

Mobile remote control

Mobile remote control

Bluetooth remote control

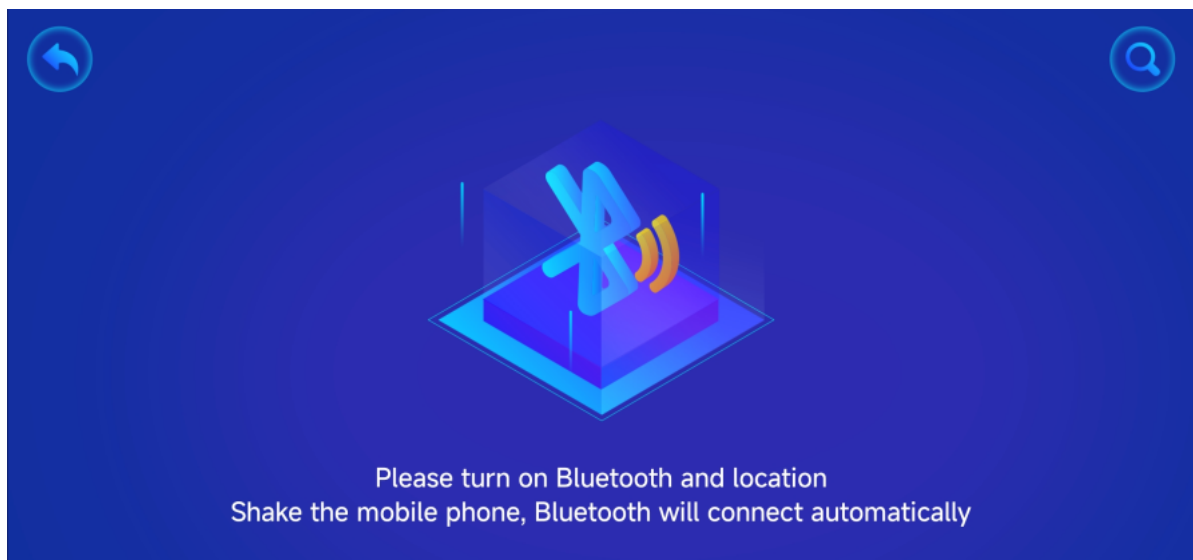
Wifi remote control

Bluetooth remote control

1. First download the XGO app. You can download it by scanning the QR code in the instruction manual or downloading it from the App Store.
2. Open the xgo APP, you will enter the homepage and click on Bluetooth connection.

