1.1

1.1 Matrices over Finite Fields

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Throughout this report p is assumed to be prime.

All programs are attached at the end of the report.

Question 1:

A typical test output is shown below.



Figure 1, a typical output for p = 11 case.

To speed up this procedure we can skip all values that are already other numbers' inverses when computing a number's inverse. This still gives the inverse of each number since there is a 1 - 1 correspondence between numbers and their inverses mod p but upper bounds the number of operations for number i by p-i. This modification speeds up the procedure by a factor of 2 because there

are at most
$$\sum_{i=1}^{p-1} i = \frac{(p-2)(p-1)}{2}$$
 operations.(cf. Question 2)

Question 2:

Note that for each number there are at most p-1 operations, and there are p-1numbers to test. Hence the complexity is p^2 .

Question 3:

Using a program that reduces a matrix into its row echelon form, we produce the following row echelon forms for different matrices:

$$\begin{bmatrix} 1 & 0 & 3 & 0 & 0 \\ 0 & 1 & 7 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & 0 & 0 & 13 \\ 0 & 1 & 0 & 0 & 6 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & 0 & 9 & 11 & 19 \\ 0 & 1 & 0 & 10 & 5 & 5 \\ 0 & 0 & 1 & 9 & 14 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$p = 11 \text{ case} \qquad p = 19 \text{ case} \qquad p = 23 \text{ case}$$

Since row operations do not alter the row space of a matrix, we see that matrix A_1 has rank 4 when p=11 or 19 and matrix A_2 has rank 3 when p=23. The bases for row spaces of matrices A_1 and A_2 for different p can be read off from their row echelon forms:

$$B_{A_{1},11} = \left\{ \begin{bmatrix} 1\\0\\3\\0\\0\\0 \end{bmatrix}^{T}, \begin{bmatrix} 0\\1\\7\\0\\0\\0 \end{bmatrix}^{T}, \begin{bmatrix} 0\\0\\0\\1\\0 \end{bmatrix}^{T}, \begin{bmatrix} 0\\0\\0\\0\\1 \end{bmatrix}^{T} \right\} \quad B_{A_{1},19} = \left\{ \begin{bmatrix} 1\\0\\0\\0\\13 \end{bmatrix}^{T}, \begin{bmatrix} 0\\0\\1\\0\\0\\3 \end{bmatrix}^{T}, \begin{bmatrix} 0\\0\\0\\1\\1\\1 \end{bmatrix}^{T} \right\}$$

$$B_{A_2,23} = \left\{ \begin{bmatrix} 1\\0\\0\\9\\11\\19 \end{bmatrix}^T, \begin{bmatrix} 0\\1\\0\\10\\5\\5 \end{bmatrix}^T, \begin{bmatrix} 0\\0\\1\\9\\14\\7 \end{bmatrix}^T \right\}, \text{ where } T \text{ denotes tranpose.}$$

Question 4:

A program that outputs the basis of the kernel of a matrix is written for Question

4. The outputs of the program for different examples are shown below:

$$\left\{ \begin{bmatrix} 7\\2\\1\\2\\1 \end{bmatrix} \right\} \qquad \left\{ \begin{bmatrix} 0\\0\\0\\0\\0 \end{bmatrix} \right\} \qquad \left\{ \begin{bmatrix} 6\\6\\9\\9\\9\\1 \end{bmatrix} \right\}$$

$$0 = 13 \text{ case} \quad p = 17 \text{ case} \quad p = 23 \text{ case}$$

My program for this question works as follows:

- 1: Transform the matrix into row echelon form.
- 2: Eliminate all rows with zero entries.
- 3: From the result in step 2, use Matlab's symbolic expression feature to express all pivotal variables in terms of other variables inductively.
- 4: Assign specific values to non-pivotal variables to obtain a basis. (Let one variable =1 and others =0.)

Question 5:

The sum of the dimension of U and the dimension of U^o is equal to the number of columns of the matrix.

Question 6:

For U the row space of $A_1 \mod 19$, U^o is the kernel of A_1 . Use the program for question 4 we find it to be $\left\{ \begin{bmatrix} 6 & 13 & 16 & 18 & 1 \end{bmatrix}^T \right\}$.

The annihilator of U^o , $(U^o)^o$, is the set of all row vectors **t** such that $\mathbf{ts} = 0$, where **s** is the basis vector we just found. By taking the transpose of this relation we have $\mathbf{s}^T \mathbf{t}^T = 0$, i.e. \mathbf{t}^T is in the kernel of the matrix $\begin{bmatrix} 6 & 13 & 16 & 18 & 1 \end{bmatrix}$.

