

Yael Ben Shalom

☎ 312-560-6007 | ✉ yael.bshalom@gmail.com | 🔗 [linkedin.com/in/yael-benshalom](https://www.linkedin.com/in/yael-benshalom) | 🔗 yaelbenshalom.github.io

EDUCATION

MS in Robotics, Northwestern University, USA

📅 Sep 2020 - Dec 2021 (Expected)

- Coursework Focus – Machine Learning, Perception, Navigation, Computer Vision, Robotics Manipulation GPA – 3.94/4.00

BS in Mechanical Engineering, Tel Aviv University, Israel

📅 Sep 2014 - Jul 2018

- Majored in Robotics and Autonomous Systems – Dynamics, Mechatronics, and Control GPA - 87/100

PROFESSIONAL EXPERIENCE

Robotics Software Engineer Intern, Augean Robotics (Burro), USA

📅 Jun 2021 - Sep 2021

- Developed real-time vision-based obstacle avoidance and path-following methods, using reinforcement learning algorithms
- Built a robotic arm motion planning algorithm that leverages sensors to enable autonomous harvesting while avoiding collision
- Designed and integrated a state-machine architecture that improves runtime efficiency, modularity, and failure recovery ability
- Implemented production-level code for a large fleet of autonomous ground vehicles, ensuring a high degree of reliability

Mechanical Engineer, R&D Department, Elbit Systems, Israel

📅 Jun 2016 - Jul 2020

- Designed the electrical packaging of 5 electro-optic systems in core \$4M products, with 70+ units each
- Led three award-winning mechanical concepts; each received a \$250K grant from the Israeli Chief Scientist
- Initiated a study to reduce manufacturing time and costs of 3D-printed products; reduced 3D-printed prototype costs by 50% by introducing new materials, increasing printers' utilization, and optimizing printing requirements

Technical Program Manager, Intelligence Corps Technological Unit (81), Israel Defense Forces, Israel

📅 Nov 2012 - May 2013

- Coordinated a cross-functional project team of 100 people from defining requirements to product launch under a tight schedule
- Received Colonel's Award for Outstanding Performance and Leadership

Electrical Technician, Intelligence Corps Technological Unit (81), Israel Defense Forces, Israel

📅 Nov 2010 - Nov 2012

- Served as a team leader's expert on electro-optic systems manufacturing and testing
- Specialized in research, development, manufacturing, quality assurance (QA), and integration of electro-optic systems

SELECTED PROJECTS

🔗 yaelbenshalom.github.io

Recycling Robot with Machine Learning and Computer Vision Perception – Northwestern University

[Website]

Robotic Manipulation, Machine Learning, Motion Planning, Computer Vision, Image processing, Range Imaging, ROS, Python

- Programmed and controlled a Baxter robot to accurately pick and place a mixture of objects into different recycle bins, with more than 95% accuracy. Used inverse kinematics, MoveIt motion planning framework, and machine-learning-based classifier
- Created a machine-learning-based trash classification and segmentation software to recognize, classify, and localize more than 60 recyclable object types in a real-time image

Motorized Prosthetic Elbow – Northwestern University

[Website]

Rehabilitation Robotics, Medical Devices, Mechatronics, Feedback Control Systems, PID Controller, PCB Design, SolidWorks, C

- Designed, built, and controlled a motorized prosthetic elbow that imitates healthy arm motion to help amputees prevent falling, avoid injuries, and maintain balance while walking
- Defined precise system requirements by analyzing dozens of arm movement data patterns and simulating full arm dynamics

EKF SLAM from scratch on Turtlebot3 – Northwestern University

[Website]

Differential Drive Kinematics, EKF SLAM, Feature detection, Unsupervised Learning, Path Planning, ROS, C++

- Implemented feature-based Extended-Kalman-Filter SLAM and landmark detection with Unknown Data Association on Turtlebot3 from scratch, using a 2D-LiDAR scanner
- Wrote a 2D Kinematics library in C++ for differential drive robots, with complete unit testing

Robot Navigation and Control inside a Maze – Tel Aviv University

[Website]

Autonomous Vehicle, AI, SLAM, Mechatronics, Motion Planning, Path Planning, Arduino, C++

- Built a wheeled robot and coded it to navigate autonomously through an obstacle course using an embedded microprocessor, motors, and distance sensors (IR, TOF, and ultrasonic); applied real-time adaptive motion control

SKILLS & ADDITIONAL INFORMATION

- **Programming:** Python, C, C++, Matlab, HTML, CSS, JavaScript, Simulink, Git, Linux
- **Robotics:** Robot Operating System (ROS), TensorFlow, PyTorch, CUDA, OpenCV, MoveIt, Gazebo, Rviz, CoppeliaSim, Arduino
- **Mechanical Engineering:** SolidWorks, Altair Inspire, Ansys, CFdesign, SolidWorks Visualize, 3D printing
- **Electrical Engineering:** Eagle, PCB manufacturing, soldering
- Volunteered as a mentor in Cracking the Glass Ceiling, empowering underprivileged young women to pursue STEM education