Roboduino Communication protocol								
$1,0,0,0# Car advance								
First bit	1234567		1:advance 2:stop 3:left 4:right 5: spin left 6: spin right 7:stop					
Second bit	1:accelerate	2:decelerate						
Thrid bit	1:whistle	2:Turn off beep						
Forth bit	1:switch RGB light							
$Servo,UD000# Vertical servo angle: 000-180								
$Servo,LRL# Horizontal servo rotate left								
$Servo,LRR# Horizontal servo rotate right								
$Servo,LRS# Horizontal servo rotate stop								
$Music,11# select music 11Star , 21Bingo , 31MerryChristmas , 41Ode , 51Birthday Close music ($Music,00#)								
$Mode,11# select mode Start 11:Color Light mode 21:Avoiding mode 31:Tracking mode Close mode ($Mode,00#)								
Return Data :								
$CSB,000# Return ultrasonic data								