draw_line(tmp_image, tracking_points)
plt.imshow(tmp_image)

#plt.figure(figsize=(15,20))
plt.show()

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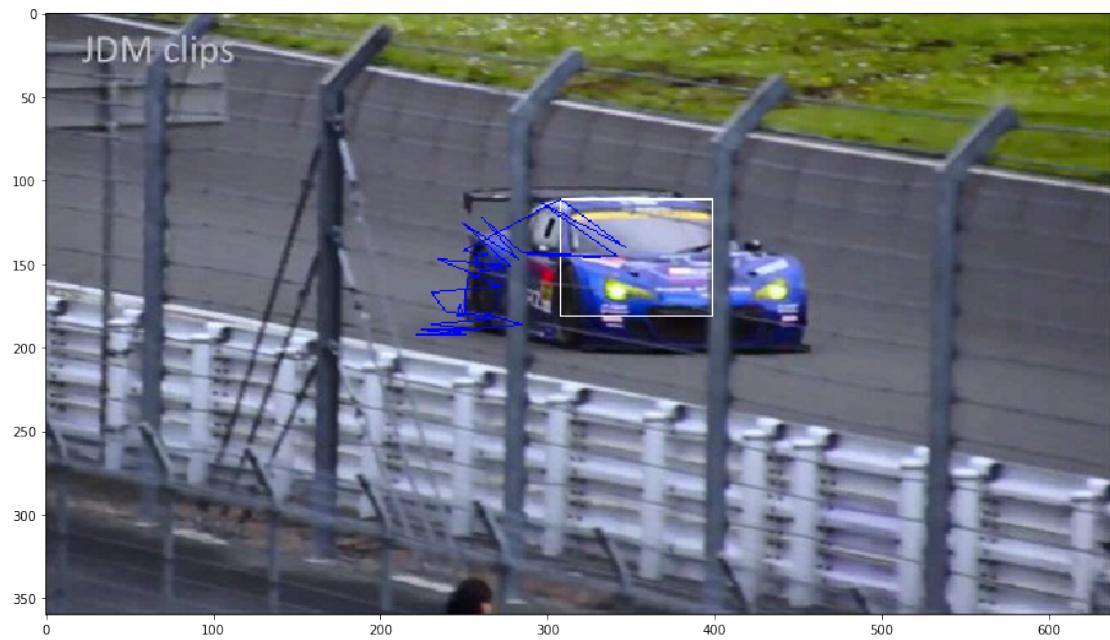




