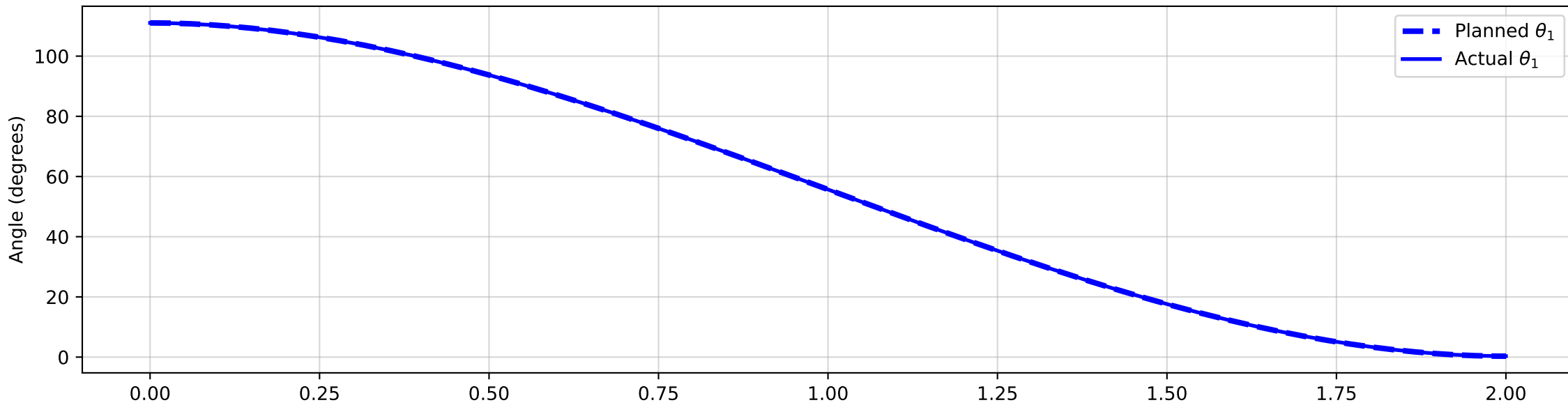


Joint Angle Tracking (Cubic Interpolation + PD Control, T=2.0s)

Joint 1 Angle θ_1



Joint 2 Angle θ_2

