

# **Processor Architecture I: ISA & Logic Design**

Introduction to Computer Systems  
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# **Part A**

## **Instruction Set Architecture**

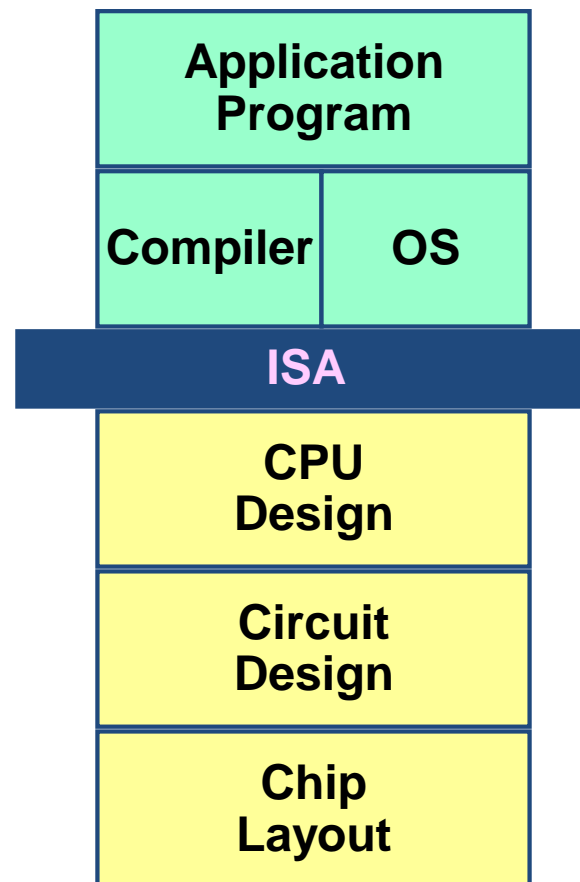
# Instruction Set Architecture

## ■ Assembly Language View

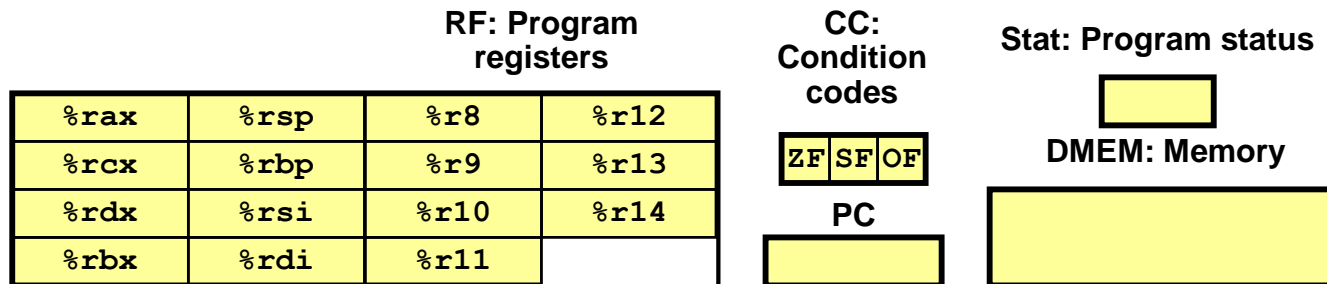
- Processor state
  - Registers, memory, ...
- Instructions
  - `addq, pushq, ret, ...`
  - How instructions are encoded as bytes

## ■ Layer of Abstraction

- Above: how to program machine
  - Processor executes instructions in a sequence
- Below: what needs to be built
  - Use variety of tricks to make it run fast
  - E.g., execute multiple instructions simultaneously



# Y86-64 Processor State



## ■ Program Registers

- 15 registers (omit %r15). Each 64 bits

## ■ Condition Codes

- Single-bit flags set by arithmetic or logical instructions

» ZF: Zero                      SF: Negative                      OF: Overflow

## ■ Program Counter

- Indicates address of next instruction

## ■ Program Status

- Indicates either normal operation or some error condition

## ■ Memory

- Byte-addressable storage array
- Words stored in little-endian byte order

# Y86-64 Instruction Set #1

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest							
call Dest	8	0	Dest							
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

# Y86-64 Instructions


## ■ Format

- 1–10 bytes of information read from memory
  - Can determine instruction length from first byte
  - Not as many instruction types, and simpler encoding than with x86-64
- Each accesses and modifies some part(s) of the program state

# Y86-64 Instruction Set #2

Byte	0	1	2	3	4	5	6	
halt	0	0						
nop	1	0						
cmovXX rA, rB	2	fn	rA	rB				rrmovq 2 0
irmovq V, rB	3	0	F	rB			V	cmovle 2 1
rmmovq rA, D(rB)	4	0	rA	rB			D	cmovl 2 2
rmovq D(rB), rA	5	0	rA	rB			D	cmove 2 3
OPq rA, rB	6	fn	rA	rB				cmovne 2 4
jXX Dest	7	fn					Dest	cmovge 2 5
call Dest	8	0					Dest	cmovg 2 6
ret	9	0						
pushq rA	A	0	rA	F				
popq rA	B	0	rA	F				

# Y86-64 Instruction Set #3

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest							
call Dest	8	0	Dest							
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

addq 6 0

subq 6 1

andq 6 2

xorq 6 3



# Y86-64 Instruction Set #4

Byte	0	1	2	3	4	5	6	7		
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
rrmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest							
call Dest	8	0	Dest							
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

jmp	7	0
jle	7	1
j1	7	2
je	7	3
jne	7	4
jge	7	5
jg	7	6

# Encoding Registers

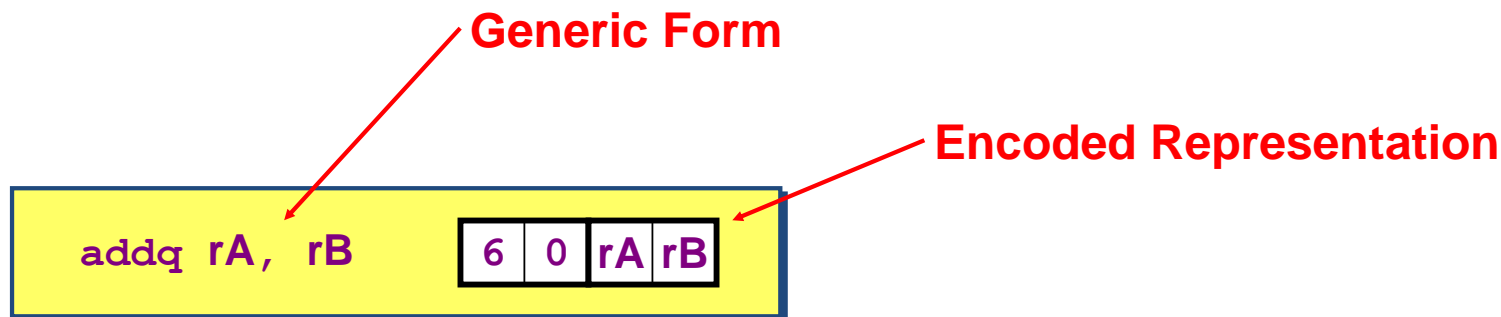
- Each register has 4-bit ID

%rax	0	%r8	8
%rcx	1	%r9	9
%rdx	2	%r10	A
%rbx	3	%r11	B
%rsp	4	%r12	C
%rbp	5	%r13	D
%rsi	6	%r14	E
%rdi	7	No Register	F

- Same encoding as in x86-64
- Register ID 15 (0xF) indicates “no register”
  - Will use this in our hardware design in multiple places

# Instruction Example

## ■ Addition Instruction



- Add value in register rA to that in register rB
  - Store result in register rB
  - Note that Y86-64 only allows addition to be applied to register data
- Set condition codes based on result
- e.g., `addq %rax,%rsi` Encoding: 60 06
- Two-byte encoding
  - First indicates instruction type
  - Second gives source and destination registers

# Arithmetic and Logical Operations

## Instruction Code

Add

`addq rA, rB`

6 0 rA rB

## Function Code

Subtract (rA from rB)

`subq rA, rB`

6 1 rA rB

And

`andq rA, rB`

6 2 rA rB

Exclusive-Or

`xorq rA, rB`

6 3 rA rB

- Refer to generically as “OPq”
- Encodings differ only by “function code”
  - Low-order 4 bytes in first instruction word
- Set condition codes as side effect

# Move Operations

Register → Register

`rrmovq rA, rB`



Immediate → Register

`irmovq V, rB`



Register → Memory

`rmmovq rA, D(rB)`



Memory → Register

`mrmovq D(rB), rA`



- Like the x86-64 `movq` instruction
- Simpler format for memory addresses
- Give different names to keep them distinct

# Move Instruction Examples

## X86-64

```
movq $0xabcd, %rdx
```

Encoding: 30 f2 cd ab 00 00 00 00 00 00

```
movq %rsp, %rbx
```

Encoding: 20 43

```
movq -12(%rbp), %rcx
```

Encoding: 50 15 f4 ff ff ff ff ff ff

```
movq %rsi, 0x41c(%rsp)
```

Encoding: 40 64 1c 04 00 00 00 00 00 00

## Y86-64

```
irmovq $0xabcd, %rdx
```

```
rrmovq %rsp, %rbx
```

```
mrmovq -12(%rbp), %rcx
```

```
rmmovq %rsi, 0x41c(%rsp)
```

# Conditional Move Instructions

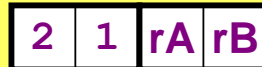
## Move Unconditionally

`rrmovq rA, rB`



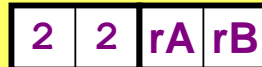
## Move When Less or Equal

`cmovle rA, rB`



## Move When Less

`cmovl rA, rB`



## Move When Equal

`cmove rA, rB`



## Move When Not Equal

`cmovne rA, rB`



## Move When Greater or Equal

`cmovge rA, rB`



## Move When Greater

`cmovg rA, rB`



- Refer to generically as “`cmovXX`”
- Encodings differ only by “function code”
- Based on values of condition codes
- Variants of `rrmovq` instruction
  - (Conditionally) copy value from source to destination register

# Jump Instructions

## Jump (Conditionally)



- Refer to generically as “jxx”
- Encodings differ only by “function code” fn
- Based on values of condition codes
- Same as x86-64 counterparts
- Encode full destination address
  - Unlike PC-relative addressing seen in x86-64