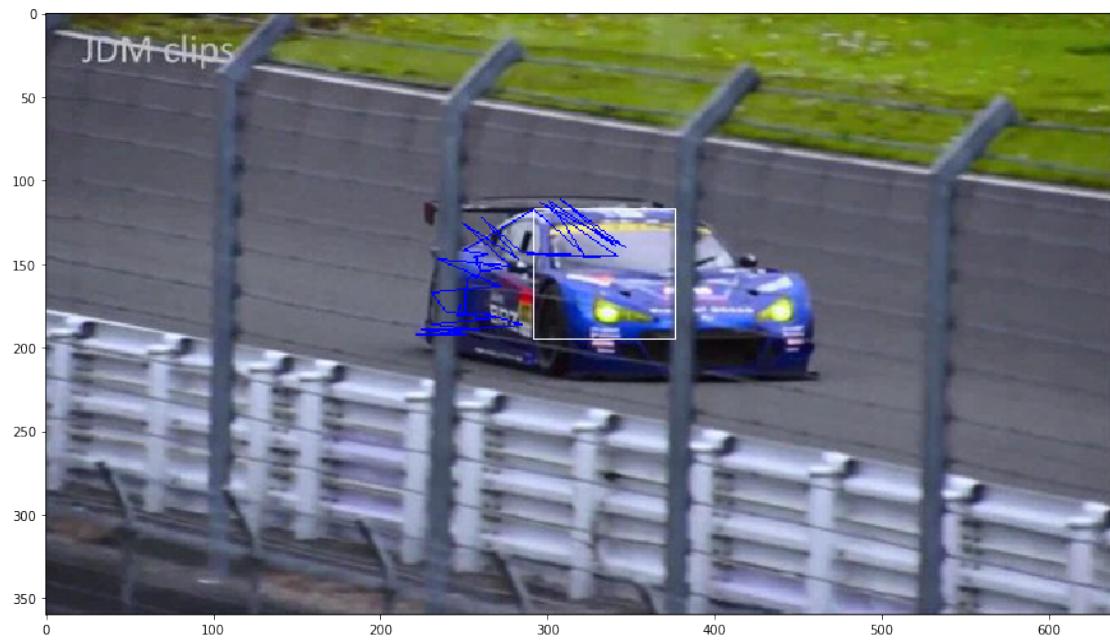
















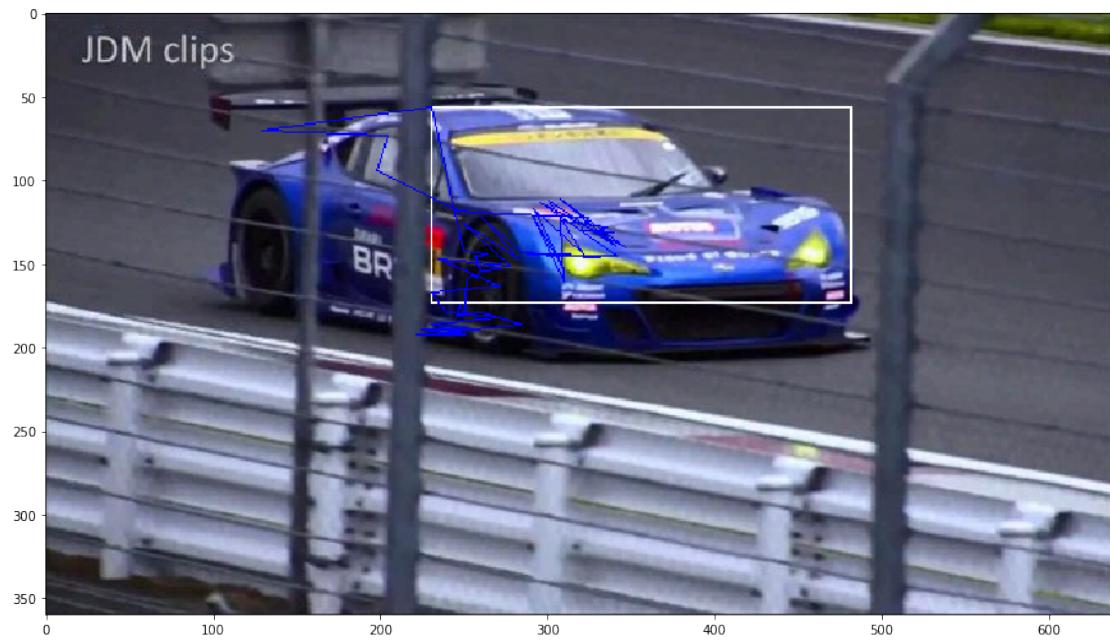


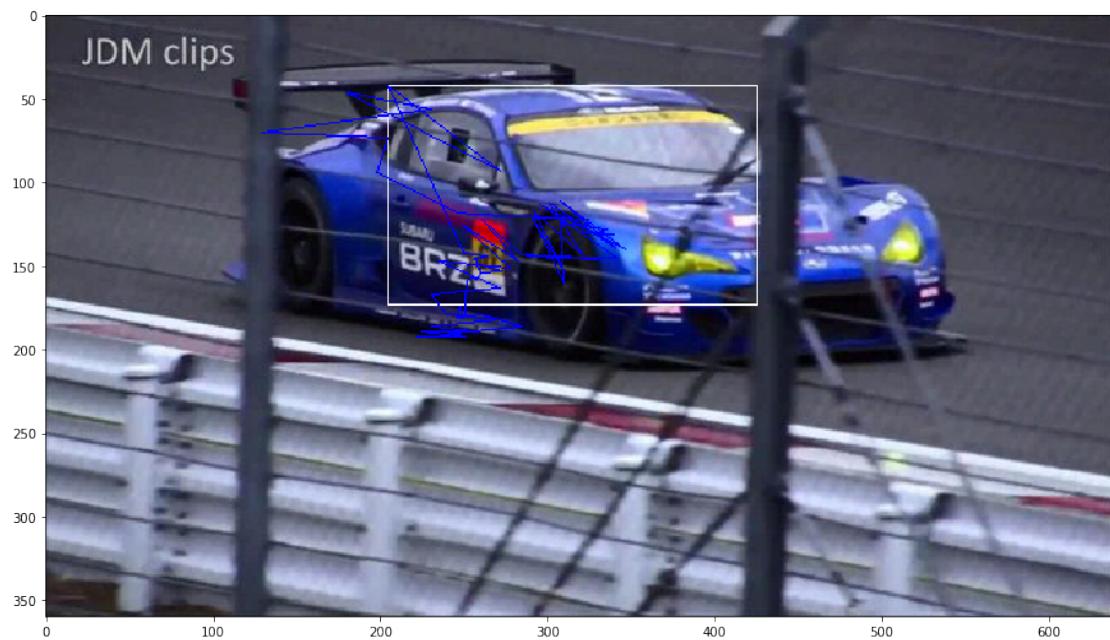


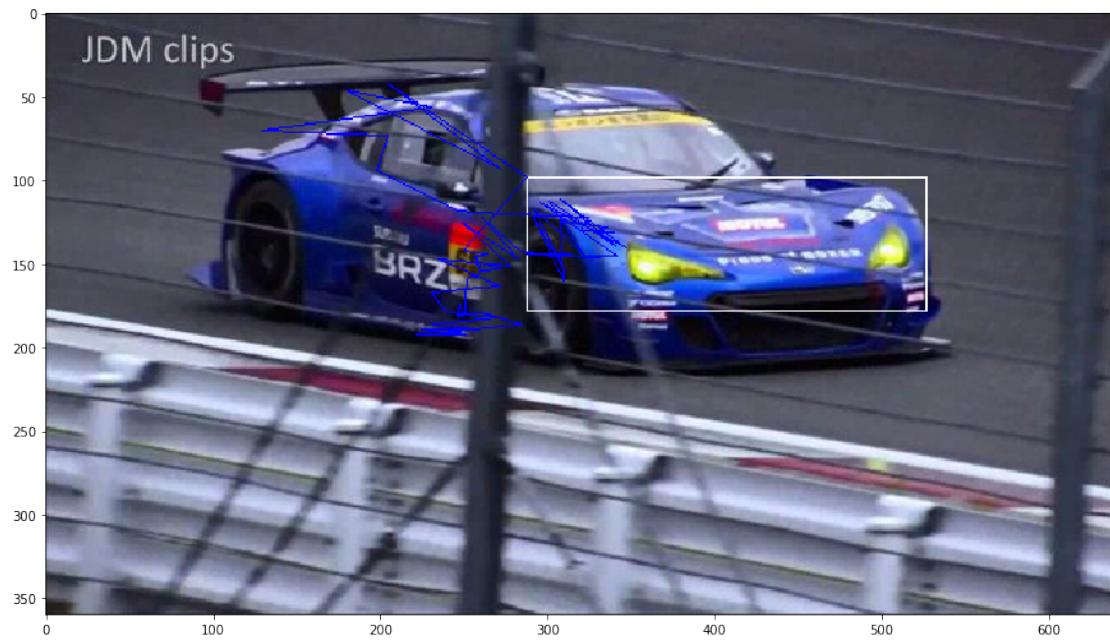


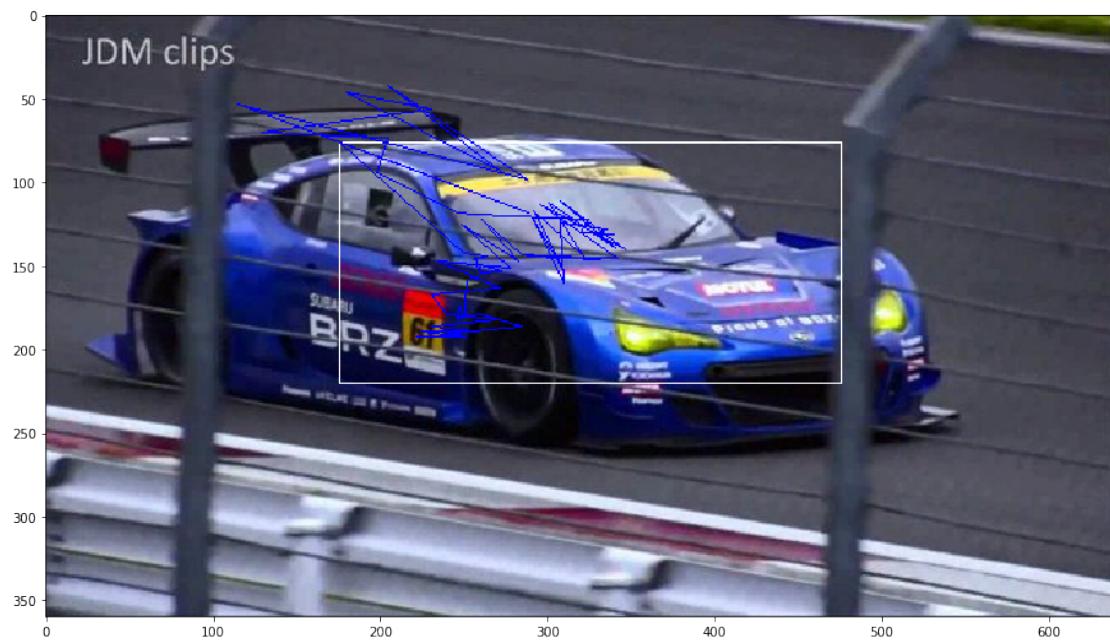






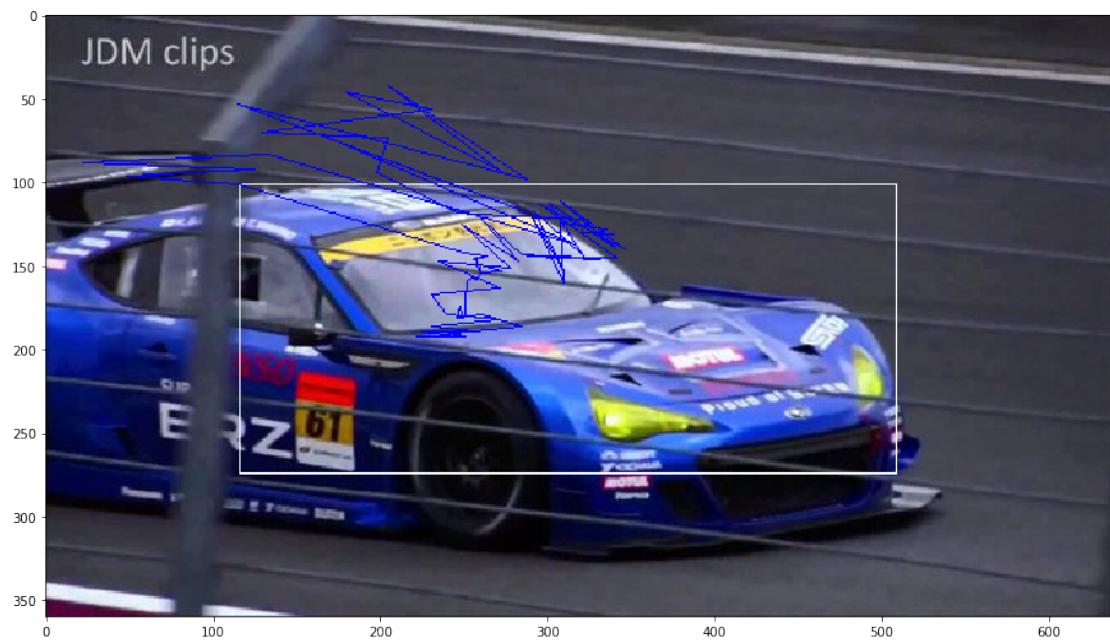


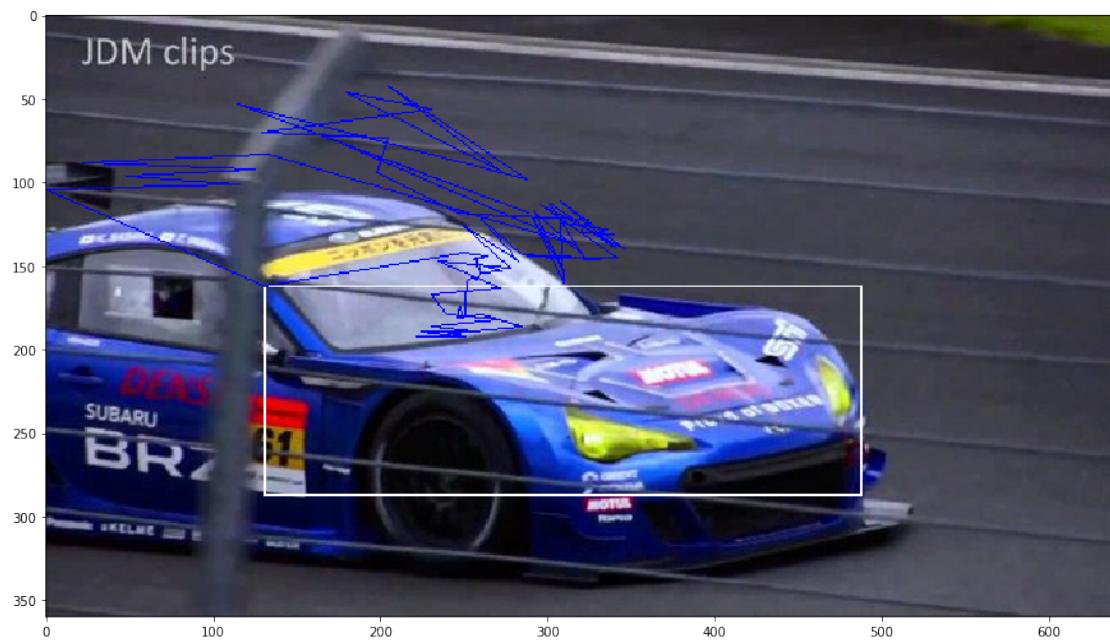
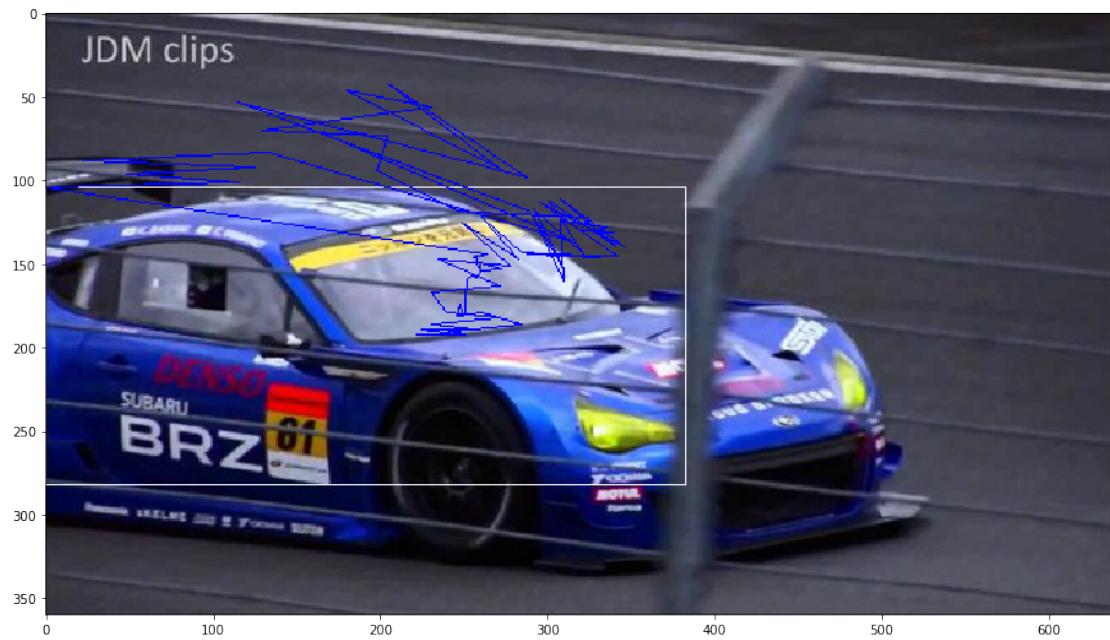


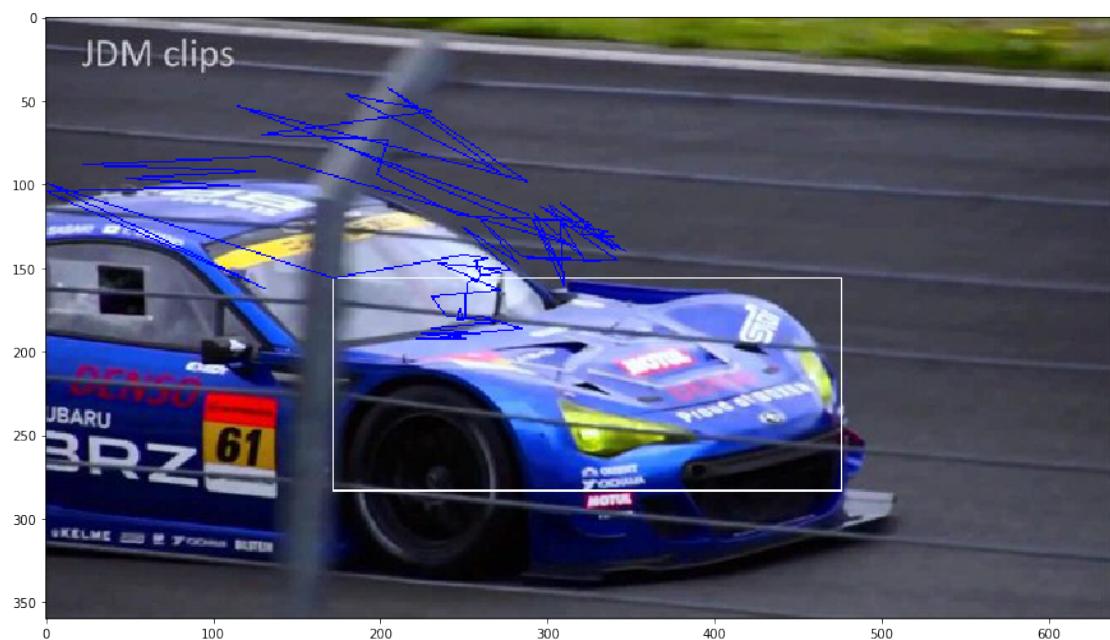


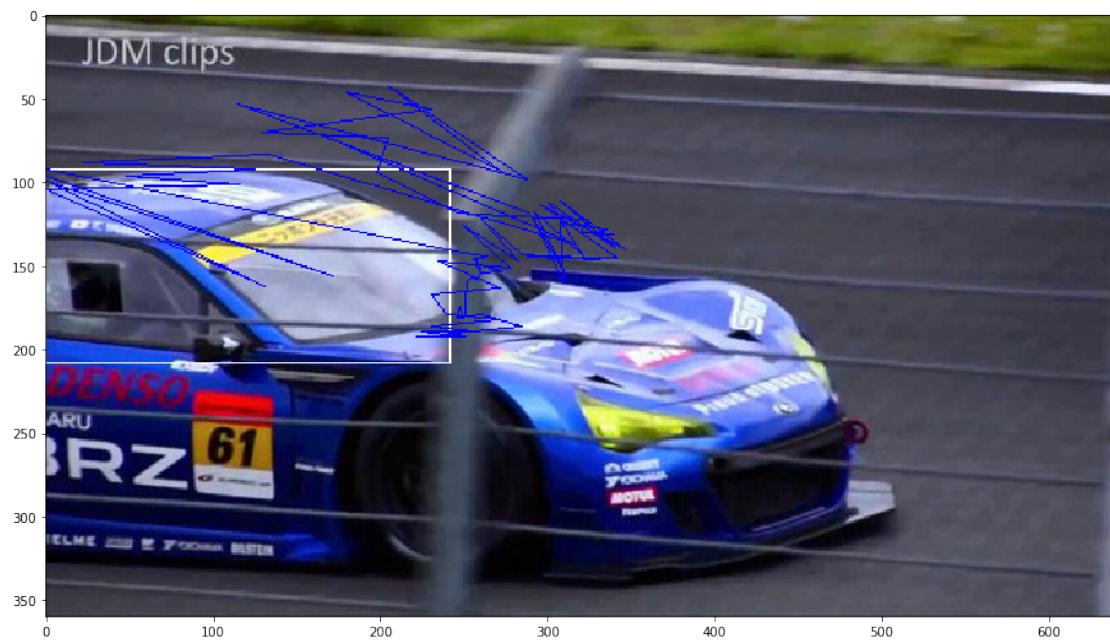
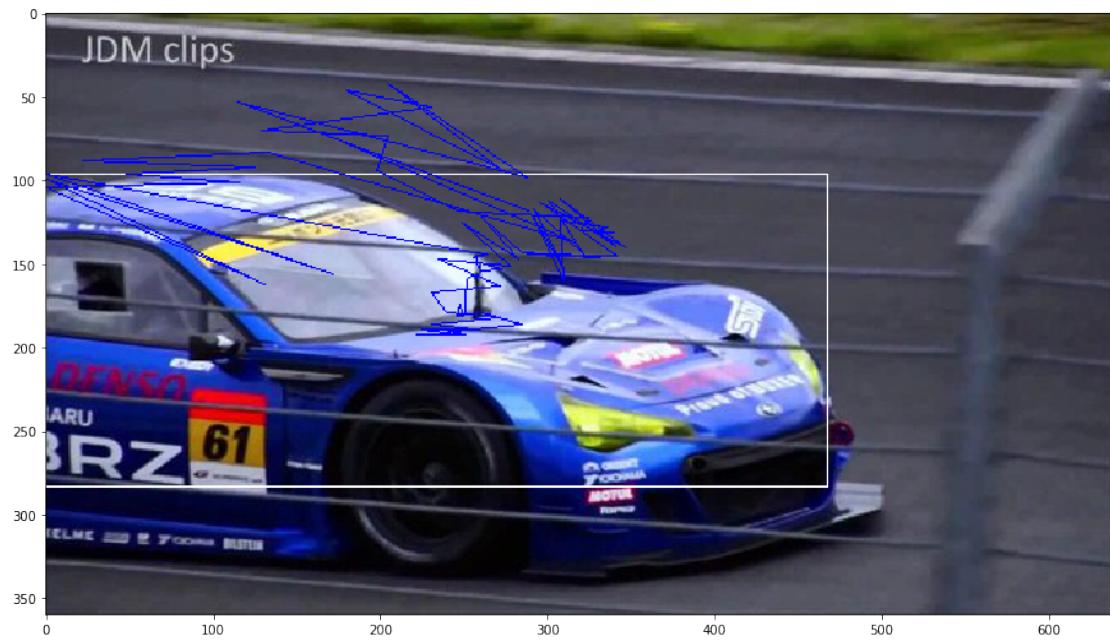




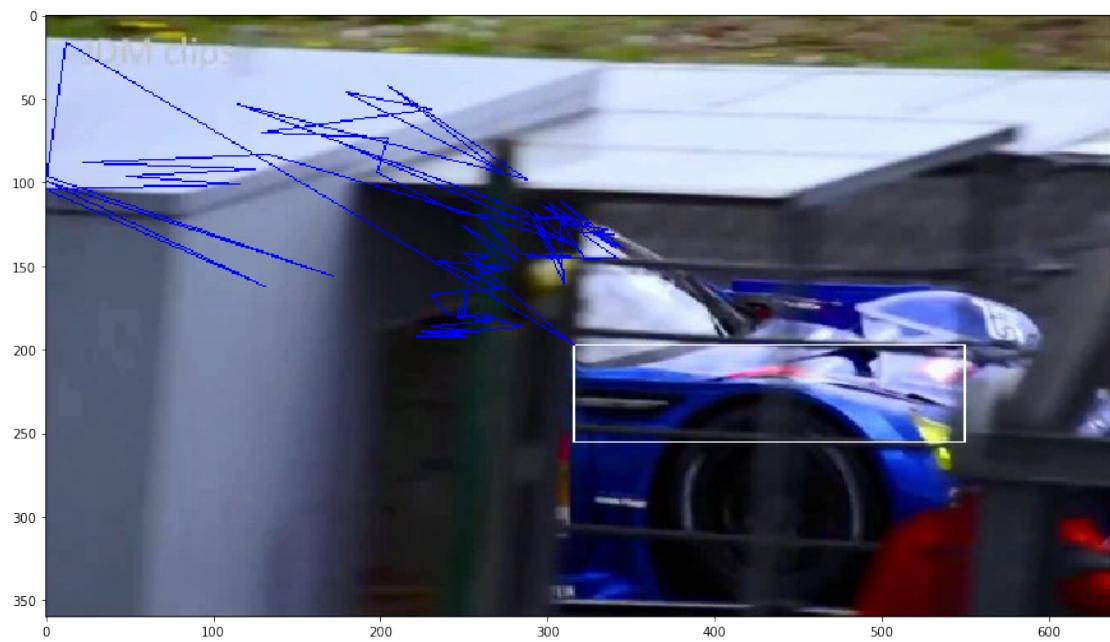
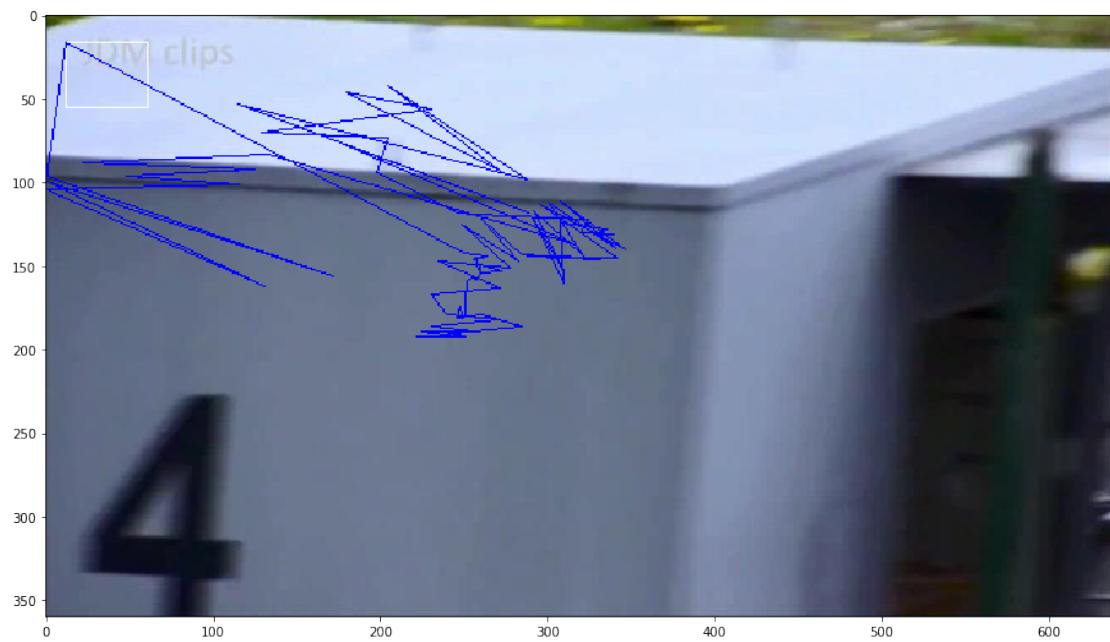


