fig1. task a
those two are the same because no noise
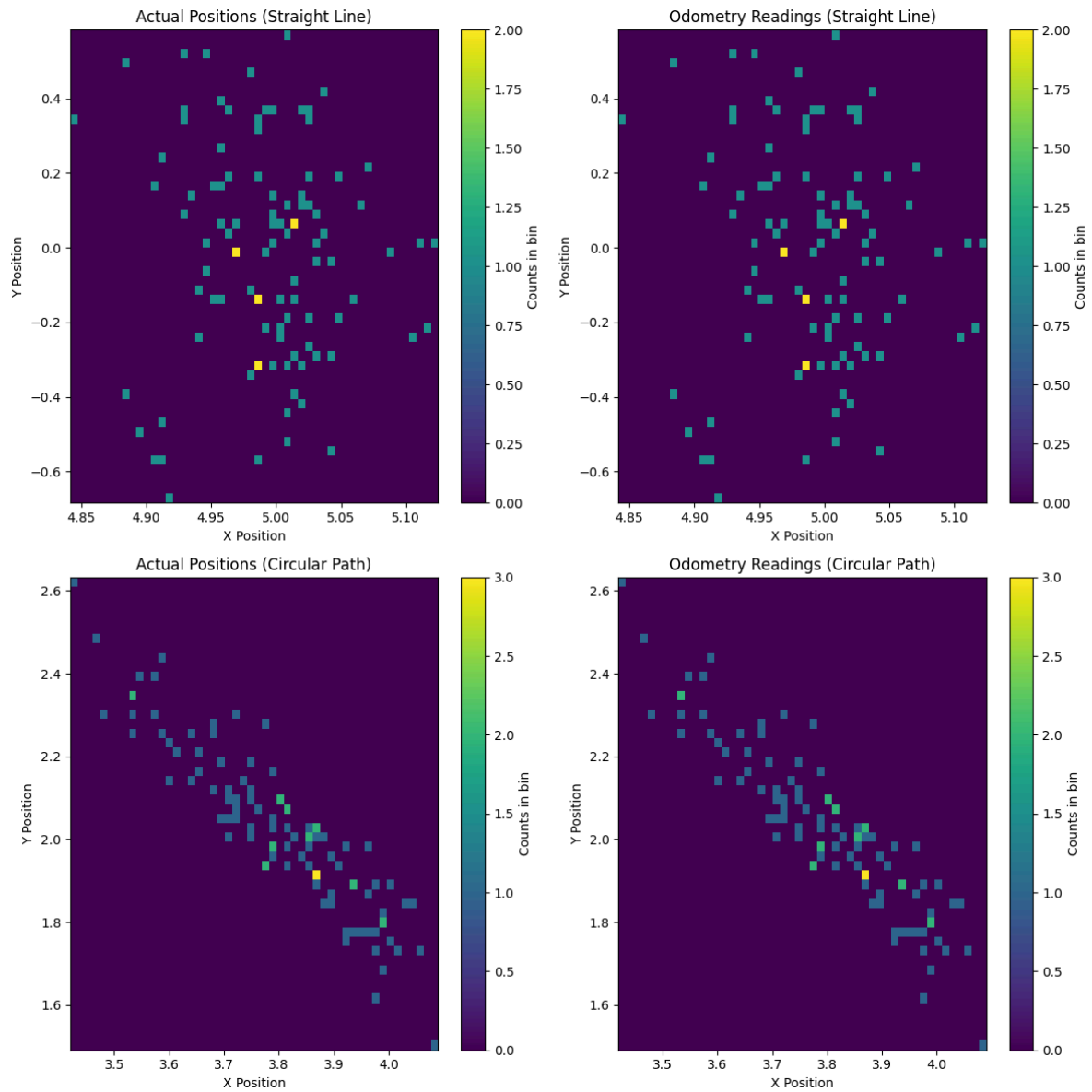
fig2. task b
still same because no noise in odometry, but there are circular path plots
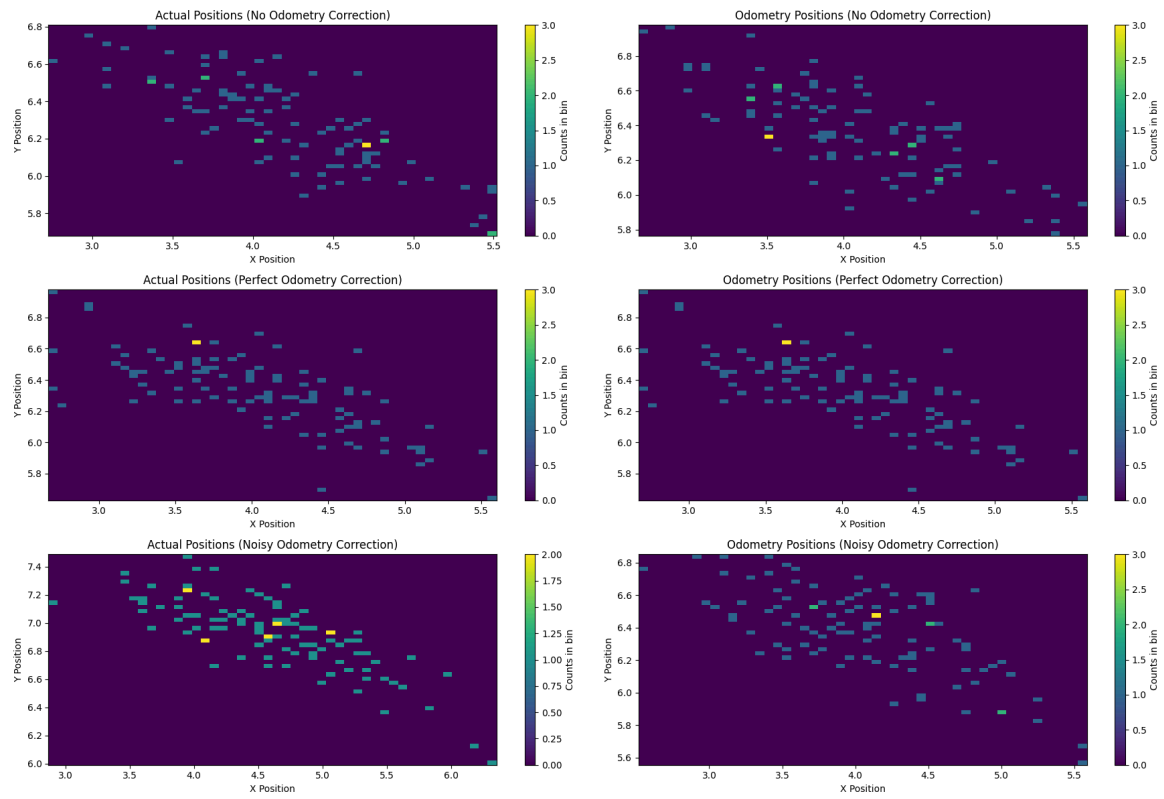
fig3. task c
only the "perfect odometry" look the same because "perfect" means no noise in measurement, but with correction we can see some improvement of odometry accuracy