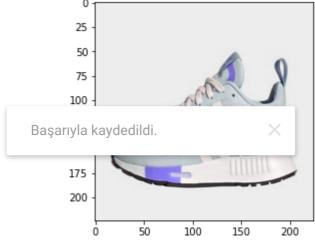
```
import time
start = time.time()
import os
import cv2
import random
import seaborn as sns
import numpy as np
import matplotlib.pyplot as plt
import tensorflow as tf
import keras
import keras.metrics
from keras.models import Sequential
from keras.layers import Flatten, MaxPooling2D, Conv2D, Dense
from sklearn.metrics import f1_score, confusion_matrix, ConfusionMatrixDisplay
from sklearn.pipeline import Pipeline, make pipeline
from keras.callbacks import EarlyStopping, ModelCheckpoint, ReduceLROnPlateau
img_array = cv2.imread('/content/drive/MyDrive/archive (1)/test/adidas/Adidas (18).jpg')
# img_array = cv2.cvtColor(img_array,cv2.COLOR_BGR2RGB)
plt.imshow(img_array)
plt.show()
       25
       50
```



```
data = '/content/drive/MyDrive/archive (1)/train'
categories = ['adidas','nike']
# For test our create_data function will be work
for ct in categories:
  path = os.path.join(data,ct)
  for img in os.listdir(path):
    img_array = cv2.imread(os.path.join(path,img))
    # img_array = cv2.cvtColor(img_array,cv2.COLOR_BGR2RGB)
    plt.imshow(img_array)
    plt.show()
    break
break
```

```
25 - 50 - 75 - 100 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 150 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200 - 200
```

print(img_array.shape)