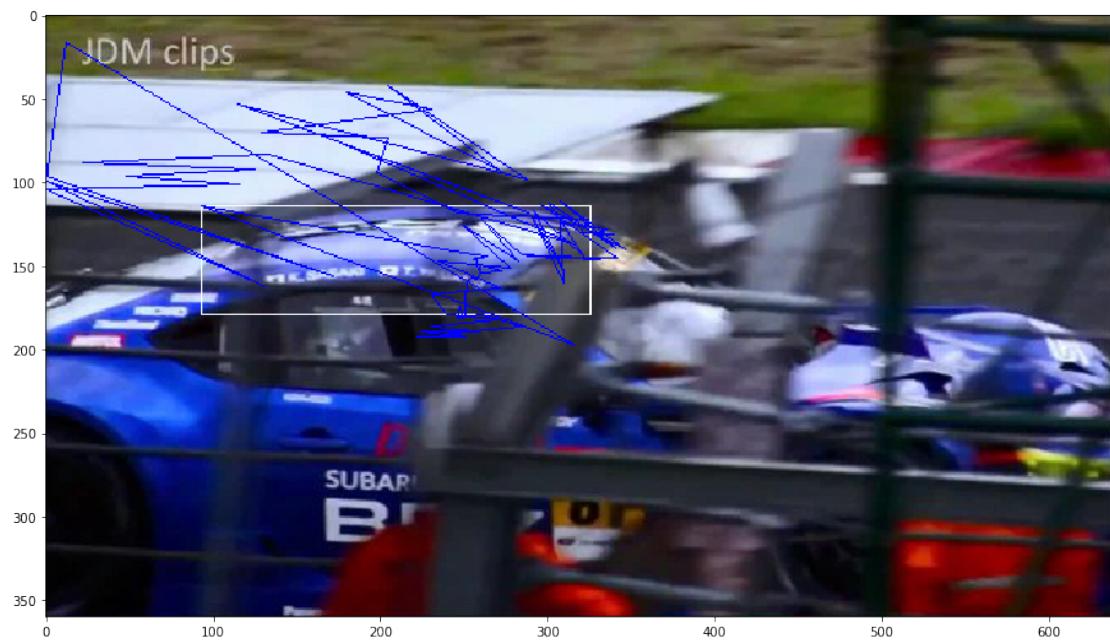


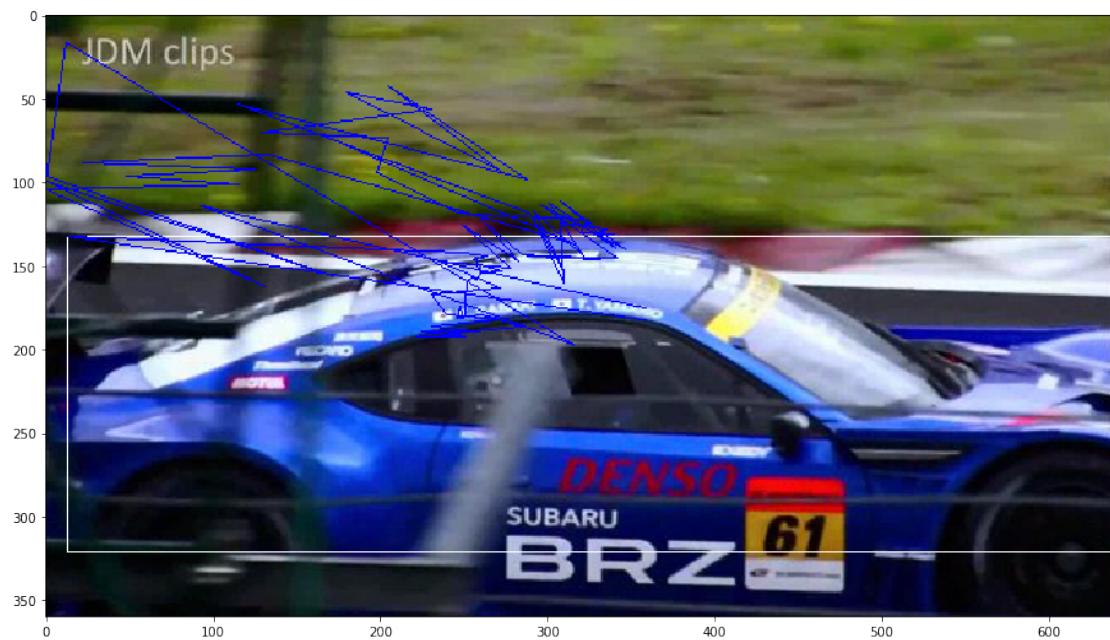


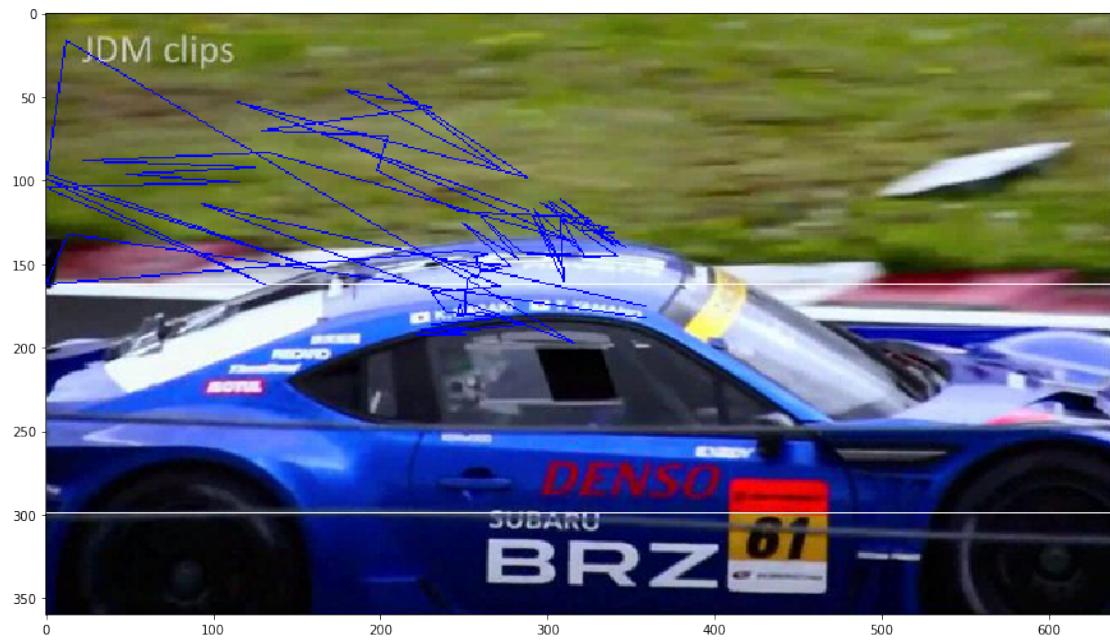


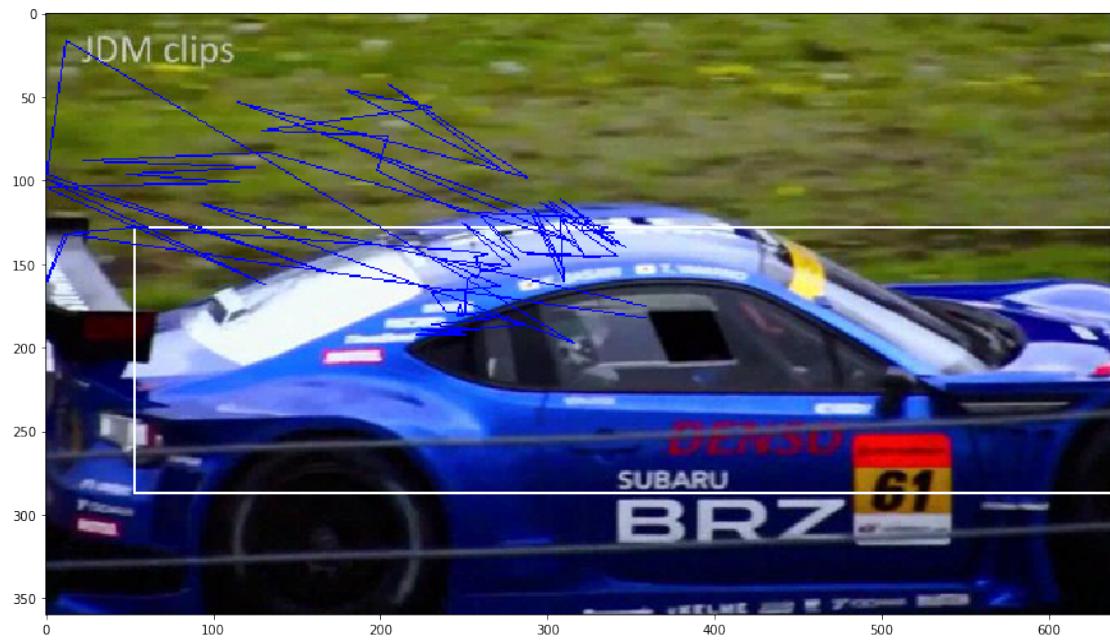
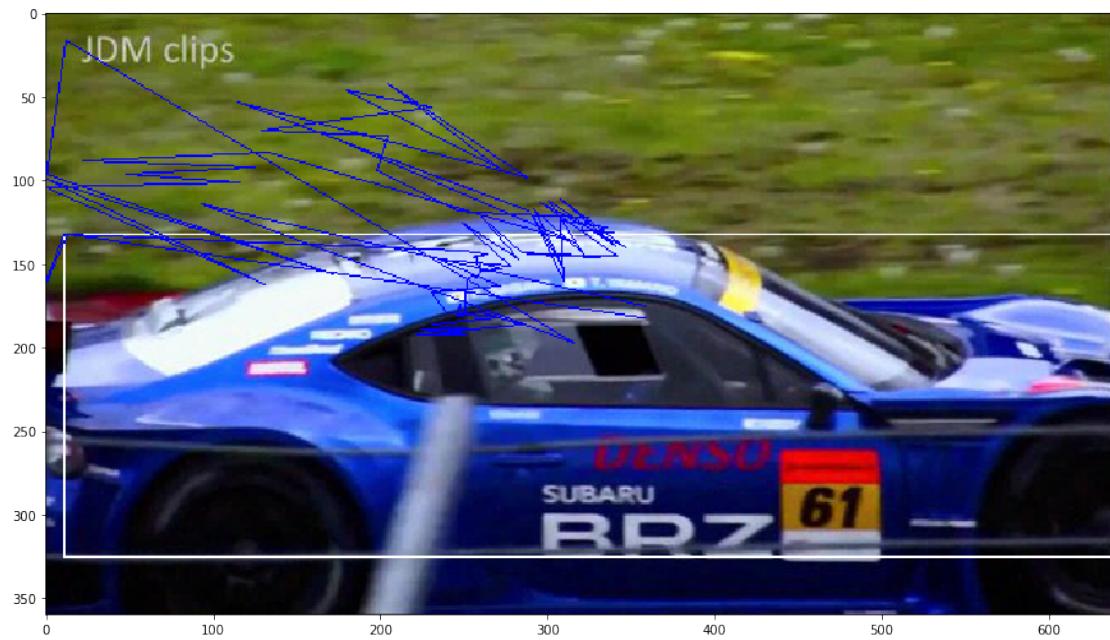


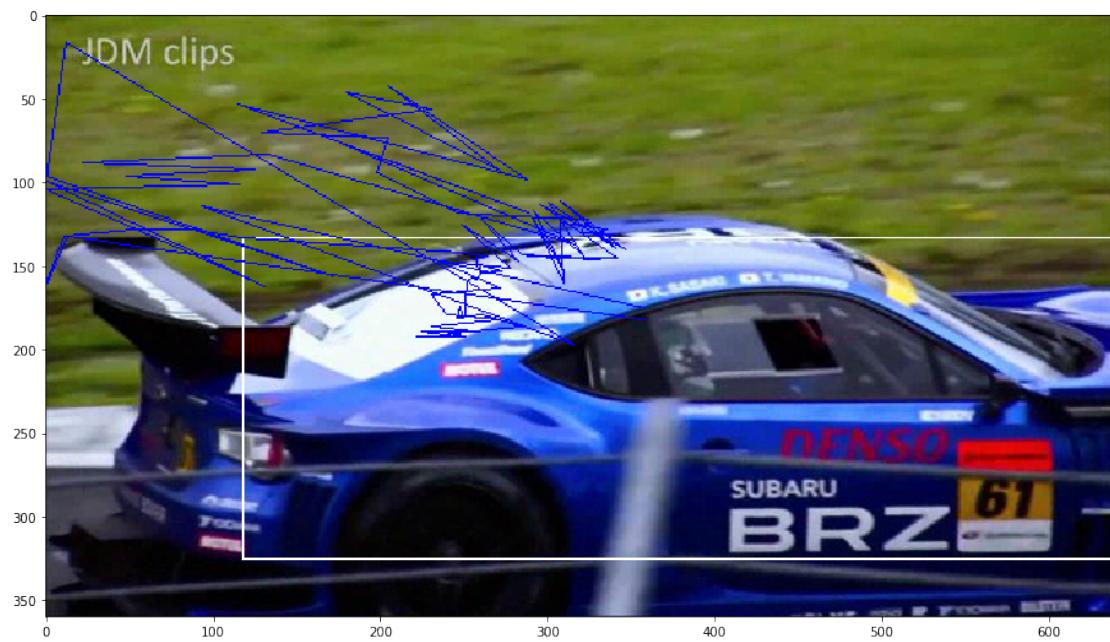


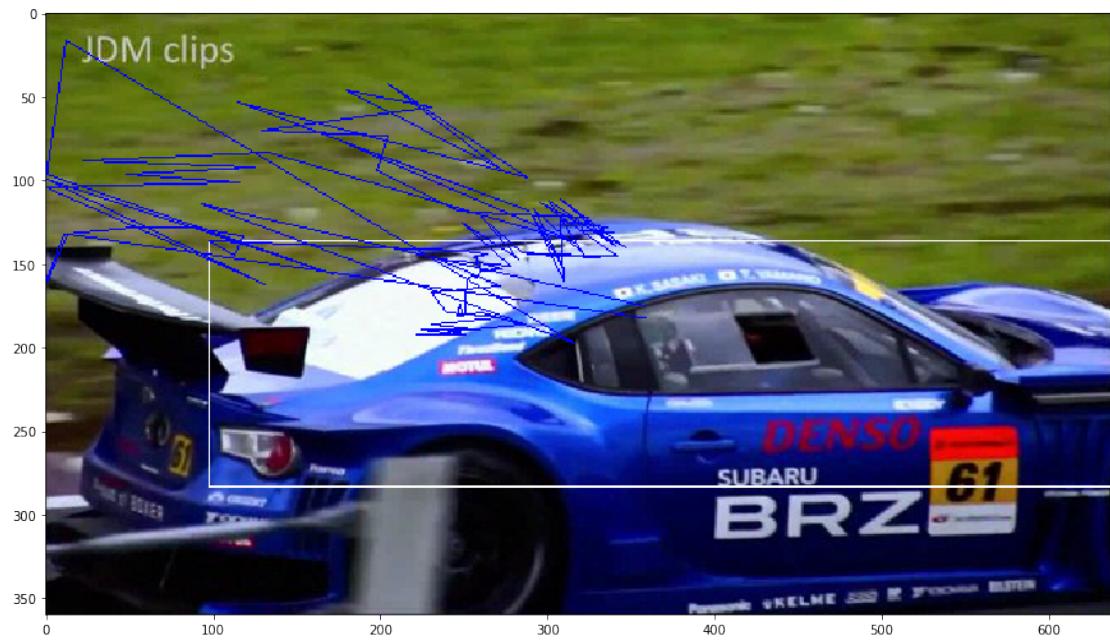
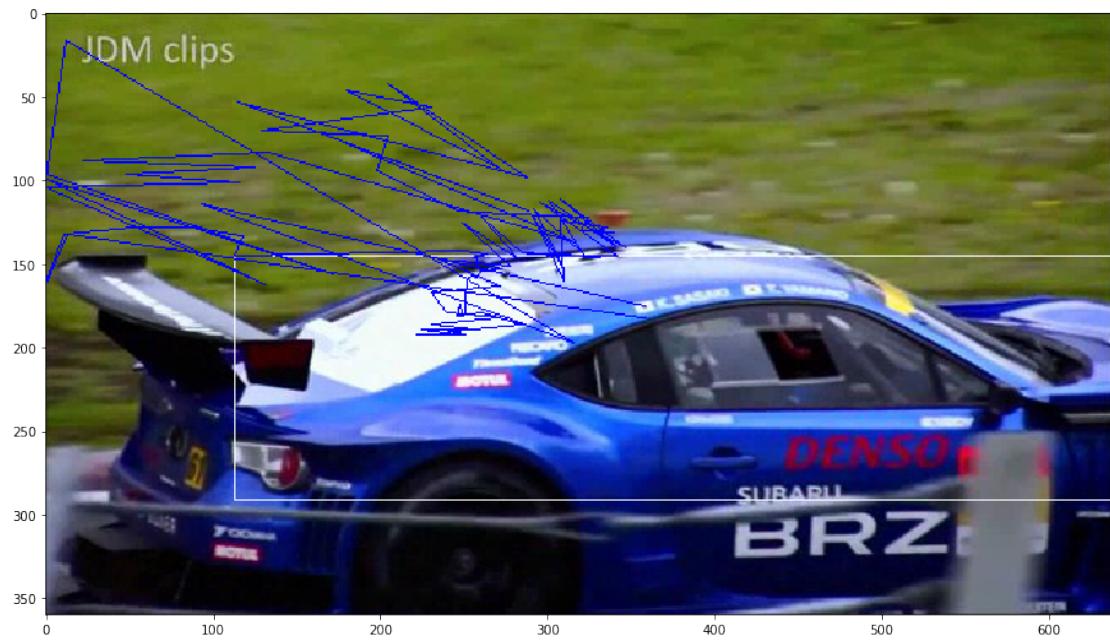