Using the program for question 4 we find that $(U^{o})^{o}$ has a basis

$$B_{(U^{\circ})^{\circ},19} = \left\{ \begin{bmatrix} 1\\1\\0\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 10\\0\\1\\0\\0 \end{bmatrix}^{T}, \begin{bmatrix} 16\\0\\0\\1\\0\\0 \end{bmatrix}^{T}, \begin{bmatrix} 3\\0\\0\\0\\1\\0 \end{bmatrix}^{T} \right\}$$

To show that A_1 spans the row space of $B_{(U^o)^o,19}$, we put these basis vectors and rows in the row echelon form of A_1 in one matrix and perform Gaussian elimination: (using program from question 1)

From the result of Gaussian elimination we can see that all basis vectors of $(U^o)^o$ are in the row space of A_1 . Since $(U^o)^o$ and A_1 have the same dimension we conclude that they are equal.

Question 7:

A program is written for Quesiton 7. The program takes 2 matrices and a prime number p as inputs and outputs their row spaces, the intersection and the sum of their row spaces.

My program for this question works as follows:

- 1. Transform the input matrices A and B into row echelon forms to obtain bases for their row spaces.
- 2. Join the two matrices obtained in step 1 together to obtain a new matrix consisting of a spanning set of U + W, where U and W are row spaces of the input matrices.
- 3. Perform Gaussian elimination on the new matrix to obtain a basis for U+W
- 4. Find bases for the kernels of the two input matrices and transpose them. Apply step 1, 2, 3 to obtain a matrix H consisting of a transposed basis for

 $U^o + W^o$. The kernel of the matrix H is $(U^o + W^o)^o = U \cap W$, which can be found by using the program for question 4.

The outputs of the program for different examples are shown below: (X, Y, Z, and W represent bases for U, W, U + W and $U \cap W$) When $A = A_1$, $B = B_1$, p = 11:

$$X = \left\{ \begin{bmatrix} 1 \\ 0 \\ 3 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 7 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}^{T} \right\}, \qquad Y = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 2 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 3 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 4 \\ 0 \end{bmatrix}^{T} \right\}$$

$$Z = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}^{T} \right\} \qquad W = \left\{ \begin{bmatrix} 7 \\ 5 \\ 1 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 8 \\ 6 \\ 0 \\ 1 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}^{T} \right\}$$

When $A = A_3$, $B = Ker(A_3)$, p = 19:

$$X = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 3 \\ 14 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 16 \\ 9 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 17 \\ 6 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 17 \\ 6 \end{bmatrix}^{T} \right\}, \qquad Y = \left\{ \begin{bmatrix} 1 \\ 0 \\ 9 \\ 18 \\ 6 \\ 1 \\ 12 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 2 \\ 0 \\ 4 \\ 14 \end{bmatrix}^{T} \right\}$$

$$Z = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T} \right\}, \qquad W = \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}^{T}\right\}$$

When $A = A_3$, $B = Ker(A_3)$, p = 23:

The relation between the dimensions of U, W, U + W and $U \cap W$ is $\dim(U) + \dim(W) - \dim(U \cap W) = \dim(U + W)$, where dim denotes dimension.

Question 8:

There are 2 surprising features:

- 1. The dimensions of U+W and $U\cap W$ change with respect to different modules. This is surprising since dimension of a space is unique for the real field.
- 2. There exists a nontrivial kernel vector that is a linear combination of row vectors. This is surprising since, for the real field, there is Gram-Schmidt process that reduces a basis to an orthonormal basis by defining the canonical inner product, which implies that all nontrivial linear combination of row vectors cannot be sent to 0 by the matrix.

Reference

Source Code

```
Callings of functions:
\mathbf{A} = [0,1,7,2,10;8,0,2,5,1;2,1,2,5,5;7,4,5,3,0]\% \mathbf{A} \mathbf{1}
B = [6,16,11,14,1,4;7,9,1,1,21,0;8,2,9,12,17,7;2,19,2,19,7,12]\%A2
C = [4,6,5,2,3;5,0,3,0,1;1,5,7,1,0;5,5,0,3,1;2,1,2,4,0]\%B1
D = [3,7,19,3,9,6;10,2,20,15,3,0;14,1,3,14,11,3;26,1,21,6,3,5;0,1,3,19,0,3]\%B2
L = [1,0,0,0,3,0,0;0,5,0,1,6,3,0;0,0,5,0,2,0,0;2,4,0,0,0,5,1;4,3,0,0,6,2,6]\%A3
s = transpose(KernelBasis(L,19))%kernel of A3 mod 19
t = transpose(KernelBasis(L,23))%kernel of A3 mod 23
\%Q3
GaussE(A,11)
GaussE(A,19)
GaussE(B,23)
\%Q4
KernelBasis(C,13)
KernelBasis(C,17)
KernelBasis(D,23)
\%Q7
[q,w,e,r] = SumIntersection(A,C,11)
[a,b,c,d] = SumIntersection(L,s,19)
[t,y,u,i] = SumIntersection(L,t,23)
Code for Question 1:
function [Inv]=InverseModP(p)
Inv = zeros(1,p-1);
for i = 1:p-1
for j = 1:p-1
if mod(i*j,p)==1
```

```
\quad \text{end} \quad
end
end
Code for Question 3:
function [F]=OneStep(B,p,Inv)% one step of gaussian elimination: reduce a
submatrix such that the (1,1) entry is 1 and there is only 1 non-zero entry in
the first column
d = size(B);
r = d(1);
c = d(2);
s=0;
E=B;
if B == zeros(r,c)
F=B;
else
for i=1:c
s=i;
if B(1:r,1) = = zeros(r,1)
x = size(B);
B = B(1:r,2:(x(2)));
else
break
end
end
if B(1,1) = 0
for k=2:r
if B(k,1) = 0
z=B(k,:);B(k,:)=B(1,:);B(1,:)=z;
B(1,:)=mod(B(1,:)*Inv(B(1,1)),p);
break
end
end
else
B(1,:)=mod(B(1,:)*Inv(B(1,1)),p);
\quad \text{end} \quad
for j=2:r
B(j,\!:)\!\!=\!\! \operatorname{mod}(B(j,\!:)\!\!-\!\! (B(j,\!1))^*\!(B(1,\!:)),\!p);
end
E(1:r,s:c)=B;
F=E;
\quad \text{end} \quad
end
```