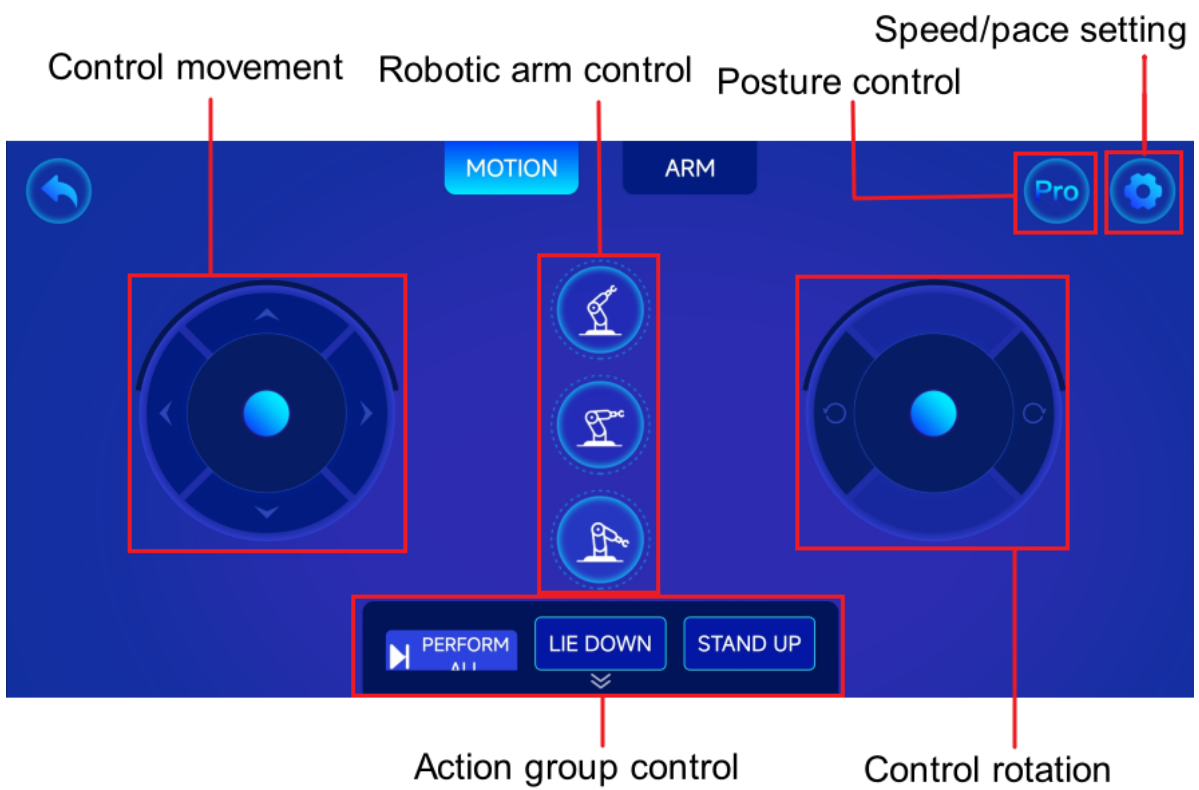


3. Turn on the location permission and Bluetooth switch of your phone, then shake the phone to connect to the robot dog and automatically return to the home page.