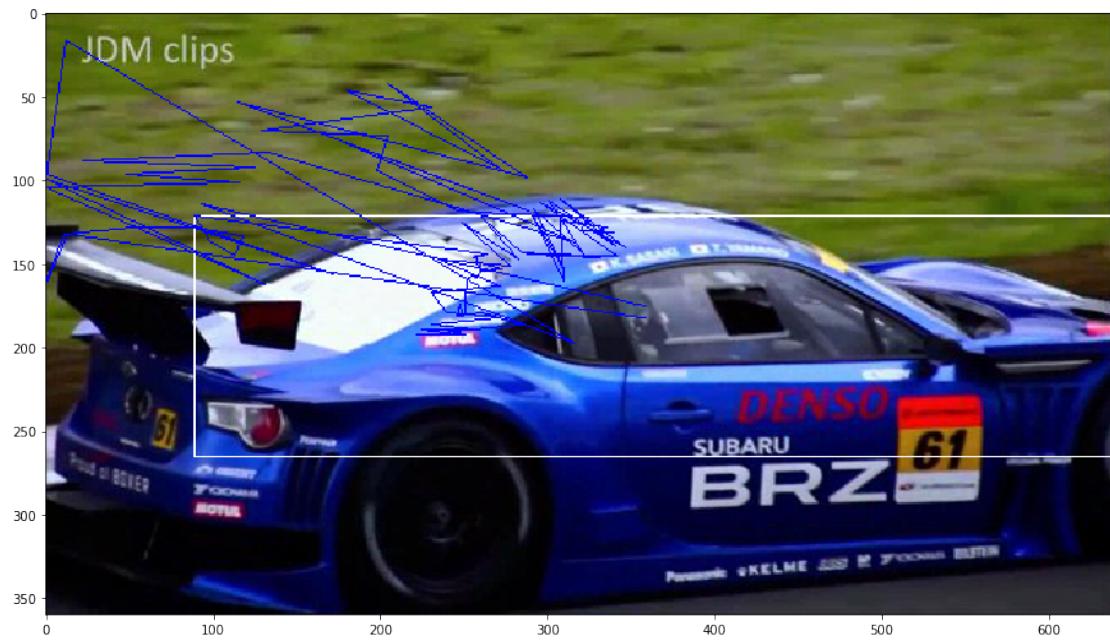






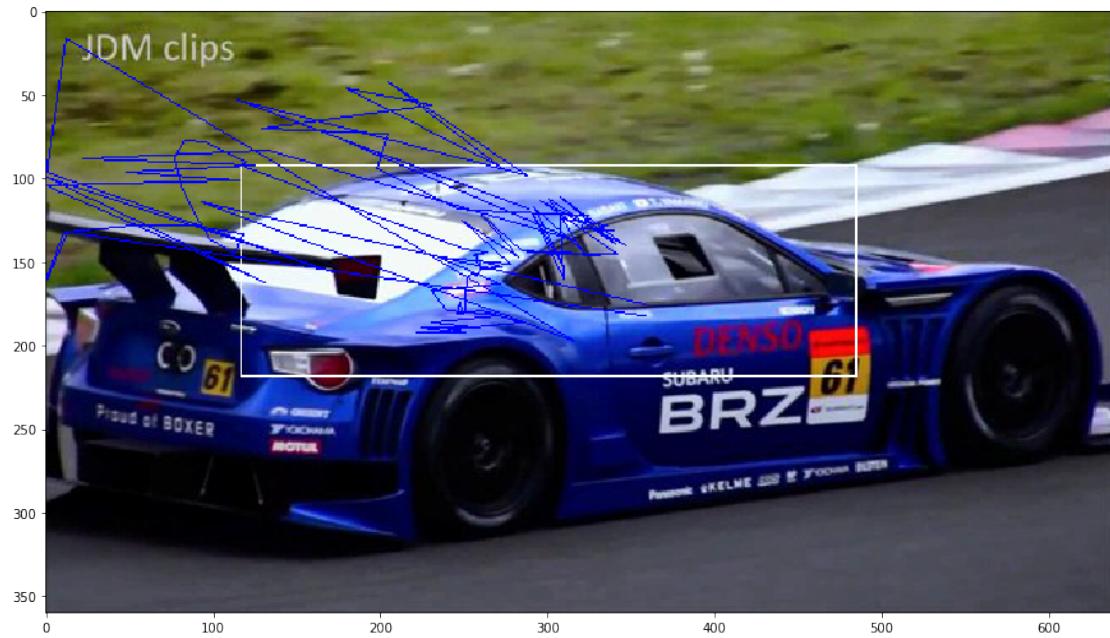


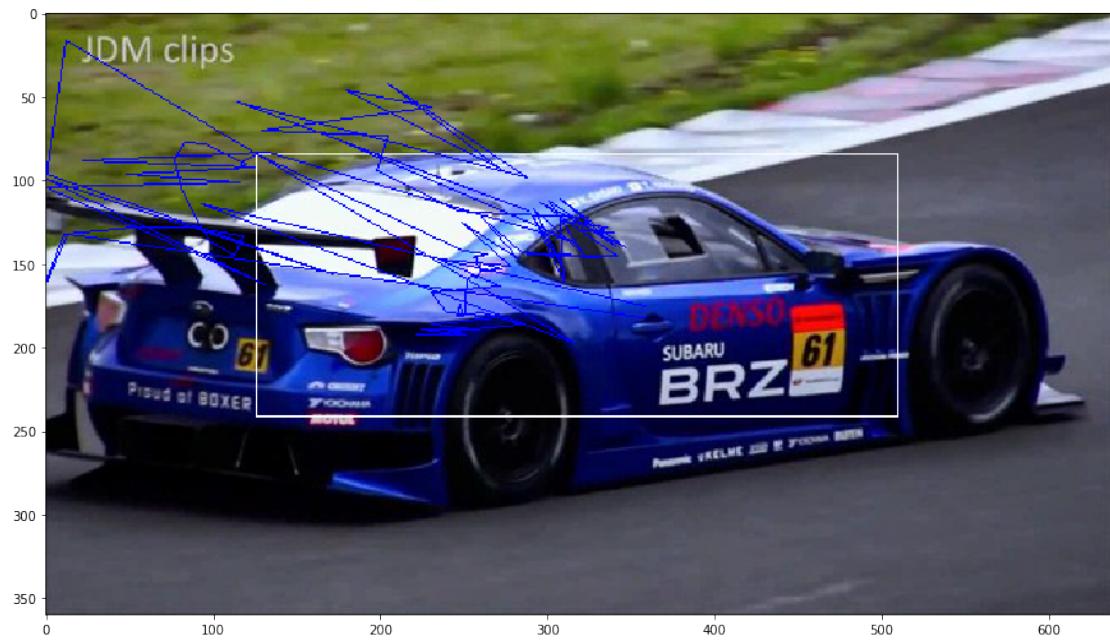


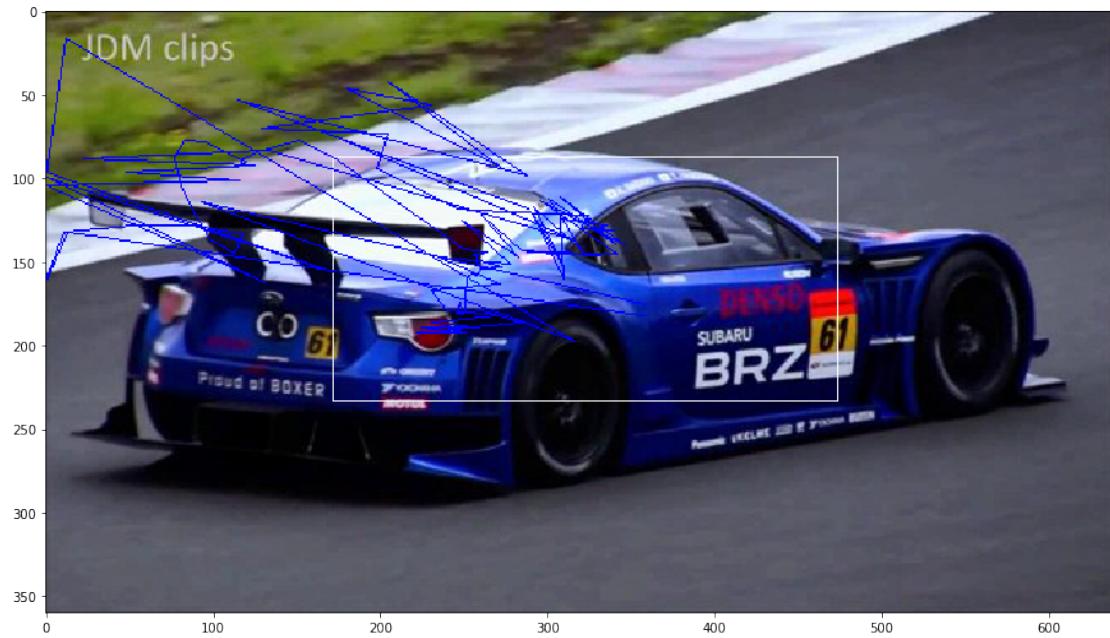


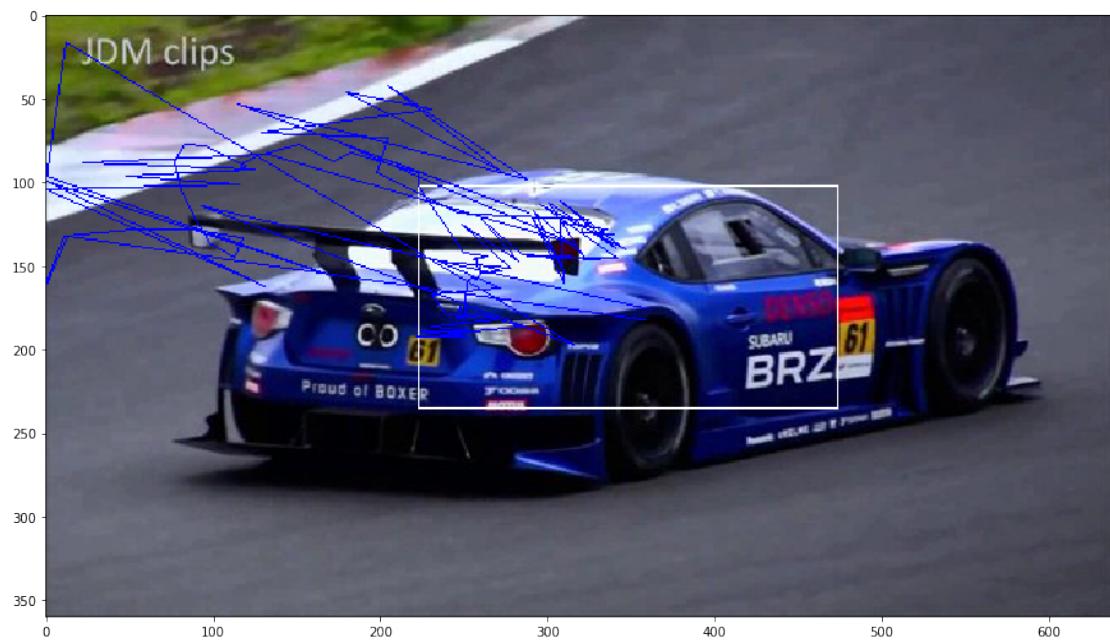
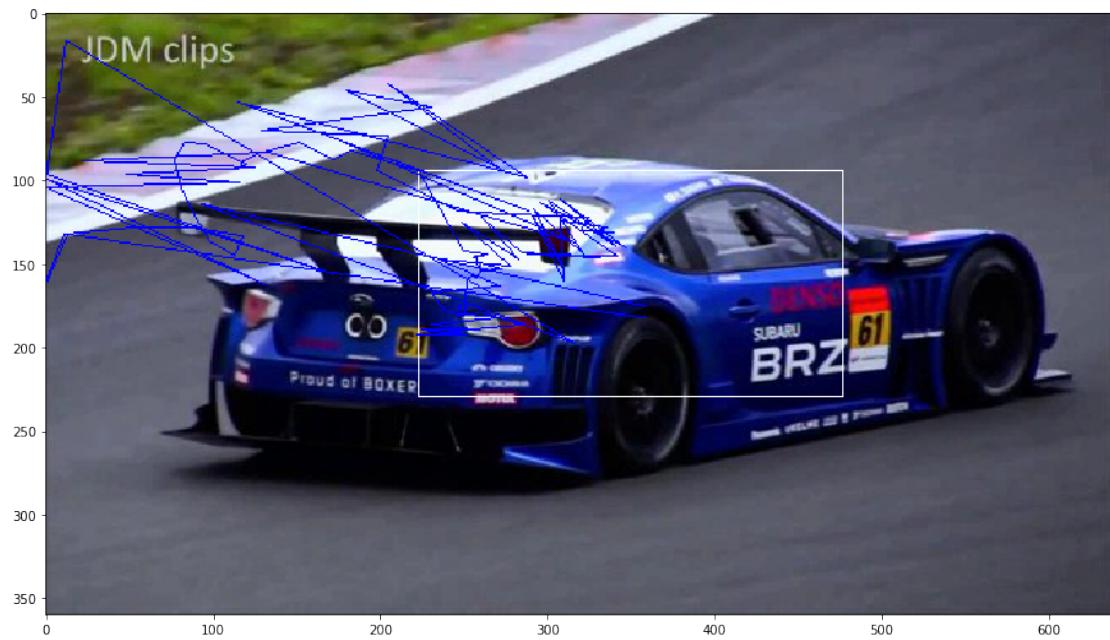


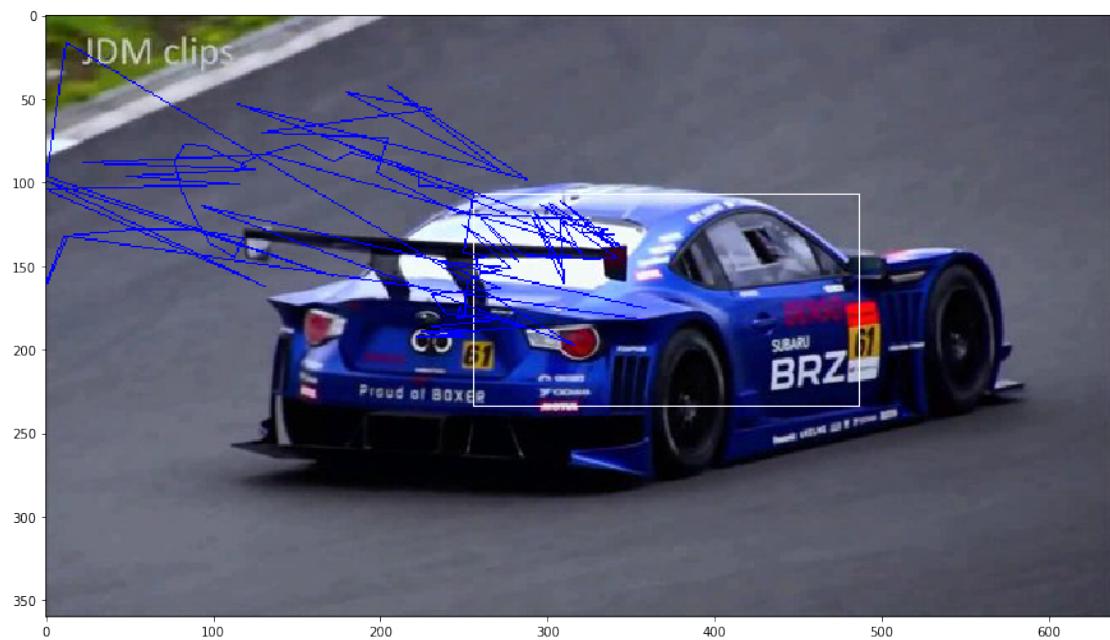
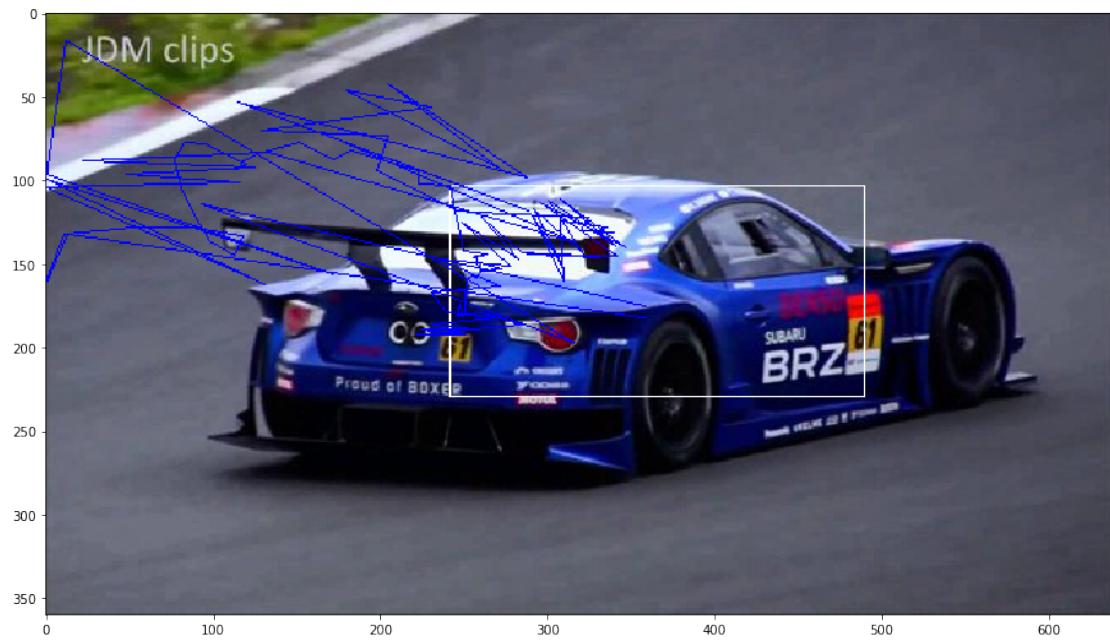


