

Manage APP control service

In the factory image, the APP control service will be automatically started when the machine is turned on. There are two services in total, the first is the ROS node service, and the second is the APP program service.

Close the service

The APP and handle trial service are automatically started when the machine is turned on by default in the factory image, which may cause interference in actual development. Therefore, if you do not need to automatically start the APP and handle control service when the machine is turned on, please enter the following command.

Temporarily disable APP program service

```
arm-stop
```

Permanently disable APP service

```
sudo systemctl disable yahboom_arm.service  
sudo systemctl disable yahboom_app.service
```

Query APP service status

```
sudo systemctl status yahboom_arm.service  
sudo systemctl status yahboom_app.service
```

Enable service

If you permanently disabled the APP service in the previous step and want to enable it later, or restore the APP service to start automatically at boot, please enter the following command.

Temporarily start the APP service

```
sudo systemctl start yahboom_arm.service  
sudo systemctl start yahboom_app.service
```

Set the APP service to start automatically at boot

```
sudo systemctl enable yahboom_arm.service  
sudo systemctl enable yahboom_app.service
```