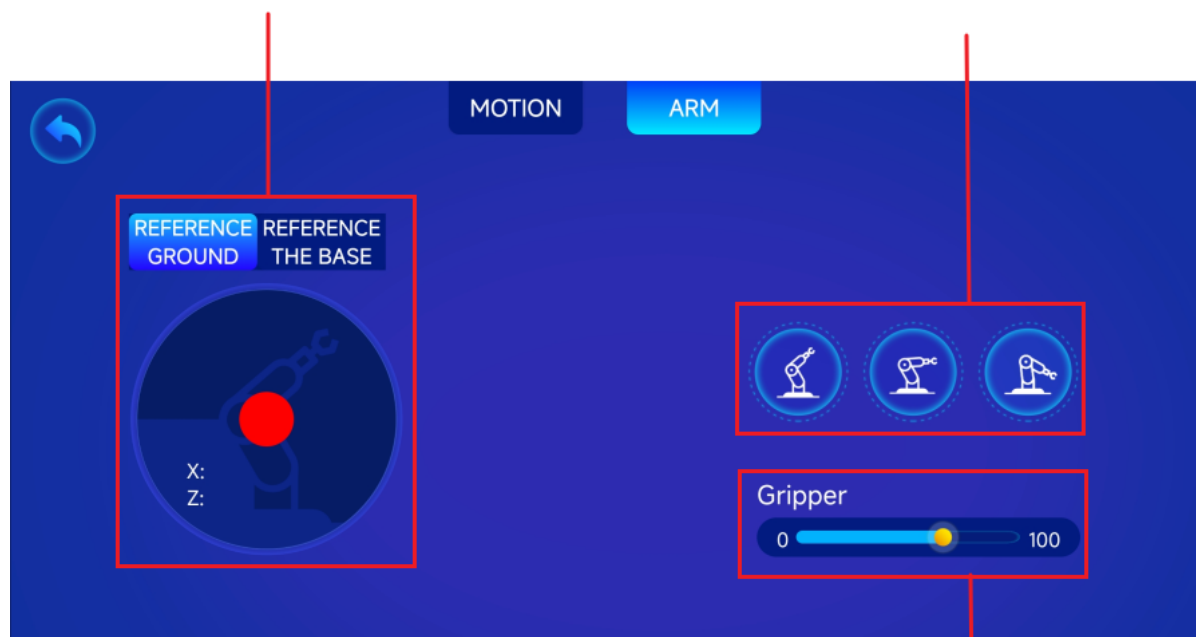


4. Then click the arrow on the home page to enter the remote control interface



Robotic arm reference position control

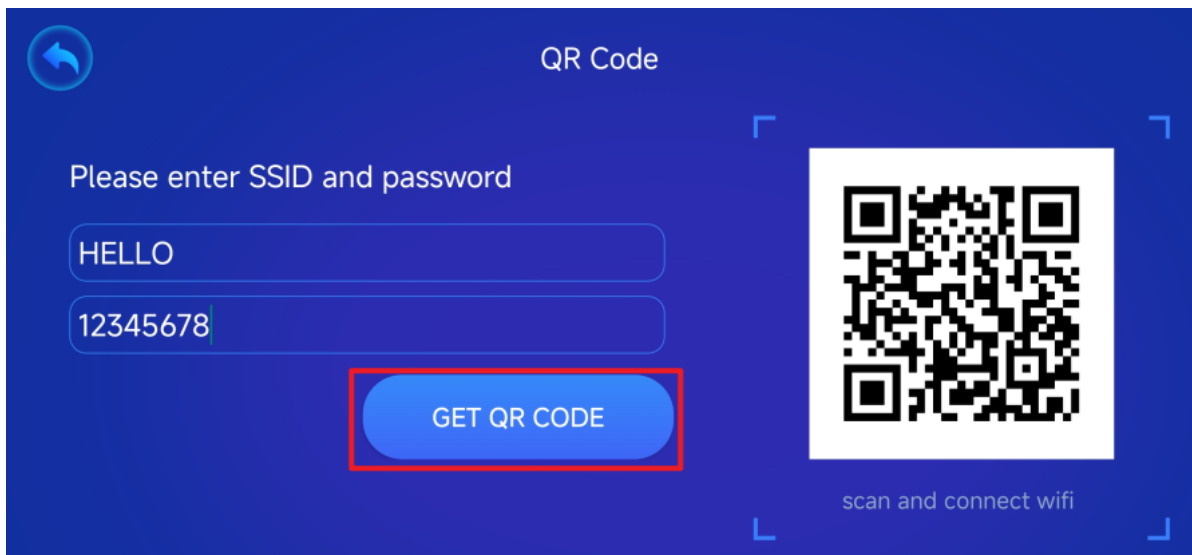
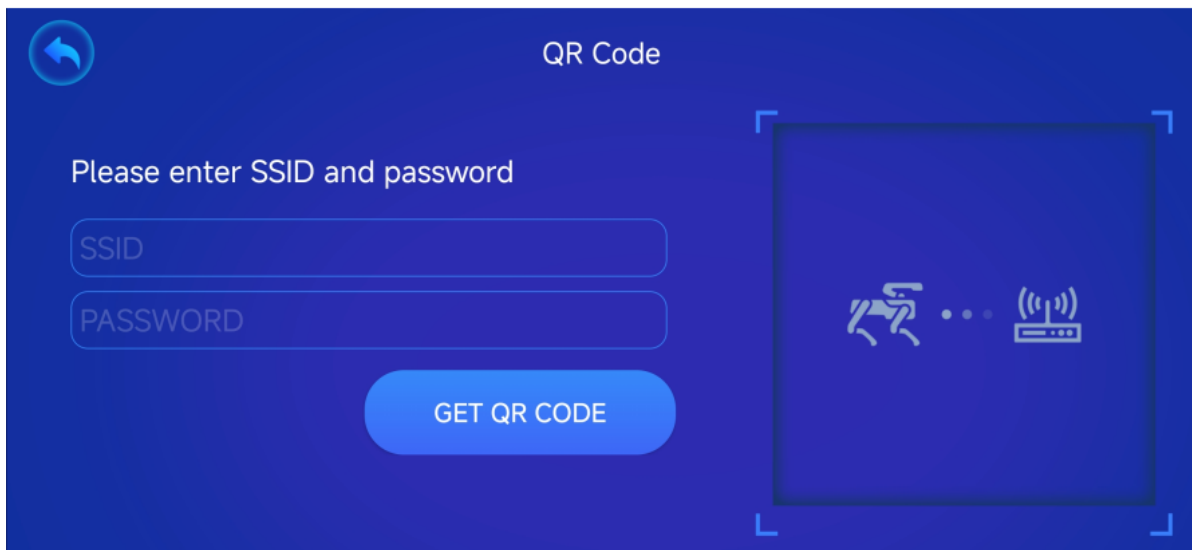
Robotic arm action setting