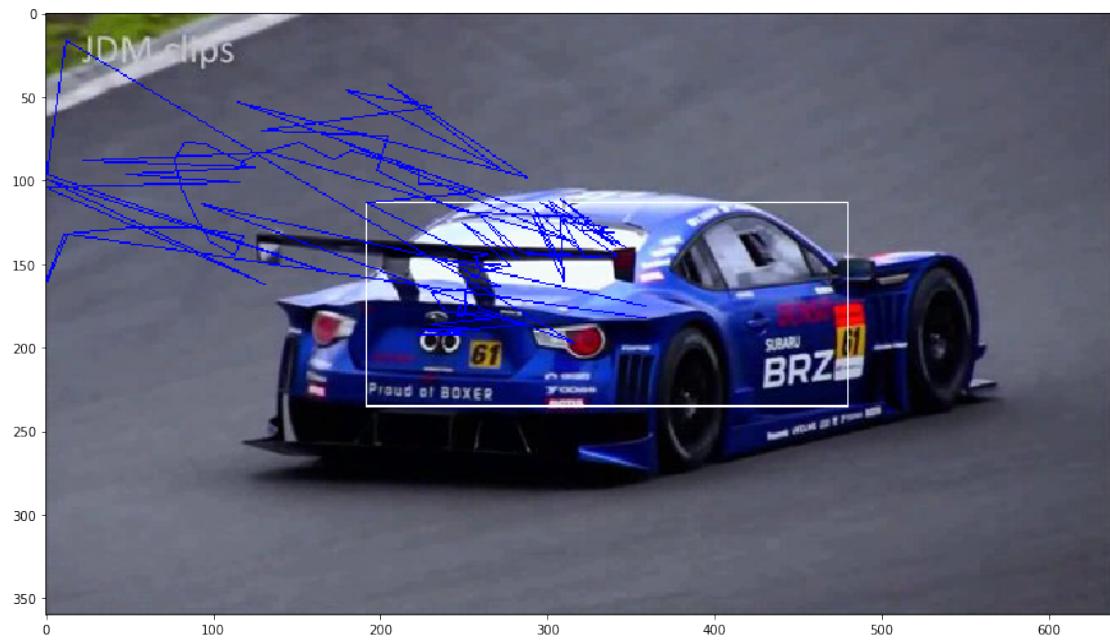


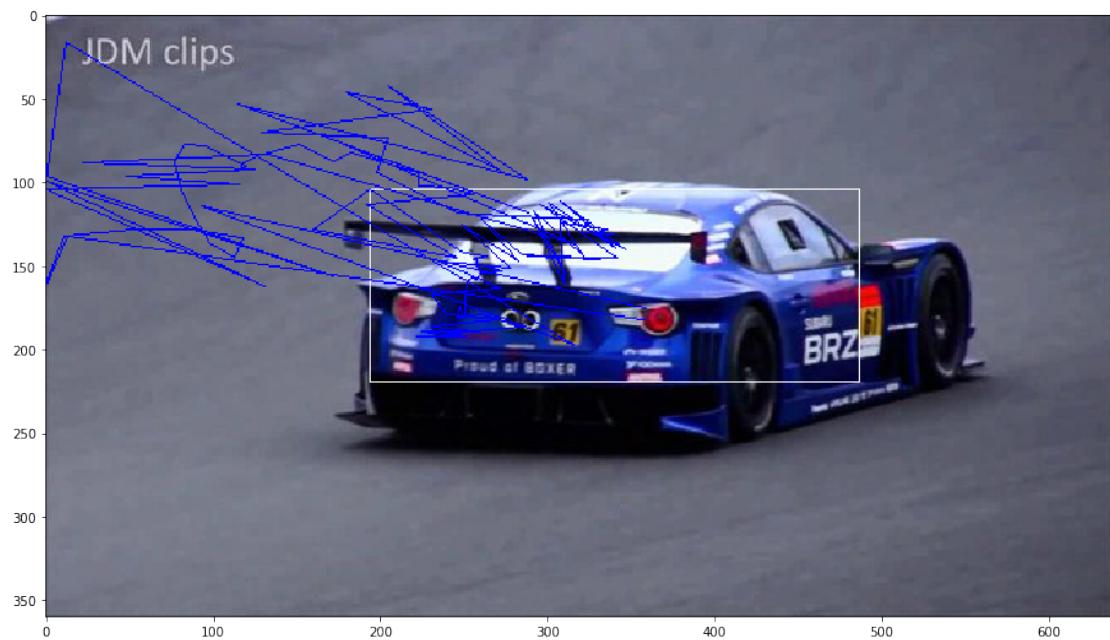
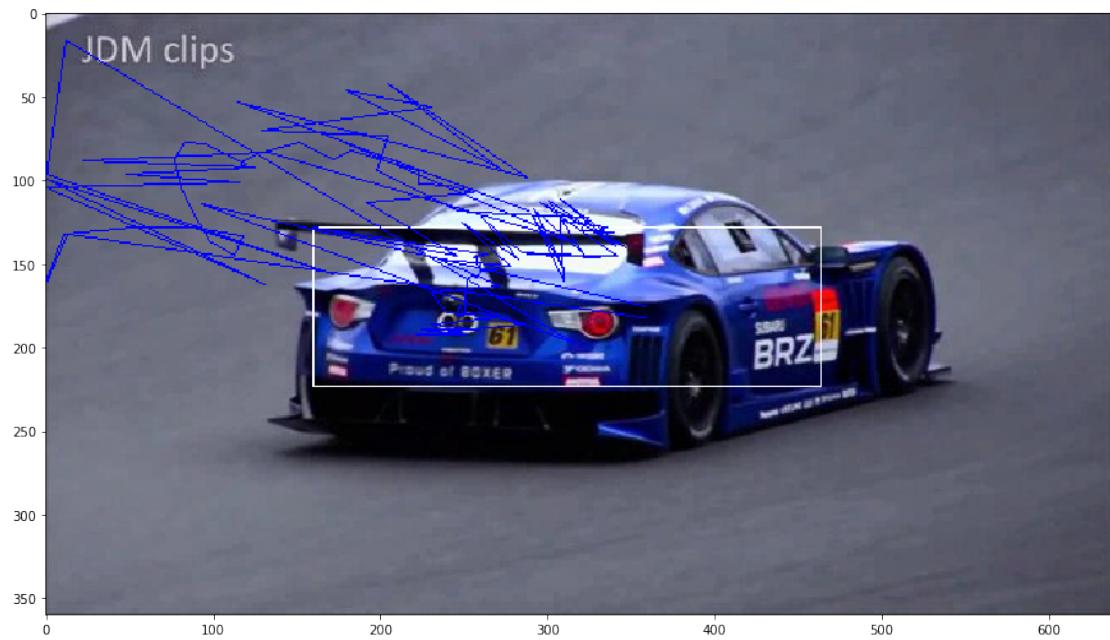


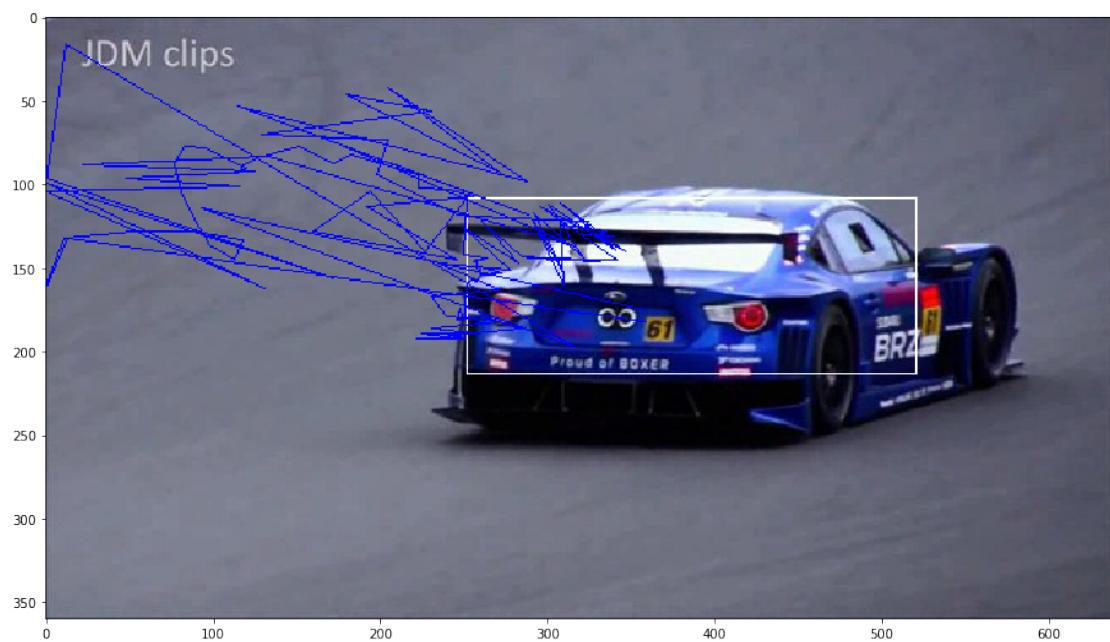
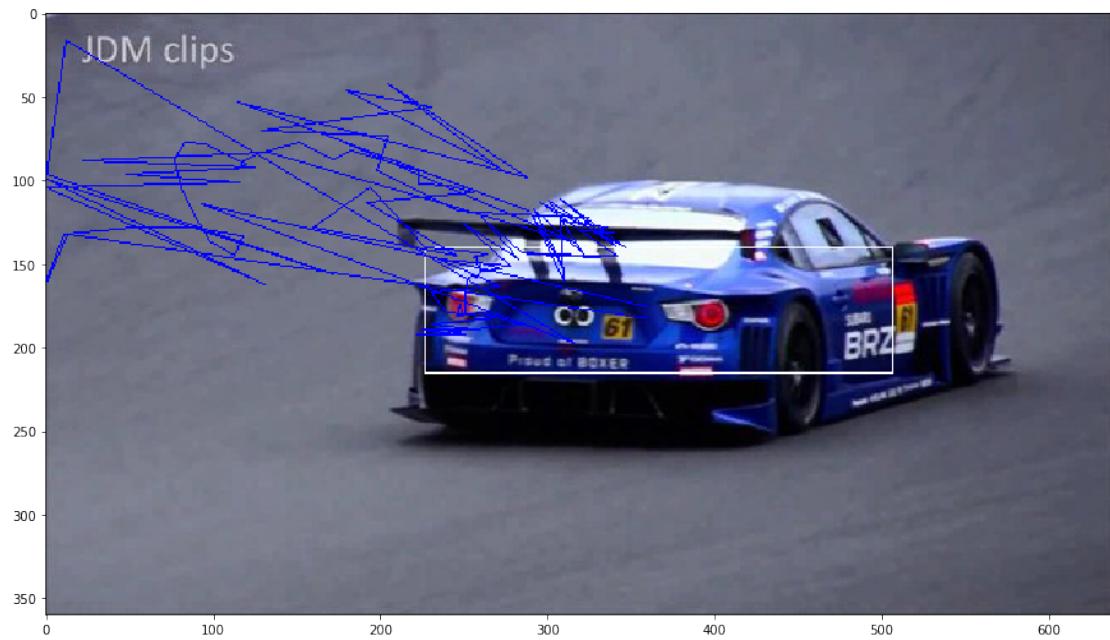


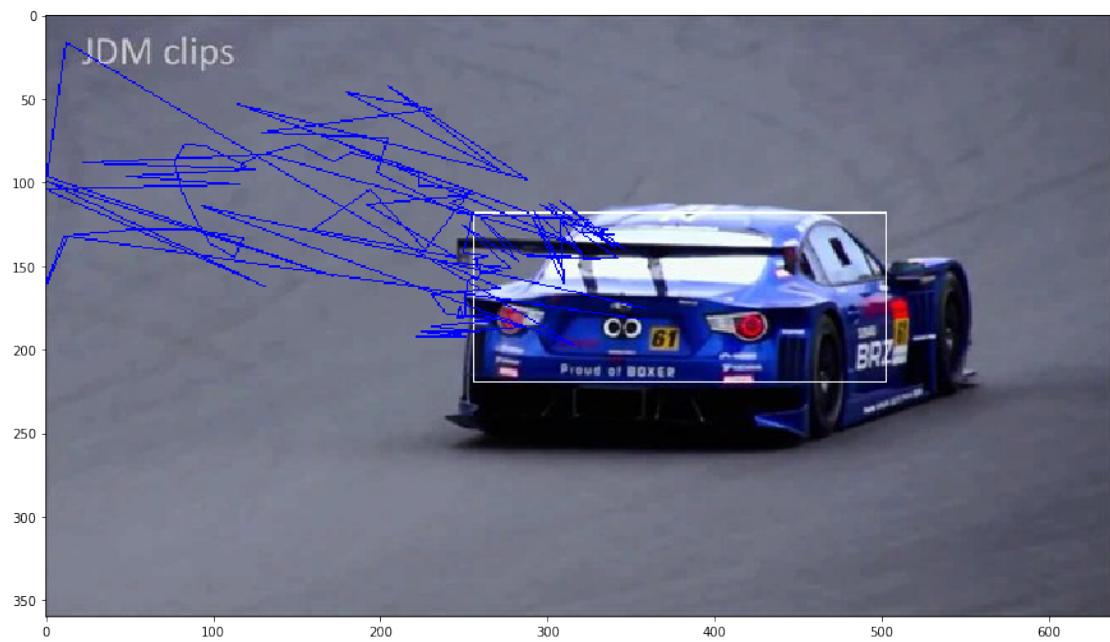
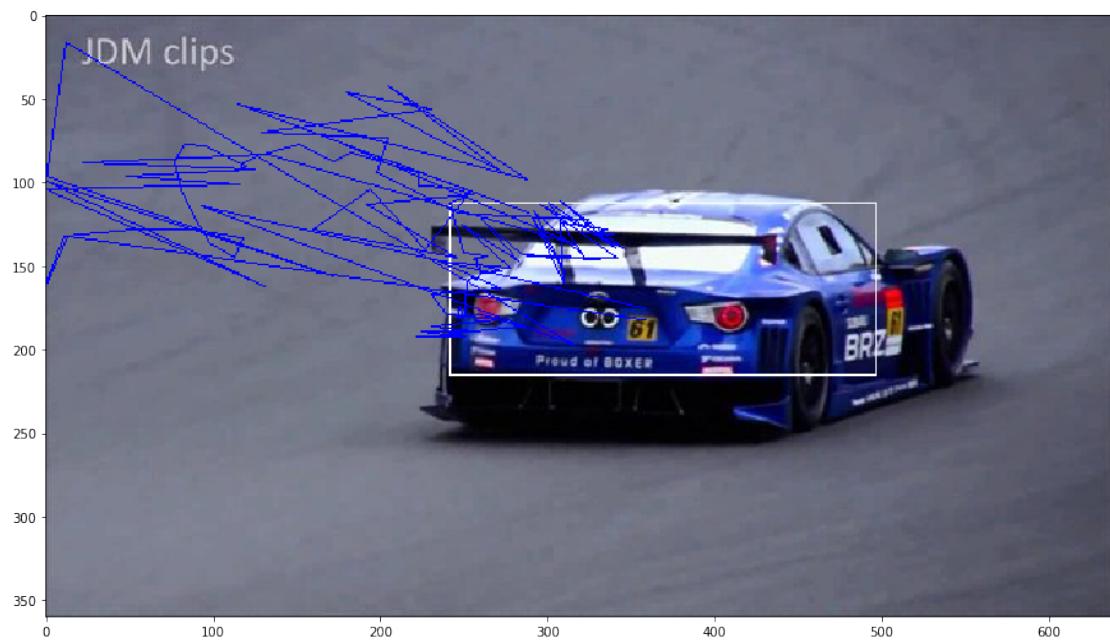


