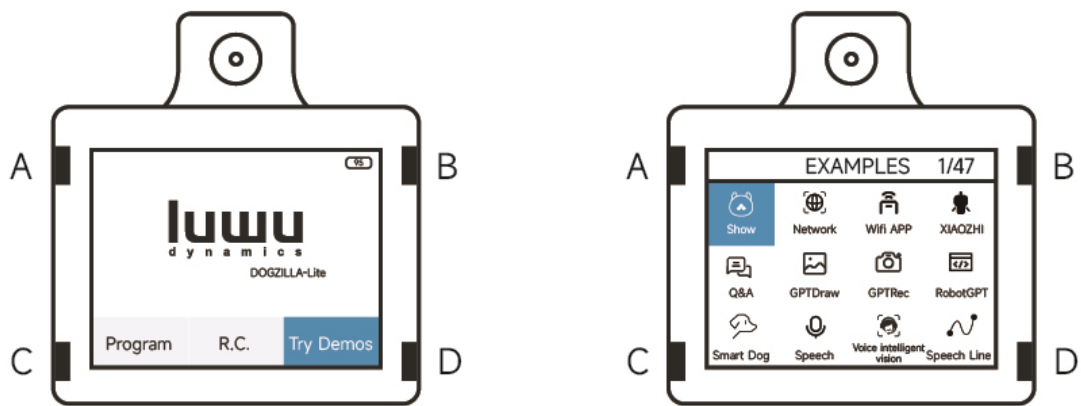


# Web page image transmission control

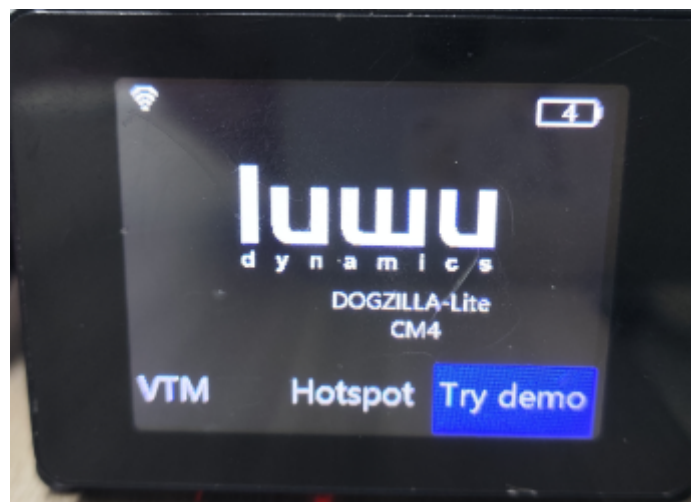
The function of the dog head screen is shown in the figure:

The A and B keys are left and right selection keys, the C key is the exit key, and the D key is the confirmation key.



1. Enter the network configuration mode and connect the robot dog to the same LAN. The specific steps are as follows:

I. First enter the network configuration mode of the sample program.



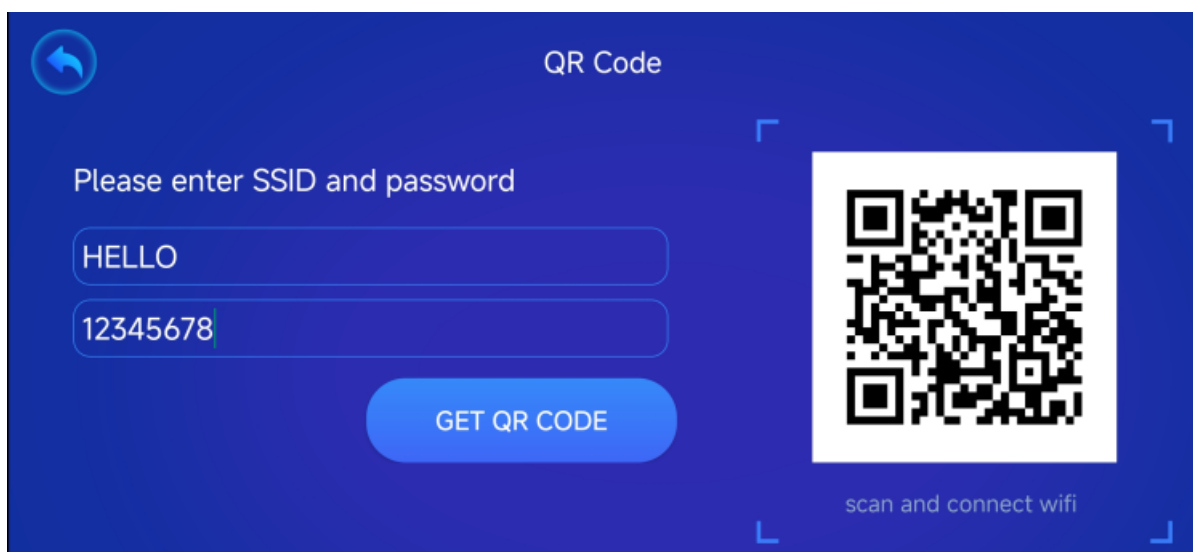
II. Press button D to enter network configuration.



