

Summary

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0. Structure of What we've learned.

	Electrostatics	Magnetostatics
Maxwell's Equation	$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ ① $\nabla \times \vec{E} = 0$ ②	$\nabla \cdot \vec{B} = 0$ ③ $\nabla \times \vec{B} = \mu_0 \vec{J}$ ④
Superposition & Symmetry (Gauss)	$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \rho(r') \frac{\vec{r} - \vec{r}'}{ \vec{r} - \vec{r}' ^3} d\tau'$ $\phi \vec{E} \cdot d\vec{a} = \frac{Q_{enc}}{\epsilon_0}$	(Biot-Savart) $\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}' \times (\vec{r} - \vec{r}')}{ \vec{r} - \vec{r}' ^3}$ (Ampere) $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$
Boundary Conditions	$E_{\perp out} - E_{\perp in} = \frac{\sigma}{\epsilon_0}$ (from ①) $E_{ out} = E_{ in}$ (from ②)	$B_{\perp out} = B_{\perp in}$ (from ③) $B_{ out} - B_{ in} = \mu_0 \vec{K} \times \hat{n}$ (from ④)
Potential & Relation (Poisson)	$\nabla \times \vec{E} = 0 \Rightarrow \vec{E} = -\nabla V$ $V = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(r') d\tau'}{ \vec{r} - \vec{r}' }$ $\nabla^2 V = -\frac{\rho}{\epsilon_0}$ (from ①)	$\nabla \cdot \vec{B} = 0 \Rightarrow \vec{B} = \nabla \times \vec{A}$ $\vec{A}(r) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(r') d\tau'}{ \vec{r} - \vec{r}' }$ (3 equations:) $\nabla^2 \vec{A} = -\mu_0 \vec{J}$ (from ④)
Multiple Expansion & Dipole	$V = \frac{1}{4\pi\epsilon_0} \int \rho(r') d\tau' \sum_n \frac{(r')^n}{r^{n+1}} P_n(\cos\theta)$ $\vec{P} = \int \vec{r}' \rho(r') d\tau'$ $V_{dip} = \frac{1}{4\pi\epsilon_0} \frac{\vec{P} \cdot \hat{r}}{r^2}$	$\vec{A} = \frac{\mu_0 I}{4\pi} \int d\vec{l}' \sum_n \frac{(r')^n}{r^{n+1}} P_n(\cos\theta)$ $\vec{m} = I \int d\vec{a}$ $\vec{A}_{dip} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$
Field in Matter	$\vec{P} \equiv$ dipole moment per volume $\vec{D} := \epsilon_0 \vec{E} + \vec{P}$ s.t. $\left\{ \begin{array}{l} \nabla \cdot \vec{D} = \rho_f \\ \nabla \times \vec{D} = \nabla \times \vec{P} \text{ not necessarily } 0 \\ D_{\perp out} - D_{\perp in} = \sigma_f \\ D_{ out} - D_{ in} = P_{ out} - P_{ in} \end{array} \right.$	$\vec{M} \equiv$ dipole moment per volume $\vec{H} := \frac{\vec{B}}{\mu_0} - \vec{M}$ s.t. $\left\{ \begin{array}{l} \nabla \cdot \vec{H} = -\nabla \cdot \vec{M} \text{ not necessarily } 0 \\ \nabla \times \vec{H} = \vec{J}_f \\ H_{\perp out} - H_{\perp in} = -(M_{\perp out} - M_{\perp in}) \\ H_{ out} - H_{ in} = \vec{K}_f \times \hat{n} \end{array} \right.$
Bound Charge/Current	$\rho_b = -\nabla \cdot \vec{P}$ $\sigma_b = \vec{P} \cdot \hat{n}$ (\hat{n} out of material)	$\vec{J}_b = \nabla \times \vec{M}$ $\vec{K}_b = \vec{M} \times \hat{n}$
Linear Material	$\vec{P} = \chi_e \vec{E} \Rightarrow \vec{D} = \epsilon_0 (1 + \chi_e) \vec{E} = \epsilon \vec{E}$ $\rho_b = -\nabla \cdot \left(\frac{\chi_e}{1 + \chi_e} \vec{D} \right) = -\frac{\chi_e}{1 + \chi_e} \rho_f$ $\rho_f = 0 \Rightarrow \rho_b = 0 \Rightarrow \nabla^2 V = 0$ $\nabla \times \vec{P} = \chi_e \nabla \times \vec{E} = 0$	$\vec{M} = \chi_m \vec{H} \Rightarrow \vec{B} = \mu_0 (1 + \chi_m) \vec{H} = \mu \vec{H}$ $\vec{J}_b = \nabla \times (\chi_m \vec{H}) = \chi_m \vec{J}_f$ $\vec{J}_f = 0 \Rightarrow \nabla \times \vec{H} = 0 \Rightarrow \vec{H} = -\nabla V$ $\nabla \cdot \vec{M} = \frac{1}{\mu_0} \frac{\chi_m}{1 + \chi_m} \nabla \cdot \vec{B} = 0 \Rightarrow \nabla^2 V = \nabla \cdot \vec{M} = 0$
Solving Problem	1) Image Charge 2) $\nabla^2 V = 0 \Rightarrow$ Laplace Equation	$\nabla^2 V = 0 \Rightarrow$ Laplace Equation $-\nabla V = \vec{H}$ (it also applies to \vec{B})

