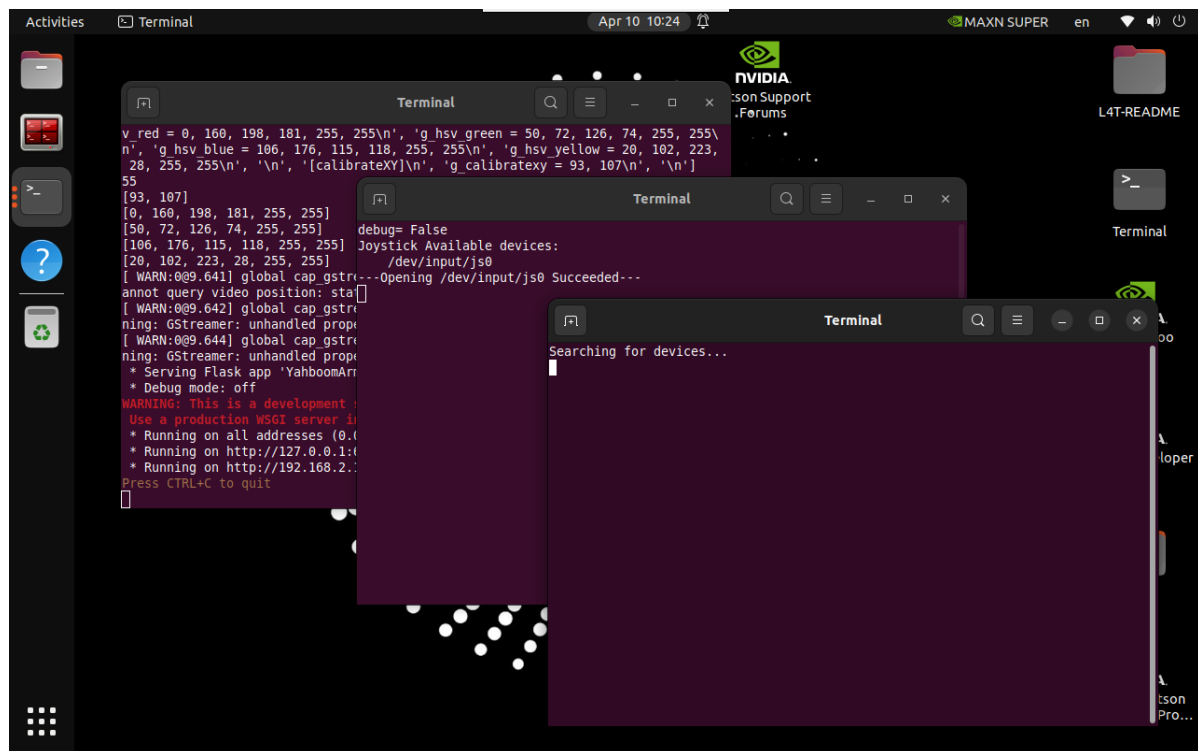# Manage APP control service

In the factory image, the APP control program will be automatically started when the computer is turned on. There are two programs in total, the first is the ROS node and the second is the APP program.