III. Open the XGO interface, select the network configuration mode, fill in the wifi that the phone can search into the app, and click to generate the QR code interface.



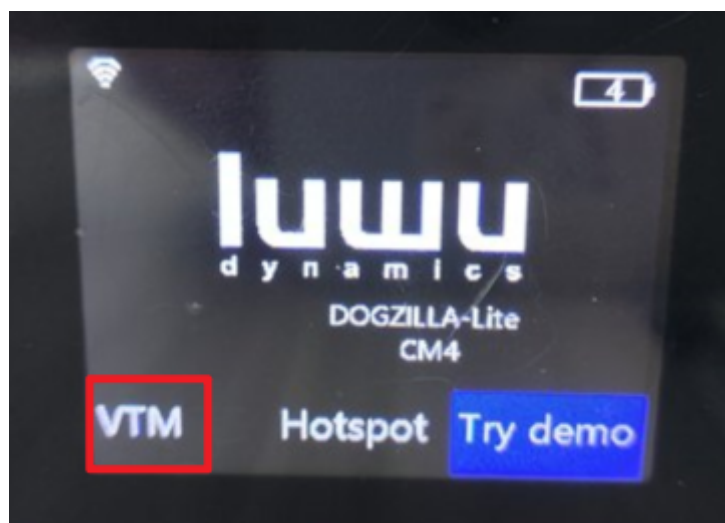
For example: the mobile phone searches for a wifi named "Hello" and the password is: 12345678, then fill in the app like this and click to generate a QR code.



IV. Scan the generated QR code with the robot dog. After successful scanning, it will connect to the WiFi set by the QR code and then automatically exit the page.

