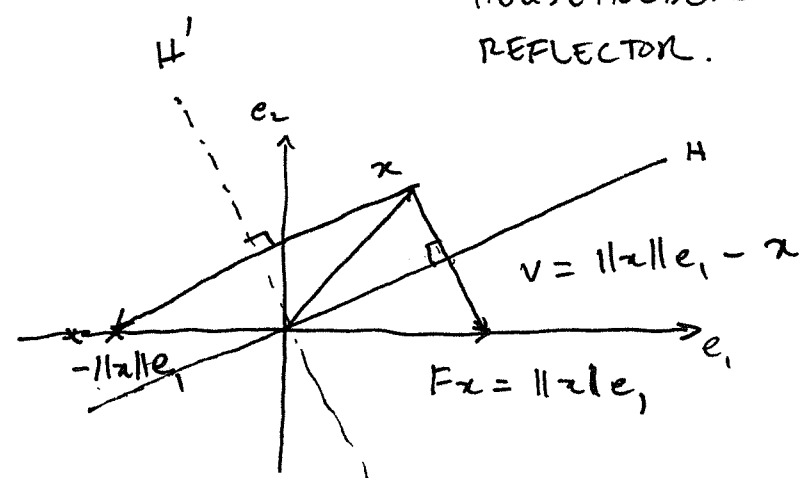


HOUSEHOLDER TRIANGULARIZATION

$$Q_n \dots Q_2 Q_1 A = R$$

$$Q_k = \begin{bmatrix} I & 0 \\ 0 & F \end{bmatrix}$$

HOUSEHOLDER REFLECTOR.



PROJECTION ONTO H

$$P = I - q q^* \quad \text{WHERE} \quad q = \frac{v}{\|v\|}$$

TO GO TWICE THE DISTANCE IN q

$$F = I - 2 q q^* = I - 2 \frac{v v^*}{v^* v}$$

①

TURNS OUT THERE ARE TWO CHOICES. ②

WHILE MATHEMATICALLY SPEAKING BOTH CHOICES ARE EQUALLY GOOD, NUMERICALLY WE'D LIKE TO CHOOSE THE ~~ADJECT~~ REFLECTION FURTHEST AWAY FROM x .

$$V = -\text{sign}(x_1) \|x\| e_1 - x$$

or

$$V = \text{sign}(x_1) \|x\| e_1 + x$$

TAKING ALSO $\text{sign}(0) = 1$

Notes

HOUSEHOLDER ALGORITHM

③

for $k = 1$ to n

$x = A_{k:m, k} \leftarrow$ VECTOR OF
THE k THROUGH
 m ENTRIES OF
THE k TH COLUMN

$$V_k = \text{sign}(x_1) \|x\|_2 e_1 + x \begin{bmatrix} a_k \\ x \end{bmatrix}$$

$$V_k = V_k / \|V_k\|_2$$

$$A_{k:m, k:n} = A_{k:m, k:n} - 2V_k (V_k^* A_{k:m, k:n})$$

END. FOR

A IS REDUCED TO UPPER
TRIANGULAR FORM WITHOUT
EVER EXPLICITLY COMPUTING Q.

HOWEVER, WE KNOW HOW TO APPLY Q (AND Q^*)

ONCE THE V_k 'S ARE KNOWN

SINCE

$$Q^* = Q_n \dots Q_2 Q_1$$

$$Q = Q_1 Q_2 \dots Q_n$$

RATHER THAN COMPUTING Q

FROM THE Q_k 'S THEN APPLYING

Q_1 THE SEQ SEQUENCE CAN

BE APPLIED DIRECTLY

IMPLICIT CALCULATION OF $Q^* b$

for $k = 1$ to n

$$b_{k:m} = b_{k:m} - 2V_k (V_k^* b_{k:m})$$

END FOR

IMPLICIT CALCULATION OF ~~Q~~ Qx ^⑤

for $k=n$ DOWN TO 1

$$x_{k:m} = x_{k:m} - 2v_k(v_k^* x_{k:m})$$

END FOR

TO FORM Q WE RECOGNIZE
THAT

$$QI = Q$$

AND PERFORM THE IMPLICIT
CALCULATION

$$Qe_i = g_i \quad \text{for all } i=1, \dots, m$$

EXAMPLE: LEGENDRE POLYNOMIALS

$$P_n(x) \quad \text{on} \quad [-1, 1]$$

POLYNOMIALS THAT ARE
ORTHOGONAL WITH RESPECT TO

THE INNER PRODUCT ^⑥

$$(f, g) = \int_{-1}^1 \overline{f(x)} g(x) dx$$

FOR $P_n(x)$ AND $P_m(x)$

$$\int_{-1}^1 \overline{P_n(x)} P_m(x) dx = \frac{2}{2n+1} \delta_{nm}$$

THE FIRST FEW ARE

$$P_0(x) = 1$$

$$P_1(x) = x$$

$$P_2(x) = \frac{3x^2}{2} - \frac{1}{2}$$

$$P_3(x) = \frac{5x^3}{2} - \frac{3}{2}x$$

\vdots

THEY CAN BE GENERATED
BY THE CONTINUOUS VERSION
OF QR APPLIED TO THE
"MATRIX" WHOSE "COLUMNS"
ARE THE MONOMIALS

$$A = \begin{bmatrix} 1 & x & x^2 & x^3 & \dots & x^{n-1} \end{bmatrix}$$

USING A CONTINUOUS VERSION
OF GRAM-SCHMIDT REPLACING

$$f_i^* \cdot v_j \quad \text{BY} \quad \underbrace{\int_{-1}^1 \bar{f}_i(x) v_j(x) dx}_{r_{ij}}$$

⑦

AND

$$\|v\|_2 \quad \text{BY} \quad \left(\underbrace{\int_{-1}^1 \bar{v}(x) v(x) dx}_{r_{ii}} \right)^{1/2} \quad \text{⑧}$$

WE OBTAIN

$$A = \begin{bmatrix} q_0(x) & q_1(x) & \dots & q_{n-1}(x) \end{bmatrix} \begin{bmatrix} r_{11} & \dots & r_{1n} \\ \vdots & \ddots & \vdots \\ r_{n1} & \dots & r_{nn} \end{bmatrix}$$

$P_n(x)$ IS RELATED TO $q_n(x)$

THROUGH

$$P_n(x) = \frac{q_n(x)}{q_n(1)}$$