

# EE2211 Introduction to Machine Learning

Lecture 5 Semester 2 2023/2024

Yueming Jin ymjin@nus.edu.sg

Electrical and Computer Engineering Department National University of Singapore

Acknowledgement:

EE2211 development team

(Xinchao, Helen, Thomas, Kar-Ann, Vincent, Chen Khong, Robby, and Haizhou)

### **Course Contents**



- Introduction and Preliminaries (Xinchao)
  - Introduction
  - Data Engineering
  - Introduction to Probability and Statistics
- Fundamental Machine Learning Algorithms I (Yueming)
  - Systems of linear equations
  - Least squares, Linear regression
  - Ridge regression, Polynomial regression
- Fundamental Machine Learning Algorithms II (Yueming)
  - Over-fitting, bias/variance trade-off
  - Optimization, Gradient descent
  - Decision Trees, Random Forest
- Performance and More Algorithms (Xinchao)
  - Performance Issues
  - K-means Clustering
  - Neural Networks



### **Least Squares and Linear Regression**

#### **Module II Contents**

- Notations, Vectors, Matrices (introduced in L3)
- Operations on Vectors and Matrices
- Systems of Linear Equations
- Set and Functions
- Derivative and Gradient
- Least Squares, Linear Regression
- Linear Regression with Multiple Outputs
- Linear Regression for Classification
- Ridge Regression
- Polynomial Regression



### **Recap: Linear and Affine Functions**

#### **Linear Functions**

A function  $f: \mathbb{R}^d \to \mathbb{R}$  is **linear** if it satisfies the following two properties:

- Homogeneity  $f(\alpha x) = \alpha f(x)$  Scaling
- Additivity f(x + y) = f(x) + f(y) Adding

#### Inner product function

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} = a_1 x_1 + a_2 x_2 + \cdots + a_d x_d$$

#### **Affine function**

 $f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + \mathbf{b}$  scalar  $\mathbf{b}$  is called the offset (or bias)

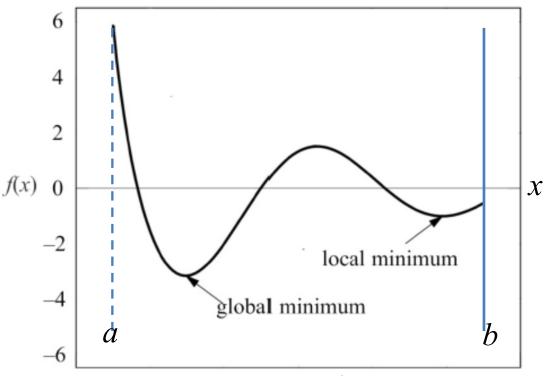
Ref: [Book4] Stephen Boyd and Lieven Vandenberghe, "Introduction to Applied Linear Algebra", Cambridge University Press, 2018 (p31)

### **Functions: Maximum and Minimum**



- f(x) has a **local minimum** at x = c if  $f(x) \ge f(c)$  for every x in some open interval around x = c
- f(x) has a **global minimum** at x = c if  $f(x) \ge f(c)$  for all x in the domain of f

A local and a global minima of a function



$$a < x \le b$$

Note: An **interval** is a set of real numbers with the property that any number that lies between two numbers in the set is also included in the set.

An **open interval** does not include its endpoints and is denoted using parentheses. E.g. (0, 1) means "all numbers greater than 0 and less than 1".

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p6-7 of chp2).

### **Functions: Maximum and Minimum**



#### Max and Arg Max

- Given a set of values  $\mathcal{A} = \{a_1, a_2, ..., a_m\}$ ,
- The operator  $\max_{a \in \mathcal{A}} f(a)$  returns the highest value f(a) for all elements in the set A
- The operator  $\arg\max_{a\in\mathcal{A}}f(a)$  returns the element of the set  $\mathcal{A}$  that maximizes f(a)
- When the set is **implicit** or **infinite**, we can write

$$\max_{a} f(a) \quad \text{or} \quad \arg\max_{a} f(a)$$
  
E.g.  $f(a) = 3a$ ,  $a \in [0,1] \rightarrow \max_{a} f(a) = 3$  and  $\arg\max_{a} f(a) = 1$ 

E.g. 
$$f(a) = 3a$$
,  $a \in [0,1] \to \max_{a} f(a) = 3$  and  $\max_{a} f(a) = 1$ 

#### Min and Arg Min operate in a similar manner

Note: **arg max** returns a value from the **domain** of the function and **max** returns from the range (codomain) of the function.