# Jump Instructions

## Jump Unconditionally

<b>jmp Dest</b>	7	0	Dest
-----------------	---	---	------

## Jump When Less or Equal

<b>jle Dest</b>	7	1	Dest
-----------------	---	---	------

## Jump When Less

<b>jlt Dest</b>	7	2	Dest
-----------------	---	---	------

## Jump When Equal

<b>je Dest</b>	7	3	Dest
----------------	---	---	------

## Jump When Not Equal

<b>jne Dest</b>	7	4	Dest
-----------------	---	---	------

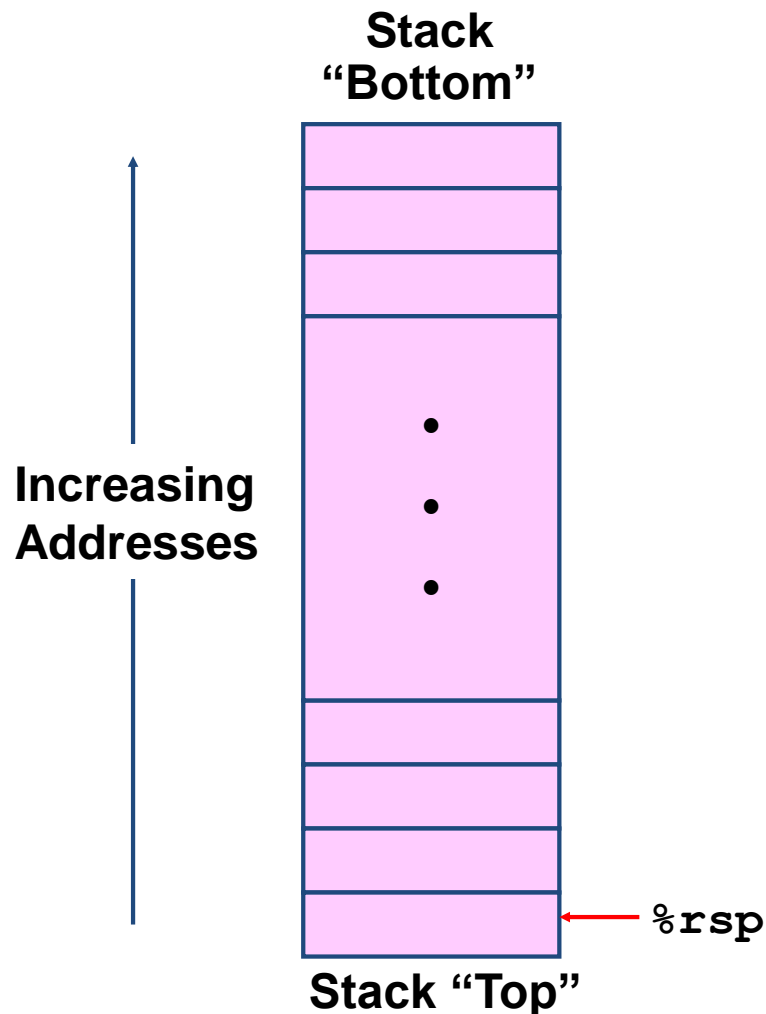
## Jump When Greater or Equal

<b>jge Dest</b>	7	5	Dest
-----------------	---	---	------

## Jump When Greater

<b>jg Dest</b>	7	6	Dest
----------------	---	---	------

# Y86-64 Program Stack



- Region of memory holding program data
- Used in Y86-64 (and x86-64) for supporting procedure calls
- Stack top indicated by `%rsp`
  - Address of top stack element
- Stack grows toward lower addresses
  - Top element is at highest address in the stack
  - When pushing, must first decrement stack pointer
  - After popping, increment stack pointer

# Stack Operations

**pushq rA**

A	0	rA	F
---	---	----	---

- Decrement `%rsp` by 8
- Store word from `rA` to memory at `%rsp`
- Like x86-64

**popq rA**

B	0	rA	F
---	---	----	---

- Read word from memory at `%rsp`
- Save in `rA`
- Increment `%rsp` by 8
- Like x86-64

# Subroutine Call and Return

**call Dest**

8

0

Dest

- Push address of next instruction onto stack
- Start executing instructions at Dest
- Like x86-64

**ret**

9

0

- Pop value from stack
- Use as address for next instruction
- Like x86-64

# Miscellaneous Instructions

`nop`

1	0
---	---

- Don't do anything

`halt`

0	0
---	---

- Stop executing instructions
- x86-64 has comparable instruction, but can't execute it in user mode
- We will use it to stop the simulator
- Encoding ensures that program hitting memory initialized to zero will halt

# Status Conditions

Mnemonic	Code
AOK	1

- Normal operation

Mnemonic	Code
HLT	2

- Halt instruction encountered

Mnemonic	Code
ADR	3

- Bad address (either instruction or data) encountered

Mnemonic	Code
INS	4

- Invalid instruction encountered

- **Desired Behavior**

- If AOK, keep going
- Otherwise, stop program execution

# Writing Y86-64 Code

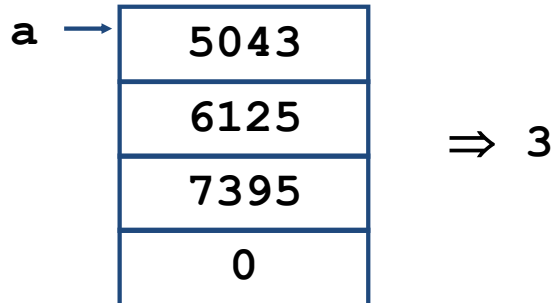
## ■ Try to Use C Compiler as Much as Possible

- Write code in C
- Compile for x86-64 with `gcc -Og -S`
- Transliterate into Y86-64
- *Modern compilers make this more difficult*

## ■ Coding Example

- Find number of elements in null-terminated list

```
int len1(int a[]);
```



# Y86-64 Code Generation Example

## ■ First Try

- Write typical array code

```
/* Find number of elements in
   null-terminated list */
long len(long a[])
{
    long len;
    for (len = 0; a[len]; len++)
        ;
    return len;
}
```

- Compile with `gcc -Og -S`

## ■ Problem

- Hard to do array indexing on Y86-64
  - Since don't have scaled addressing modes

L3:

```
addq $1,%rax
cmpq $0, (%rdi,%rax,8)
jne L3
```



# Y86-64 Code Generation Example #2

## ■ Second Try

- Write C code that mimics expected Y86-64 code

```
long len2(long *a)
{
    long ip = (long) a;
    long val = *(long *) ip;
    long len = 0;
    while (val) {
        ip += sizeof(long);
        len++;
        val = *(long *) ip;
    }
    return len;
}
```

## ■ Result

- Compiler generates exact same code as before!
- Compiler converts both versions into same intermediate form

# Y86-64 Code Generation Example #3

```

len:
    irmovq $1, %r8          # Constant 1
    irmovq $8, %r9          # Constant 8
    irmovq $0, %rax         # len = 0
    mrmovq (%rdi), %rdx     # val = *a
    andq %rdx, %rdx         # Test val
    je Done                 # If zero, goto Done

Loop:
    addq %r8, %rax          # len++
    addq %r9, %rdi          # a++
    mrmovq (%rdi), %rdx     # val = *a
    andq %rdx, %rdx         # Test val
    jne Loop                # If !0, goto Loop

Done:
    ret

```

Register	Use
%rdi	a
%rax	len
%rdx	val
%r8	1
%r9	8

# Y86-64 Sample Program Structure #1

```

init:                                # Initialization
    . . .
    call Main
    halt

    .align 8                          # Program data
array:
    . . .

Main:                                # Main function
    . . .
    call len    . . .

len:                                  # Length function
    . . .

    .pos 0x100                        # Placement of stack
Stack:

```

- Program starts at address 0
- Must set up stack
  - Where located
  - Pointer values
  - Make sure don't overwrite code!
- Must initialize data

# Y86-64 Program Structure #2

```
init:
    # Set up stack pointer
    irmovq Stack, %rsp
    # Execute main program
    call Main
    # Terminate
    halt

# Array of 4 elements + terminating 0
    .align 8
Array:
    .quad 0x000d000d000d000d
    .quad 0x00c000c000c000c0
    .quad 0x0b000b000b000b00
    .quad 0xa000a000a000a000
    .quad 0
```

- Program starts at address 0
- Must set up stack
- Must initialize data
- Can use symbolic names

# Y86-64 Program Structure #3

```
Main:
    irmovq array,%rdi
    # call len(array)
    call len
    ret
```

- Set up call to len
  - Follow x86-64 procedure conventions
  - Push array address as argument

# Assembling Y86-64 Program

```
unix> yas len.yas
```

- Generates “object code” file `len.yo`
  - Actually looks like disassembler output

```

0x054:                                | len:
0x054: 30f8010000000000000000000000 |   irmovq $1, %r8           # Constant 1
0x05e: 30f9080000000000000000000000 |   irmovq $8, %r9           # Constant 8
0x068: 30f0000000000000000000000000 |   irmovq $0, %rax          # len = 0
0x072: 5027000000000000000000000000 |   mrmovq (%rdi), %rdx       # val = *a
0x07c: 6222                             |   andq %rdx, %rdx          # Test val
0x07e: 73a0000000000000000000000000 |   je Done                  # If zero, goto Done
0x087:                                | Loop:
0x087: 6080                             |   addq %r8, %rax            # len++
0x089: 6097                             |   addq %r9, %rdi            # a++
0x08b: 5027000000000000000000000000 |   mrmovq (%rdi), %rdx       # val = *a
0x095: 6222                             |   andq %rdx, %rdx          # Test val
0x097: 7487000000000000000000000000 |   jne Loop                  # If !0, goto Loop
0x0a0:                                | Done:
0x0a0: 90                             |   ret

```

# Simulating Y86-64 Program

```
unix> yis len.yo
```

## ■ Instruction set simulator

- Computes effect of each instruction on processor state
- Prints changes in state from original

```
Stopped in 33 steps at PC = 0x13.  Status 'HLT', CC Z=1 S=0 O=0
```

```
Changes to registers:
```

%rax:	0x0000000000000000	0x0000000000000004
%rsp:	0x0000000000000000	0x0000000000000100
%rdi:	0x0000000000000000	0x0000000000000038
%r8:	0x0000000000000000	0x0000000000000001
%r9:	0x0000000000000000	0x0000000000000008

```
Changes to memory:
```

0x00f0:	0x0000000000000000	0x0000000000000053
0x00f8:	0x0000000000000000	0x0000000000000013

# CISC Instruction Sets

- Complex Instruction Set Computer
  - IA32 is example
- Stack-oriented instruction set
  - Use stack to pass arguments, save program counter
  - Explicit push and pop instructions
- Arithmetic instructions can access memory
  - `addq %rax, 12(%rbx,%rcx,8)`
    - requires memory read and write
    - Complex address calculation
- Condition codes
  - Set as side effect of arithmetic and logical instructions
- Philosophy
  - Add instructions to perform “typical” programming tasks



