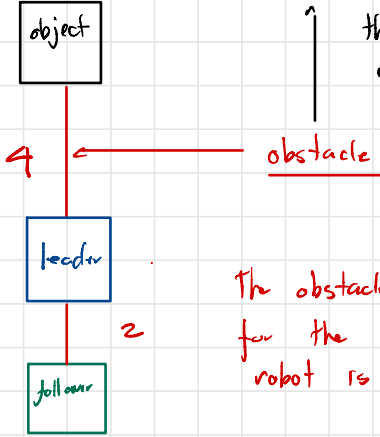


# Brainstorming

Theorem

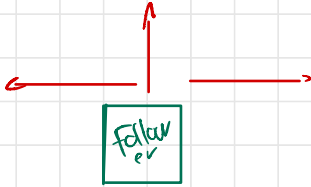
Variable is defined  
in the C code.  
It's the threshold for  
the robot to turn  
or take action.

The obstacle  
threshold for  
the leader  
robot is 4.



The obstacle threshold  
for the follower  
robot is 2

Follower Robot  
Original Robot view



vs

New follower robot  
view

