SUPPLEMENTARY MATERIAL: AUDIO IMAGE GENERATION FOR DENOISING

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1. TRAINING ALGORITHM

Alg. 1 shows the overall training algorithm of our model.

Algorithm 1 The training process of AIGD model

- 1: **Input:** Noise audio signal x, clean audio signal y, and AIGD model $F(\cdot, \cdot, \theta)$.
- 2: **Output:** Trained image generator $F(\cdot, \cdot, \theta)$
- 3: Generate noisy audio image I_N and clean audio images I using STFT(x) and STFT(y)
- 4: **while** θ is not converged **do**
- 5: **for** $t = T 1, \dots, 1$ **do**
- 6: Sample I^t using Eq. (17)
- 7: end for
- 8: Predict denoised image $\hat{I} = F(I^1, 1, \theta)$
- 9: Compute gradient using the objective function in Eq. (24)
- 10: Update θ by gradient
- 11: end while

2. RESULTS ON DNS 2020 CHALLENGE DATASET AND BIRDSOUNDSDENOISING DATASET

As shown in Tab. 1, our AIGD model outperforms all other state-of-the-art models in all four metrics. Especially, the PESQ metrics are much higher than other models, which further reveals that our AIGD model achieves state-of-the-art performance in audio-denoising tasks. In Tab. 3, we ignored the F1, IoU, and Dice scores, given the original paper treated it as an image segmentation problem. Our AIGD model also achieves the highest SDR score of all the models. Therefore, the AIGD model also performs better in a real-world bird sound denoising dataset.

3. MORE RESULTS

Computation time. We also list the computation time of our AIGD model across three datasets, as shown in Tab. 2. Given our AIGD model has the T steps generation process, the computation time for each audio is increased during the

training. Across three datasets, the mean computing time of training per audio is around 2.4 minutes. The major reason is due to the diffusion process and the gradient computation. Our mean inference time of the three datasets is 1.07 seconds per audio. However, compared with the best baseline methods MANNER [1], FS-CANet [2] and PtDeepLab [3] of three benchmark datasets respectively, the computation cost of our AIGD model is still in a reasonable range.

$$L = \mathcal{C}L_2 + \alpha L_{im}^{total} + (1 - \alpha)L_R, \tag{1}$$

$$L_S = 1 - abs(SSIM(F(I_N), I)) = \{1 - abs(SSIM(F(I_N), I)) + 1 - abs(SSIM$$

$$L_R = const_{upper} - SDR(\hat{y}, y) \tag{3}$$

Parameters analysis. In Eq. (1), α balances the image quality check loss and audio reconstruction loss. We first conduct the parameter analysis of α , which is selected from $\{0, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1\}$. "0" means that we only minimize the reconstruction loss, while "1" means that we only minimize the image check model. As shown in Fig. 1a, we chose $\alpha = 0.5$ as our best hyperparameter since PESQ achieves the highest value. Next, we explore the relationship among PESQ, SDR, and SSIM metrics. We defined complex absolute structural similarity loss L_S and reconstruction loss L_B in Eqs. (2) and (3), the lower of these two loss functions, the better the denoised results. While the higher SDR, SSIM, and PESQ, the better the results since they measure the closeness between the predictions and ground truth. As shown in Fig. 1b, with the increasing number of iterations, SSIM and PESQ converged fast and approached the highest value (1 and 4.5). Although there are some oscillations at the end of the SDR value, it is still converged, and the highest value is 25.39. Hence, we set the upper bound of reconstruction in Eq. (3) as 30.

Ablation study. To demonstrate the effectiveness of the proposed three loss functions: complex L2 norm (2), complex absolute structure similarity (S), and reconstruction (R), we conduct an ablation study with respect to each loss in Tab. 4.