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p6-7 of chp2).

• The **derivative** f' of a function f is a function that  $\frac{1}{4}$  describes how fast f grows (or decreases)



- If the derivative is a constant value, e.g. 5 or −3
  - The function *f* grows (or decreases) constantly at any point *x* of its domain
- When the derivative f' is a function
  - If f' is positive at some x, then the function f grows at this point
  - If f' is negative at some x, then the function f decreases at this point
  - The derivative of zero at x means that the function's slope at x is horizontal (e.g. maximum or minimum points)
- The process of finding a derivative is called differentiation.
- Gradient is the generalization of derivative for functions that take several inputs (or one input in the form of a vector or some other complex structure).

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p8 of chp2).



The gradient of a function is a vector of partial derivatives

#### Differentiation of a scalar function w.r.t. a vector

If  $f(\mathbf{x})$  is a scalar function of d variables,  $\mathbf{x}$  is a d x1 vector. Then differentiation of  $f(\mathbf{x})$  w.r.t.  $\mathbf{x}$  results in a d x1 vector

$$\frac{df(\mathbf{x})}{d\mathbf{x}} = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_d} \end{bmatrix} \qquad \frac{1}{(\chi, \chi, \chi)}$$

$$\frac{1}{(\chi, \chi, \chi)}$$

This is referred to as the **gradient** of  $f(\mathbf{x})$  and often written as  $\nabla_{\mathbf{x}} f$ .

E.g. 
$$f(\mathbf{x}) = ax_1 + bx_2$$
  $\nabla_{\!\mathbf{x}} f = \begin{bmatrix} a \\ b \end{bmatrix}$  Ref: Duda, Hart, and Stork, "Pattern Classification", 2001 (Appendix



#### **Partial Derivatives**

#### Differentiation of a vector function w.r.t. a vector

If f(x) is a vector function of size h x1 and x is a d x1 vector. Then differentiation of f(x) results in a  $h \times d$  matrix

$$\frac{d\mathbf{f}(\mathbf{x})}{d\mathbf{x}} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_h}{\partial x_1} & \dots & \frac{\partial f_h}{\partial x_d} \end{bmatrix}$$

The matrix is referred to as the **Jacobian** of f(x)

Ref: Duda, Hart, and Stork, "Pattern Classification", 2001 (Appendix)

$$X = \begin{bmatrix} X_1 \\ Y_2 \\ Y_3 \end{bmatrix}$$

$$A = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \end{bmatrix}$$



#### Some Vector-Matrix Differentiation Formulae

$$\frac{d(\mathbf{A}\mathbf{x})}{d\mathbf{x}} = \mathbf{A}$$

$$\frac{d(\mathbf{b}^{T}\mathbf{x})}{d\mathbf{x}} = \mathbf{b}$$

$$\frac{d(\mathbf{x}^{T}\mathbf{A}\mathbf{x})}{d\mathbf{x}} = (\mathbf{A} + \mathbf{A}^{T})\mathbf{x}$$

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} = a_1 x_1 + a_2 x_2 + \cdots + a_d x_d$$

Derivations: https://www.math.uwaterloo.ca/~hwolkowi/matrixcookbook.pdf

Ref: Duda, Hart, and Stork, "Pattern Classification", 2001 (Appendix)



 Linear regression is a popular regression learning algorithm that learns a model which is a linear combination of features of the input example.

$$\mathbf{X}\mathbf{w} = \mathbf{y}, \quad \mathbf{X} \in \mathbf{\mathcal{R}}^{m \times d}, \ \mathbf{w} \in \mathbf{\mathcal{R}}^{d \times 1}, \ \mathbf{y} \in \mathbf{\mathcal{R}}^{m \times 1}$$

$$\mathbf{X} = \begin{bmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m,1} & x_{m,2} & \dots & x_{m,d} \end{bmatrix}, \quad \mathbf{w} = \begin{bmatrix} w_1 \\ \vdots \\ w_d \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p3 of chp3).



