Vanjee720 + cartographer compilation

1、 Operating environment

ROS(ubuntu 18.04 melodic)

cartographer

cartographer_ros

pointcloud_to_laserscan

vanjee_lidar_720

2、 Source code path

cartographer source code path：

```
src/cartographer
```

```
src/cartographer_ros
```

Vanjee 720 16-line radar driver：

```
src/vanjee_lidar_720
```

3、 Source code compilation

Start the terminal under the workspace and enter the command in the terminal：

```
cd ~/wlr_720_cartographer_ws

catkin build
```