1. Electric Field

1.1 Superposition

$$E(\vec{r}) = \frac{Q}{4\pi\epsilon_0} \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}, \text{ for a point charge located at } \vec{r}'$$

Discrete: $E(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_i q_i \frac{\vec{r} - \vec{r}_i}{|\vec{r} - \vec{r}_i|^3}$
 Continuous: $E(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \rho(\vec{r}') \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} d\tau'$

1.2 Gauss' Law

Conditions: Symmetry \Rightarrow constant field over surface

Infinite line: $\vec{E}(\vec{r}) = \frac{\lambda}{2\pi\epsilon_0 r} \hat{r}$

Infinite plane: $\vec{E} = \frac{\sigma}{2\epsilon_0} \hat{n}$

2. Potential

2.1 Superposition

$$V = - \int_{\infty}^{\vec{r}} \vec{E} \cdot d\vec{l} = \frac{Q}{4\pi\epsilon_0} \frac{1}{|\vec{r} - \vec{r}'|} \quad \text{for } \infty \text{ as reference point}$$

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d\tau'$$

2.2 Energy

Discrete: $W = \frac{1}{2} \sum_i q_i V(\vec{r}_i)$

Continuous: $W = \frac{1}{2} \int \rho(\vec{r}') V(\vec{r}') d\tau'$

Plug in $\rho = \epsilon_0 \cdot (\nabla \cdot \vec{E})$, $W = \frac{1}{2} \epsilon_0 \int (\nabla \cdot \vec{E}) V d\tau'$

Integrating for whole space: $W = \frac{1}{2} \epsilon_0 \int E^2 d\tau'$

2.3 Conductors

① $\vec{E} = 0$ inside

② V is constant inside the conductor and on the surface

③ $\vec{E}_{\text{out}} = \frac{\sigma}{\epsilon_0} \hat{n}$ is perpendicular to the surface

④ $f = \frac{E}{A} = \frac{\sigma}{2\epsilon_0} \cdot \sigma = \frac{\sigma^2}{2\epsilon_0}$

2.4 Capacitors

$$C = \frac{|Q|}{V}$$

$C = \frac{\epsilon_0 A}{d}$ for parallel plates

3. Boundary Value Problem

3.1 Poisson's Equation

$$\nabla \cdot \vec{E} = -\nabla^2 V = \frac{\rho}{\epsilon_0} \Rightarrow \nabla^2 V = -\frac{\rho}{\epsilon_0}$$

Given $\rho(\vec{r})$ and V on the boundaries, solving V and thus \vec{E}, σ

3.2 Boundary Conditions

① $E_{\text{up}}^+ - E_{\text{down}}^- = \frac{\sigma}{\epsilon_0}$

② $E_{\text{up}}'' = E_{\text{down}}''$

③ V is continuous

} Always True, derived from Maxwell's Equation

3.3 Uniqueness Theorem

First: Potential V inside a volume has unique solution if:

① ρ inside is specified ② V on the boundary is specified

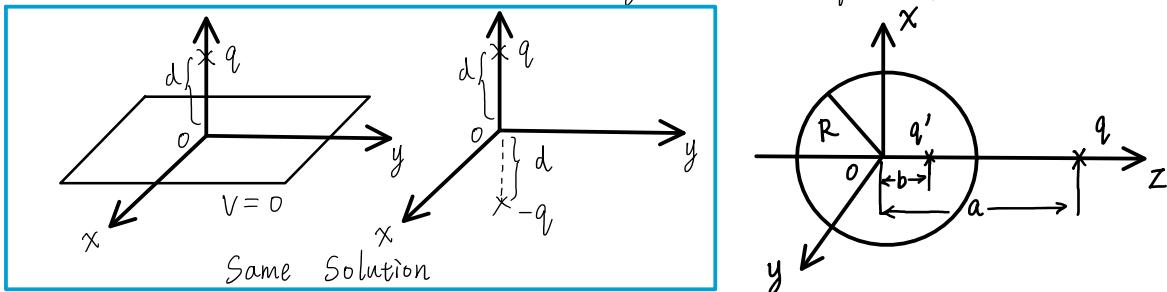
Second: In a region bounded by conductors, \vec{E} has unique solution if:

① ρ is known

② total Q of each conductor is specified

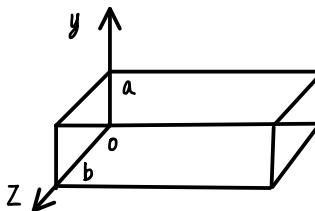
3.4 Image Charge

Put image charges outside of required region (ρ not changed), as long as boundary values are same, two distributions would give same (unique) solution.



3.5 Laplace Equation: $\nabla^2 V = 0$

3.5.1 Cartesian Coordinate



$$\nabla^2 V = 0 \Rightarrow \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

Two boundary surfaces \Rightarrow Trig function

Direction of Propagation \Rightarrow Exponential

Boundary Conditions \Rightarrow constants

Fourier transform \rightarrow coefficients

$$\text{Example: } V(0, y, z) = V_0 \Rightarrow V_0 = \sum_{m,n} V_{mn} \sin \frac{n\pi y}{a} \sin \frac{m\pi z}{b}$$

$$V_{mn} = \frac{4}{ab} \int_0^a \int_0^b V_0 \sin \frac{n\pi y}{a} \sin \frac{m\pi z}{b} dz dy$$

3.5.2 Spherical Coordinate: Legendre Polynomials

$$\text{Assume symmetry in } \varphi, V(r, \theta) = \sum_l (A_l r^l + \frac{B_l}{r^{l+1}}) P_l(\cos \theta)$$

Inside the shell, $B_l = 0$ since it diverges at center

Outside the shell, usually $A_l = 0$, unless there is \vec{E} at $r = \infty$

$$V_{in}(R) = V_{out}(R) \Rightarrow A_l R^{2l+1} = B_l$$

$$\sigma = \epsilon_0 \left(\frac{\partial V}{\partial r} |_{in} - \frac{\partial V}{\partial r} |_{out} \right) = \sum_l \left[l \cdot A_l R^{l-1} + (l+1) \frac{A_l R^{2l+1}}{R^{l+2}} \right] P_l(\cos \theta) \cdot \epsilon_0$$

$= \epsilon_0 \sum_l (2l+1) A_l R^{l-1} P_l(\cos \theta)$ is the surface charge

3.6 Multiple Expansion

$$V = \frac{1}{4\pi\epsilon_0} \int \frac{P(r') dr'}{|\vec{r} - \vec{r}'|} = \frac{1}{4\pi\epsilon_0} \int \rho(r') dr' \sum_n \frac{(r')^n}{r'^{n+1}} P_n(\cos \theta)$$

$$= \frac{1}{4\pi\epsilon_0} \left[\underbrace{\frac{1}{r} \int \rho(r') dr'}_{\text{monopole}} + \underbrace{\frac{1}{r^2} \int r' \cos \theta \rho(r') dr'}_{\text{dipole}} + \dots \right]$$

$$\text{Dipole moment: } \vec{P} = \int \vec{r}' \rho(r') dr' \quad V = \frac{1}{4\pi\epsilon_0} \frac{\vec{r} \cdot \vec{P}}{r^2}$$