Gripper control

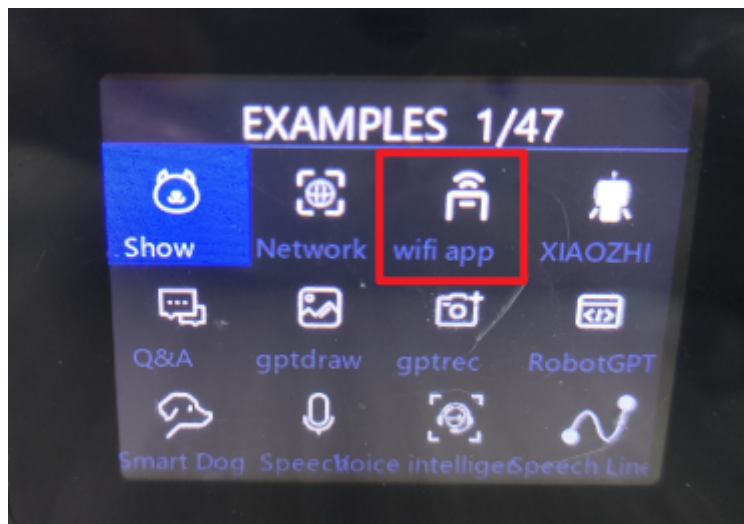
5. Configure your own network for the robot dog (large models and wifi app control need to be connected to the network first)

Click the upper right corner, fill in the network name and password, generate a QR code image, click the robot dog to enter the wireless network in the sample program, and configure the network by scanning the QR code

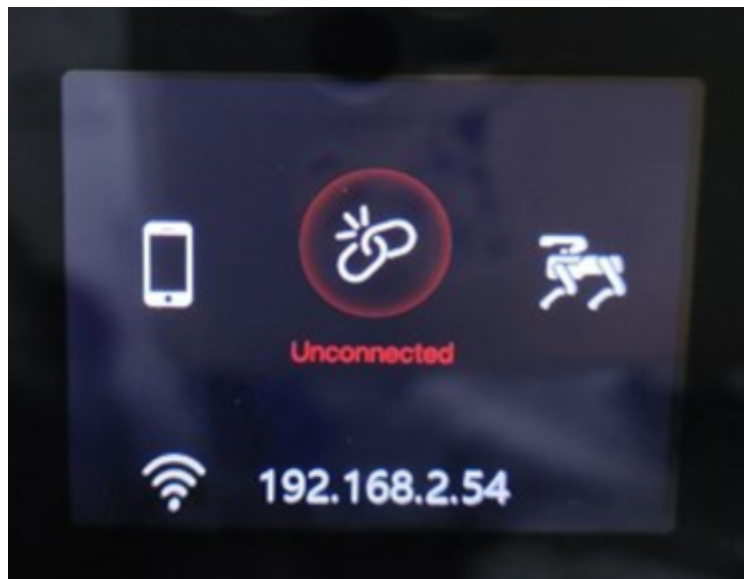


Wifi remote control

1. First download and install the "YahboomRobot" app: <http://www.yahboom.net/software/app/#YahBoomRobot>
2. Enter the mobile remote control of the sample program



