Topics

- Time complexity
- -> STL ". Vectors, Pair, Bet, Map

Time complexity

- · time taken to execute an algorithm according to the size of input.
- · why is it required?

 -> our logic/algo shouldn't take months/years

 to be executed. It should be done in some time limit.
- · we would express it as a function of input, fcm.
- · A normal computer has it processing speed in GHZ i.e. approx 10° instructions/sec.
- for calculating time we would calculate no. of instructions i.e. f(n) would represent no of instructions as function of n. f(n) = no. of instruction

f(n)= 3n+2+1=3n+3

You needn't worry about exact calculation rather you should worry about predominant term i.e. here it's 3" n

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eupn forget conefficient of predominant term
                                                           n is the main thing ]
# int count = 0 //1

for (int i=0; i < n; ++i) // 2*(n+1) + 1
    { for (int j=0; j < h; ++j) // n= (2 ** (n+1)+1)
           \begin{cases} (aunt +=j) \end{cases}  // n^*n f(n) = 3n^2 + 4m + 3 predominant term
 * We talk about time complexity keeping in mind n is very large like of order of 105, 109 etc.
    Hence for f(n) = 3n^2 + 4n + 3, 4n + 3 is insignificant as compared to 3^4n^2 Moreover 3 is also insignificant
     if n is very large. This is called Asymtotic complexity.
    Big-O notation
    · used to classify algo based on growth rate of
      operations as input size grows
  so, for f(n) = 3n+3
                                        we say it runs in O(n) time complexity (O(n) read as order of n
    Similary f(n)=3n2+4n+3
                                         we say it o(n2)
                                         say it O(1)
                f(n) = 7
                                 م
· Most common classes
     · O(1) -> constant time
     O (log n) -> logarithmic
    O Ch) -> Linear
     · O(n2) -> Quadratic
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O(2") -> exponential

· O(n!) -> factorial

Light-green zone is good, cool!

Dark-green zone is excellent, congrats

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Defor: Criven two increasing fus f(n) & q(n)

we say f(n) is O(q(n)) "read as order of q(n)"
  if there exists constant c and not s.t.
                                  4 v> v0
                 f(n) < c.g(n)
\mathcal{E}.g:-f(n)=3n+3 g(n)=n \lim_{n\to\infty}\frac{f(n)}{g(n)}=3
                3n+3 < 7.n
c=7 \quad N_0=1
      ho=1
         f(n) = O(g(n)) = O(n)
eg:-f(n) = 3n+3 g(n) = n^2
                3n+3 < c.n2
                                    ANSNO
                   6 < C.1 him f(n) = 0
        1=0 N
                  3n+3 2 7n2 4n≥1
              f(n)= 0 (g(n)) = 0 (n2)
8.g:- f(n) = 4 n2 g(n) = n
     F C & no s.t.
                  4 n2 < c. n
                                   ∀n≥no
                                    Anzno
                ( contractiction).
    42 = fcm = 0 (g(n)) = 0(n)
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consider we are given an array of length N of integers and we want to find out if there exist a subset with sum = K^2

Idea: Check all subsets of array one by Dneiits sum is k.

There are 2" subsets and in finding sym of each subset it will take max O(n) time. So this would run in O(n.2") time complexity.

Consider n can be max 103. So we are intersted in finding worst time complexity. So no of instructions would be of order 109. 2109. Consider. each processin speed 109/s

Time required = 109.209 x 10-9 = 2109 s

≈ 2^{(0000,000,000} s Age of universe ≈ 2⁶⁰ s

STL CStandard template library of C++)

containers: place to hold data along with some special functionality.

"Use correct header in order to use its container
like #include < vector > . Also write "using namespace stal;

* Vector: It's just an array with added functionalities Declaration: vector <int> v; Not the vector <int > v(10); // vector with 10 elements

vector <int > v(10,-1); // vector with 10 elements

vector <int > v(10,-1);

vector <ehor> v(10,-1);

vector <ehor> v(10,-1);

vector <ehor> v(10,-1);

vector <ehor> vector</ei> -> push_back(); adds element out the end increasing size by 1. vector Lint> V; for (int i=0; i < n; ++i)

v. push-back (i); //gives you vector hoving elements v. Pop_book(); 0,1,2...,n-1

- size c); gives you current size of vector/no-ad elements.. v. size C); -it's unsigned integer, when you want to use it atleast typeoust into (int) > empty(); gives true if vector is empty v.empty() -> clearc); remove all elements of vector viclear() -> resize(); it makes if contain the require no. of v. resize (25) elements. Some intialisations: vector kint > V2 = V1; //visavedor → erase c); vector cint> v3 (v1);

→ insert(); [bit(v.begm(), v.end()) - s O(nlo [boit (v.begm(), v.end()) -8 O(nlogn) (* Pairs : keeping two examents together borcom anith), The first element of the pair is reflered to as first & second clement

Pillist = Pileard =

of the pair is reflered as second.

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Syntax:- Pair < data tyre 1, data tyre2>P;
             eg:- pair < ll, stoins > p = & 10, helloy
        pairs can und along with vectors & other STL based datastructures.
            cg:- vecto, < pair < el, el >> V;
                        V. push-bock ( & 10,203);
obe: while bothing a vector of pais. The vector is sorted according

to the first element.

ey: - [ v = [ v 5,217 , 1 ,67 , 1 4,127 , 13,87]

reduction

Jort ( v. begin), v. end();

gives: - [ v1,67 , 13,87,14,127 , 15,214]
            Two types of MDM STL unordered set - based on hashly - O(1)
                                      - unorded set. - based on hashly - O(1),
                   nt - Hairbais elements insorted order, store origine elements
                  Multiset - Stores chements in bottled order out a contain multiple instances of an element.
 maj chi, let n;
          g:- map < strig, ll7 m;
                                                   M [27 = 4.
                MI"hello" /= 4
            map < data tre, key, data trace quality m;
      Binon bearch
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Prefix [i] = V[0] + V[1] + - V[i]

prefix[i-1] = V[0] + V[i] + - V[i-1]

prefix[i-1] + V[i] = prefix[i]

prefix[i] = V[0]

prefix[i] = V[0]

prefix[i] = prefix[i-1] + V[i]

prefix[i] = prefix[i-1] + V[i]

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