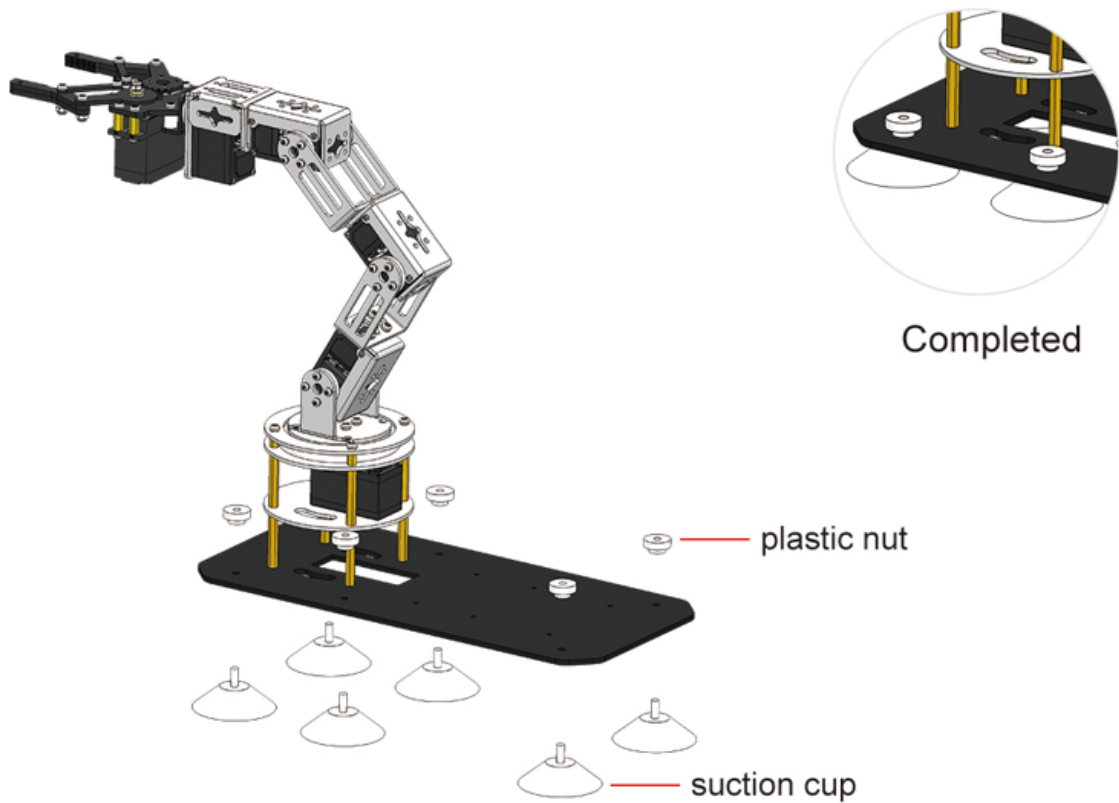


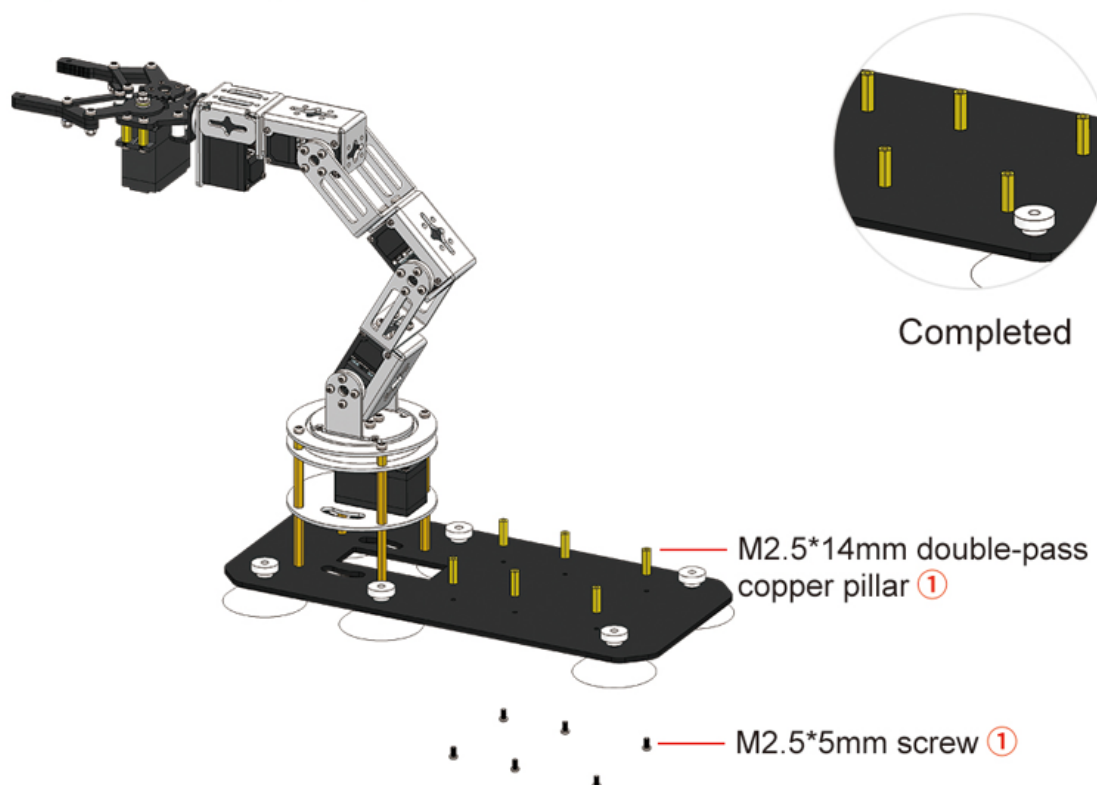
2.Assemble

1. Install Robotic arm

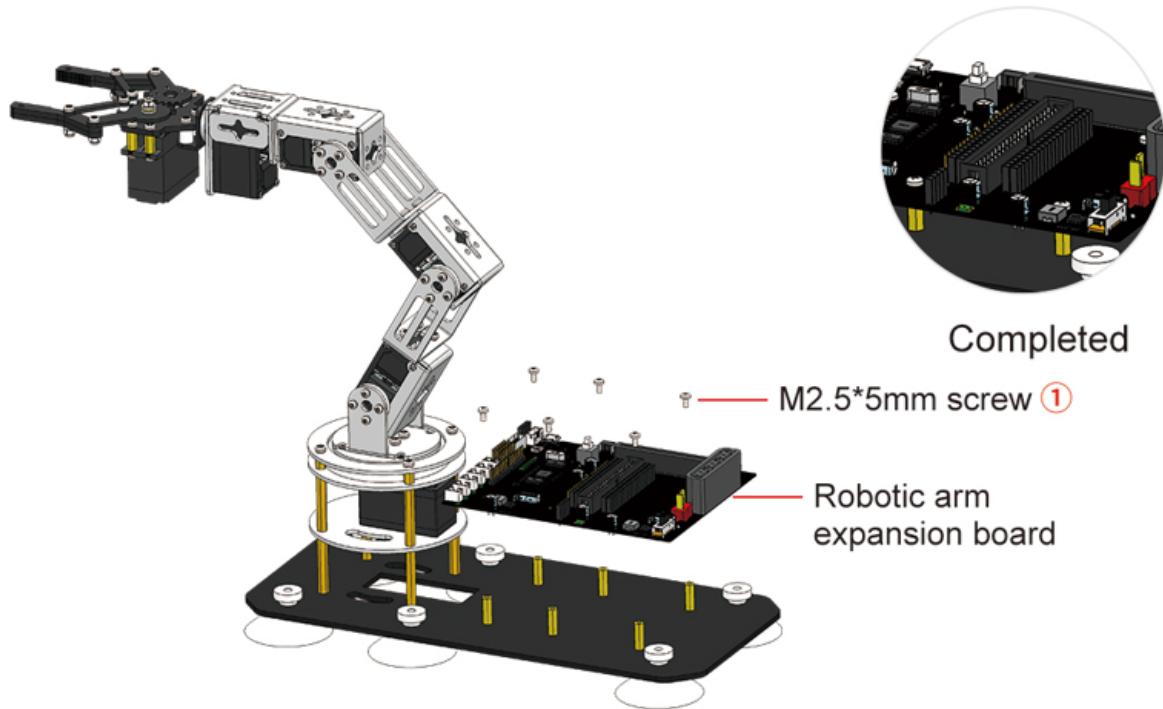