**Problem Statement:** To predict the unknown y for a given x (testing)

- We have a collection of labeled examples (training) $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^m$ 
  - m is the size of the collection
  - $-\mathbf{x}_i$  is the d-dimensional feature vector of example i=1,...,m (input)
  - $-y_i$  is a real-valued target (1-D)
  - Note:
    - when y<sub>i</sub> is continuous valued, it is a regression problem
    - when  $y_i$  is discrete valued, it is a classification problem
- We want to build a model  $f_{\mathbf{w},b}(\mathbf{x})$  as a linear combination of features of example  $\mathbf{x}$ :  $f_{\mathbf{w},b}(\mathbf{x}) = \mathbf{x}^T \mathbf{w} + b$ 
  - where  $\mathbf{w}$  is a d-dimensional vector of parameters and b is a real number.
- The notation  $f_{\mathbf{w},b}$  means that the model f is parametrized by two values:  $\mathbf{w}$  and b

Ref: [Book4] Stephen Boyd and Lieven Vandenberghe, "Introduction to Applied Linear Algebra", Cambridge University Press, 2018 (chp.14)

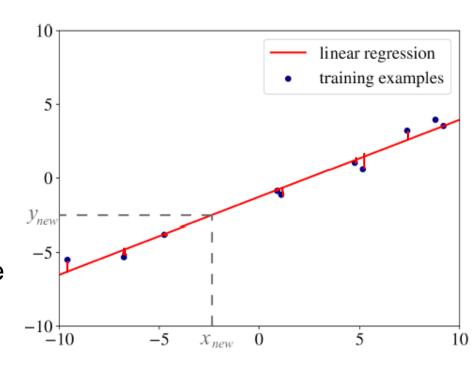


### Learning objective function

To find the optimal values for w\* and b\* which minimizes the following expression:

$$\frac{1}{m} \sum_{i=1}^{m} (f_{\mathbf{w},b}(\mathbf{x}_i) - \mathbf{y}_i)^2$$

 In mathematics, the expression we minimize or maximize is called an objective function, or, simply, an objective



 $(f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2$  is called the **loss function**: a measure of the difference between  $f_{\mathbf{w}}(\mathbf{x}_i)$  and  $\mathbf{y}_i$  or a penalty for misclassification of example *i*.

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (chp3.1.2)



#### Learning objective function (using simplified notation hereon)

 To find the optimal values for w\* which minimizes the following expression:

$$\sum_{i=1}^{m} (f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2$$

with 
$$f_{\mathbf{w}}(\mathbf{x}_i) = \mathbf{x}^T \mathbf{w}$$
,  
where we define  $\mathbf{w} = [b, w_1, ... w_d]^T = [w_0, w_1, ... w_d]^T$ ,  
and  $\mathbf{x}_i = [1, x_{i,1}, ... x_{i,d}]^T = [x_{i,0}, x_{i,1}, ... x_{i,d}]^T$ ,  $i = 1, ..., m$ 

This particular choice of the loss function is called squared error loss

Note: The normalization factor  $\frac{1}{m}$  can be omitted as it does not affect the optimization.

$$\sum_{i=1}^{m} (f_{\mathbf{w},b}(\mathbf{x}_i) - \mathbf{y}_i)^2$$



- All model-based learning algorithms have a loss function
- What we do to find the best model is to minimize the objective known as the cost function
- Cost function is a sum of loss functions over training set plus possibly some model complexity penalty (regularization)
- In linear regression, the cost function is given by the *average* loss, also called the **empirical risk** because we do not have all the data (e.g. testing data)
  - The average of all penalties is obtained by applying the model to the training data

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (chp3.1.2)



#### Learning (Training)

• Consider the set of feature vector  $\mathbf{x}_i$  and target output  $y_i$  indexed by i = 1, ..., m, a linear model  $f_{\mathbf{w}}(\mathbf{x}) = \mathbf{x}^T \mathbf{w}$  can be stacked as

De stacked as 
$$f_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{w} \qquad \mathbf{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$
Learning Model 
$$= \begin{bmatrix} \mathbf{x}_1^T \mathbf{w} \\ \vdots \\ \mathbf{x}_m^T \mathbf{w} \end{bmatrix}$$
where 
$$\mathbf{x}_i^T \mathbf{w} = [1, x_{i,1}, \dots, x_{i,d}] \begin{bmatrix} b \\ w_1 \\ \vdots \\ w_d \end{bmatrix}$$

