### POPAN and Model Selection

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October 27, 2017

We already did a POPAN model! (In a Bayesian way) Recall:

- ▶ 3 latent states
- two proceses ("recruitment", death)
- ► full-capture modelling

### Transition Matrix

from t-1 to t

		Unborn	Alive	Dead
	Unborn	$\int 1 - \psi_t$	0	0 \
$\Phi_t =$	Alive	$\psi_{t}$	$\phi_{t-1}$	0
	Dead	0 /	$1 - \phi_{t-1}$	1 /

#### where:

- $lackbox \phi_t$  is the apparent survival at t
- $\blacktriangleright \psi_t$  are *related* to the POPAN pent

### Emission Matrix

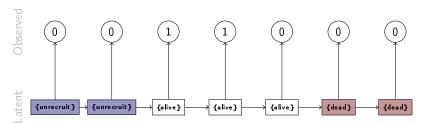
capture at t

$$oldsymbol{\Psi}_t = egin{array}{ccc} extstyle extstyl$$

 $\triangleright$   $p_t$  is the capture-probability at t

We already did a POPAN model! (In a Bayesian way)

 $\blacktriangleright$  example capture history (y = {0011000}) and plausible latent state sequence (Z)



### POPAN-type models

Some notes on the real POPAN...

#### **POPAN**

- pent: probabilty of entry at each capture period
- ▶ super population: estimated total number of animals who recruited into the study area during the study, over all captures periods. Includes animals who you may have never seen. Mostly important to estimate  $N_t$
- births: more like "apparent births" (anologous to apparent survival).
   Derived.

# POPAN-like Bayesian HMM

- pent: no pent, must be derived from psi
- psi are not technically a recruitment parameter, but a "removal entry parameter": the movement from the "unborn" (or unrecruited) state to "alive".
- can similar derive Births, Superpopulation, and N\_t

recall to estimate the entry probabilities pent:

```
cumprob[1] <- psi[1]
for(t in 2:T){    cumprob[t] <- psi[t]*prod(1-psi[1:(t-1)]) }
cumprob.norm <- sum(cumprob[1:T])
for(t in 1:T){ pent[t] <- cumprob[t]/cumprob.norm } #t</pre>
```

▶ note: pent[1] equals psi[1] and both are entirely MEANINGLESS! (Program MARK won't even report pent[1] Confounded with p[1]

# Confounded Parameters in full-time-varying parameterization

- phi[T-1] and p[T] : final survival and final capture
- psi[1] and p[1] : initial entry and initial capture
- psi[T] and phi[T-1]: final entry and final survival

(one reason why the robust design is so important)

```
for(i in 1:M){ # loop through individuals
    # check if i was a new recruit at t=1
    recruit_i[i,1] <- equals(z[i,1],2)
    for(t in 1:T){
        # check if individual i was a new recruit at t
            recruit_i[i,t] <- equals(z[i,t-1],1)*equals(z[i,t],2)
    } # t
} # M
for(t in 1:T){
    recruits[t] <- sum(recruit_i[1:M,t])
}</pre>
```

### POPAN review: Notes of Superpopulation

in our Bayesian HMM Popan-like model...

```
cumprob[1] <- psi[1]
for(t in 2:T){
    cumprob[t] <- psi[t]*prod(1-psi[1:(t-1)])
}
cumprob.norm <- sum(cumprob[1:T])
Superpop <- M*cumprob.norm</pre>
```

(idea: sum(cumprob[1:T]) is the total probability that one of the  $M^{th}$  individuals will enter the study area (i.e., leave the 'un-recruited' or 'unborn' state.)

#### POPAN: other fun recruitment-things to calculate

Pradel recruitment models are related to POPAN, and our Bayesian HMM Popan-like model. Another important parameter to estimate could be the:

lacktriangle "realized" population rate-of-growth  $\lambda_t$ 

$$\lambda_t = \frac{N_{t+1}}{N_t} = \frac{N_t \phi_t + \mathsf{recruits}_t}{N_t}$$

In the Bayesian POPAN, the  $\lambda_t$  are not a process parameters: but derivatives

▶ To estimate the population  $\bar{\lambda}$ , consider a hierarchical model:

$$\lambda_t \sim \mathcal{N}(\bar{\lambda}, \sigma_{\lambda})$$

Recall: the difference between first-capture (e.g., CJS) and full-capture modelling (POPAN).

$$\mathbf{y}_i = \underbrace{0000}_{\text{full-capture}} \underbrace{101011000}_{\text{full-capture}}$$

leading zeros: what are they?