Startup Page

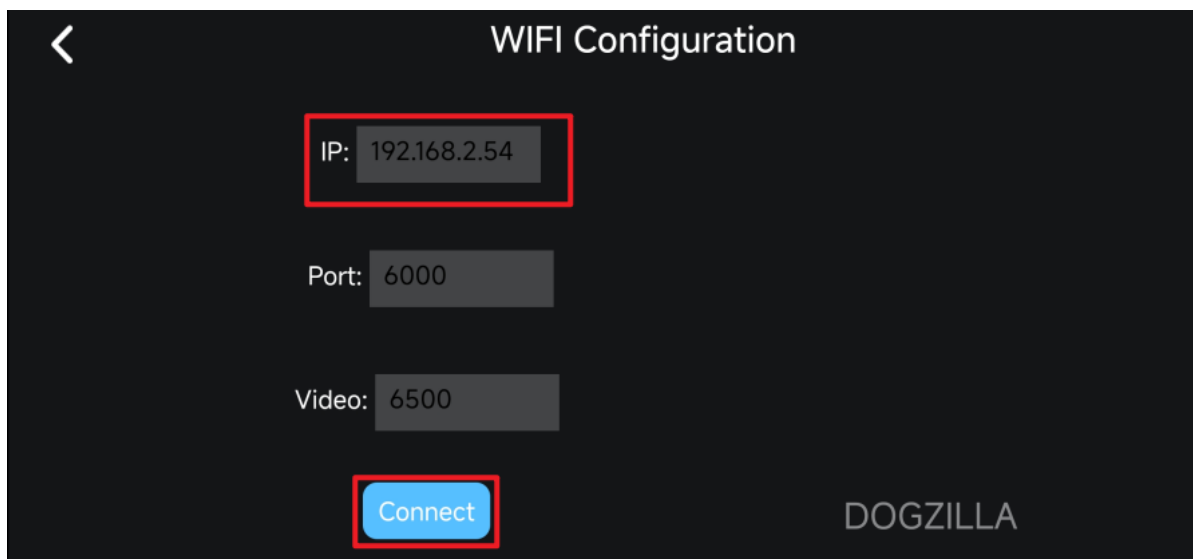


3. Then open the mobile remote control APP

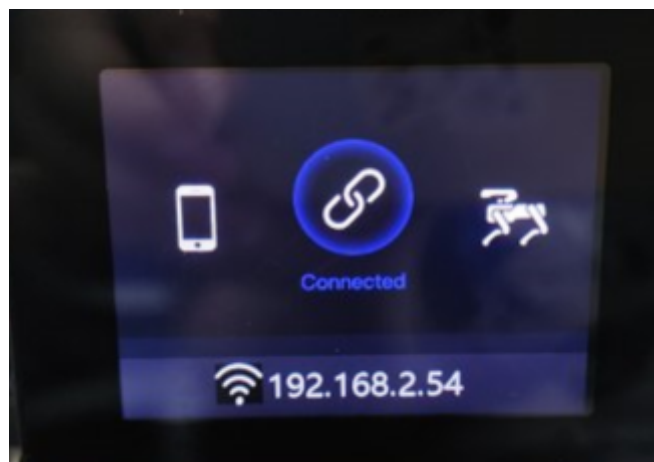
Select ROS robot->DOGZILLA to enter the remote control interface



4. Fill in the IP address of the robot dog page in the app column, and keep the rest unchanged.
Note that **the app and the dog need to be in the same local area network**



After the connection is successful, the dog's page changes as shown below



5. Finally, you can remotely control the dog. Note: this app cannot remotely control its robotic arm.