(224, 224, 3)

```
IMG_Size = 150
new_array = cv2.resize(img_array, (IMG_Size,IMG_Size))
plt.imshow(new_array)
plt.show()
```



```
training_data = []
test_data = []
val_data = []

def create_data(my_data_path,my_data):
    for ct in categories:
    path = os.path.join(my_data_path,ct)
        class_num = categories.index(ct)
        for img in os.listdir(path):
        datagen = tf.keras.preprocessing.image.ImageDataGenerator(rescale=1./225)
        generator = datagen.flow_from_directory(my_data_path, shuffle=True, batch_size=32)
        try:
            img_array = cv2.imread(os.path.join(path,img))
            # img_array = cv2.cvtColor(img_array,cv2.COLOR_GRAY2RGB)
            new_array = cv2.resize(img_array, (IMG_Size,IMG_Size))
            my_data.append([new_array,class_num])
```

```
except Exception as e:
          pass
test_data_path = '/content/drive/MyDrive/archive (1)/test'
train_data_path = '/content/drive/MyDrive/archive (1)/test'
val_data_path = '/content/drive/MyDrive/archive (1)/validation'
create_data(train_data_path,training_data)
create_data(test_data_path,test_data)
create_data(val_data_path,val_data)
random.shuffle(training_data)
random.shuffle(test_data)
for sample in training_data[:10]: # For test shuflle
  print(sample[1])
     1
     0
     1
     0
     0
     1
     1
     0
     1
x = []
y = []
for features, label in training_data:
  x.append(features)
 Başarıyla kaydedildi.
x test = | |
y_{test} = []
for features, label in test_data:
  x_test.append(features)
  y_test.append(label)
x_val = []
y_val = []
for features, label in val data:
  x val.append(features)
  y_val.append(label)
x = np.array(x)
x_test = np.array(x_test)
x_val = np.array(x_val)
y = np.array(y)
y_test = np.array(y_test)
y_val = np.array(y_val)
```

```
x.shape,y.shape,x_test.shape,y_test.shape,x_val.shape,y_val.shape
     ((60, 150, 150, 3), (60,), (60, 150, 150, 3), (60,), (55, 150, 150, 3), (55,))
x = np.array(x).reshape(-1, IMG_Size, IMG_Size, 3)
x_test = np.array(x_test).reshape(-1, IMG_Size, IMG_Size, 3)
x_val = np.array(x_val).reshape(-1, IMG_Size, IMG_Size, 3)
x.shape,y.shape,x_test.shape,y_test.shape,x_val.shape,y_val.shape
     ((60, 150, 150, 3), (60,), (60, 150, 150, 3), (60,), (55, 150, 150, 3), (55,))
y = y.reshape(-1,1)
y_test = y_test.reshape(-1,1)
y_val = y_val.reshape(-1,1)
from sklearn.preprocessing import OneHotEncoder
enc = OneHotEncoder(handle_unknown='ignore')
enc.fit(y)
enc.fit(y_test)
enc.fit(y_val)
x.shape,y.shape,x_test.shape,y_test.shape,x_val.shape,y_val.shape
     ((60, 150, 150, 3),
      (60, 1),
 Başarıyla kaydedildi.
      (55, 1)
best_model = ModelCheckpoint('/content/drive/MyDrive/bestmodel.hdf5', monitor='accuracy',
best_val_acc = ModelCheckpoint('/content/drive/MyDrive/best_val_acc.hdf5', monitor='val_ac
model = Sequential()
model.add(Conv2D(128, (3,3), input_shape=(150, 150, 3) , activation='relu'))
model.add(MaxPooling2D(2,2))
model.add(Conv2D(256, (3,3), activation='relu'))
model.add(MaxPooling2D(2,2))
model.add(Conv2D(256, (3,3), activation='relu'))
model.add(Flatten())
model.add(Dense(256, activation='relu'))
model.add(Dense(128, activation='relu'))
model.add(tf.keras.layers.Dropout(.2))
model.add(Dense(6, activation='softmax'))
opt = tf.keras.optimizers.Adam(learning_rate=0.001, decay=1e-6)
```

```
# Compile model
model.compile(
    loss='sparse_categorical_crossentropy', # binary_crossentropy, sparse_categorical_cros
   optimizer=opt,
   run_eagerly=True,
   metrics=['accuracy']
)
hist = model.fit(x, y, validation_data=(x_val,y_val), verbose=2, epochs=20, shuffle=True,
     Epoch 1/20
     2/2 - 35s - loss: 575.5352 - accuracy: 0.2500 - val loss: 1714.5830 - val accuracy:
     Epoch 2/20
     2/2 - 32s - loss: 954.5818 - accuracy: 0.5000 - val_loss: 45.8089 - val_accuracy: 0.
     Epoch 3/20
     2/2 - 35s - loss: 33.4230 - accuracy: 0.5167 - val_loss: 6.2965 - val_accuracy: 0.50
     Epoch 4/20
     2/2 - 34s - loss: 3.0799 - accuracy: 0.6667 - val loss: 0.8517 - val accuracy: 0.454
     Epoch 5/20
     2/2 - 46s - loss: 1.1580 - accuracy: 0.7333 - val_loss: 1.1766 - val_accuracy: 0.672
     Epoch 6/20
     2/2 - 37s - loss: 0.7841 - accuracy: 0.8167 - val_loss: 3.7669 - val_accuracy: 0.545
     Epoch 7/20
     2/2 - 28s - loss: 1.1789 - accuracy: 0.7667 - val_loss: 3.3433 - val_accuracy: 0.490
     Epoch 8/20
     2/2 - 32s - loss: 2.0127 - accuracy: 0.8000 - val_loss: 2.1312 - val_accuracy: 0.618
     Epoch 9/20
     2/2 - 34s - loss: 0.3079 - accuracy: 0.9167 - val_loss: 2.9074 - val_accuracy: 0.490
     Epoch 10/20
     2/2 - 37s - loss: 0.2324 - accuracy: 0.9500 - val_loss: 1.9650 - val_accuracy: 0.563
     Epoch 11/20
     2/2 - 35s - loss: 0.1417 - accuracy: 0.9667 - val_loss: 2.0513 - val_accuracy: 0.600
     Epoch 12/20
                                   iracy: 0.9167 - val_loss: 4.1698 - val_accuracy: 0.545
 Başarıyla kaydedildi.
                 1035. 0.5551 accuracy: 0.9167 - val_loss: 1.9645 - val_accuracy: 0.581
     Epoch 14/20
     2/2 - 31s - loss: 0.2179 - accuracy: 0.9833 - val loss: 2.4311 - val accuracy: 0.527
     Epoch 15/20
     2/2 - 29s - loss: 0.3749 - accuracy: 0.9167 - val loss: 1.9064 - val accuracy: 0.563
     Epoch 16/20
     2/2 - 24s - loss: 0.2024 - accuracy: 0.9667 - val_loss: 1.9749 - val_accuracy: 0.563
     Epoch 17/20
     2/2 - 30s - loss: 0.0680 - accuracy: 1.0000 - val loss: 2.3094 - val accuracy: 0.563
     Epoch 18/20
     2/2 - 27s - loss: 0.0367 - accuracy: 1.0000 - val loss: 3.1910 - val accuracy: 0.600
     Epoch 19/20
     2/2 - 25s - loss: 0.0444 - accuracy: 0.9833 - val_loss: 5.2440 - val_accuracy: 0.545
     Epoch 20/20
     2/2 - 25s - loss: 0.5225 - accuracy: 0.9167 - val_loss: 2.6957 - val_accuracy: 0.618
```

```
hist.history??
```

```
def visualization(name,h,color):
   t = h.history[name]
```

```
my_max = max(t)
my_min = min(t)
print(f'Name : {name:10} max : {my_max:10} min : {my_min:10}')
plt.plot(t,color=color,linewidth=3.0)
plt.title(name)
plt.ylabel(name)
plt.xlabel('Epoch')
plt.legend([name],loc='upper left')
plt.show()

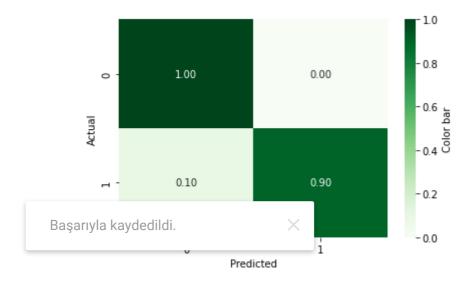
visualization('accuracy',hist,'Blue')
visualization('loss',hist,'Red')
visualization('val_accuracy',hist,'Green')
visualization('val_loss',hist,'Black')
```