**Note**: The **bias/offset term** is responsible for **translating** the line/plane/hyperplane away from the origin.



#### **Least Squares Regression**

In vector-matrix notation, the minimization of the objective function can be written compactly using  $\mathbf{e} = \mathbf{X}\mathbf{w} - \mathbf{y}$ :

$$J(\mathbf{w}) = \mathbf{e}^{T}\mathbf{e}$$

$$= (\mathbf{X}\mathbf{w} - \mathbf{y})^{T}(\mathbf{X}\mathbf{w} - \mathbf{y})$$

$$= (\mathbf{w}^{T}\mathbf{X}^{T} - \mathbf{y}^{T})(\mathbf{X}\mathbf{w} - \mathbf{y})$$

$$= \mathbf{w}^{T}\mathbf{X}^{T}\mathbf{X}\mathbf{w} - \mathbf{w}^{T}\mathbf{X}^{T}\mathbf{y} - \mathbf{y}^{T}\mathbf{X}\mathbf{w} + \mathbf{y}^{T}\mathbf{y}$$

$$= \mathbf{w}^{T}\mathbf{X}^{T}\mathbf{X}\mathbf{w} - 2\mathbf{y}^{T}\mathbf{X}\mathbf{w} + \mathbf{y}^{T}\mathbf{y}.$$

Note: when 
$$f_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{w}$$
, then 
$$\sum_{i=1}^{m} (f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2 = (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y}).$$



Differentiating J(w) with respect to w and setting the

$$\frac{\partial}{\partial \mathbf{w}} J(\mathbf{w}) = \mathbf{0}$$

$$\frac{\partial}{\partial \mathbf{w}} (\mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w} - 2\mathbf{y}^T \mathbf{X} \mathbf{w} + \mathbf{y}^T \mathbf{y}) = \mathbf{0}$$

$$\Rightarrow 2\mathbf{X}^T \mathbf{X} \mathbf{w} - 2\mathbf{X}^T \mathbf{y} = \mathbf{0}$$

$$\Rightarrow \mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

 $\Rightarrow$  Any minimizer  $\hat{\mathbf{w}}$  of  $J(\mathbf{w})$  must satisfy  $\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{y}) = \mathbf{0}$ .

If  $\mathbf{X}^T\mathbf{X}$  is invertible, then

Learning/training:

$$\widehat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Prediction/testing:

$$\hat{\boldsymbol{f}}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new} \hat{\mathbf{w}}$$



**Example 1** Training set  $\{(x_i, y_i)\}_{i=1}^m \{x = -9\} \rightarrow \{y = -6\}$ 

$$\{(x_i, y_i)\}_{i=1}^m$$

$$\{x = -9\} \rightarrow \{y = -6\}$$

$$\{x = -7\} \rightarrow \{y = -6\}$$
  
 $\{x = -5\} \rightarrow \{y = -4\}$ 

$$\begin{bmatrix} 1 & -9 \\ 1 & -7 \\ 1 & -5 \\ 1 & 1 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} = \begin{bmatrix} -6 \\ -6 \\ -4 \\ -1 \\ 1 \end{bmatrix}$$

$$\{x = 1\} \rightarrow \{y = -1\}$$

$$\{x = 5\} \rightarrow \{y = 1\}$$

$$\{x = 9\} \rightarrow \{y = 4\}$$

This set of linear equations has no exact solution

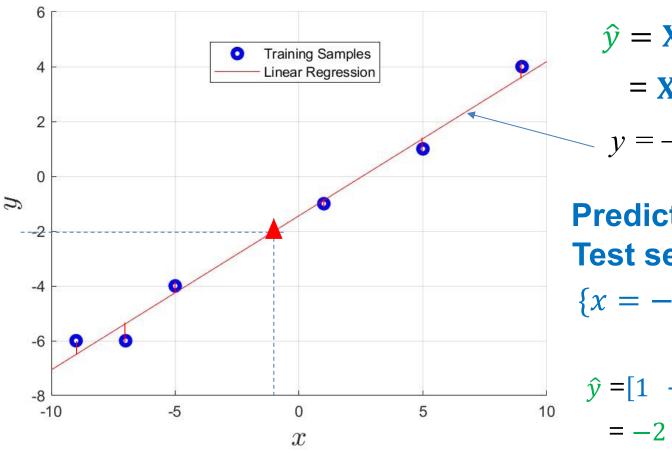
However,  $\mathbf{X}^T\mathbf{X}$  is invertible