# RISC Instruction Sets

- Reduced Instruction Set Computer
- Internal project at IBM, later popularized by Hennessy (Stanford) and Patterson (Berkeley)
- Fewer, simpler instructions
  - Might take more to get given task done
  - Can execute them with small and fast hardware
- Register-oriented instruction set
  - Many more (typically 32) registers
  - Use for arguments, return pointer, temporaries
- Only load and store instructions can access memory
  - Similar to Y86-64 `mrmovq` and `rmmovq`
- No Condition codes
  - Test instructions return 0/1 in register

# MIPS Registers

\$0	\$0	Constant 0
\$1	\$at	Reserved Temp.
\$2	\$v0	Return Values
\$3	\$v1	
\$4	\$a0	Procedure arguments
\$5	\$a1	
\$6	\$a2	
\$7	\$a3	
\$8	\$t0	Caller Save Temporaries: May be overwritten by called procedures
\$9	\$t1	
\$10	\$t2	
\$11	\$t3	
\$12	\$t4	
\$13	\$t5	
\$14	\$t6	
\$15	\$t7	

\$16	\$s0	Callee Save Temporaries: May not be overwritten by called procedures
\$17	\$s1	
\$18	\$s2	
\$19	\$s3	
\$20	\$s4	
\$21	\$s5	
\$22	\$s6	
\$23	\$s7	Caller Save Temp
\$24	\$t8	
\$25	\$t9	Reserved for Operating Sys
\$26	\$k0	
\$27	\$k1	Global Pointer
\$28	\$gp	
\$29	\$sp	Stack Pointer
\$30	\$s8	Callee Save Temp
\$31	\$ra	Return Address

# MIPS Instruction Examples

## R-R

Op	Ra	Rb	Rd	00000	Fn
----	----	----	----	-------	----

`addu $3,$2,$1`      # Register add:  $\$3 = \$2 + \$1$

## R-I

Op	Ra	Rb	Immediate
----	----	----	-----------

`addu $3,$2, 3145`      # Immediate add:  $\$3 = \$2 + 3145$

`sll $3,$2,2`      # Shift left:  $\$3 = \$2 \ll 2$

## Branch

Op	Ra	Rb	Offset
----	----	----	--------

`beq $3,$2,dest`      # Branch when  $\$3 = \$2$

## Load/Store

Op	Ra	Rb	Offset
----	----	----	--------

`lw $3,16($2)`      # Load Word:  $\$3 = M[\$2 + 16]$

`sw $3,16($2)`      # Store Word:  $M[\$2 + 16] = \$3$

# CISC vs. RISC

## ■ Original Debate

- Strong opinions!
- CISC proponents---easy for compiler, fewer code bytes
- RISC proponents---better for optimizing compilers, can make run fast with simple chip design

## ■ Current Status

- For desktop processors, choice of ISA not a technical issue
  - With enough hardware, can make anything run fast
  - Code compatibility more important
- x86-64 adopted many RISC features
  - More registers; use them for argument passing
- For embedded processors, RISC makes sense
  - Smaller, cheaper, less power
  - Most cell phones use ARM processor

# Summary

## ■ Y86-64 Instruction Set Architecture

- Similar state and instructions as x86-64
- Simpler encodings
- Somewhere between CISC and RISC

## ■ How Important is ISA Design?

- Less now than before
  - With enough hardware, can make almost anything go fast

# **Part B**

## **Logic Design**

# Overview of Logic Design

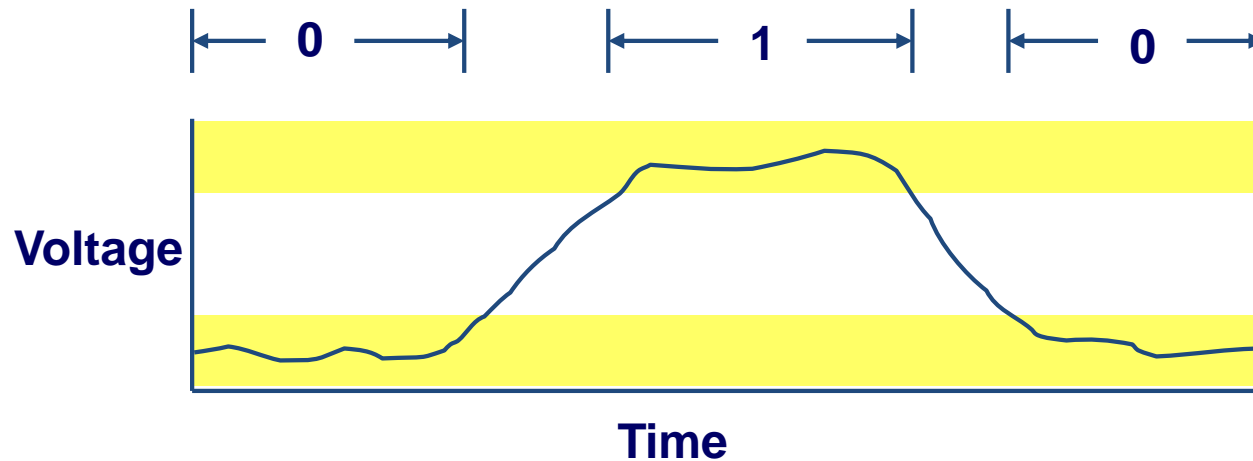
## ■ Fundamental Hardware Requirements

- Communication
  - How to get values from one place to another
- Computation
- Storage

## ■ Bits are Our Friends

- Everything expressed in terms of values 0 and 1
- Communication
  - Low or high voltage on wire
- Computation
  - Compute Boolean functions
- Storage
  - Store bits of information

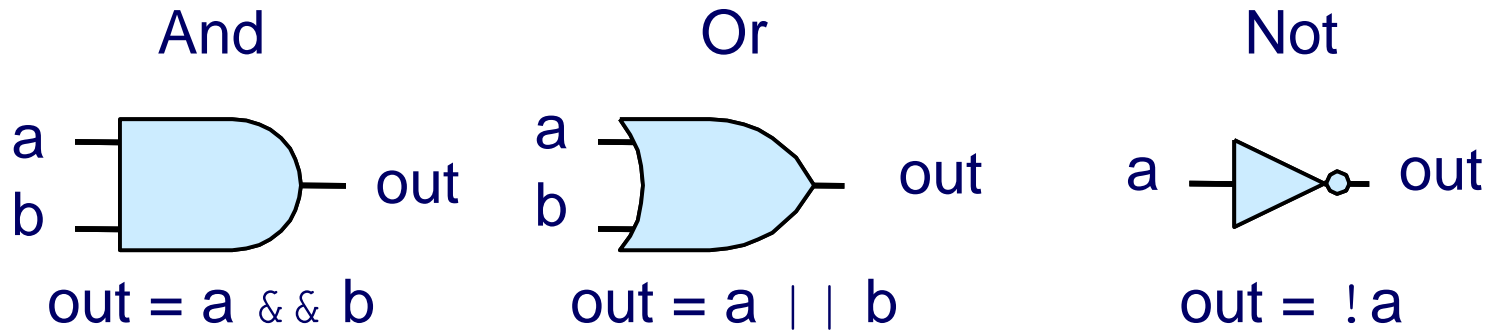
# Digital Signals



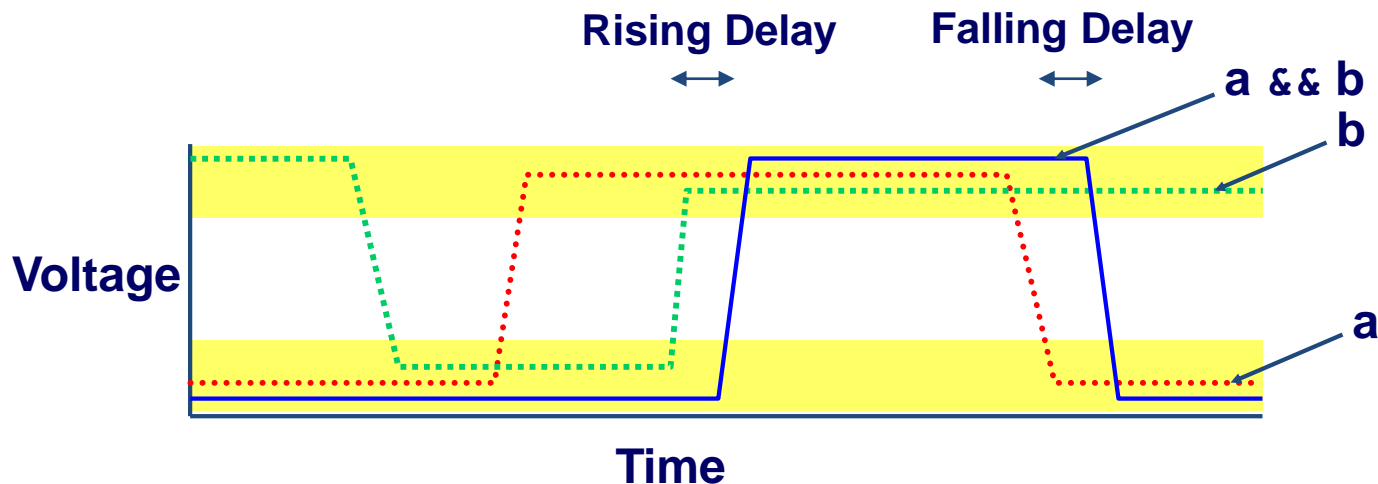
- Use voltage thresholds to extract discrete values from continuous signal
- Simplest version: 1-bit signal
  - Either high range (1) or low range (0)
  - With guard range between them
- Not strongly affected by noise or low quality circuit elements
  - Can make circuits simple, small, and fast