Close the APP program

The APP and handle trial service are automatically started when the computer is turned on by default in the factory image, which may cause interference in actual development. Therefore, if you do not need to automatically start the APP and handle control service when the computer is turned on, please do the following.
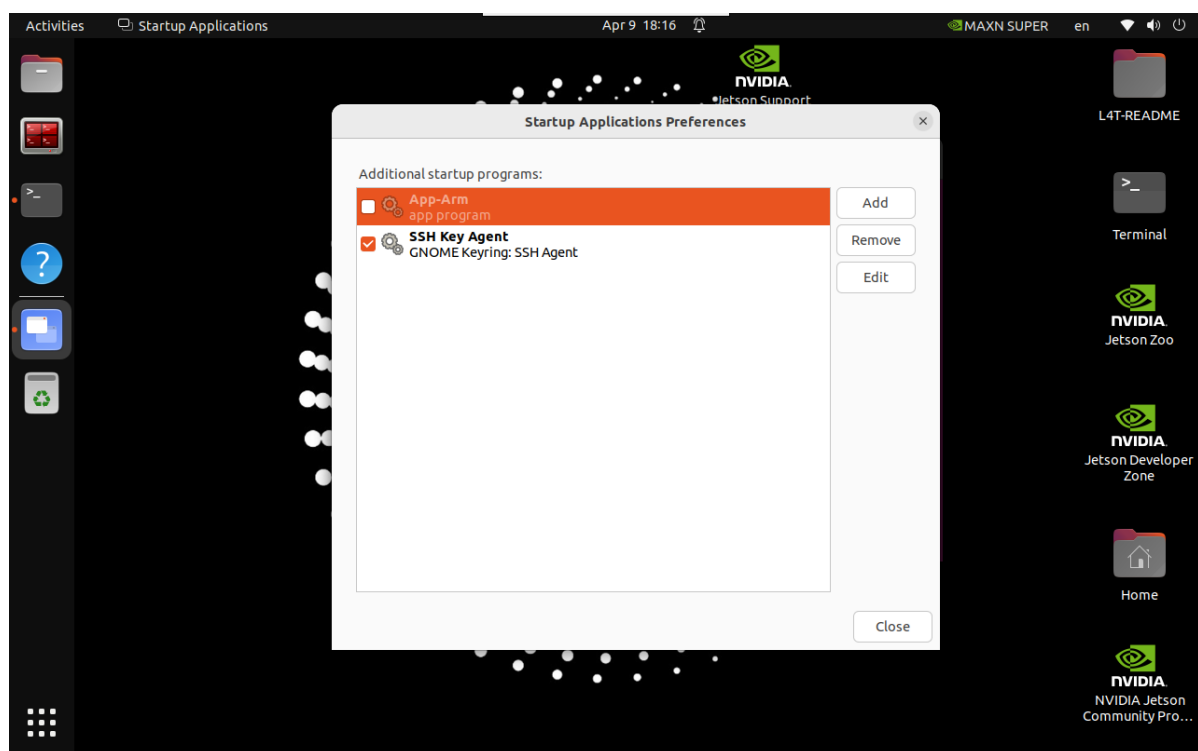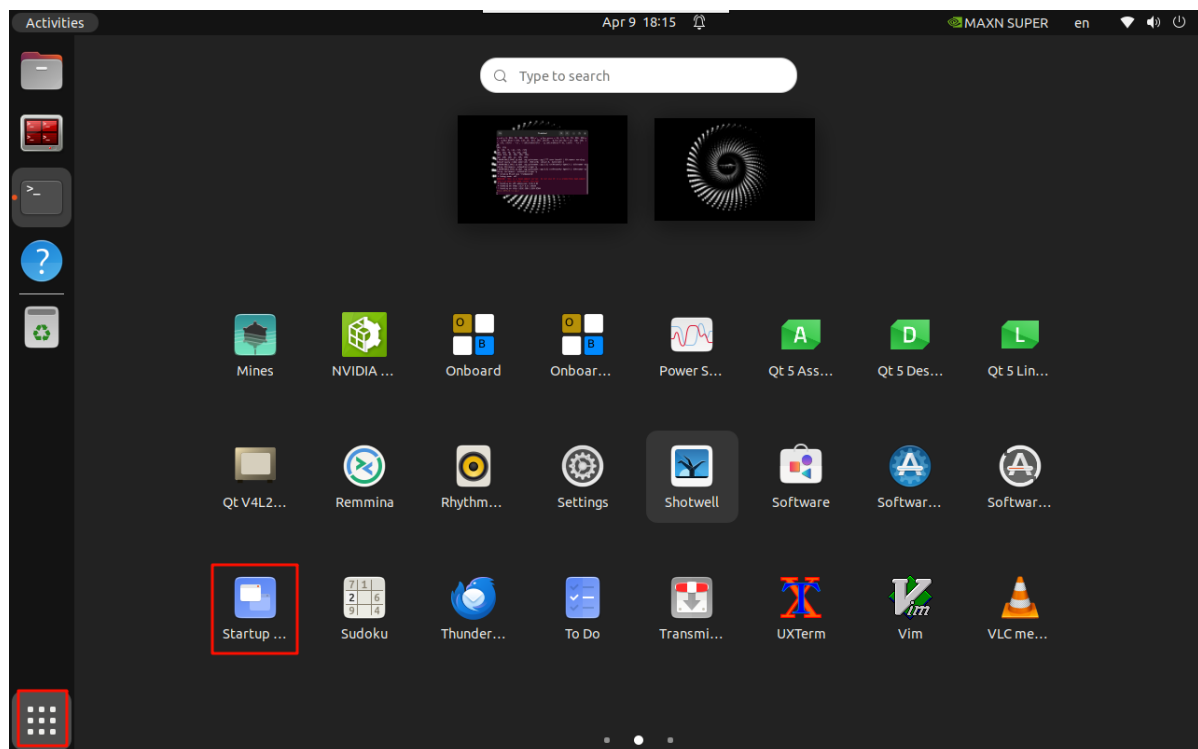
Temporarily close the APP program service


```
#Three terminals, APP control program, handle control program, APP search device
program
After booting up the terminal, press CTRL+C to end the program, or close the
window
```