Least square approximation

$$\widehat{\mathbf{w}} = \mathbf{X}^{\dagger} \mathbf{y} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \mathbf{y}$$

$$= \begin{bmatrix} 6 & -6 \\ -6 & 262 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ -9 & -7 & -5 & 1 & 5 & 9 \end{bmatrix} \begin{bmatrix} -6 \\ -6 \\ -4 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1.4375 \\ 0.5625 \end{bmatrix}$$





Linear Regression on one-dimensional samples

## $\hat{y} = X\hat{\mathbf{w}}$ $= \mathbf{x} \begin{bmatrix} -1.4375 \\ 0.5625 \end{bmatrix}$ y = -1.4375 + 0.5625x

### **Prediction: Test set**

$${x = -1} \rightarrow {y = ?}$$

$$\hat{y} = \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} -1.4375 \\ 0.5625 \end{bmatrix}$$
$$= -2$$

Python demo 1



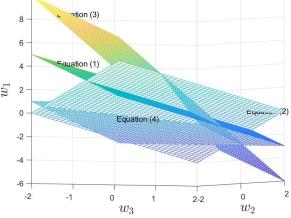
#### **Example 2** $\{(x_i, y_i)\}_{i=1}^m$

$$\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^m$$

#### **Training set**

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & 3 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix}$$

$$\{x_1 = 1, x_2 = 1, x_3 = 1\} \rightarrow \{y = 1\}$$
  
 $\{x_1 = 1, x_2 = -1, x_3 = 1\} \rightarrow \{y = 0\}$   
 $\{x_1 = 1, x_2 = 1, x_3 = 3\} \rightarrow \{y = 2\}$   
 $\{x_1 = 1, x_2 = 1, x_3 = 0\} \rightarrow \{y = -1\}$ 



This set of linear equations has no exact solution

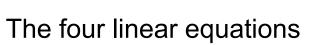
However,  $\mathbf{X}^T\mathbf{X}$  is invertible

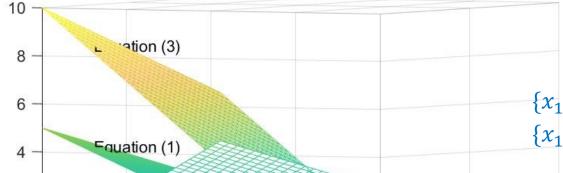
$$\widehat{\mathbf{w}} = \mathbf{X}^{\dagger} \mathbf{y} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

#### **Least square approximation**

$$= \begin{bmatrix} 4 & 2 & 5 \\ 2 & 4 & 3 \\ 5 & 3 & 11 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix}$$







#### **Prediction:**

#### **Test set**

$$\{x_1 = 1, x_2 = 6, x_3 = 8\} \rightarrow \{y = ?\}$$
  
 $\{x_1 = 1, x_2 = 0, x_3 = -1\} \rightarrow \{y = ?\}$ 

$$\widehat{\mathbf{y}} = \widehat{\mathbf{f}}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new}\widehat{\mathbf{w}}$$

$$\hat{\mathbf{y}} = \begin{bmatrix} 1 & 6 & 8 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix}$$
$$= \begin{bmatrix} 7.7500 \\ -1.6786 \end{bmatrix}$$



### **Learning of Vectored Function (Multiple Outputs)**

For one sample: a linear model  $\mathbf{f}_{\mathbf{w}}(\mathbf{x}) = \mathbf{x}^T \mathbf{W}$  Vector function

For m samples:  $\mathbf{F}_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{W} = \mathbf{Y}$ 