- ▶ the animal was missed?
- ▶ the animal was not-yet-born? or not yet recruited? or not yet immigrated?
- existed in a temporary emigration state?

Recall: the difference between first-capture (e.g., CJS) and full-capture modelling (POPAN).

$$y_i = \underbrace{0000101011000}_{\text{full-capture}}$$

To model recruitment we will use the idea of pseudo-individuals and PXDA parameter-expansion and data-augmentation.  $^{1}$ [Royle and Dorazio, 2012]}. These are animals with an all-zero capture-history:  $y_{aug}$ =0000000000 Implimentation

- we add  $n^{(aug)}$  pseudo-individuals to our data set.  $M = n^{(obs)} + n^{(aug)}$
- we add a "unrecruited" |atent state
- we add a "removal entry" process  $\phi$  that models the movement  $z = \text{unrecruited} \rightarrow \text{alive}$

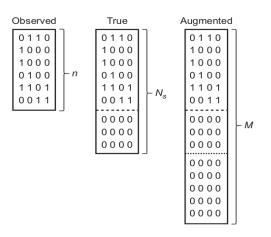


Figure: Kery and Schaub, 2001

```
n \equiv observed animals N_s \equiv the "true" super-population (to estimate) M \equiv \mathrm{n} + \mathrm{n}^{(\mathrm{Aug})}
```



#### What are "pseudo-individuals?"

- recruited but missed (un-captured)
- recruited but died/left before capture
- some never recruited (stay in state {unrecruited})

#### Pseudo individuals are important beyond POPAN:

- ▶ full-capture PCRD [Rankin et al., 2016]
- spatial capture-recapture [Royle et al., 2011]
- occupancy models [Kéry and Schaub, 2011]
- ▶ and more...

#### Technical advice:

- ▶ set  $n^{\text{aug}} \approx n$
- check that it is enough (or too much): Monitor the cumulative entry probability

$$\psi_1 + \psi_2(1 - \psi_1) + \cdots + \psi_T \cdot \prod_{\tau=1}^{I-1} (1 - \psi_{\tau})$$

 $\ldots$  ensure its posterior distribution stays  $\ll 1$ .

# POPAN: cumulative entry probability

$$\psi_1 + \psi_2(1 - \psi_1) + \cdots + \psi_T \cdot \prod_{\tau=1}^{r-1} (1 - \psi_\tau)$$

or in JAGS...

```
cumprob[1] <- psi[1]
for(t in 2:T){    cumprob[t] <- psi[t]*prod(1-psi[1:(t-1)]) }
cumprob.norm <- sum(cumprob[1:T])</pre>
```

- ... make sure its 95%CI doesn't get close to 1.
  - ightharpoonup if yes, then increase  $n^{\text{aug}}$
  - if cumprob.norm  $\ll$  0.8, you could consider decreasing  $n^{\text{aug}}$  (to save computation time)

#### POPAN Demonstration

#### Time to open up JAGS!

▶ Demonstration: Analyze a POPAN model for Hunt et al. [2017].

Pay-attention to data-augmentation and cumprob

► Next: Exercise: Model Selection on the POPAN

- Tim N. Hunt, Lars Bejder, Simon J. Allen, Robert W. Rankin, Daniella Hanf, and Guido J. Parra. Demographic characteristics of Australian humpback dolphins reveal important habitat toward the south-western limit of their range. *Endangered Species Research*, 32:71–88, 2017. doi: 10.3354/esr00784.
- Marc Kéry and Michael Schaub. Bayesian Population Analysis Using WinBUGS: A Hierarchical Perspective. Academic Press, Oxford, UK, October 2011. ISBN 978-0-12-387021-6. URL http://www.sciencedirect.com/science/book/9780123870209.
- Robert W. Rankin, Krista E. Nicholson, Simon J. Allen, Michael Krützen, Lars Bejder, and Kenneth H. Pollock. A full-capture Hierarchical Bayesian model of Pollock's Closed Robust Design and application to dolphins. *Frontiers in Marine Science*, 3(25), 2016. doi: 10.3389/fmars.2016.00025.
- J Andrew Royle and Robert M Dorazio. Parameter-expanded data augmentation for Bayesian analysis of capture-recapture models. *Journal of Ornithology*, 152(2):521–537, 2012. doi: 10.1007/s10336-010-0619-4.
- J.A. Royle, M. Kéry, and J. Guélat. Spatial capture-recapture models for search-encounter data. *Methods in Ecology and Evolution*, 2(6):602–611, 2011.