Inv(i)=j;

function [R]=Gauss E(A,p)% apply OneStep function to submatrices of the orig-

```
\begin{split} &\operatorname{inal\ matrix}\\ d = \operatorname{size}(A);\\ r = d(1);\\ c = d(2);\\ t = &\operatorname{InverseModP}(p);\\ &\operatorname{for\ } i = 1:r\\ &\operatorname{try\ \%Use\ try\ to\ deal\ with\ empty\ matrix!}\\ A(i:r,i:c) &= &\operatorname{OneStep}(A(i:r,i:c),p,t);\\ R = &A;\\ &\operatorname{catch}\\ &\operatorname{break}\\ &\operatorname{end}\\ &\operatorname{end}\\ &\operatorname{end} \end{split}
```

Code for Question 4:

```
function [B]=KernelBasis(A,p)
R = GaussE(A,p); \% Reduced\ matrix
d = size(R);
r = d(1);
c = d(2);
u = 0;
for i = 1:r
if R(i,1:c) = = zeros(1,c)
u = u;
else
u = u + 1;
end
end
R = R(1:u,1:c);%ignore all 0 rows
d = size(R);
r = d(1);
c = d(2);
for i = 1:c
x(i)=sym(['x',num2str(i)]);
\quad \text{end} \quad
for i = r:-1:1 \% find algebraic expressions of non-pivotal vars.
for j = 1:c
if R(i,j) == 0
continue
else
if i == c
x(c)=0;
else
s = 0;
```

```
for k = j+1:c
s = s - R(i,k)*x(k);
end
x(j) = s;
break
end
end
end
end
q = zeros(1,c);
for i = 1:r % storing indices of non-pivotal vars
for j = 1:c
if R(i,j) == 0
continue
else
q(j) = 1;
break
end
\quad \text{end} \quad
end
for i = 1:c
for j = 1:c
C(i,j) = sym(['x',num2str(1),num2str(j)]);
end
\quad \text{end} \quad
D=C;
v = transpose(C(1,1:c));
if q == ones(1,c)
C = zeros(c,1);
else
for i = 1:c
if q(i) == 1
continue
else \%q(i)==0
z = subs(x,x(i),1);%substitute
for j = 1:c
if (q(j) == 0) & (j = i)
z = subs(z, z(j), 0);
end
C(i,1:c)=z;
end
end
end
end
C = transpose(C);
if q == ones(1,c)
```

```
else
for i=1:c
d = size(C);
f = d(2);
for j = 1:f
if C(1:c,j) == v
C(:,j)=[];
break
end
end
end
end
try
C(1,1)%test if C is an empty matrix and use 'try' to deal with the case where
C is empty
B=mod(C,p);
catch
B = zeros(c,1);
end%there is some redundancy in the last 40 lines but this program works for
all questions.
Code for Question 7:
function [A,B,C,D] = SumIntersection(Q,R,p)%A,B are row spaces of Q and R,
C = Q + R, D = Q intersection R
A = GaussE(Q,p);
B = GaussE(R,p);
c = size(A);
d = size(B);
G = zeros(c(1)+d(1),c(2));%Initialize a zero matrix
for i = 1:c(1)
G(i,1:c(2)) = A(i,1:c(2));
end
for i = 1:d(1)
G(c(1) + i,1:c(2)) = B(i,1:c(2));
end
C = GaussE(G,p);
clear c
clear d
N = KernelBasis(Q,p);
M = KernelBasis(R,p);
N = transpose(N);
```

C = zeros(c,1);

M = transpose(M);c = size(N);

```
\begin{split} d &= size(M); \\ H &= zeros(c(1) + d(1), c(2)); \\ for & i = 1 {:} c(1) \\ H(i, 1 {:} c(2)) &= N(i, 1 {:} c(2)); \\ end \\ for & i = 1 {:} d(1) \\ H(c(1) + i, 1 {:} c(2)) &= M(i, 1 {:} c(2)); \\ end \\ S &= KernelBasis(H,p); \\ D &= transpose(S); \\ end \end{split}
```