4. Field in Dielectrics

4.1 Polarization

$\vec{P} \equiv$ dipole moment per unit volume is the polarization

We could decompose the dipole to surface charge and volume charge:

$$\sigma_b = \vec{P} \cdot \hat{n}$$
 (\hat{n} is pointing outward the dielectric) $P_b = -\nabla' \cdot \vec{P}$

edge of distribution

non-uniformity of polarization

4.2 Electric Displacement

$$\text{Definition: } \vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

Maxwell Equations: $\nabla \cdot \vec{D} = \rho_f / \epsilon_0$, $\nabla \times \vec{D} = \nabla \times \vec{P}$ is not necessarily 0.
 Boundary Conditions: $\begin{cases} D_{\perp \text{out}} - D_{\perp \text{in}} = \sigma_f \\ D_{\parallel \text{out}} - D_{\parallel \text{in}} = P_{\parallel \text{out}} - P_{\parallel \text{in}} \end{cases}$

4.3 Linear Dielectrics

$$\vec{P} = \epsilon_0 \chi_e \vec{E} \text{ in linear dielectrics}, \vec{D} = \epsilon_0 (1 + \chi_e) \vec{E} = \epsilon_0 \epsilon_r \vec{E} = \epsilon \vec{E}$$

$$\therefore P_b = -\nabla \cdot \vec{P} = -\nabla \cdot \left(\frac{\chi_e}{1 + \chi_e} \vec{D} \right) = -\frac{\chi_e}{1 + \chi_e} \rho_f$$

If $\rho_f = 0$, we could conclude $P_b = 0$ and solve Laplace Equation.

Boundary Conditions

$$\begin{cases} V_{\text{in}}(R) = V_{\text{out}}(R) \\ \epsilon \frac{\partial V_{\text{in}}}{\partial r}(R) = \epsilon_0 \frac{\partial V_{\text{out}}}{\partial r}(R) \quad \text{since } \rho_f = \sigma_f = 0 \\ V_{\text{out}} \rightarrow E \text{ as } r \rightarrow \infty \end{cases}$$

Tips: Look for $l=0$ and $l=1$, and other l s.

5. Magnetic Field

5.1 Current

$$K = \sigma \vec{v} \quad \vec{J} = \rho \vec{v}$$

$$I = \frac{dq}{dt} \quad I = \int \vec{K} \cdot d\vec{l} = \int \vec{J} \cdot d\vec{a} \text{ for surface and volume current}$$

In magnetostatics, steady current ($\frac{d\vec{J}}{dt} = 0$) is studied.

5.2 Ampere's Law

$$\int (\nabla \times \vec{B}) \cdot d\vec{a} = \oint \vec{B} \cdot d\vec{l} = \int \mu_0 \vec{J} \cdot d\vec{a} = \mu_0 I_{\text{enc}}$$

Requires Symmetry: B points at same direction to l and is uniform.

5.3 Biot-Savart Law (Superposition)

$$\vec{B}(r) = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

Tips: could use Biot-Savart Law to find the symmetry without evaluating the field; then apply Ampere's Law.

5.4 Vector Potential

$$\vec{B} = \nabla \times \vec{A}, \text{ choose } \vec{A} \text{ s.t. } \nabla \cdot \vec{A} = 0$$

$$\text{so } \nabla^2 \vec{A} = \nabla^2 A_x \hat{x} + \nabla^2 A_y \hat{y} + \nabla^2 A_z \hat{z} = -\mu_0 \vec{J} \quad (3 \text{ Equations})$$

$$\vec{A}(r) = \frac{\mu_0 I}{4\pi} \int \frac{\vec{J}(r') d\vec{l}'}{|\vec{r} - \vec{r}'|^3} \quad \text{need to be calculated}$$

5.5 Boundary Conditions

in spherical / cylindrical Laplacian

$$\begin{cases} B_{\perp \text{out}} - B_{\perp \text{in}} = 0 \\ B_{\parallel \text{out}} - B_{\parallel \text{in}} = \mu_0 \vec{K} \times \hat{n} \end{cases}$$