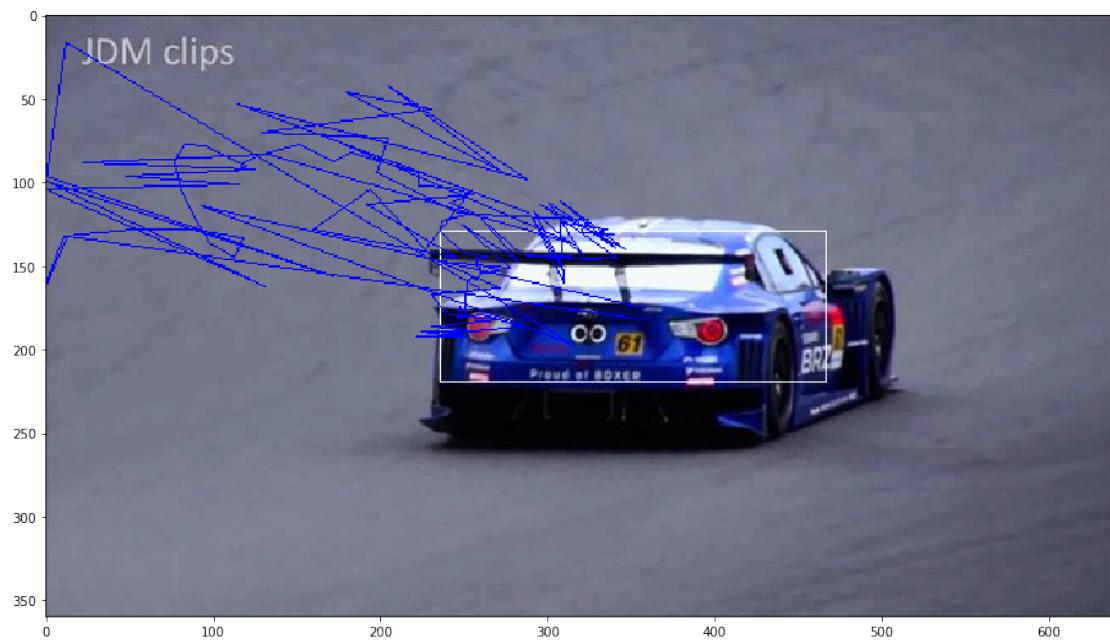
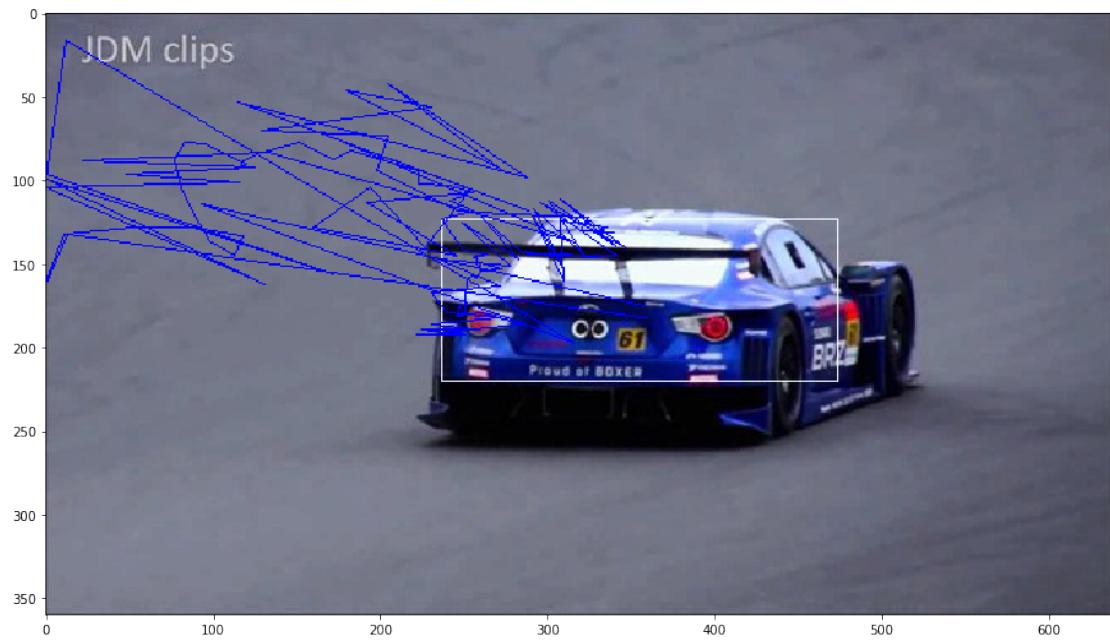


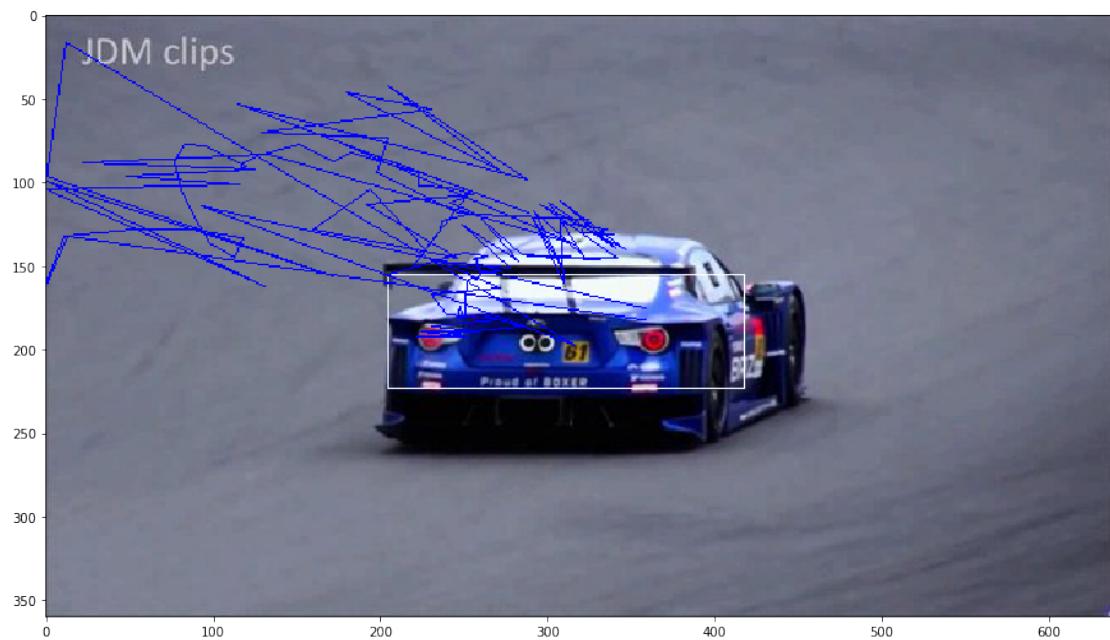
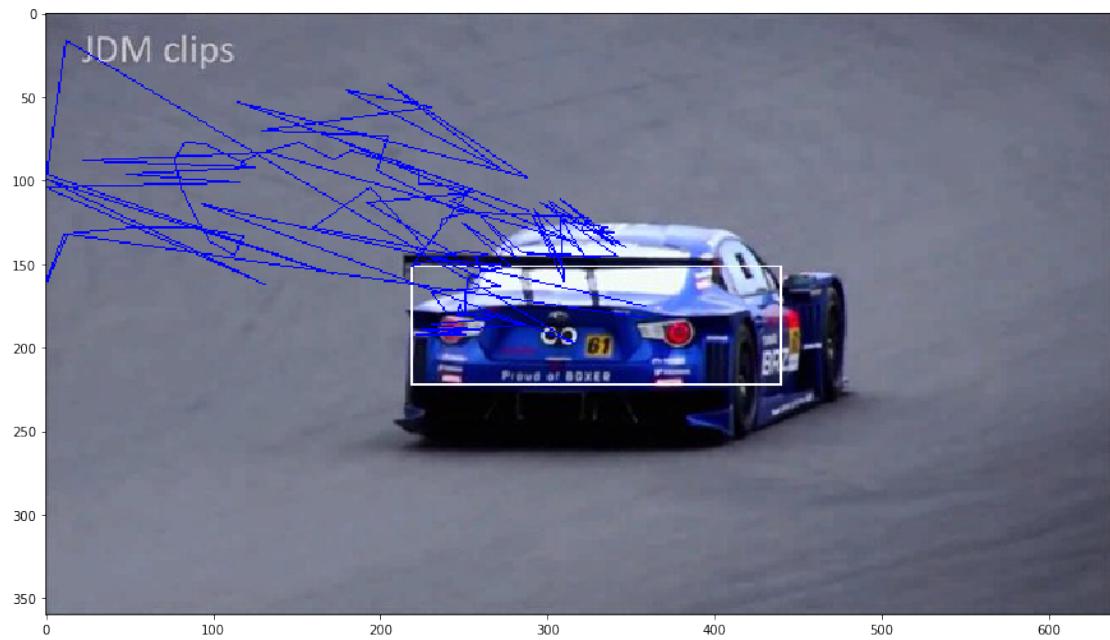


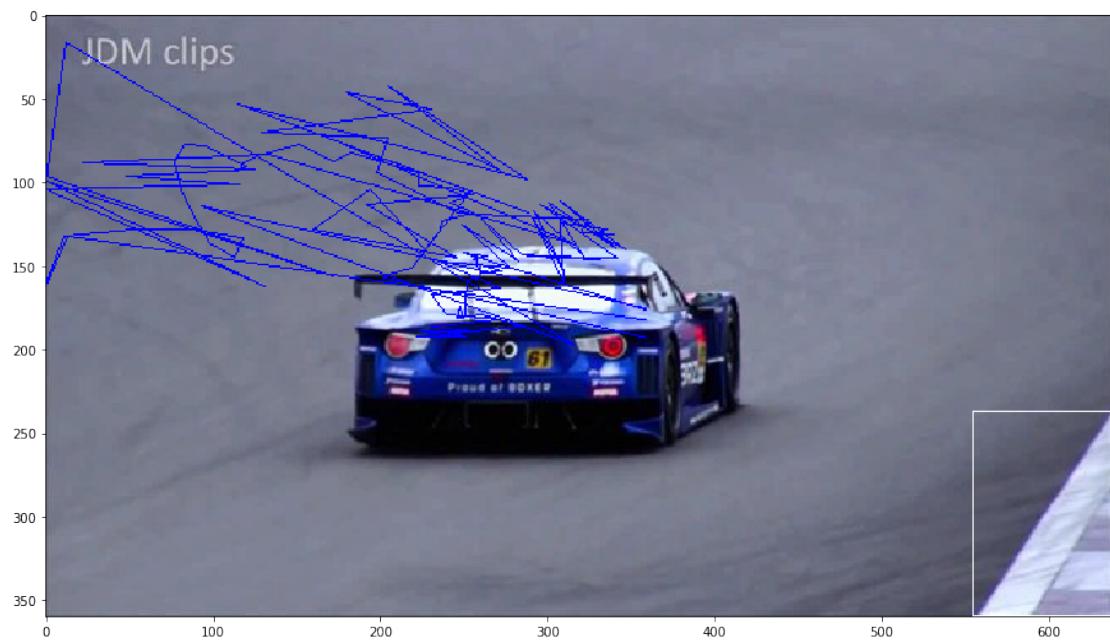
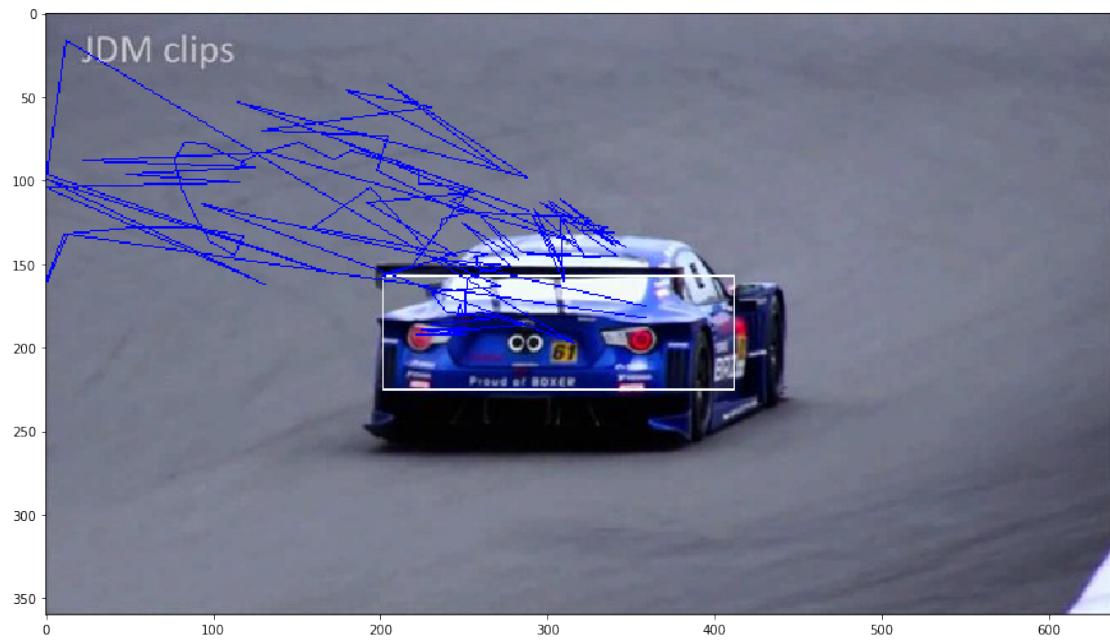


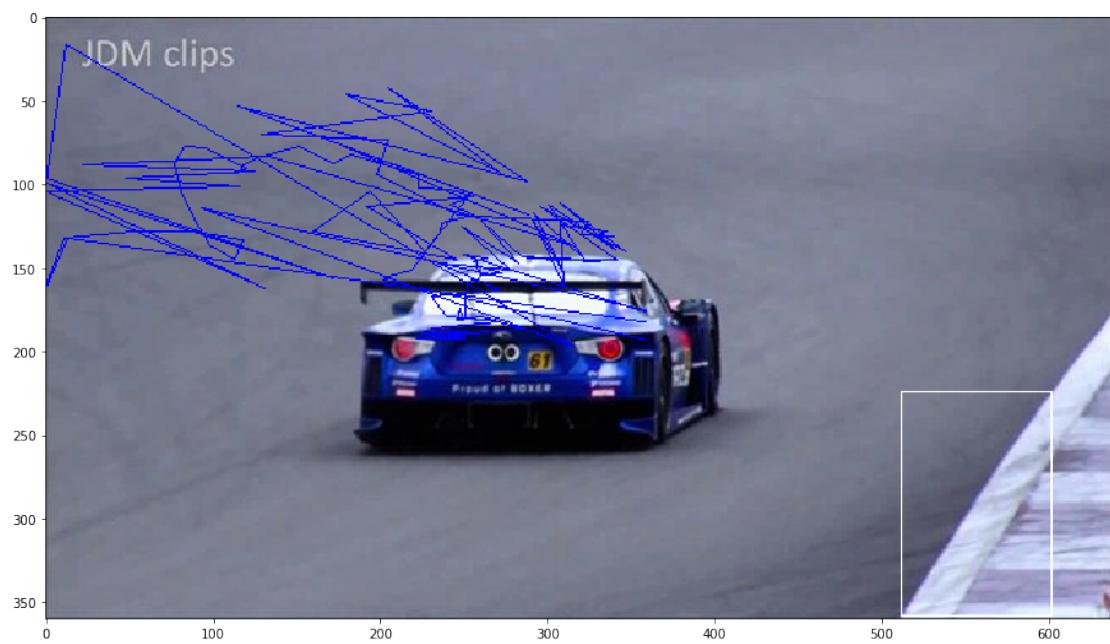
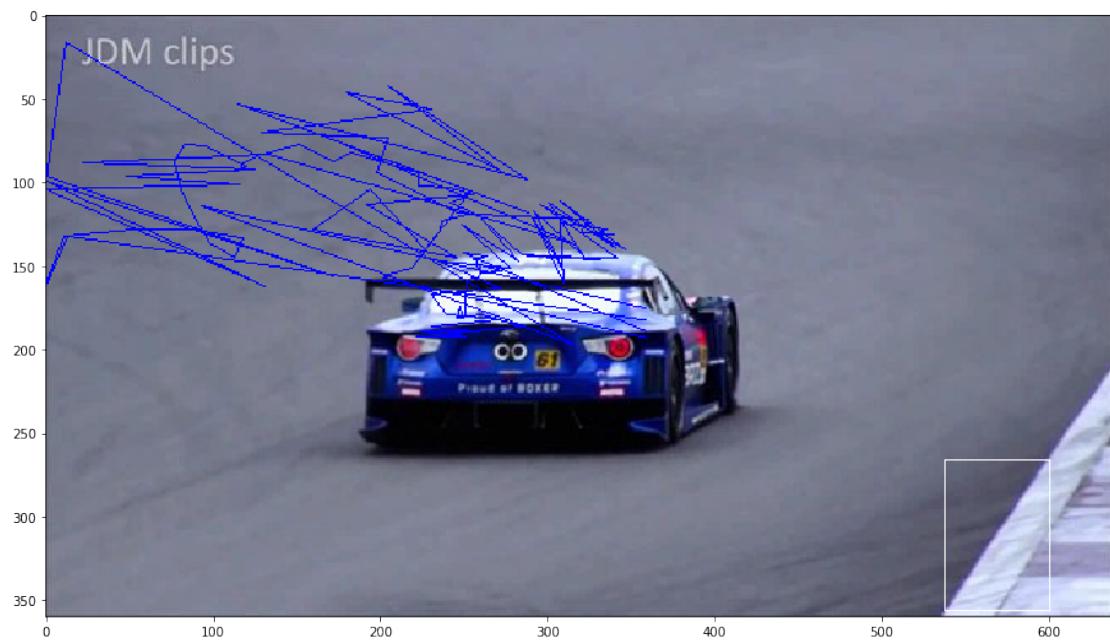


