FOR AE CMXM WE WITH PARTIAL PIVOTTING. HAVE $L_{m-1}P_{m-1}\cdots L_2P_2L_1P_1A=U$ CAN ALSO BE WRITTEN THIS AS

 $(L_{m-1} \cdots L_2 L_1)(P_{m-1} \cdots P_2 P_1)A$ = U $L_k = P_{m-1} \cdots P_{k+1} L_k P_{k+1} \cdots P_{m-1}$

PA = Lu

ALGORITHM FOR LU U=A P=I for K=1 to m-1 SELECT izk to [SELECT MAXIMITE | WILL | PIVOT $U_{k}, k:m \longrightarrow U_{i}, k:m$ $U_{k}, k:m$ $U_{$ PK,: 2 Pi,: for j = k+1 to m ljk = Ujk/Uvx

Ujikim = Ujikim - ljk Ukikim
END FOX

END TOR.

OF FLOPS N 3 m3

CONSIDER AGAIN

A=

1

1

STANDARD GAUSSIAN ELLAND ELIMINATION LEADS TO LARGE ENTRIES OF L AND U.

THIS AMPLIFICATION IS AT THE HEART OF THE INSTABILITY THM: A = LU FOR NONSINGULAR A6 CMXM RE COMPUTED BY STANDARD GAUSSIAN ELIMINATION ON A COMPUTER SATISFYING FPAI AND FPAII. \$1F NO ZERO-PIVOTS ARE ENCOUNTERY THEN COMPUTED [AND I SATISRY $\widetilde{L}\widetilde{u} = A + \varepsilon A$ $\frac{0.8AU}{U_{L}UU_{UU}} = O(\varepsilon)$ FOR SOME SAE CMXM BACKWARD STABILITY IF 11 LII IIII = OCHAIN

BUT IF ILIIIIUIL & OCHAII) (S)
(AN EXPECT DACKWARD WETABILITY.

PIVOTING

THM APPLIES REPLACING
A BY PA.

with PARTIAL PWOTING

LE KNOW ||L|| = O(1)

THEN FOR BACKWARD

STABILITY , WE MUST HAVE

ILUII = O (ILAII).

THIS & CAN BE MEASURED

BY A GROWTH FACTOR.

P= mAxij | Nij | mAxij | aij |

So. THEN WE HAVE

UNII = O(Q || A ||)

THM: PA = LU BE COMPUTED USING GAUSSIAN ELIMINATION WITH PIVOTING ON A COMPUTER SATISFYING FPAI AND FPAIL. THEN Z, W, AND P SATISFY $\frac{||\delta A||}{||A||} = O(\rho \epsilon)$ FOR SOME SAEC MXM WHERE P

1) THE GROWTH FACTOR.

AFTER EACH STEP K. THE 6+1 THROUGH IN ENTRIES IN THE LAST COLUMN WILL BE

$$U = \begin{bmatrix} 1 & 1 \\ 1 & 24 \\ 1 & 8 \\ 1 & 16 \end{bmatrix}$$

ENTRY umm is 2^{m-1} THUS, $Q=2^{m-1}$

THIS IS HUGE FOX LARGE MATRICE)!