Sample 1 
$$\mathbf{x}_{1}^{T}$$
  $\vdots$   $\mathbf{w} = \begin{bmatrix} 1 & x_{1,1} & \dots & x_{1,d} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{m,1} & \dots & x_{m,d} \end{bmatrix} \begin{bmatrix} w_{0,1} & \dots & w_{0,h} \\ w_{1,1} & \dots & w_{1,h} \\ \vdots & \ddots & \vdots \\ w_{d,1} & \dots & w_{d,h} \end{bmatrix}$ 
Sample 1  $\mathbf{w}$   $\mathbf{w}$ 

Sample 1's output 
$$y_{1,1}$$
 ...  $y_{1,h}$   $\vdots$   $y_{m,1}$  ...  $y_{m,h}$ 

$$\mathbf{X} \in \mathcal{R}^{m \times (d+1)}$$
,  $\mathbf{W} \in \mathcal{R}^{(d+1) \times h}$ ,  $\mathbf{Y} \in \mathcal{R}^{m \times h}$ 



Objective: 
$$\sum_{i=1}^{m} (\mathbf{f_w}(\mathbf{x}_i) - \mathbf{y}_i)^2 = \mathbf{E}^T \mathbf{E}$$

### **Least Squares Regression of Multiple Outputs**

In matrix notation, the sum of squared errors cost function can be written compactly using  $\mathbf{E} = \mathbf{XW} - \mathbf{Y}$ :

$$J(\mathbf{W}) = \operatorname{trace}(\mathbf{E}^T \mathbf{E})$$
$$= \operatorname{trace}[(\mathbf{X}\mathbf{W} - \mathbf{Y})^T (\mathbf{X}\mathbf{W} - \mathbf{Y})]$$

If  $\mathbf{X}^T\mathbf{X}$  is invertible, then

**Learning/training:**  $\hat{\mathbf{W}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$ 

Prediction/testing:  $\hat{\mathbf{F}}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new}\hat{\mathbf{W}}$ 

Ref: Hastie, Tibshirani, Friedman, "The Elements of Statistical Learning", (2<sup>nd</sup> ed., 12<sup>th</sup> printing) 2017 (chp.3.2.4)



#### **Least Squares Regression of Multiple Outputs**

$$J(\mathbf{W}) = \operatorname{trace}(\mathbf{E}^T \mathbf{E})$$

= trace(
$$\begin{bmatrix} \mathbf{e}_1^T \\ \vdots \\ \mathbf{e}_h^T \end{bmatrix}$$
[ $\mathbf{e}_1 \quad \mathbf{e}_2 \dots \mathbf{e}_h$ ])

$$= \operatorname{trace}(\begin{bmatrix} \mathbf{e}_{1}^{T} \mathbf{e}_{1} & \mathbf{e}_{1}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{1}^{T} \mathbf{e}_{h} \\ \mathbf{e}_{2}^{T} \mathbf{e}_{1} & \mathbf{e}_{2}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{2}^{T} \mathbf{e}_{h} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{e}_{h}^{T} \mathbf{e}_{1} & \mathbf{e}_{h}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{h}^{T} \mathbf{e}_{h} \end{bmatrix}) = \sum_{k=1}^{h} \mathbf{e}_{k}^{T} \mathbf{e}_{k}$$

### Linear Regression of multiple outputs



### Example 3

Training set 
$$\{x_1 = 1, x_2 = 1, x_3 = 1\} \rightarrow \{y_1 = 1, y_2 = 0\}$$

$$\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^m \begin{cases} x_1 = 1, x_2 = -1, x_3 = 1\} \rightarrow \{y_1 = 0, y_2 = 1\} \\ \{x_1 = 1, x_2 = 1, x_3 = 3\} \rightarrow \{y_1 = 2, y_2 = -1\} \\ \{x_1 = 1, x_2 = 1, x_3 = 0\} \rightarrow \{y_1 = -1, y_2 = 3\} \end{cases}$$

$$\mathbf{X} \qquad \mathbf{W} \qquad \mathbf{Y}$$
Bias 
$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & 3 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} w_{1,1} & w_{1,2} \\ w_{2,1} & w_{2,2} \\ w_{3,1} & w_{3,2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 2 & -1 \\ -1 & 3 \end{bmatrix}$$

This set of linear equations has NO exact solution

$$\hat{\mathbf{W}} = \mathbf{X}^{\dagger} \mathbf{Y} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \mathbf{Y}$$
  $\mathbf{X}^{T} \mathbf{X}$  is invertible