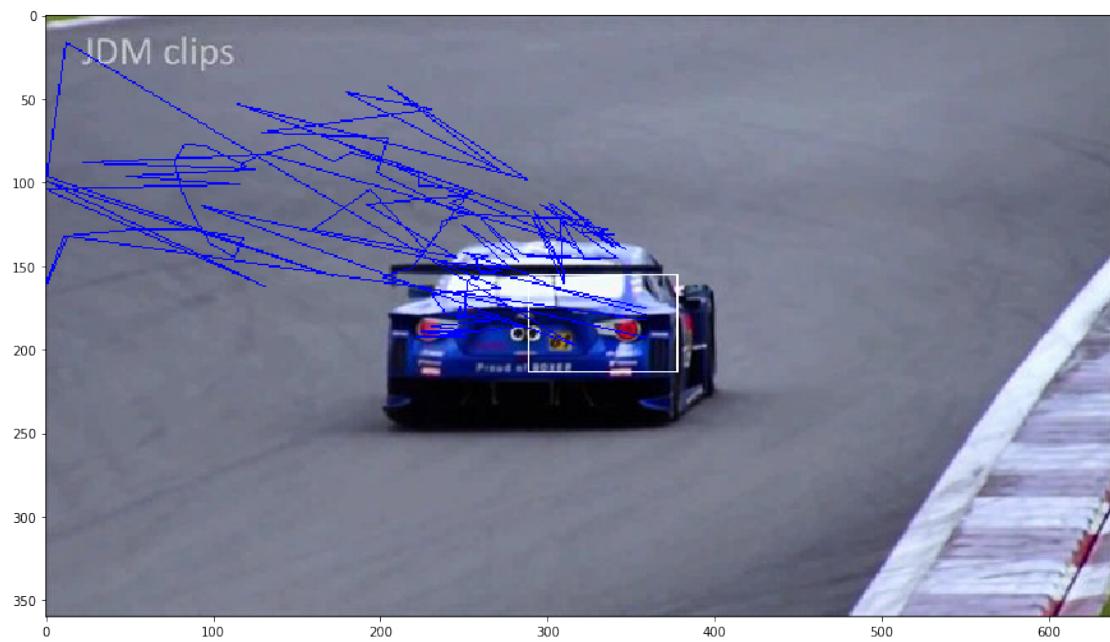
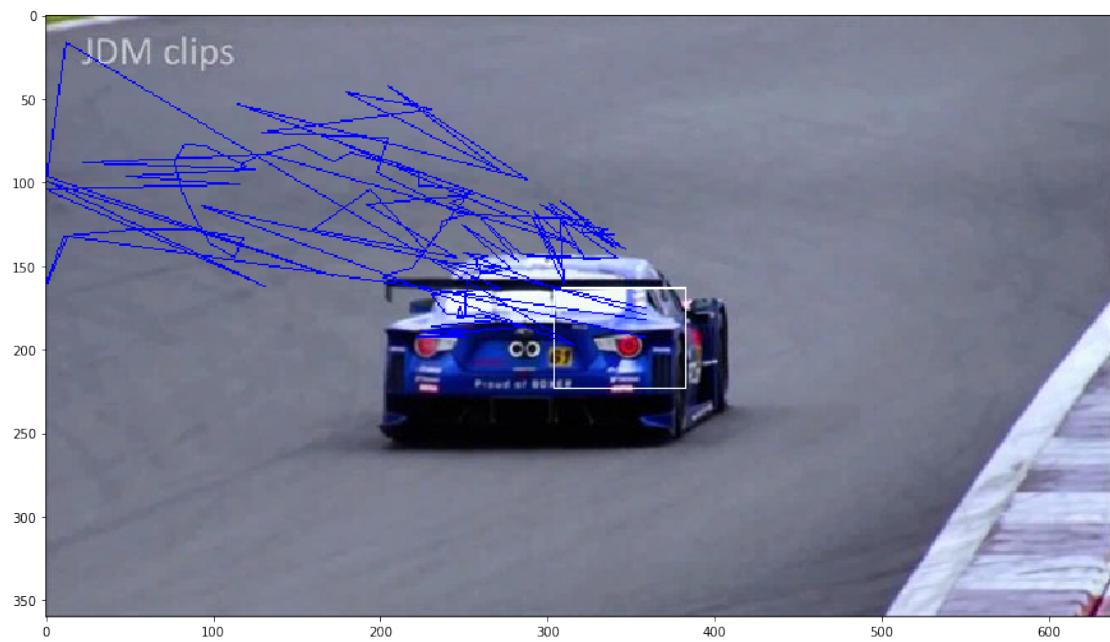


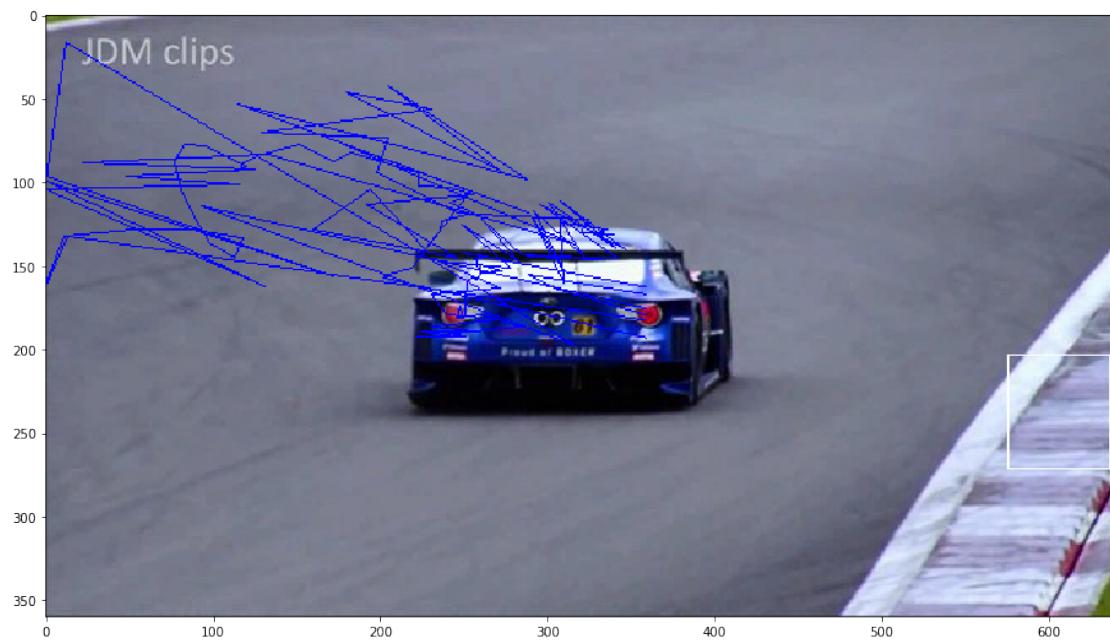


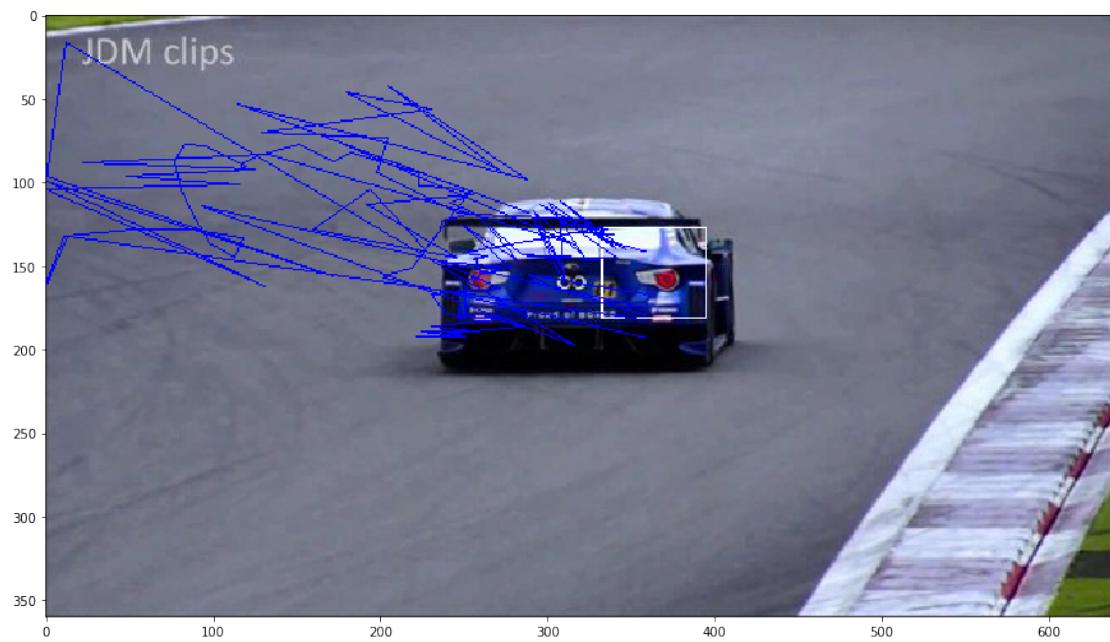
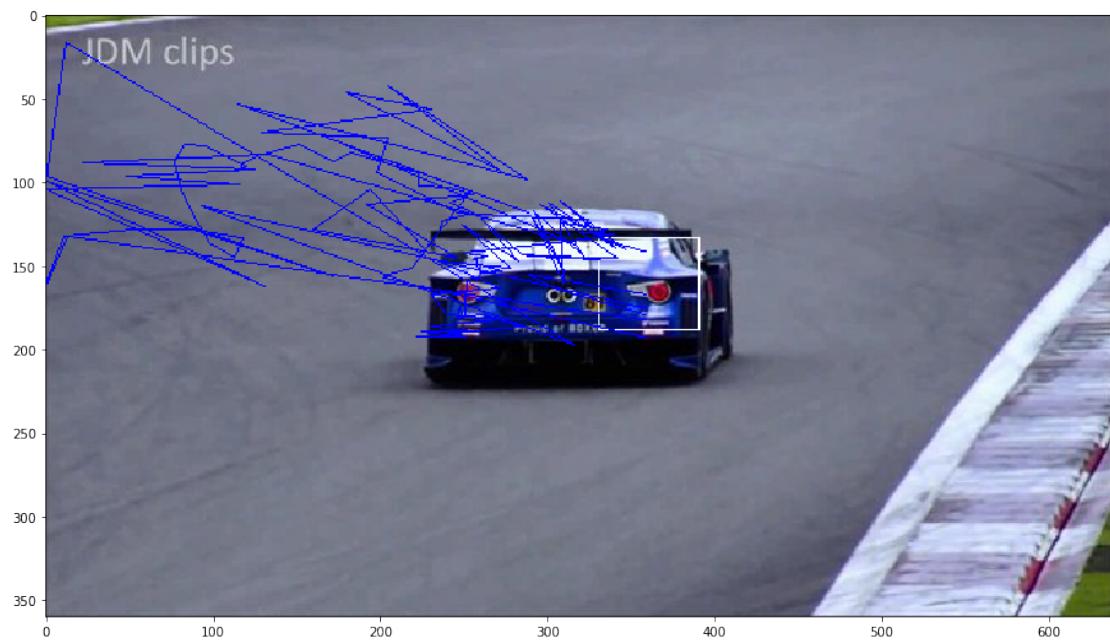


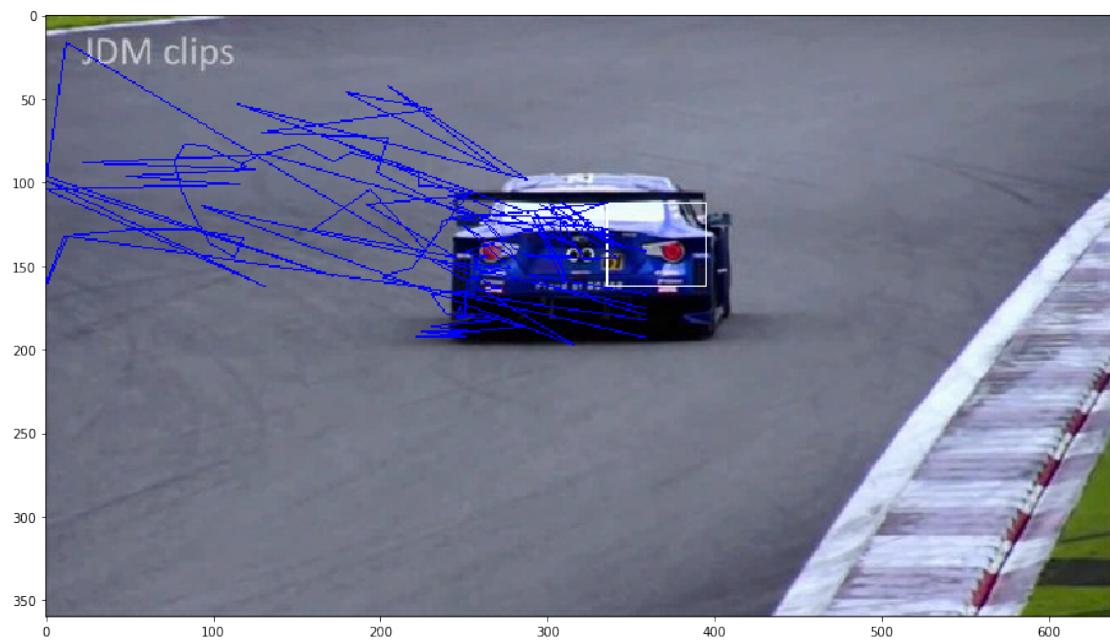
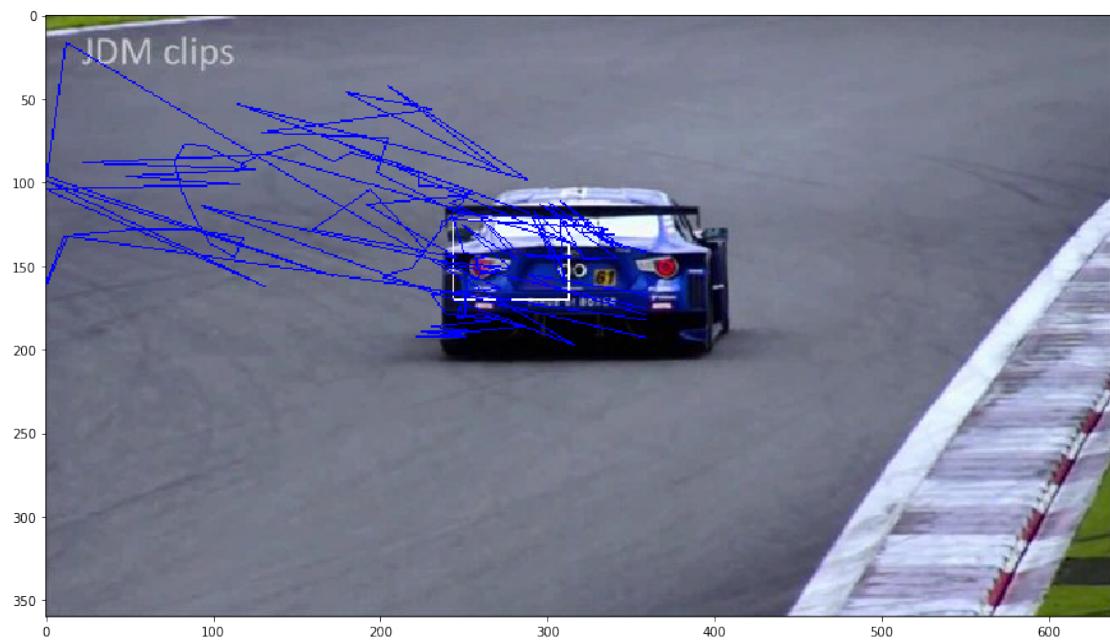