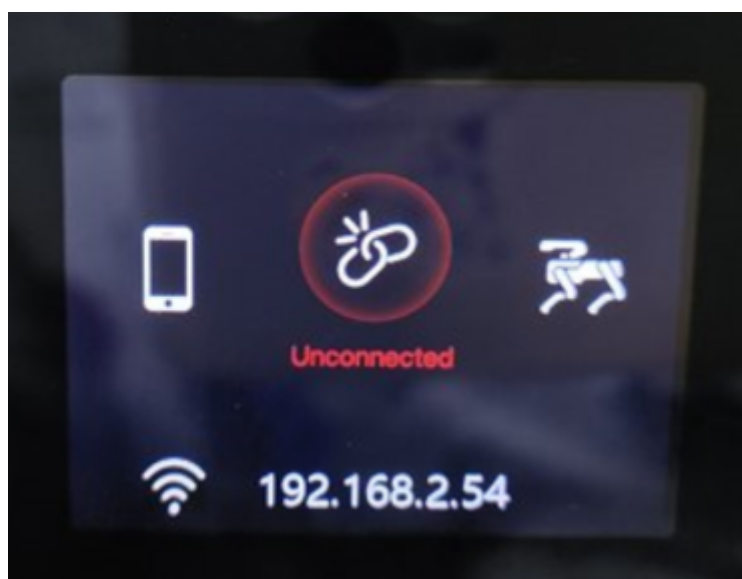


V. Press the C button on the screen to exit to the image transmission mode

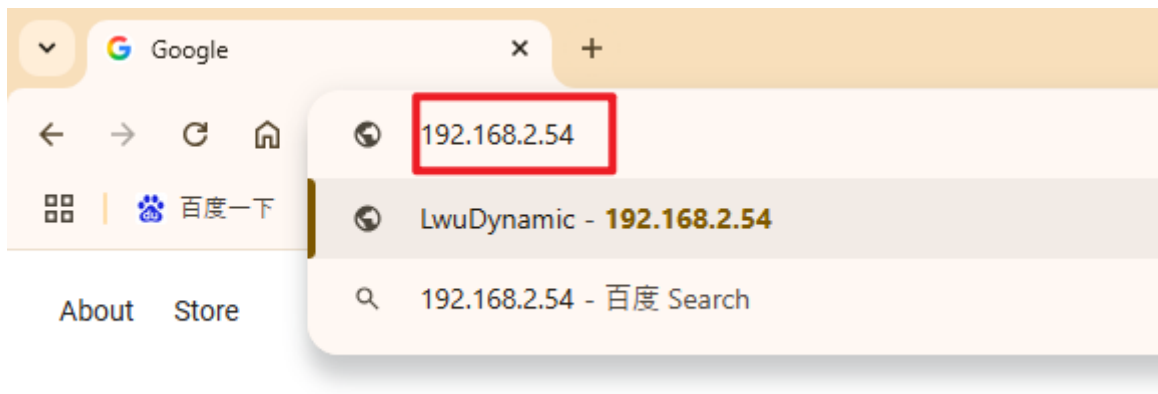


2. Steps of image transmission remote control

I. Select image transmission mode and press D key to enter

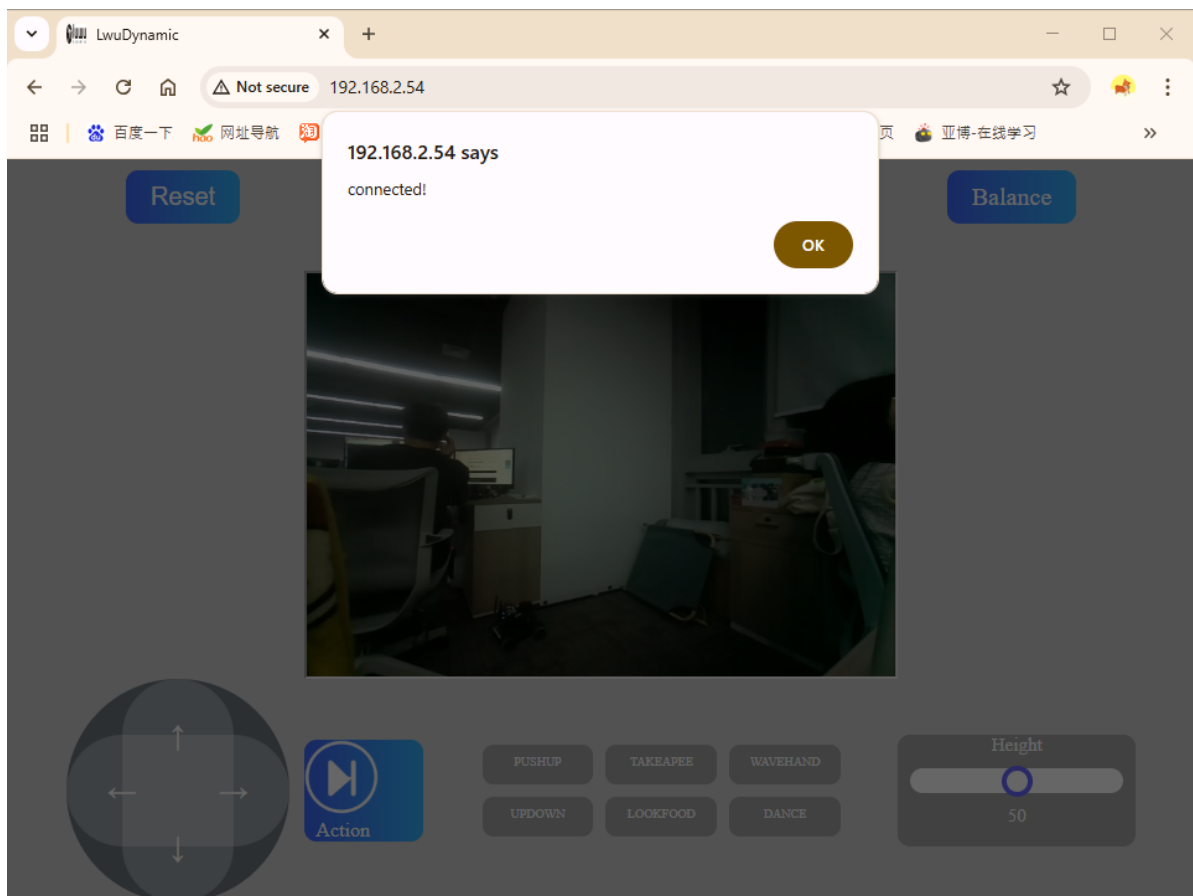


II. Open the browser of your computer/mobile phone. It is recommended to use the computer browser to enter the dog's IP address. For example, the dog's **IP address in the picture above is 192.168.2.62** , so it will be as shown in the picture



Press the browser's confirmation button to enter the image transmission mode.

III. Click the confirmation button to successfully connect to the robot dog (mobile control requires long pressing the button to control)

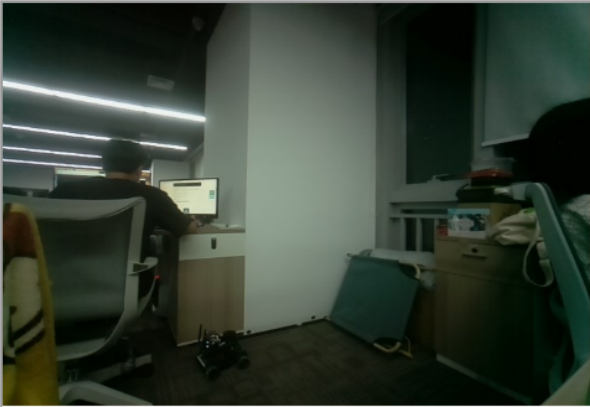


Reset

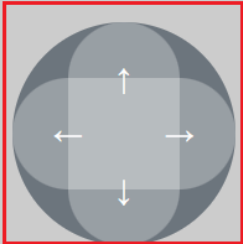
Reset dog status

Balance

Self-balancing mode



Movement control



Action group execution



Action

PUSHUP

TAKEAPEE


WAVEHAND

UPDOWN

LOOKFOOD

DANCE

Height



50

Height adjustment