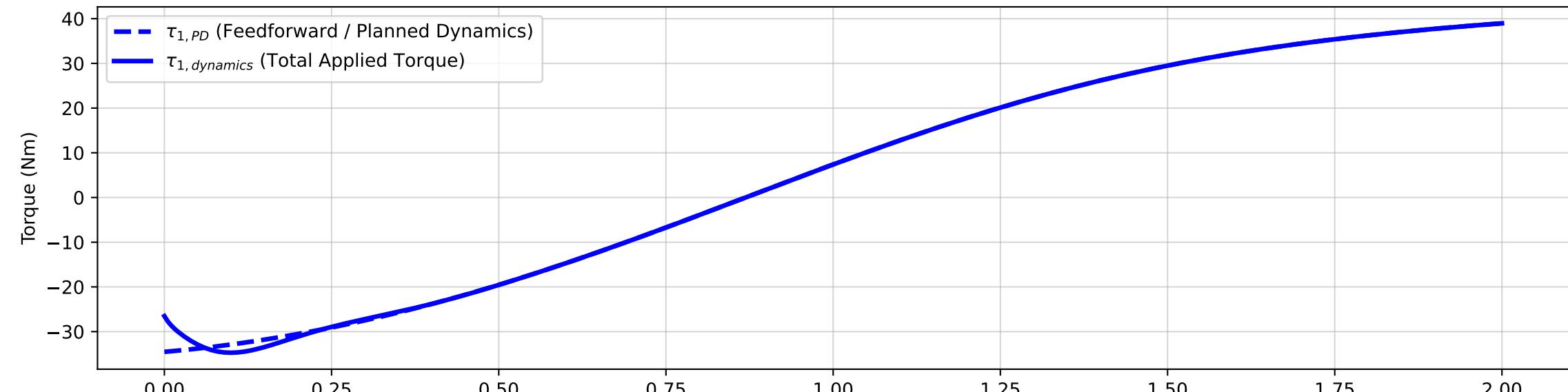


Joint Torque Comparison (Feedforward Dynamics vs. Feedforward + PD Feedback)

Joint 1 Torque τ_1



Joint 2 Torque τ_2

