										communication	protocol							
									Lower comput	er (car receiving o		l format						
General protocol		state of motion		rotate		whistle		accelerate and decelerate		Shake left and right		sing		light		outfire		Servo reset
	1 Data packet header0	2	3	4	5	6	7 Separator symbol		9 Separator symbol	10	11 Separator symbol	12	13 Separator symbol	14	15	16	17 Separator symbol	18
stop	Pata packet neaderu	Command bit_1	Separator symbol	Command bit_2	Separator symbol	Command bit_3	Separator symbol	Command bit_4	Separator symbol	Command bit_6	Separator symbol	Data bit_6	Separator symbol	Data bit_9	Separator symbol	Data bit_10	Separator symbol	O Data Dit_11
run	s	1		0		0	,	0		0		0	-	0		0		0
back	s	2		0		0		0		0		0		0		0		0
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turn right	\$	4		0		0		0		0		0		0		0		0
turn left in place	\$	0		1		0		0		0		0		0		0		0
turn right in place whistle	0	0		0		•		0		0		0		0	•	0		0
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Shake left	\$	0	,	0		0	,	0		1		0	,	0	,	0	,	0
Shake right	\$	0		0		0		0		2		0		0		0		0
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ounser reading	Data packet header	Command bit	Separator symbol	Command word	value	Separator symbol	Command word	value	Separator symbol	Command word	value	Separator symbol	Command word	value	Separator symbol	Command word	value	Separator symbol
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Notes		1	1			_						_	L1L2R1F	12			L1R1	
for exmaple	\$4WD,CSB125,PV8.3,	GS214,LF1011,F	W01,GM10#															
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Gyro reading				MPI	J6050			MPU6050		MPU	8050		MPU605	0		MP	J8050	
Gyro reading	Data packet header	Command bit	Separator symbol	MPI Command word	J6050 value	Separator symbol	Command word	APU6050 value	Separator symbol	MPU Command word	8050 value	Separator symbol	MPU605 Command word	0 value	Separator symbol	MP Command word		Separator symbol
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