# 2.4G 10-channel Remote Control

#### 2.4G 10-channel Remote Control

Product parameters
Function keys
Default channel
SBUS receiver
Pairing steps
PWM receiver
Pairing steps

## **Product parameters**

# **Product Parameters**

Number of channels	10
Applicable models	ROS Robot、robot car、AGV mobile carrier、drone etc
Frequency range	2.4GHz ISM
Spread spectrum method	FHSS
Wireless remote control distance	300~800m(open area)
Receiver signal	SBUS/PWM signal
Connect automatically	After pairing, it supports automatic connection after power on
Low voltage alarm	Support
Antenna length	About 9cm
Number of antennas	Dual Antenna
Weight	About 320g (battery not included)
Size	Remote control(antenna not included): 175mm*150mm*68mm SBUS Receiver (antenna not included): 28mm*15mm*3mm PWM Receiver (antenna not included): 37.8mm*23.7mm*13.5mm
Transmit power	≈120MA
Modulation pattern	GFSK
Responding speed	PWM<20MS
Receive sensitivity	-96dbm
Receiver power supply range	DC 3.5V-9V
Transmitter power supply range	DC 3.7V-9V
Power supply method	AA battery*4 or lithium battery

# **Function keys**

Note: The SWA channel joystick will reset automatically when it is moved, but the SWB, SWC, and SWD joysticks will not reset automatically

# **Functions Distribution**

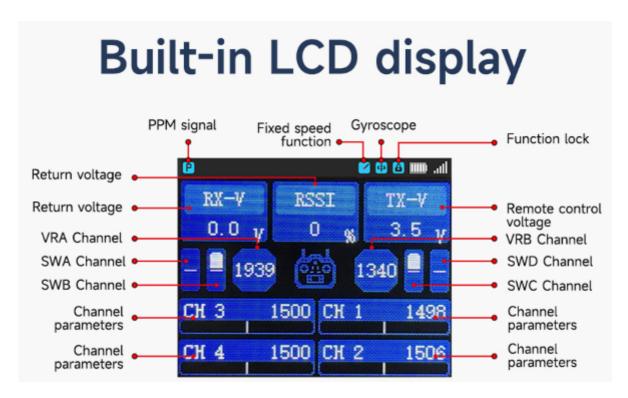


①Antenna ②VRA Channel ③VRB Channel ④SWB Channel

⑤SWC Channel ⑥SWA Channel(Self-reset) ⑦SWD Channel ⑧Power switch

③Fine adjustment key ④Fine adjustment key ⑤Up key ⑥Back key

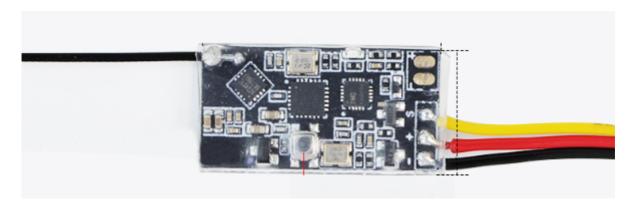
①Down key ®Confirm key



### **Default channel**

HT-10A remote control	Default channel: Remote control does not perform channel mapping
CH1	Right joystick: slide left and right
CH2	Right joystick: slide up and down
CH3	Left joystick: slide up and down
CH4	Left joystick: slide left and right
CH5	SWA channel
CH6	SWB channel
CH7	SWC channel
CH8	SWD channel
CH9	VRA channel
CH10	VRB channel

# **SBUS** receiver



SBUS receiver	Functions
S	Singal (SIG)
+	Positive pole of power supply (VCC) : 5V
-	Negative pole of power supply (GND)

# **Pairing steps**

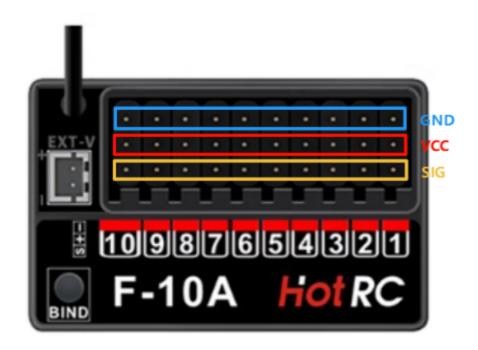
SBUS receiver indicator light status	Meaning
LED slowly flashing	Device not connected
LED quickly flashing	Pairing status
LED keep on	Connected devices

1. Power the SBUS receiver, and the LED indicator on the SBUS is in a slow flashing state;

- 2. Press and hold the button on the SBUS receiver for 1 second, and the LED will flash, indicating that the SBUS receiver has entered pairing mode;
- 3. Turn on the power switch of the HT-10A remote control, and the HT-10A remote control will automatically pair with the SBUS receiver; After successful pairing, the LED indicator light on the SBUS receiver remains on: Connected status cannot enter pairing status.

Attention: The HT-10A remote control only needs to be paired once with the SBUS receiver, and it will automatically connect the next time it is turned on, so there is no need to pair again!

### **PWM** receiver



PWM receiver	Pin function
S (Singal)	SIG (Yellow)
+ (Positive pole of power supply)	VCC (Red) : 5V
- (Negative pole of power supply)	GND (Brown)

## **Pairing steps**

SBUS receiver indicator light status	Meaning
LED slowly flashing	Device not connected
LED quickly flashing	Pairing status
LED keep on	Connected devices

- 1. Power the PWM receiver, and the LED indicator on the PWM is in a slow flashing state;
- 2. Press and hold the button on the PWM receiver for 1 second, and the LED will flash, indicating that the PWM receiver has entered pairing mode;

3. Turn on the power switch of the HT-10A remote control, and the HT-10A remote control will automatically pair with the PWM receiver; After successful pairing, the LED indicator light on the PWM receiver remains on: Connected state cannot enter pairing state.

Attention: The HT-10A remote control and PWM receiver only need to be paired once, and will automatically connect the next time it is turned on, no need to pair again!