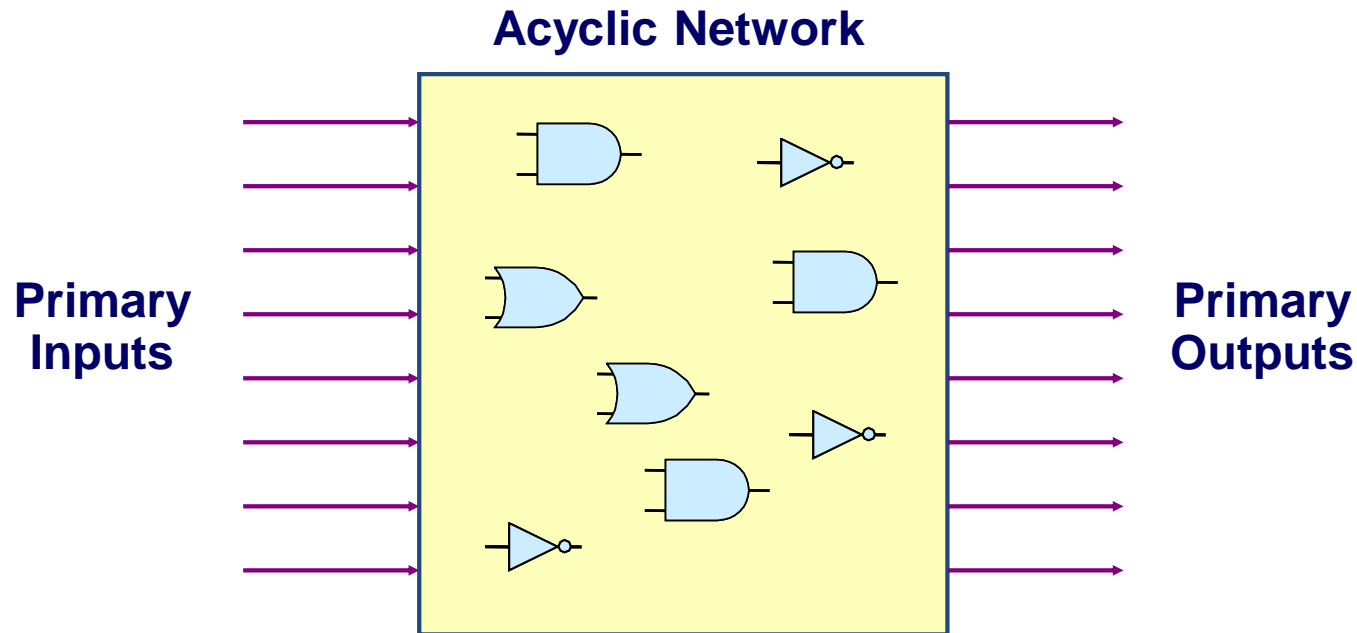
# Computing with Logic Gates



- Outputs are Boolean functions of inputs
- Respond continuously to changes in inputs
  - With some, small delay



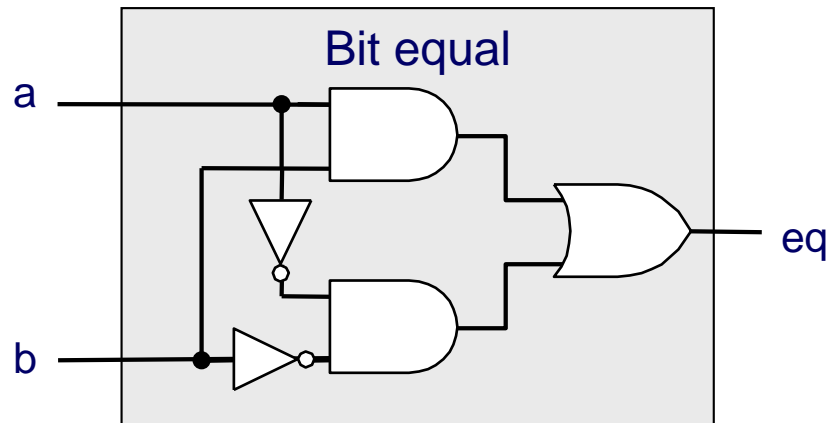
# Combinational Circuits



## ■ Acyclic Network of Logic Gates

- Continuously responds to changes on primary inputs
- Primary outputs become (after some delay) Boolean functions of primary inputs

# Bit Equality

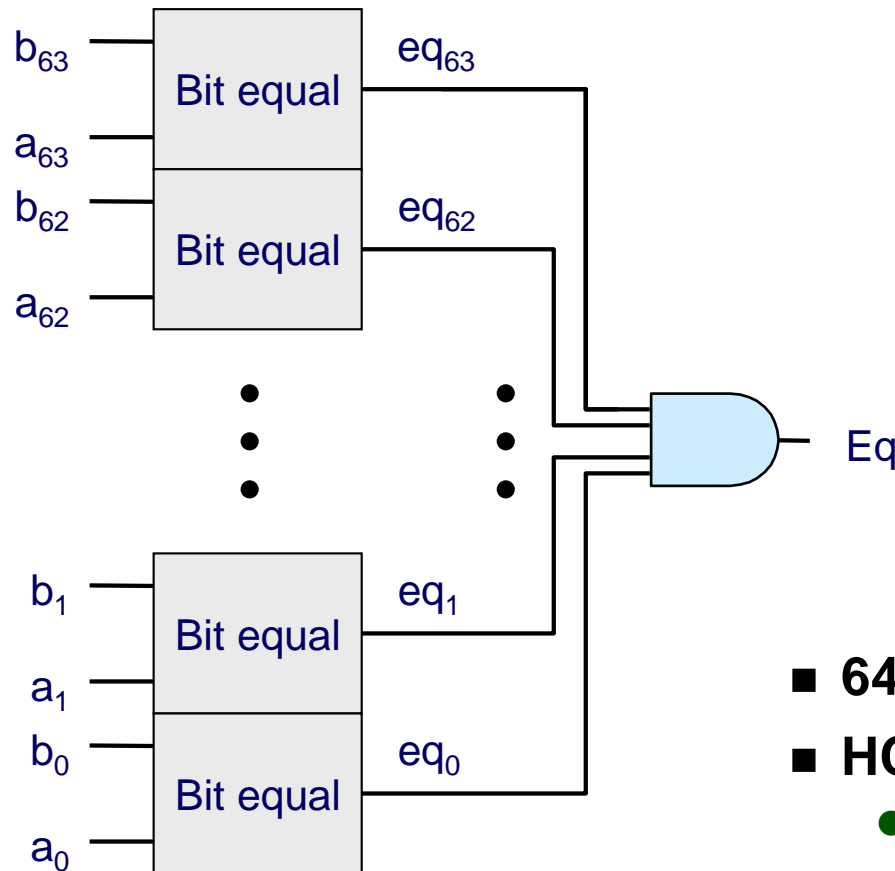


## HCL Expression

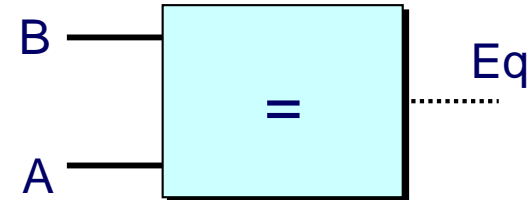
```
bool eq = (a&&b) || (!a&&!b)
```

- Generate 1 if a and b are equal
- **Hardware Control Language (HCL)**
  - Very simple hardware description language
    - Boolean operations have syntax similar to C logical operations
  - We'll use it to describe control logic for processors

# Word Equality



## Word-Level Representation

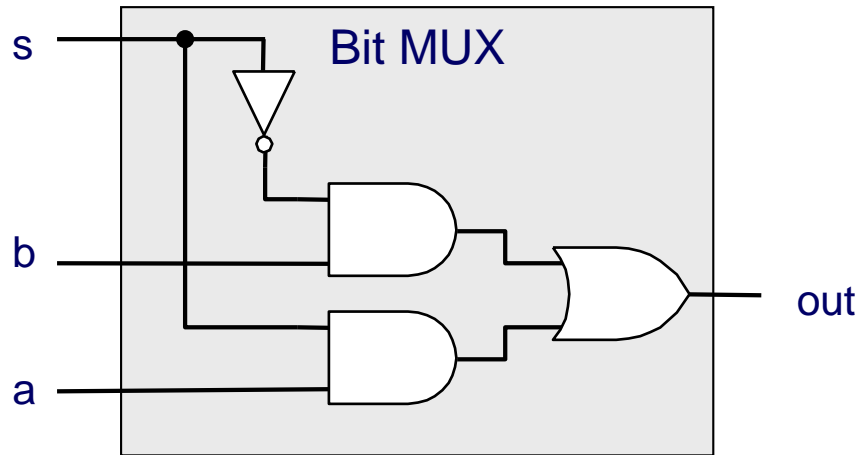


## HCL Representation

```
bool Eq = (A == B)
```

- 64-bit word size
- HCL representation
  - Equality operation
  - Generates Boolean value