Step 1: Install the suction cup



Step 2: Install copper pillars

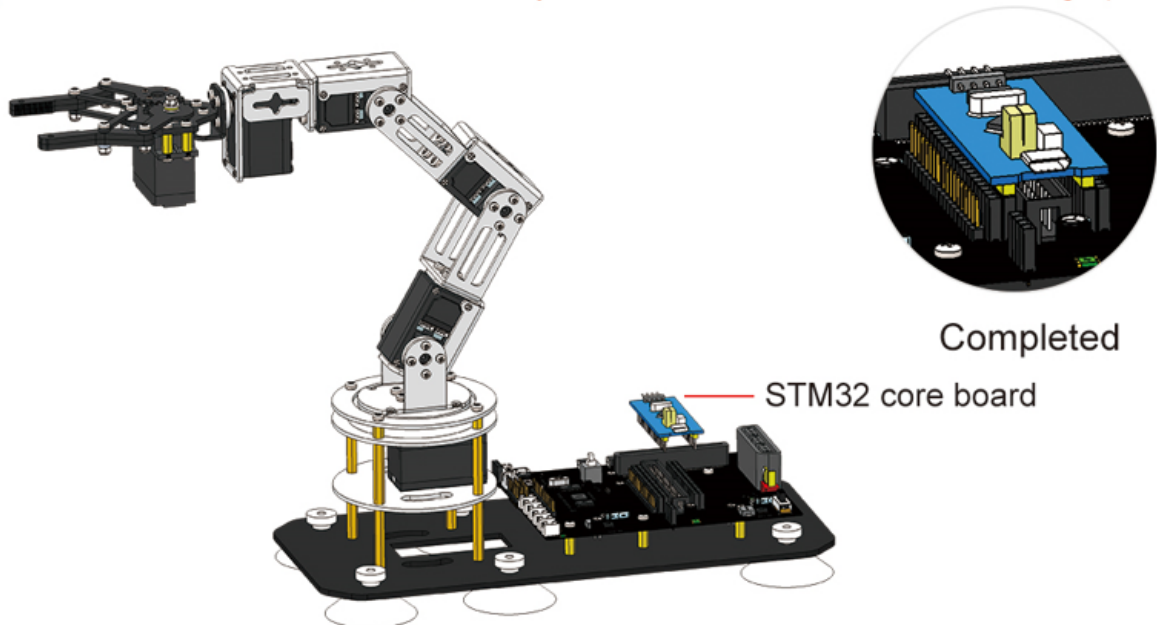


Step 3: Install robotic arm expansion board

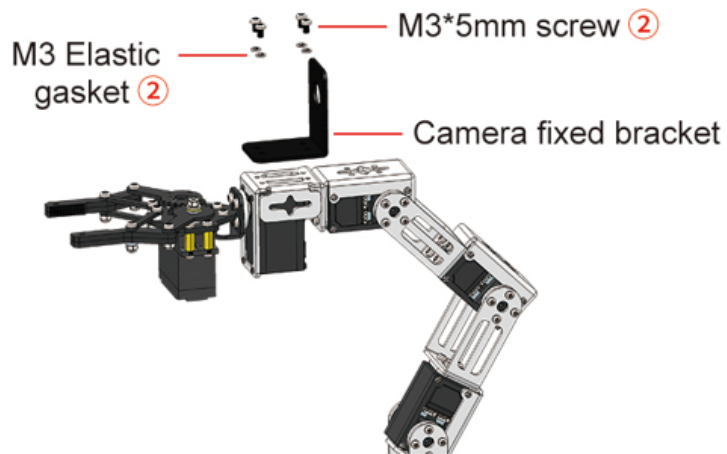


Step 4: Install STM32 core board

(Note: STM32 must be installed strictly in the direction, as shown on the right)