5.6 Multiple Expansion

$$\vec{A}(r) = \frac{\mu_0 I}{4\pi} \int \frac{\vec{J}(r') d\vec{l}'}{|\vec{r} - \vec{r}'|^3} \xrightarrow{\text{constant } I} \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{|\vec{r} - \vec{r}'|}$$

Expand $\frac{1}{|\vec{r} - \vec{r}'|}$ to $\frac{1}{r} \sum_n \left(\frac{r}{r'}\right)^n P_n(\cos \theta)$

$$\vec{A}(r) = \frac{\mu_0 I}{4\pi} \left[\underbrace{\frac{1}{r} \phi d\vec{l}'}_{\text{monopole, } 0} + \underbrace{\frac{1}{r^2} \vec{r}' \cos \theta d\vec{l}'}_{\text{dipole}} + \dots \right]$$

Dipole term: $\vec{A}(r) = \frac{\mu_0 I}{4\pi r^2} \oint (\hat{r} \cdot \vec{r}') d\vec{l}' = -\frac{\mu_0 I}{4\pi r^2} \hat{r} \times \int d\vec{a}' \leftarrow \text{area vector}$

Define $\vec{m} = \vec{I} \int d\vec{a} = \vec{I} \hat{a}$ to be the magnetic dipole moment

$$A(F) = \frac{\mu_0}{4\pi} \frac{r^2 \sin \theta}{F^2}$$

6. Magnetic Field in Matter

6.1 Magnetization

\vec{M} = magnetic dipole moment per unit volume

We could decompose the result field to 2 parts:

$$\vec{J}_b = \nabla \times \vec{M} \quad \text{and} \quad \vec{K}_b = \vec{M} \times \hat{n}$$

$$\vec{A}(r) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}_b(r')}{|r-r'|} dr' + \frac{\mu_0}{4\pi} \int \frac{\vec{K}_b(r')}{|r-r'|} da'$$

6.2 Auxiliary Field

$$\nabla \times \vec{B} = \mu_0 (\vec{J}_b + \vec{J}_f) = \mu_0 \nabla \times \vec{M} + \mu_0 \vec{J}_f \Rightarrow \nabla \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f$$

Define $\vec{H} \equiv \frac{\vec{B}}{\mu_0} - \vec{M}$, we have:

$$\begin{cases} \nabla \cdot \vec{H} = -\nabla \cdot \vec{M} \\ \nabla \times \vec{H} = \vec{J}_f \end{cases}$$

$$\text{Boundary Conditions} \begin{cases} H_{\perp \text{out}} - H_{\perp \text{in}} = -(M_{\perp \text{out}} - M_{\perp \text{in}}) \\ H_{\parallel \text{out}} - H_{\parallel \text{in}} = \vec{K}_f \times \hat{n} \end{cases}$$

6.3 Linear Material

$$\vec{M} = \chi_m \vec{H} \Rightarrow \vec{B} = \mu_0 (1 + \chi_m) \vec{H} = \mu \vec{H}$$

Properties:

$$\textcircled{1} \quad \nabla \cdot \vec{M} = \nabla \cdot \left(\frac{\vec{B}}{\mu_0} - \vec{H} \right) = \frac{\chi_m}{\mu_0 (1 + \chi_m)} \nabla \cdot \vec{B} = 0$$

$$\textcircled{2} \quad \vec{J}_b = \nabla \times \vec{M} = \chi_m \nabla \times \vec{H} = \chi_m \vec{J}_f \quad \vec{J}_f = 0 \Rightarrow \vec{J}_b = 0$$

Scalar Potential: When $\vec{J}_f = \vec{J}_b = 0$

$$\nabla \times \vec{H} = 0 \Rightarrow \vec{H} = -\nabla V$$

$$\nabla^2 V = -\nabla \cdot \vec{H} = \nabla \cdot \vec{M} = 0 \quad \text{satisfies Laplace Equation}$$

So we could apply general solution and boundary conditions above.

*Note: V is not necessarily continuous. It is when there is no surface current)