# Bit-Level Multiplexor

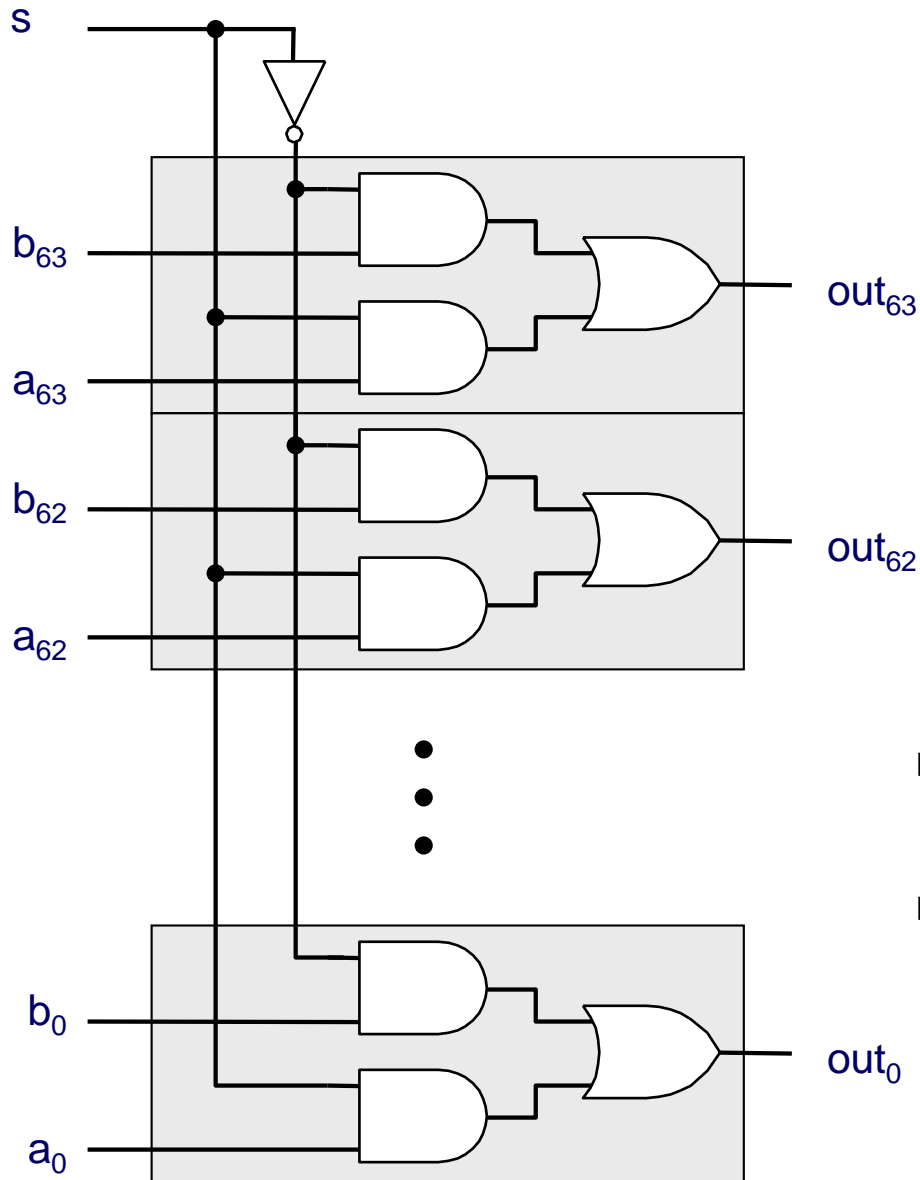


## HCL Expression

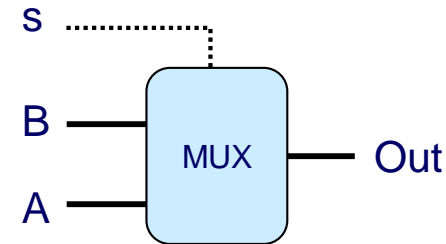
```
bool out = (s&&a) || (!s&&b)
```

- Control signal *s*
- Data signals *a* and *b*
- Output *a* when *s*=1, *b* when *s*=0

# Word Multiplexor



## Word-Level Representation



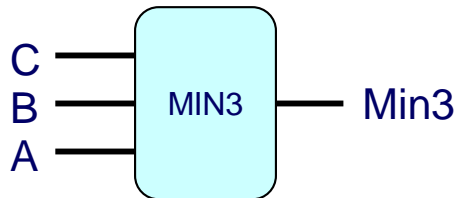
## HCL Representation

```
int Out = [
    s : A;
    1 : B;
];
```

- Select input word  $A$  or  $B$  depending on control signal  $s$
- HCL representation
  - Case expression
  - Series of test : value pairs
  - Output value for first successful test

# HCL Word-Level Examples

## Minimum of 3 Words

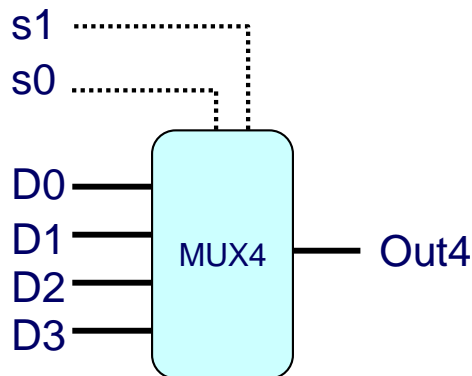


```

int Min3 = [
    A < B && A < C : A;
    B < A && B < C : B;
    1                : C;
];
  
```

- Find minimum of three input words
- HCL case expression
- Final case guarantees match

## 4-Way Multiplexor

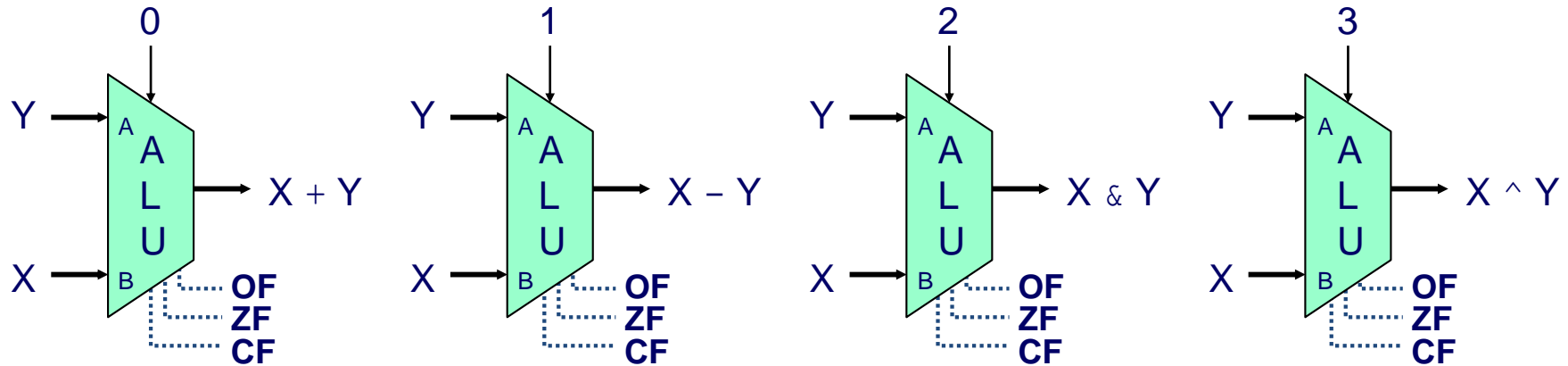


```

int Out4 = [
    !s1&&!s0: D0;
    !s1      : D1;
    !s0      : D2;
    1        : D3;
];
  
```

- Select one of 4 inputs based on two control bits
- HCL case expression
- Simplify tests by assuming sequential matching

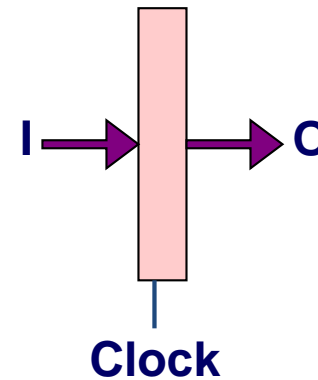
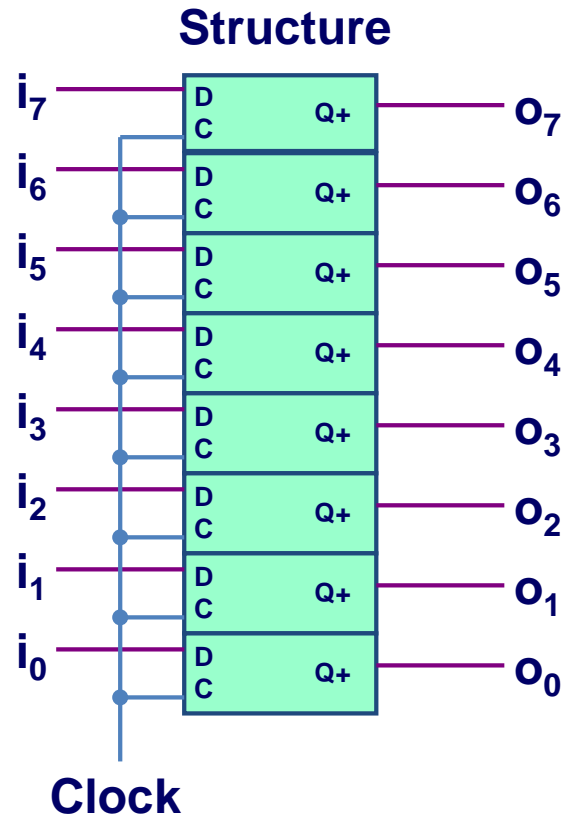
# Arithmetic Logic Unit



- **Combinational logic**
  - Continuously responding to inputs
- **Control signal selects function computed**
  - Corresponding to 4 arithmetic/logical operations in Y86-64
- **Also computes values for condition codes**

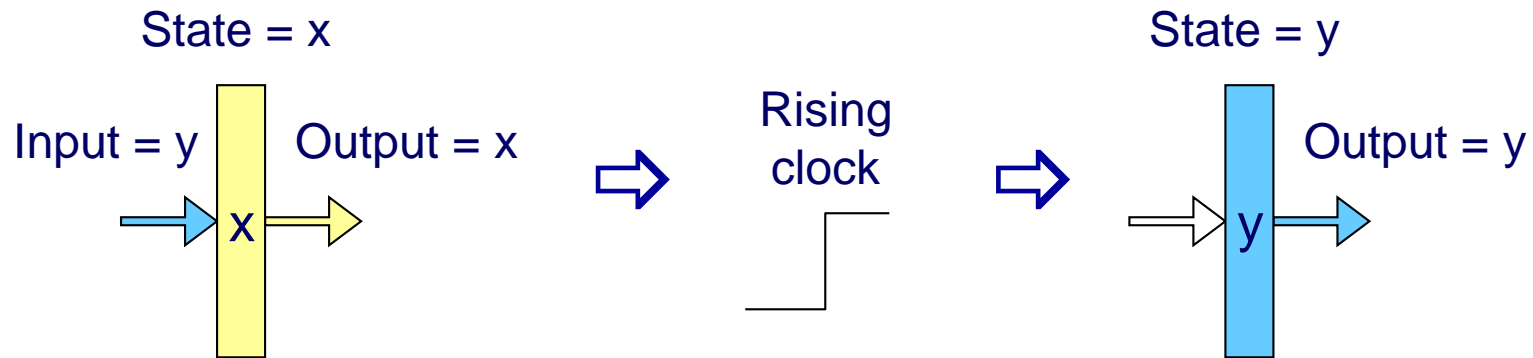


# Registers



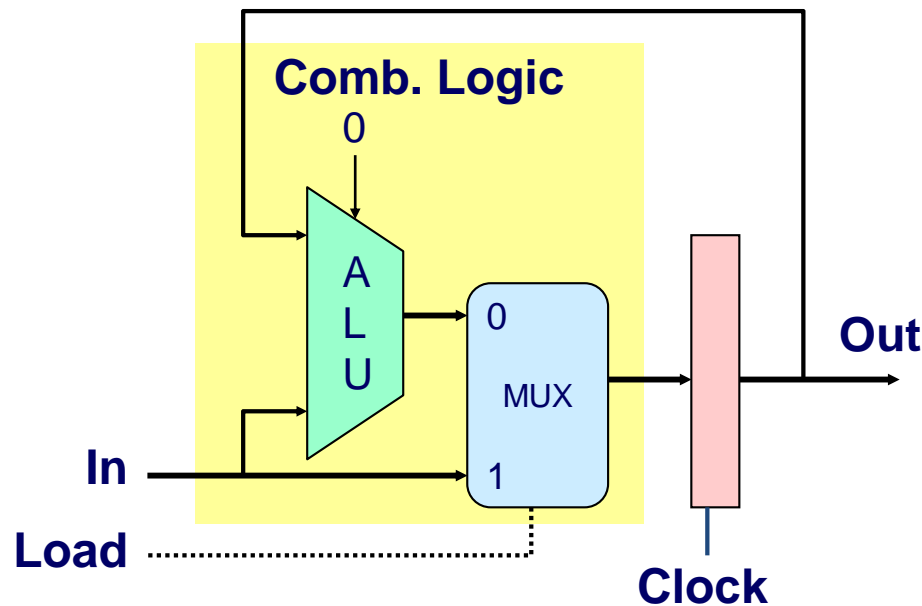
- Stores word of data
  - Different from *program registers* seen in assembly code
- Collection of edge-triggered latches
- Loads input on rising edge of clock

