

Part 1.

1. Closed form LSE method

$$\text{goal: } \operatorname{argmin} \left(\sum_i (y_i - f(x_i))^2 \right) = \operatorname{argmin} \|A\vec{x} - \vec{b}\|^2 \quad \text{where } \begin{array}{l} A \in \mathbb{R}^{m \times n} \\ \vec{b} \in \mathbb{R}^m \end{array}$$

$$\|A\vec{x} - \vec{b}\|^2 = (A\vec{x} - \vec{b})^T (A\vec{x} - \vec{b}) \quad \vec{x} \in \mathbb{R}^n$$

$$= (\vec{x}^T A^T - \vec{b}^T) (A\vec{x} - \vec{b})$$

$$= \vec{x}^T A^T A \vec{x} - \vec{x}^T A^T \vec{b} - \vec{b}^T A \vec{x} + \vec{b}^T \vec{b}$$

$$\left(\begin{array}{l} \text{since } \underbrace{\vec{x}^T A^T \vec{b}}_{1 \times n \quad n \times m \quad m \times 1} \text{ and } \underbrace{\vec{b}^T A \vec{x}}_{1 \times m \quad m \times n \quad n \times 1} \text{ is } 1 \times 1 \text{ (scalar)} \\ \text{so } (A\vec{x})^T \vec{b} = (\vec{b}^T (A\vec{x}))^T = \vec{b}^T A \vec{x} \end{array} \right)$$

$$= \vec{x}^T A^T A \vec{x} - 2\vec{b}^T A \vec{x} + \vec{b}^T \vec{b}$$

$$\text{Let } g = \vec{x}^T A^T A \vec{x} - 2\vec{b}^T A \vec{x} + \vec{b}^T \vec{b}$$

$$\frac{\partial g}{\partial \vec{x}} = 2A^T A \vec{x} - 2A^T \vec{b} \stackrel{!}{=} 0$$

$$\vec{x} = (A^T A)^{-1} A^T \vec{b} \quad \#$$

add λ L2 norm

$$g := \|A\vec{x} - \vec{b}\|^2 + \lambda \|\vec{x}\|^2 = \vec{x}^T A^T A \vec{x} - 2\vec{b}^T A \vec{x} + \vec{b}^T \vec{b} + \lambda \|\vec{x}\|^2$$

$$\frac{\partial g}{\partial \vec{x}} = 2A^T A \vec{x} - 2A^T \vec{b} + 2\lambda \vec{x} \stackrel{!}{=} 0$$

$$\vec{x} = (A^T A + \lambda I)^{-1} A^T \vec{b} \quad \#$$

2. Steepest descent method

Let initial point x_0

learning rate α

$$x_1 = x_0 - \alpha \cdot \frac{\nabla f(x_0)}{\|\nabla f(x_0)\|}$$

: continue iterating until $\nabla f(x_0) \approx 0$

$$x_n = x_{n-1} - \alpha \cdot \frac{\nabla f(x_{n-1})}{\|\nabla f(x_{n-1})\|}$$

"steepest"

$f: \mathbb{R}^n \rightarrow \mathbb{R}$, $x_0 \in \mathbb{R}^n$ and $\text{dir}(\nabla f(x_0)) = v$

$$\left. \frac{\partial f(x)}{\partial v} \right|_{x=x_0} := (\nabla f(x_0))^T \frac{v}{\|v\|}$$

By Cauchy - Schwarz inequality ($|x^T y| \leq \|x\| \|y\|$)

$$\left| (\nabla f(x_0))^T \frac{v}{\|v\|} \right| \leq \|\nabla f(x_0)\| \frac{\|v\|}{\|v\|}$$

if $v = \nabla f(x_0)$

$$\left| (\nabla f(x_0))^T \cdot \frac{\nabla f(x_0)}{\|\nabla f(x_0)\|} \right| \leq \|\nabla f(x_0)\|$$

$$\Rightarrow \frac{\|\nabla f(x_0)\|^2}{\|\nabla f(x_0)\|} \leq \|\nabla f(x_0)\|$$

when the equation holds, $v = \nabla f(x_0)$

So, $\nabla f(x_0)$ is the steepest.

In this homework,

f is LSE + L1 norm

$$f(x) = \|Ax - b\|^2 + \lambda \|x\|$$

$$= (Ax - b)^T (Ax - b) + \lambda \|x\|$$

$$= \vec{x}^T A^T A \vec{x} - 2 \vec{b}^T A \vec{x} + \vec{b}^T \vec{b} + \lambda \|\vec{x}\|$$

$$\nabla f = 2A^T A \vec{x} - 2A^T \vec{b} + \lambda \cdot \text{sgn}(\vec{x})$$

3. Newton's Method

$$x_1 = x_0 - \frac{f'(x_0)}{f''(x_0)} = x_0 - Hf(x_0)^{-1} \nabla f(x_0)$$

$$\text{where } Hf(x) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_0^2} & \frac{\partial^2 f}{\partial x_0 \partial x_1} & \dots \\ \frac{\partial^2 f}{\partial x_1 \partial x_0} & \dots & \\ \vdots & & \end{bmatrix}$$

$$x_2 = x_1 - \frac{f'(x_1)}{f''(x_1)}$$

\vdots continue iterating until the difference $\Delta x = x_n - x_{n-1}$ is small enough

$$x_n = x_{n-1} - \frac{f'(x_{n-1})}{f''(x_{n-1})}$$

$$f(\vec{x}) = \|A\vec{x} - \vec{b}\|^2 = \vec{x}^T A^T A \vec{x} - 2\vec{x}^T A^T \vec{b} + \vec{b}^T \vec{b}$$

$$\nabla f(\vec{x}) = 2A^T A \vec{x} - 2A^T \vec{b}$$

$$Hf(\vec{x}) = 2A^T A$$

$$\vec{x}_1 = \vec{x}_0 - (2A^T A)^{-1} (2A^T A \vec{x}_0 - 2A^T \vec{b})$$

$$\vec{x}_2 = \vec{x}_1 - (2A^T A)^{-1} (2A^T A \vec{x}_1 - 2A^T \vec{b})$$

\vdots

$$\vec{x}_n = \vec{x}_{n-1} - (2A^T A)^{-1} (2A^T A \vec{x}_{n-1} - 2A^T \vec{b})$$