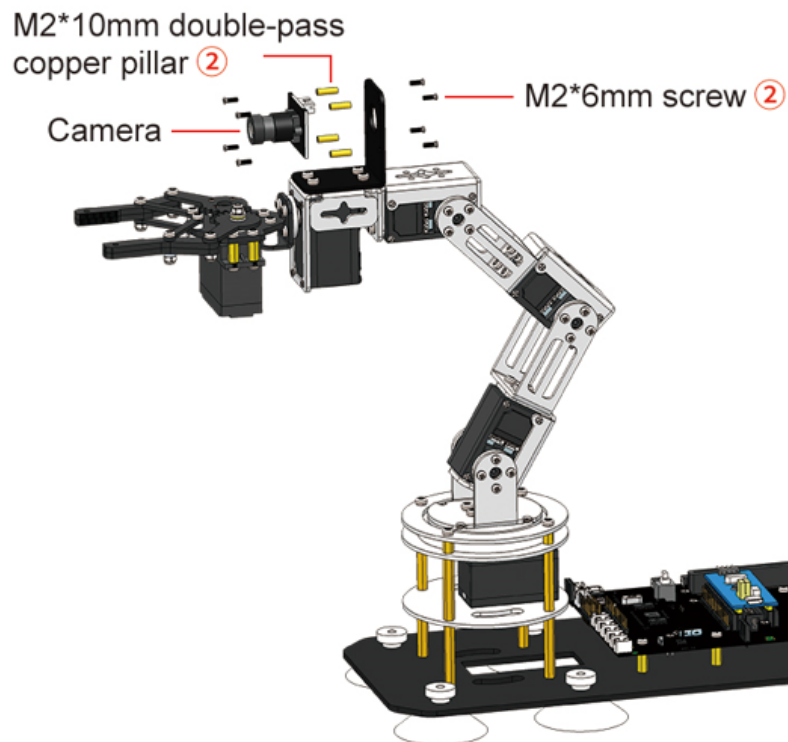
Step 5: Install camera fixed bracket



Completed

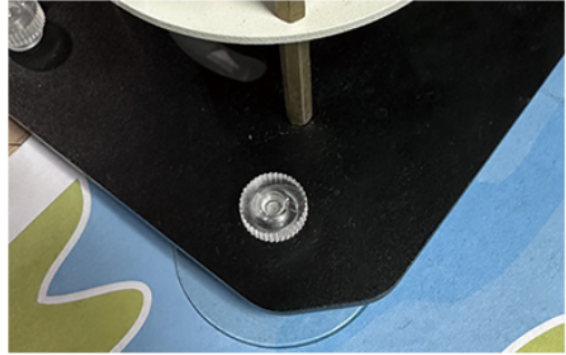
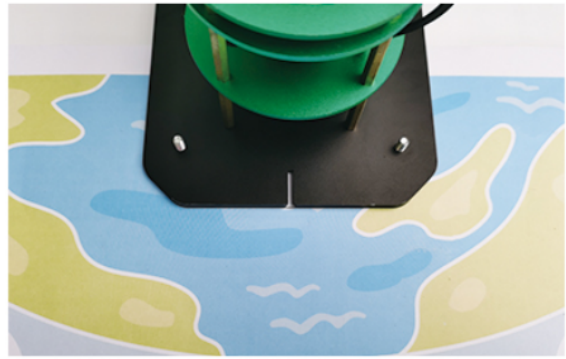
Step 6: Install the camera

(Note: Connect the camera wire to the camera before installation)



Completed

2.2 Install map



Remove the two suction cups at the front of the robotic arm, as shown in the figure below, place the map upward, pass the two suction cup screws through the map and fix it to the front of the robotic arm base. After the suction cup is installed, place the robotic arm on a smooth and clean table, press the chassis to attach the suction cup to the table.