# Register Operation

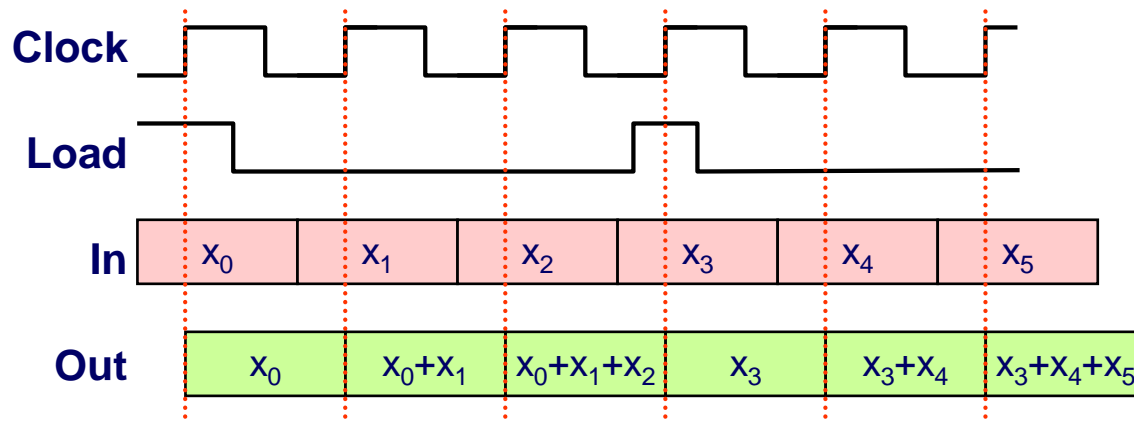


- Stores data bits
- For most of time acts as barrier between input and output
- As clock rises, loads input

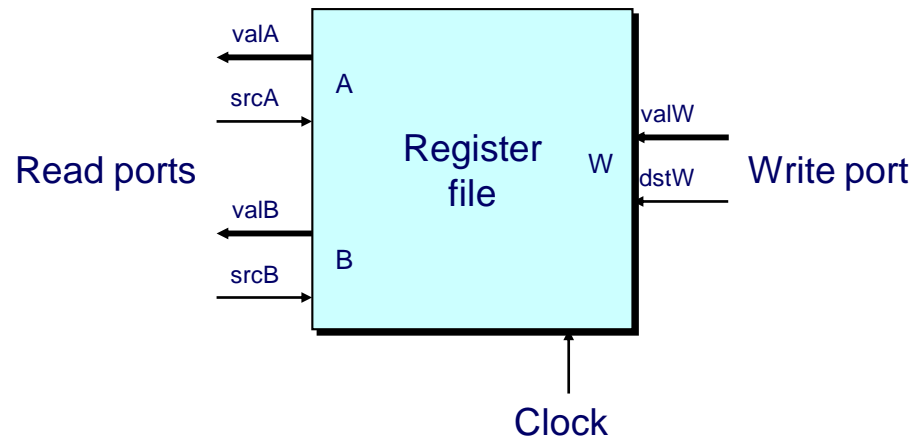
# State Machine Example



- Accumulator circuit
- Load or accumulate on each cycle

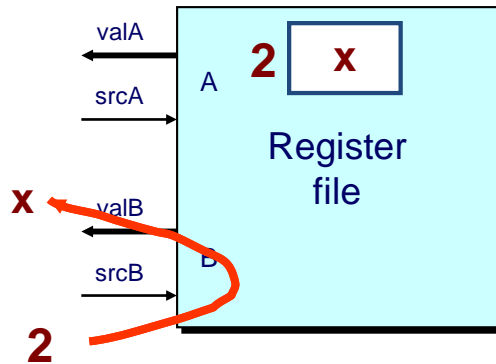


# Random-Access Memory



- **Stores multiple words of memory**
  - Address input specifies which word to read or write
- **Register file**
  - Holds values of program registers
  - `%rax`, `%rsp`, etc.
  - Register identifier serves as address
    - » ID 15 (0xF) implies no read or write performed
- **Multiple Ports**
  - Can read and/or write multiple words in one cycle
    - » Each has separate address and data input/output

# Register File Timing

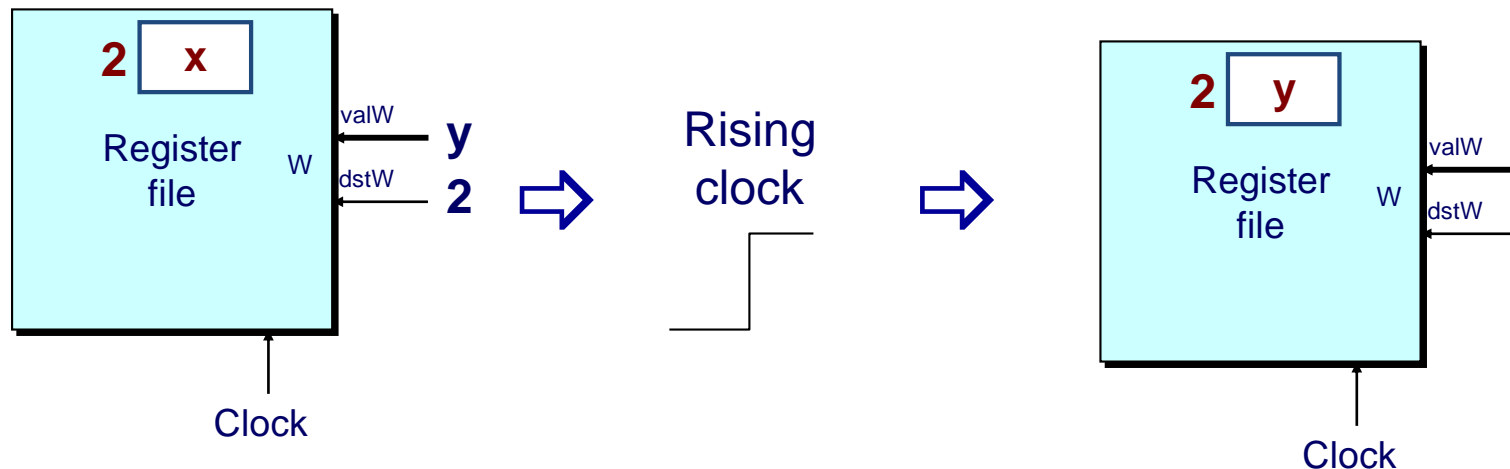


## ■ Reading

- Like combinational logic
- Output data generated based on input address
  - After some delay

## ■ Writing

- Like register
- Update only as clock rises



# Hardware Control Language

- Very simple hardware description language
- Can only express limited aspects of hardware operation
  - Parts we want to explore and modify

## ■ Data Types

- `bool`: Boolean
  - `a, b, c, ...`
- `int`: words
  - `A, B, C, ...`
  - Does not specify word size---bytes, 64-bit words, ...

## ■ Statements

- `bool a = bool-expr ;`
- `int A = int-expr ;`

# HCL Operations

- Classify by type of value returned

## ■ Boolean Expressions

- Logic Operations

- `a && b, a || b, !a`

- Word Comparisons

- `A == B, A != B, A < B, A <= B, A >= B, A > B`

- Set Membership

- `A in { B, C, D }`

» Same as `A == B || A == C || A == D`

## ■ Word Expressions

- Case expressions

- `[ a : A; b : B; c : C ]`
- Evaluate test expressions `a, b, c, ...` in sequence
- Return word expression `A, B, C, ...` for first successful test

# Summary

## ■ Computation

- Performed by combinational logic
- Computes Boolean functions
- Continuously reacts to input changes

## ■ Storage

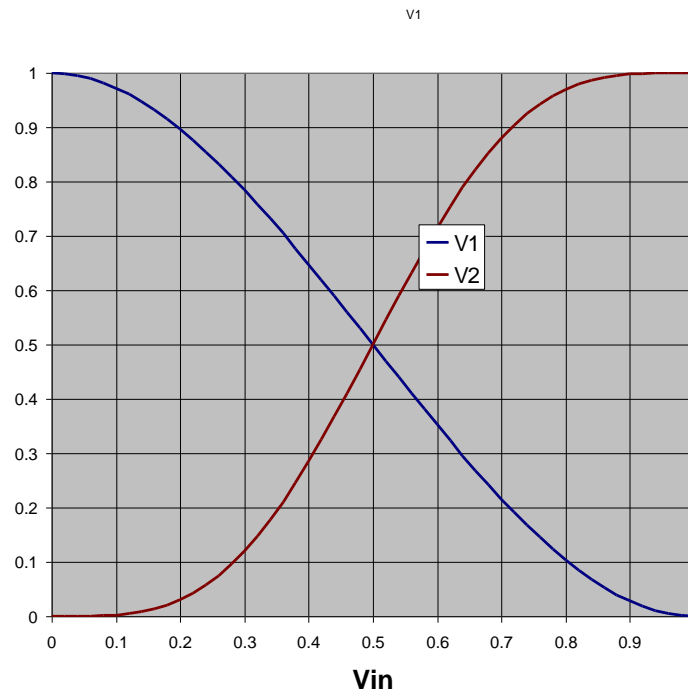
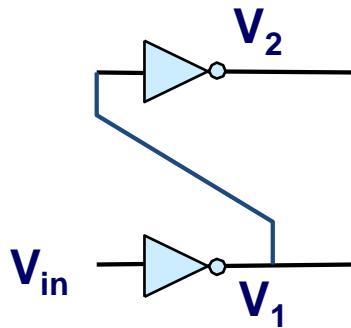
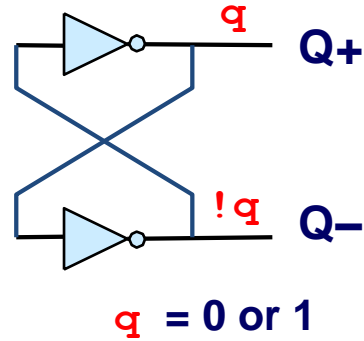
- Registers
  - Hold single words
  - Loaded as clock rises
- Random-access memories
  - Hold multiple words
  - Possible multiple read or write ports
  - Read word when address input changes
  - Write word as clock rises



