```
floatx,y,z,temp; voidsetup()
{
 pinMode(8,INPUT);
 pinMode(5,OUTPUT);
 pinMode(6,OUTPUT);
 pinMode(A5,INPUT);
 pinMode(A4,INPUT);
 Serial.begin(9600);
}
voidloop()
{
 x=digitalRead(8);
 y=analogRead(A5);
 z=analogRead(A4);
 Serial.println(x);
 Serial.println(y); Serial.println(z);
 temp=(double)z/1024;
 temp=temp*5; temp=temp-0.5;
 temp=temp*100;
 if((x>0))
   if((y<550)&&(temp>30))
    digitalWrite(5,HIGH);
    digitalWrite(6,HIGH);
```

```
}
 elseif((y<550)&&(temp<30))
  digitalWrite(5,HIGH);
  digitalWrite(6,LOW);
 }
 elseif((y>550)&&(temp>30))
 {
  digitalWrite(5,LOW);
  digitalWrite(6,HIGH);
 }
 elseif((y>550)&&(temp<30))
 {
  digitalWrite(5,LOW);
  digitalWrite(6,LOW);
 }
}
else
 digitalWrite(5,LOW);
 digitalWrite(6,LOW);
}
```

}