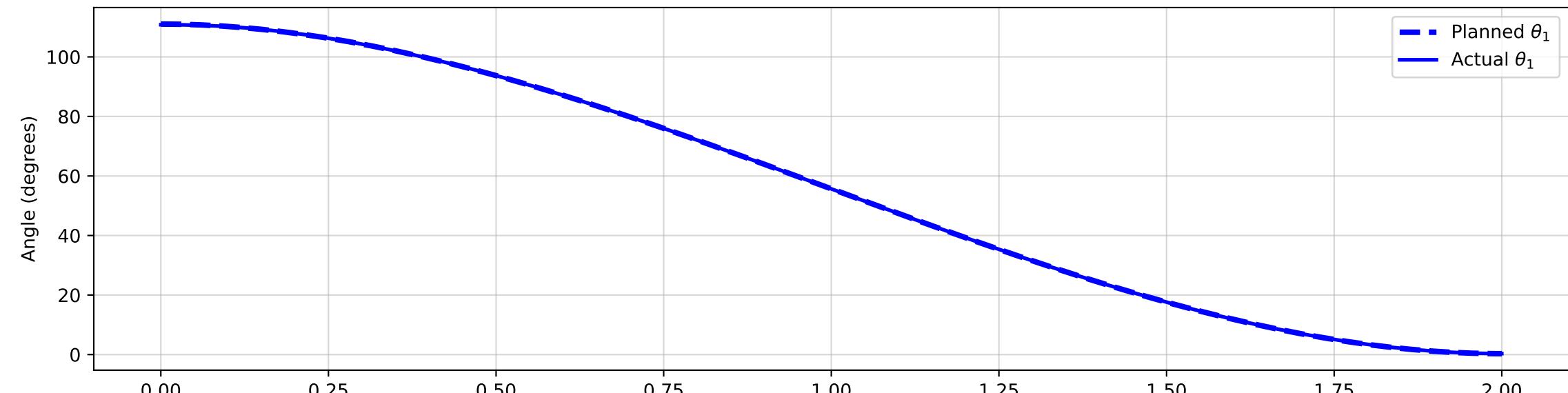


# Joint Angle Tracking (Cubic Interpolation + PD Control, T=2.0s)

Joint 1 Angle  $\theta_1$



Joint 2 Angle  $\theta_2$