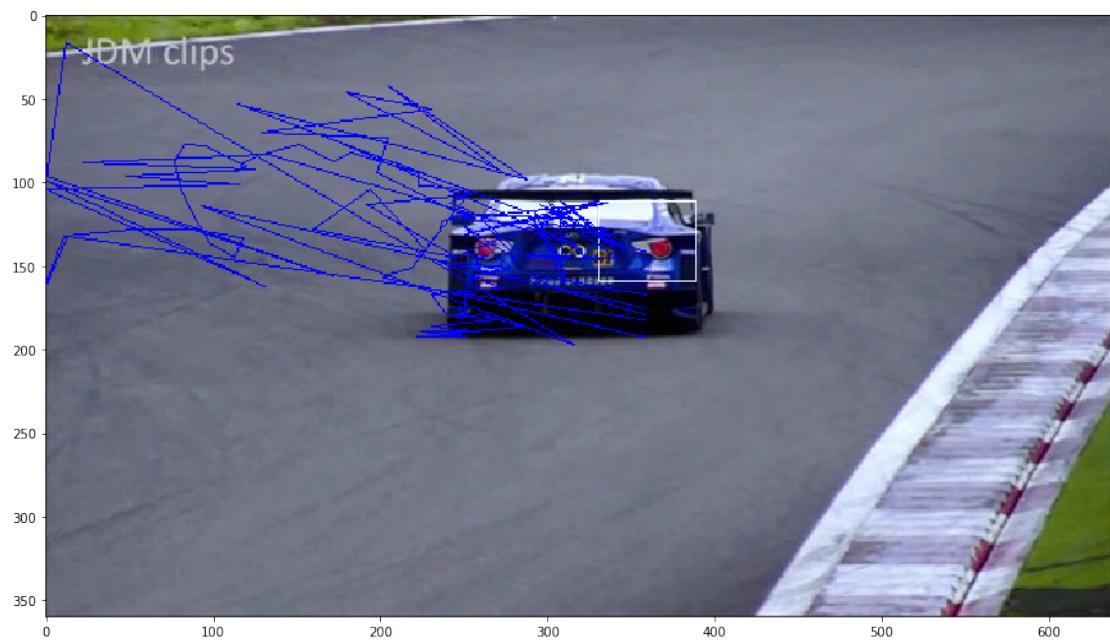
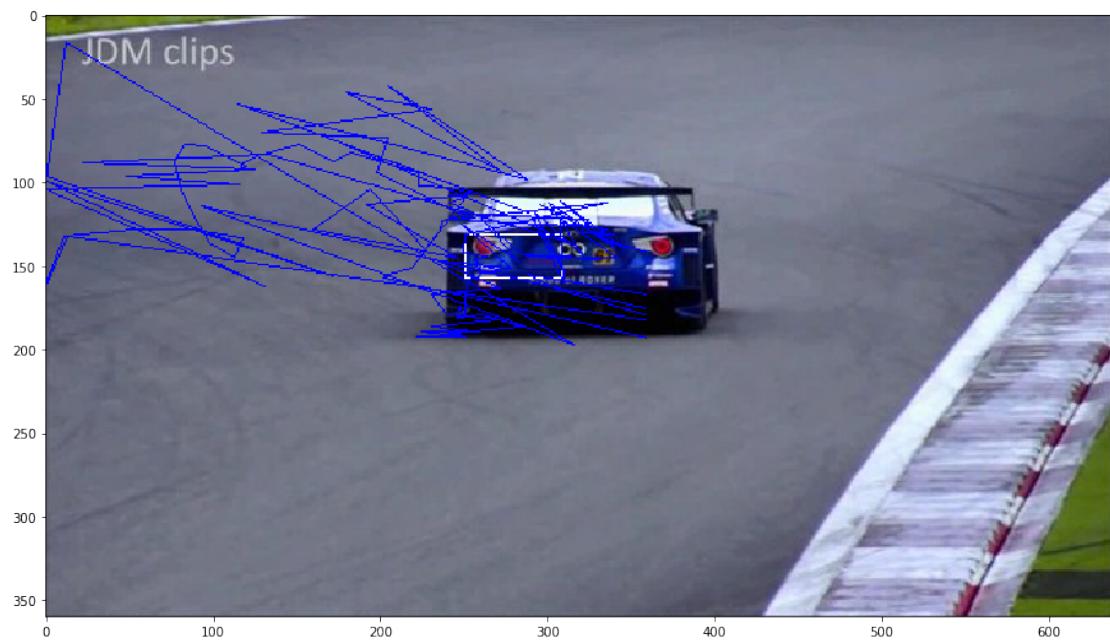


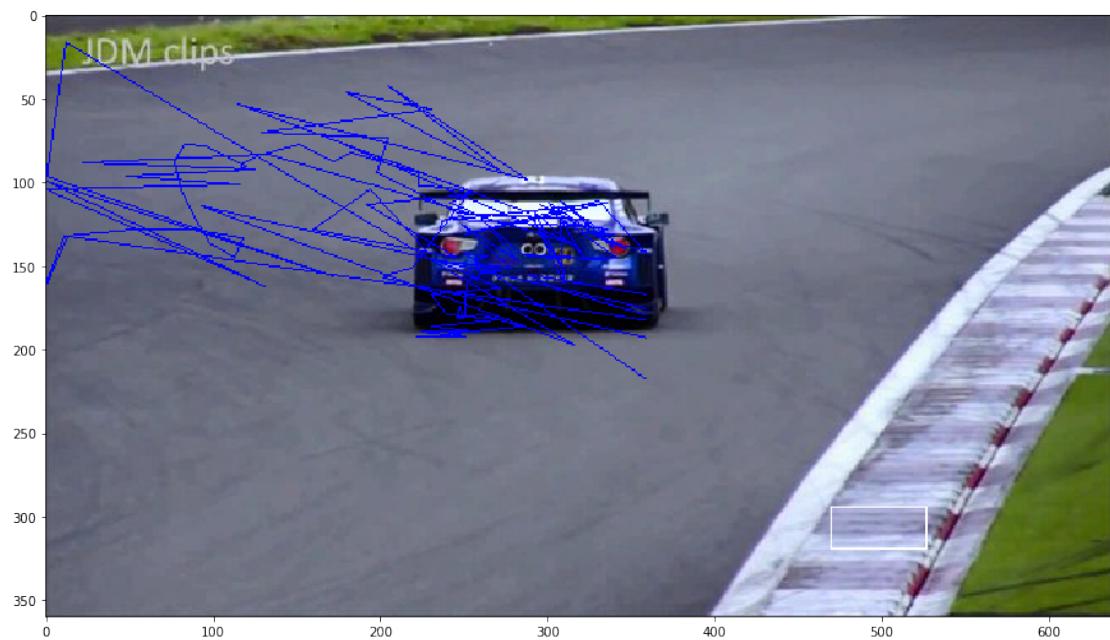
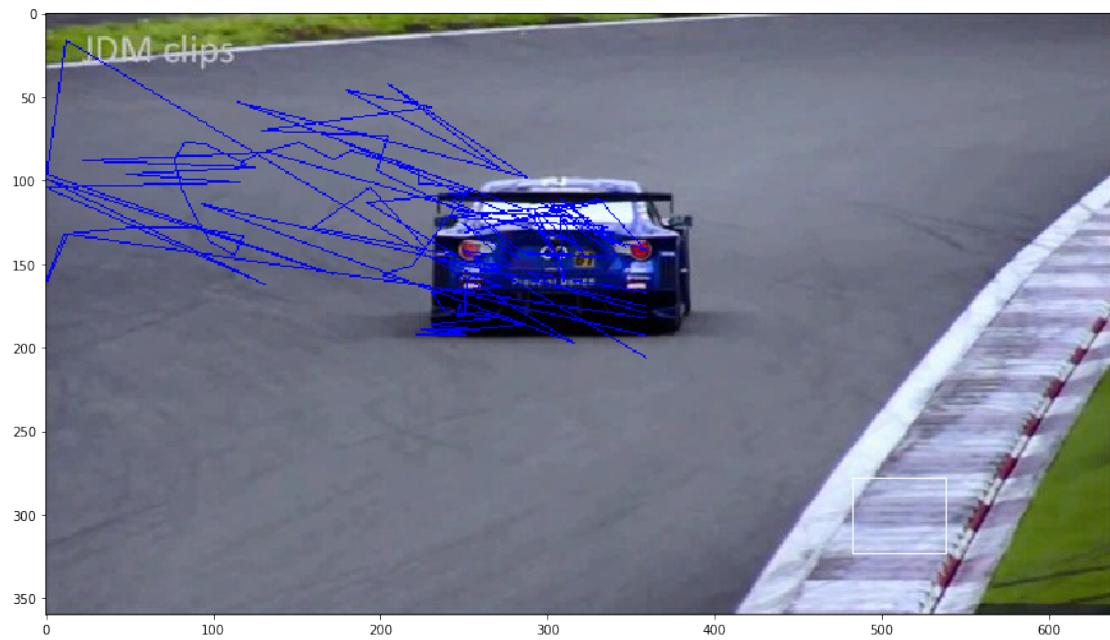


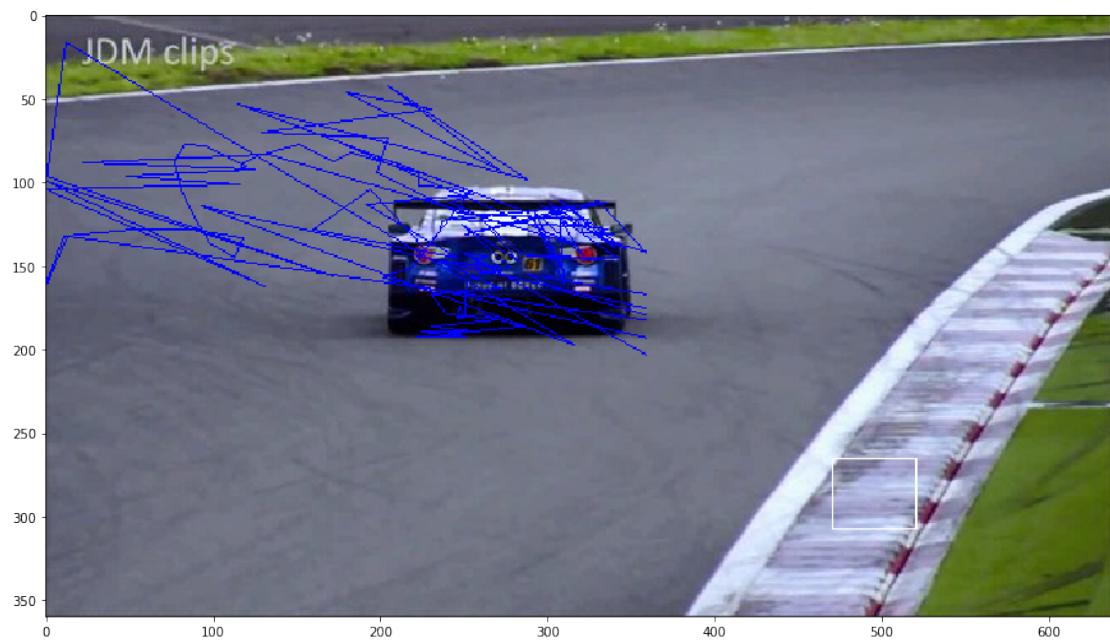
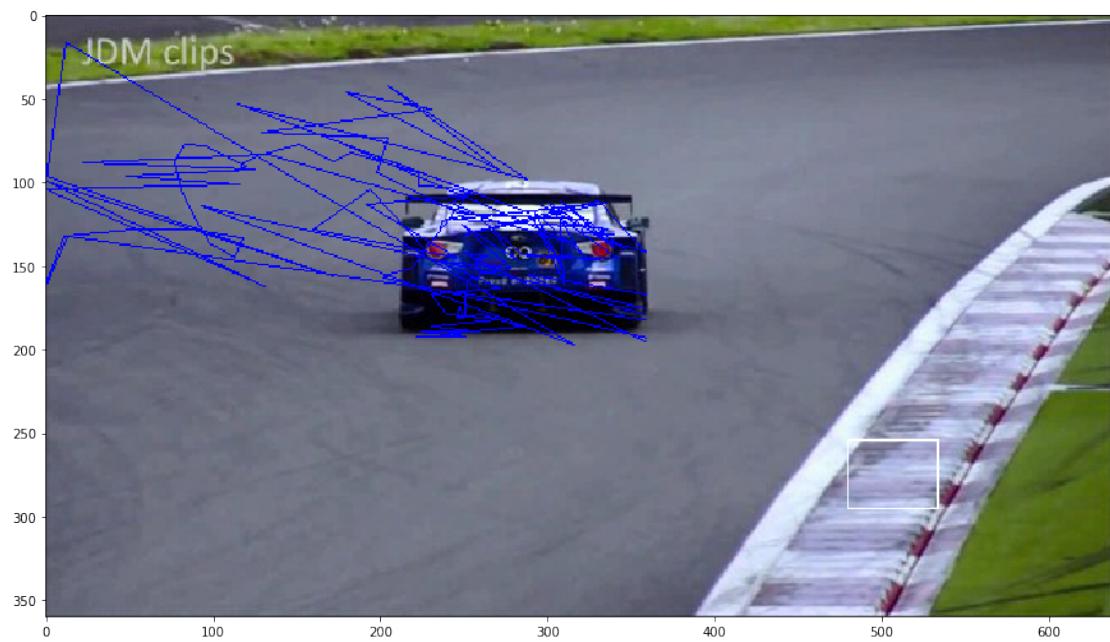


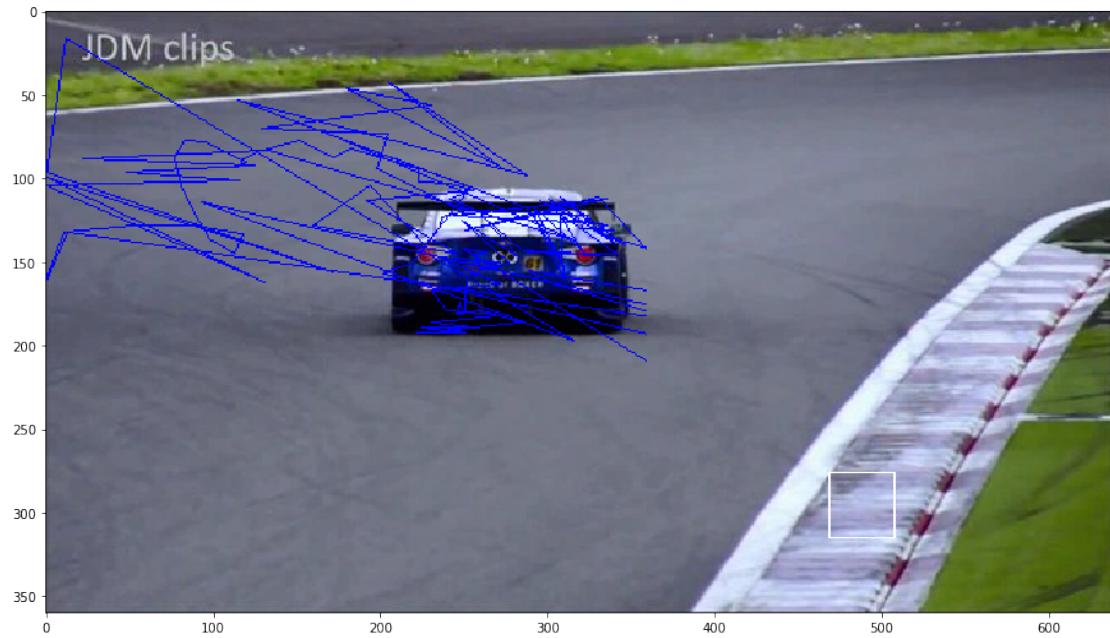












In [105]:

[(308, 149), (250, 135), (250, 135), (250, 135), (308, 149), (250, 135), (308, 149), (250, 135)]

In [111]:

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Out[111]: [[308, 250, 250, 250, 308, 250, 308, 250],  
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