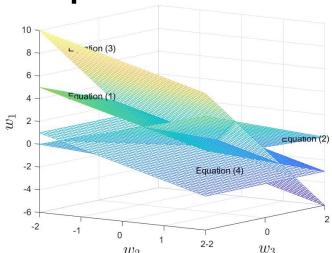
Least square approximation

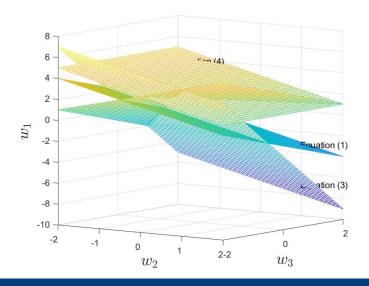
$$= \begin{bmatrix} 4 & 2 & 5 \\ 2 & 4 & 3 \\ 5 & 3 & 11 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 2 & -1 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} -0.75 & 2.25 \\ 0.1786 & 0.0357 \\ 0.9286 & -1.2143 \end{bmatrix}$$

### Linear Regression of multiple outputs



Example 3





#### **Prediction:**

#### Test set: two new samples

$$\{x_1 = 1, x_2 = 6, x_3 = 8\} \rightarrow \{y_1 = ?, y_2 = ?\}$$
  
 $\{x_1 = 1, x_2 = 0, x_3 = -1\} \rightarrow \{y_1 = ?, y_2 = ?\}$ 

$$\begin{split} \widehat{\mathbf{Y}} &= \mathbf{X}_{new} \, \widehat{\mathbf{W}} \\ \text{Bias} &= \begin{bmatrix} 1 & 6 & 8 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} -0.75 & 2.25 \\ 0.1786 & 0.0357 \\ 0.9286 & -1.2143 \end{bmatrix} \\ &= \begin{bmatrix} 7.75 & -7.25 \\ -1.6786 & 3.4643 \end{bmatrix} \end{split}$$

Python demo 2

### Linear Regression of multiple outputs



#### Example 4

The values of feature x and their corresponding values of multiple outputs target **y** are shown in the table below.

Based on the least square regression, what are the values of **w**? Based on the current mapping, when x = 2, what is the value of y?

X	[3]	[4]	[10]	[6]	[7]
У	[0, 5]	[1.5, 4]	[-3, 8]	[-4, 10]	[1, 6]

$$\widehat{\mathbf{W}} = \mathbf{X}^{\dagger} \mathbf{Y} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \mathbf{Y} = \begin{bmatrix} 1.9 & 3.6 \\ -0.4667 & 0.5 \end{bmatrix}$$

Python demo 3

$$\widehat{\mathbf{Y}_{new}} = \mathbf{X}_{new}$$

$$\widehat{\mathbf{W}} = [1]$$

$$\widehat{\mathbf{Y}_{new}} = \mathbf{X}_{new} \widehat{\mathbf{W}} = [1 \quad 2] \widehat{\mathbf{W}} = [0.9667 \quad 4.6]$$

**Prediction** 

### **Summary**

- Notations, Vectors, Matrices
- Operations on Vectors and Matrices
  - Dot-product, matrix inverse
- Systems of Linear Equations  $f_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{w} = \mathbf{y}$ 
  - Matrix-vector notation, linear dependency, invertible
  - Even-, over-, under-determined linear systems
- Functions, Derivative and Gradient
  - Inner product, linear/affine functions
  - Maximum and minimum, partial derivatives, gradient
- Least Squares, Linear Regression
  - Objective function, loss function
  - Least square solution, training/learning and testing/prediction
  - Linear regression with multiple outputs

## Prediction/testing

- Learning/training  $\hat{\mathbf{w}} = (\mathbf{X}_{train}^T \mathbf{X}_{train}^T)^{-1} \mathbf{X}_{train}^T \mathbf{y}_{train}$  $\mathbf{y}_{test} = \mathbf{X}_{test} \, \widehat{\mathbf{w}}$
- Classification
- Ridge Regression
- Polynomial Regression

Python packages: numpy, pandas, matplotlib.pyplot, numpy.linalg, and sklearn.metrics (for mean squared error), numpy.linalg.pinv

Midterm (L1 to L5) Trial quiz