Başarıyla kaydedildi.

```
0.25
    Name : accuracy
                                  1.0 min :
                      max :
                            accuracy
       1.0
               accuracy
       0.9
       0.8
       0.7
       0.6
       0.5
       0.4
       0.3
           0.0
                2.5
                     5.0
                          7.5
                               10.0
                                    12.5
                                         15.0
                                              17.5
                             Epoch
    Name : loss
                      max : 954.581787109375 min : 0.03665284439921379
       1000
                055
        800
        600
model.load_weights('/content/drive/MyDrive/bestmodel.hdf5')
res = model.evaluate(x_test, y_test)
print("test loss, test acc:", res)
     test loss, test acc: [0.04606626182794571, 1.0]
                               Epoch
                                  MyDrive/best_val_acc.hdf5')
 Başarıyla kaydedildi.
print ( test 1055, test act. , res)
    2/2 [============ ] - 5s 2s/step - loss: 0.6011 - accuracy: 0.9500
    test loss, test acc: [0.6010614633560181, 0.949999988079071]
                                             /\ / |
                    1 N
                          и
def my_predict(my_model,my_x_test):
 y_pred = my_model.predict(my_x_test)
 return y_pred
def my f1 score(my y test, my y pred):
 f1 = f1_score(my_y_test, my_y_pred, average="micro")
  return f1
def my_conf_matrix(my_y_test,my_y_pred):
  cm = confusion_matrix(my_y_test, my_y_pred)
  cm_norm = np.round(cm/np.sum(cm,axis=1).reshape(-1,1),2)
  sns.heatmap(cm_norm,cmap='Greens',annot=True,
             cbar_kws={'orientation' : 'vertical', 'label' : 'Color bar'},
             fmt='.2f'
             )
```

my_conf_matrix(y_test,y_pred_res)

Layer (type)



```
newpath = r'/content/drive/MyDrive/Model'
if not os.path.exists(newpath):
    os.makedirs(newpath)

import pickle
# To save model || You can use tensorflow model.save
pickle_out = open('/content/drive/MyDrive/Model/model.pickle','wb')
pickle.dump(model,pickle_out)
pickle_out.close()

model.summary()
    Model: "sequential_9"
```

Output Shape

Param #

•	• •	Choosipyhb Colaborate	, y
	conv2d_27 (Conv2D)	(None, 148, 148, 128)	3584
	<pre>max_pooling2d_18 (MaxPool g2D)</pre>	olin (None, 74, 74, 128)	0
	conv2d_28 (Conv2D)	(None, 72, 72, 256)	295168
	<pre>max_pooling2d_19 (MaxPool g2D)</pre>	olin (None, 36, 36, 256)	0
	conv2d_29 (Conv2D)	(None, 34, 34, 256)	590080
	flatten_9 (Flatten)	(None, 295936)	0
	dense_23 (Dense)	(None, 256)	75759872
	dense_24 (Dense)	(None, 128)	32896
	dropout_9 (Dropout)	(None, 128)	0
	dense_25 (Dense)	(None, 6)	774

Total params: 76,682,374 Trainable params: 76,682,374 Non-trainable params: 0

```
end = time.time()
print((end - start)/60)
```

30.865265921751657