Table 1. Comparison results on Divis 2020 chancing test dataset.										
Methods	With Reverb				Without Reverb					
	WB-PESQ	NB-PESQ	STOI	SI-SDR	WB-PESQ	NB-PESQ	STOI	SI-SDR		
Noisy	1.822	2.753	86.62	9.033	1.582	2.454	91.52	9.071		
DTLN [4]	-	2.700	84.68	10.530	-	3.040	94.76	16.340		
PoCoNet [5]	2.832	-	-	-	2.748	-	-	-		
Sub-band Model [6]	2.650	3.274	90.53	14.673	2.369	3.052	94.24	16.153		
FullSubNet [7]	2.969	3.473	92.62	15.750	2.777	3.305	96.11	17.290		
FullSubNet+ [8]	3.218	3.666	93.84	16.810	2.982	3.504	96.69	18.340		
FS-CANet [2]	3.218	3.665	93.93	16.820	3.017	3.513	96.74	18.080		
AIGD	3.381	3.912	95.02	18.213	3.351	4.013	98.31	20.123		

Table 1: Comparison results on DNS 2020 challenge test dataset

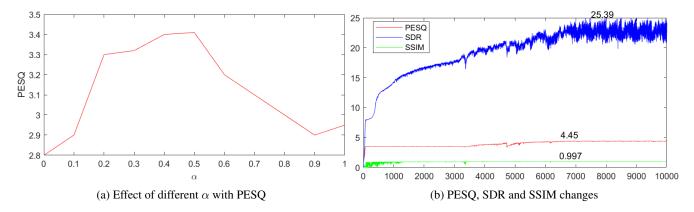


Fig. 1: (a): parameter analysis for α . (b): PESQ, SDR, and SSIM change with the increase of training iterations (10,000). The highest values are plotted for each line.

Table 2: Computation time (per audio) of three benchmark datasets (M: minutes, S: seconds, Voice: VoiceBank-DEMAND, DNS: DNS 2020 challenge, Bird: BirdSoundsDenoising).

Time	Voice		DN	S	Bird			
	Trainin	g Test	Trainin	g Test	Training	Validatio	n Test	
MANNER [1]	1.04	0.86	-	-	-	-	-	
FS-CANet [2]	-	-	1.84	0.83	-	-	-	
PtDeepLab [3]	-	-	-	-	0.99	0.79	0.82	
AIGD	2.03	1.09	3.12	1.17	1.98	1.02	1.03	

"+" means combining loss functions together. We observe that with the increasing number of loss functions, the robustness of our model keeps improving. The usefulness of loss functions is ranked as 2 > R > S. Therefore, the proposed audio image generation denoising approach is effective in improving performance, and different loss functions are helpful and important in minimizing the error between predictions and ground truth.

Reflection. From all results, we can conclude that our proposed AIGD model achieves state-of-the-art performance, which also demonstrates the superiority of the proposed architecture and novel loss functions.

One weakness of our model is that it requires a high amount of GPU memory to train the model. Our AIGD model has 35M parameters, and it took around five hours per epoch,

Table 3: Results comparisons of different methods (F1, IoU, and Dice scores are multiplied by 100. "—" means not applicable.

	Validation				Test			
Networks	$\overline{F1}$	IoU	JDice	eSDR	F1	IoU	UDice	eSDR
U ² -Net [9]	60.8	345.2	260.6	7.85	60.2	244.8	359.9	7.70
MTU-NeT [10]	69.1	56.5	569.0	8.17	68.3	355.7	768.3	7.96
Segmenter [11]	72.6	559.6	572.5	9.24	70.8	857.7	770.7	8.52
SegNet [12]	77.5	66.9	977.5	9.55	76.	165.3	376.2	9.43
DVAD [13]	82.6	573.5	582.6	10.3	81.6	572.3	381.6	9.96
PtDeepLab [3]	83.4	175.9	983.4	10.5	83.	175.4	183.0	10.4
AIGD	_	_	_	11.5	_	_	_	10.8

Table 4: Ablation study of different loss functions $\frac{\text{Methods 2 S R 2+S S+R 2+R 2+S+R}}{\text{PESQ} 3.25 2.50 2.89 3.28 2.95 3.31 3.52}$

but less than one second per audio for the inference.

4. REFERENCES

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