# Additional Slides

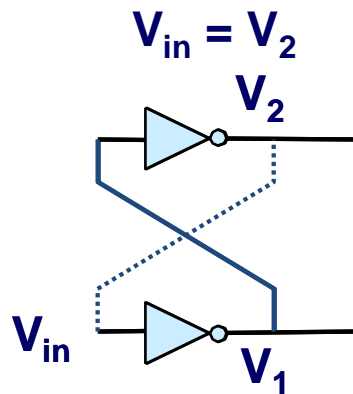
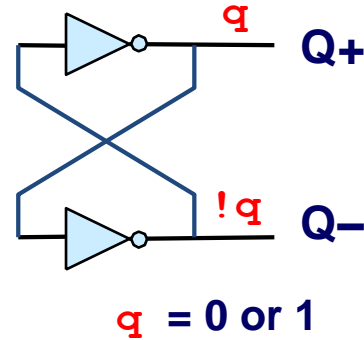
# Storing 1 Bit

## Bistable Element

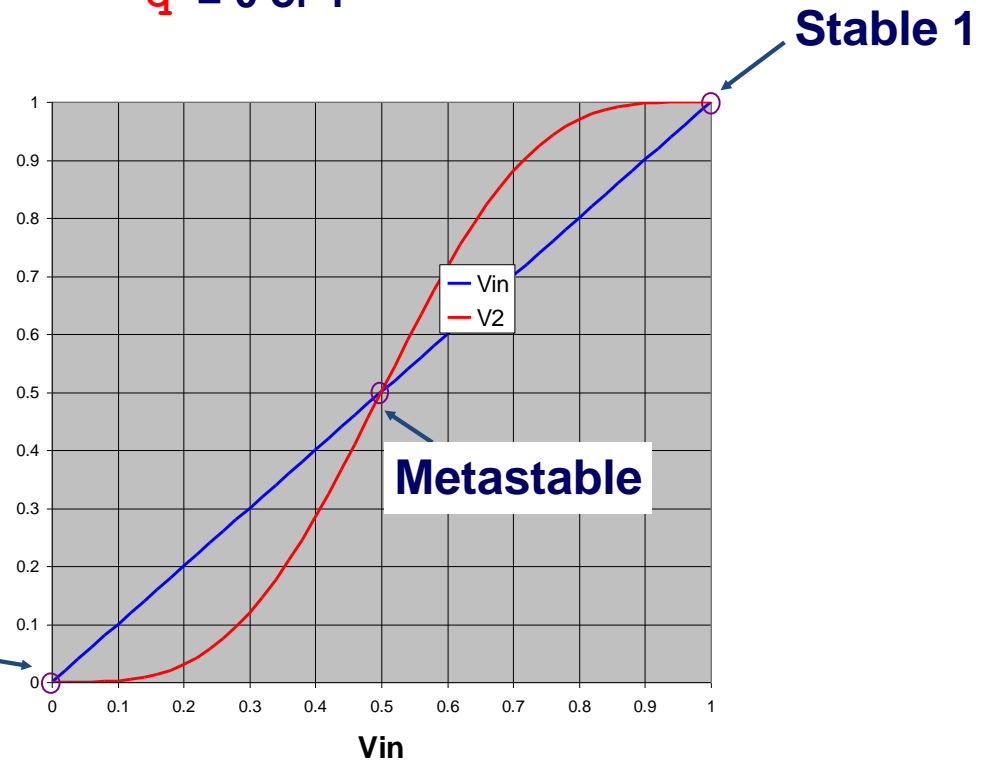


# Storing 1 Bit (cont.)

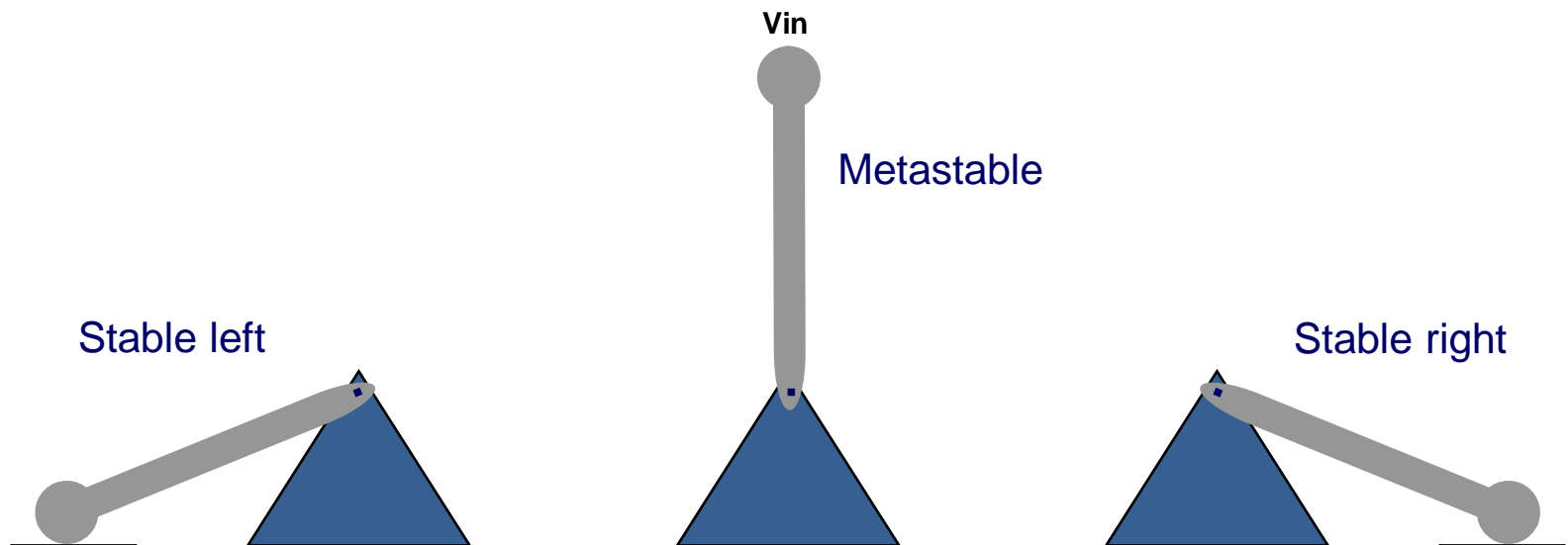
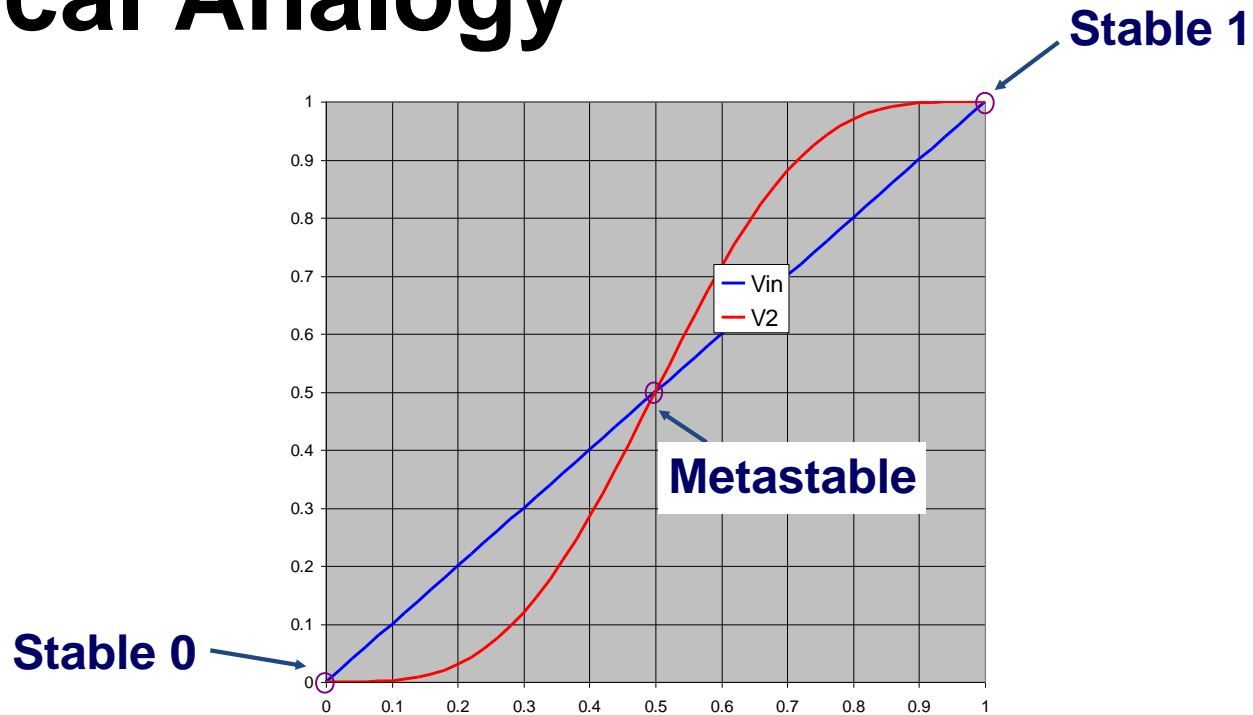
## Bistable Element