Permanently close the APP service


```
After cancelling the check of APP-Arm, restart the robotic arm
```
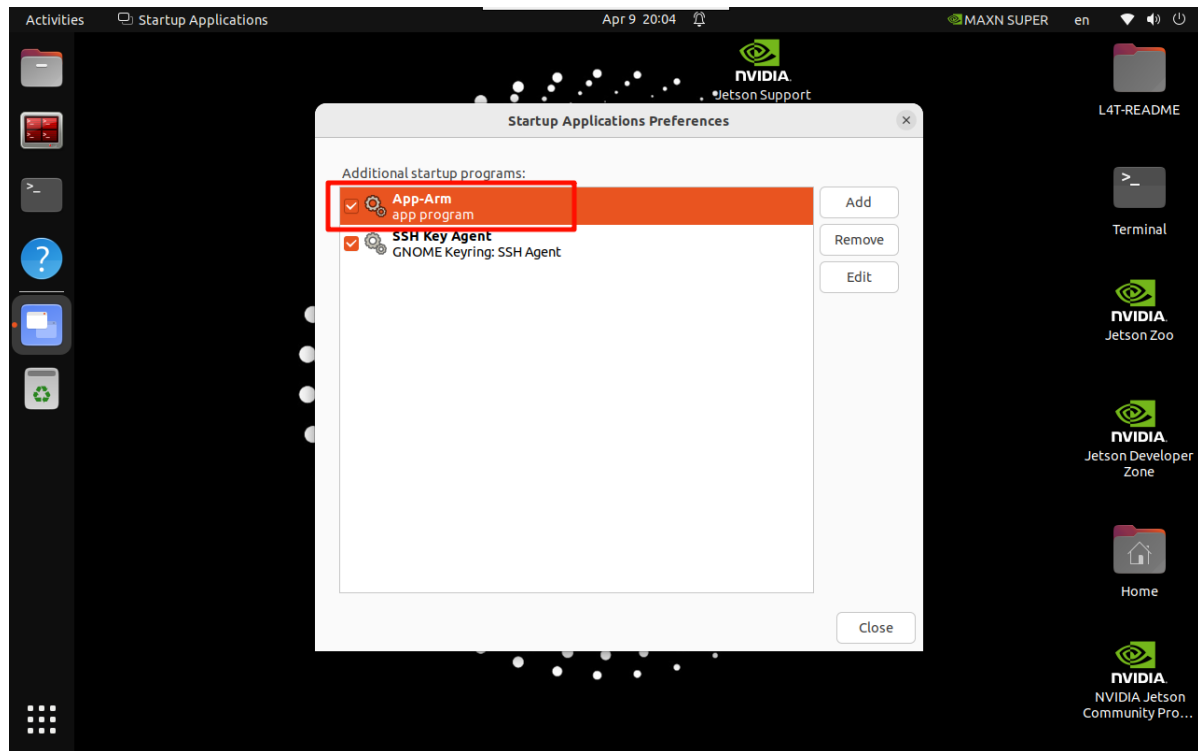
Open the APP program

If you permanently closed the APP service in the previous step, and want to open the APP service later, or restore the APP service startup function, please do the following.

Temporarily open the APP service

```
bash ~/dofbot_pro/APP_DOFBOT_PRO/start_app.sh
```

Set the APP service to start automatically


```
After checking APP-Arm, restart the robot arm
```