

Object tracking

1. Start

Input following command:

```
roslaunch astra_tracker KCFTTracker.launch
```

After startup, enter the selection mode, select the location of the object with the mouse, as shown in the following figure.

Release to start recognition.



X, Y represents the center point of the object in the image, while Z represents the distance in meters and centimeters.

View the node diagram.

```
rqt_graph
```

