

Zhuoyuan (Joey) YU

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Research interests: Robotics, Deep Reinforcement Learning, Multi-Agent Systems, Foundation Model

EDUCATION

National University of Singapore	GPA: 5.0 / 5.0	<i>Singapore</i>
Major: M.Eng. in Mechanical Engineering (By Research), <i>Department of Mechanical Engineering</i>		<i>08/2023-03/2025</i>
<ul style="list-style-type: none">Core Courses: Linear Systems, Autonomous Mobile Robotics, Advanced RoboticsResearch focus: Robotics, Multi-agent Deep Reinforcement Learning, ControlMaster thesis: Multi-agent Reliable Navigation in Dynamical Environments		
Northwestern Polytechnical University	GPA: 83.1%	<i>Xi'an China</i>
Major: B.Eng. in Aircraft Design and Engineering, <i>School of Aeronautics</i>		<i>09/2019-07/2023</i>
<ul style="list-style-type: none">Scholarship: Second Prize Scholarship Excellent Student LeaderCore Courses: Aerodynamics, Automatic Control Theory, Mathematics Analysis, Linear AlgebraNPU School of Aeronautics Student Union President <i>04/2021-06/2022</i>International Internet+ College Students Innovation and Entrepreneurship Competition <i>National Gold Award</i>“Huamo Cup” National College Students Flight Simulation Championship <i>National Third Prize</i>		

RESEARCH EXPERIENCE

- **Multi-Agent Path Finding Based on Deep Reinforcement Learning** *05/2024-01/2025*
[Joint Program between NUS and A*STAR] | *Supervisor: Guo Hongliang and Chew Chee Meng*
- Improved the existing Node2Vec algorithm to handle the dynamic topological networks better.
 - Utilized Graph Attention Networks to enhance the decision-making weights of dynamic edges.
 - Integrated reinforcement learning for online training of the network.
- Related:* Python, Pytorch, ROS1, Multi-Agent Systems, Graph Attention Networks, Natural Language Processing
- **Design and Control of Manta Ray Robot (Bioinspired Underwater Robot)** *08/2023-03/2025*
[NUS ME Control and Mechatronics Lab] | *Supervisor: Chew Chee Meng*
- Designed a new type of buoyancy system and mass adjustment system for the Manta Ray robot.
 - Improved original single-degree-of-freedom pectoral fin to dual-degree-of-freedom, enhancing controllability.
 - Upgraded Arduino-based control system to include control of the buoyancy system and the pectoral fins.
- Related:* Python, Arduino, SolidWorks, Bioinspired Robotics
- **Quadcopter Overall Design and Trajectory Re-planning** *07/2020-09/2021*
[NPU Aircraft Design and Testing Technique Engineering Laboratory] | *Supervisor: Wang Ban*
- Designed and made a quadcopter unmanned aerial vehicle (UAV).
 - Studied the trajectory re-planning and obstacle avoidance of UAVs.
- Related:* MATLAB, XFLR5, Catia, Aerodynamics

SELECTED PROJECTS

[Project Website](#)

- Autonomous Mobile Robotics [[GitHub](#)] | *ROS1, Python, OpenCV* *01/2024-04/2024*
- Integrate vision recognition to navigate the robot in a simulation environment and search objects.
- Manipulator Simulation [[GitHub](#)] | *MATLAB, Kinematics* *03/2024-04/2024*
- Establish a robotic arm model, then use inverse kinematics to calculate the corresponding joint angles.

PUBLICATIONS (* corresponding author)

Yu Zhuoyuan., Guo, H*., Chew, C. M., Adiwahono, A. H., Chan, J., Tynn, B. S. W., & Yau, W. Y, “[Multi-Robot Reliable Navigation in Uncertain Topological Environments with Graph Attention Networks](#),” *IEEE Robotics and Automation Letters* (2025)

TECHNICAL SKILLS

Programming Language: Python, MATLAB, C/C++

Software: Pytorch, ROS1, Gazebo, SolidWorks, Catia, OpenCV, LaTeX, Git, Isaac Lab

Hardware: Arduino, Mechanical Design, 3D Printing