Stable 0

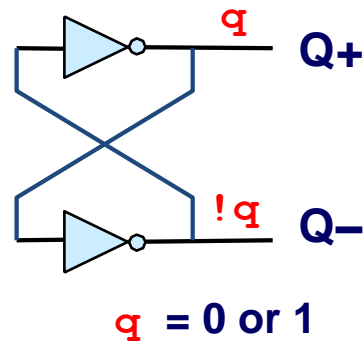


# Physical Analogy

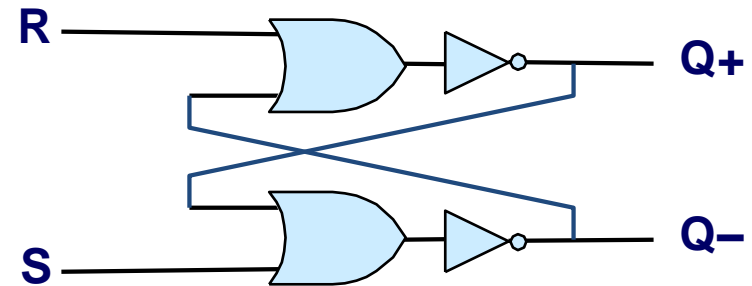


# Storing and Accessing 1 Bit

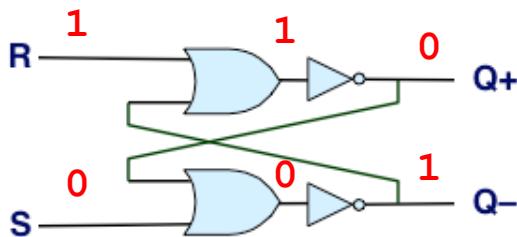
## Bistable Element



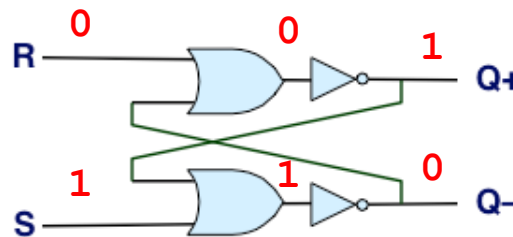
## R-S Latch



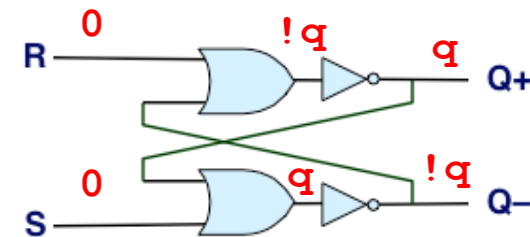
## Resetting



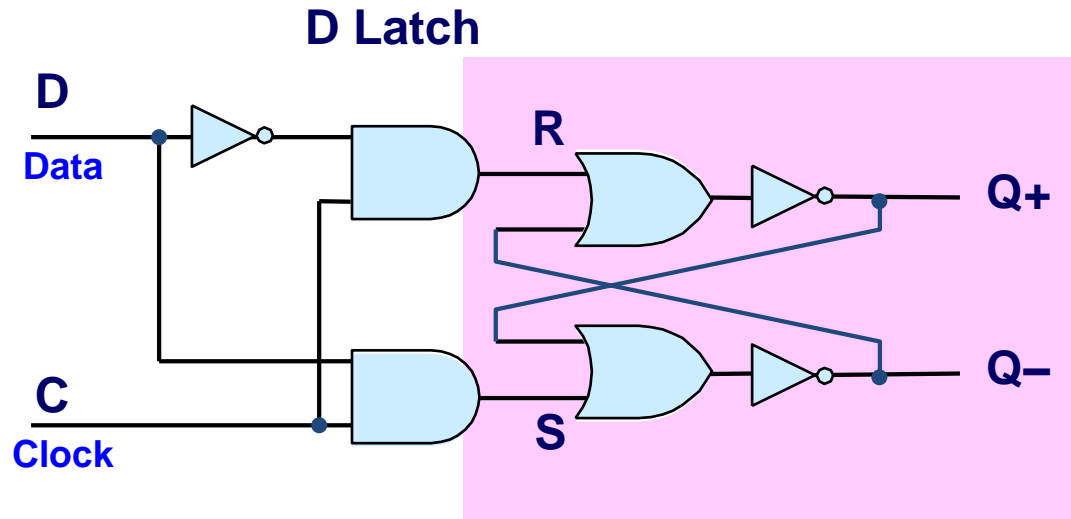
## Setting



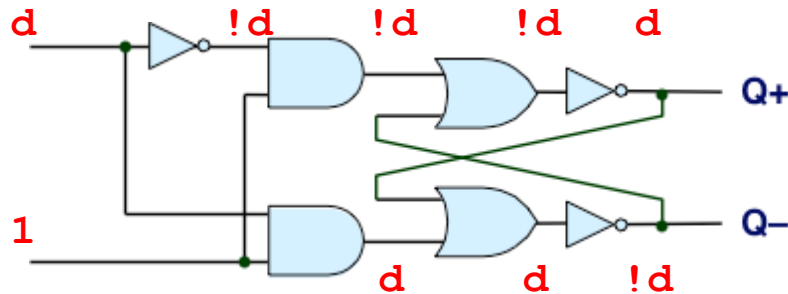
## Storing



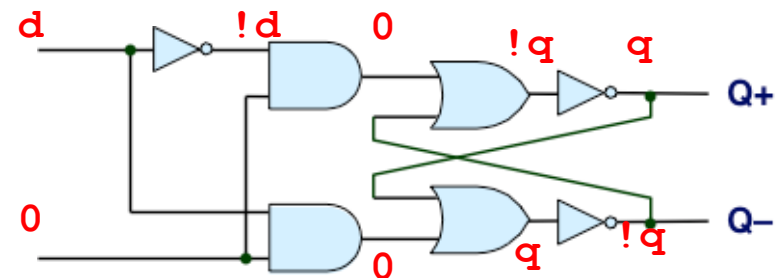
# 1-Bit Latch



## Latching

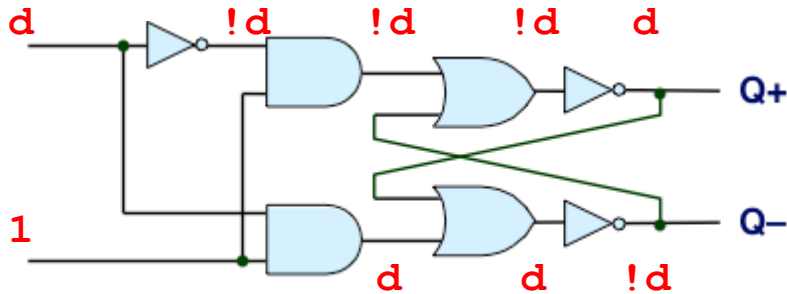


## Storing

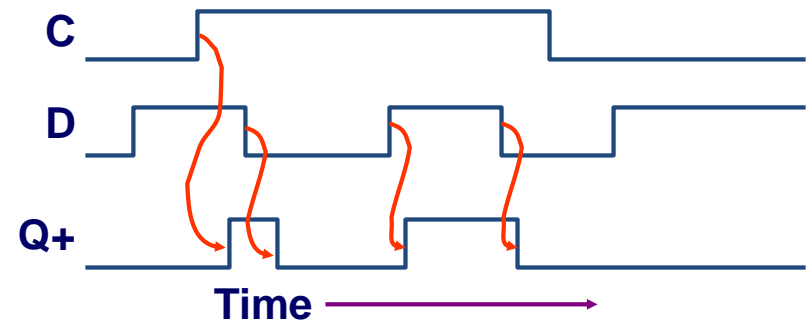


# Transparent 1-Bit Latch

## Latching

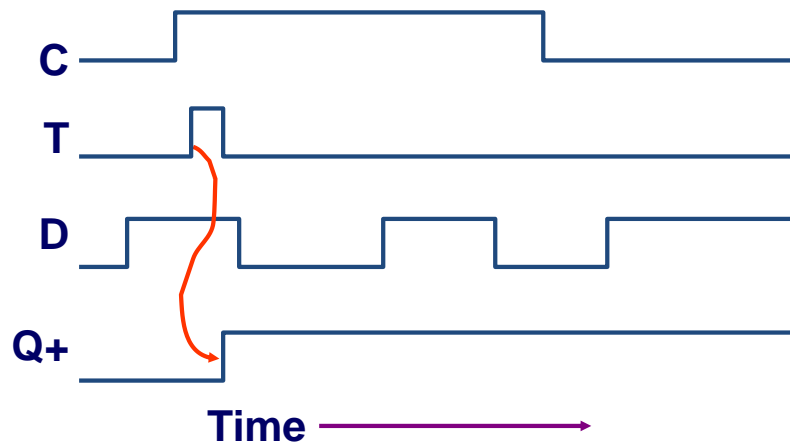
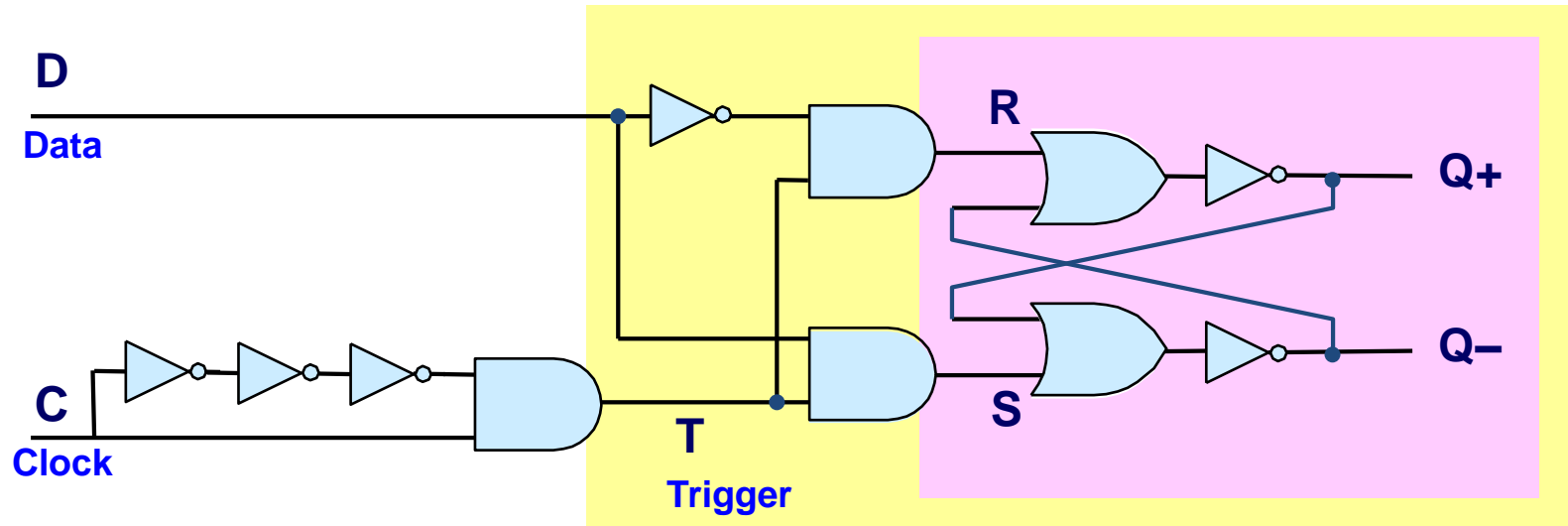


## Changing D



- When in latching mode, combinational propagation from  $D$  to  $Q+$  and  $Q-$
- Value latched depends on value of  $D$  as  $C$  falls

# Edge-Triggered Latch



- Only in latching mode for brief period
  - Rising clock edge
- Value latched depends on data as clock rises
- Output remains stable at all other times