# **Battery level reading**

## 1. Purpose of the experiment

Realize the reading of battery power.

#### 2. Experimental path source code

Enter the dog's system, end the dog program, enter "ip (ip is the dog's ip): 8888" in the browser, enter the password "yahboom"



and log in to the path of cd ~/DOGZILLA\_Lite\_class/2.Base Control/10.Read Battery and run Read Battery.ipynb .

## 3. Experimental Phenomenon

After running the code, the underlying battery power data can be printed out

```
[1]: from xgolib import XGO
    import time
    import ipywidgets as widgets
    from IPython.display import display
    from ipywidgets import interact, widgets, Button, VBox, IntSlider

dog = XGO("xgolite")

[2]: while True:
    print(dog.read_battery())
    time.sleep(1)

45
    45
    45
    45
    47
    47
    45
    45
    45
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    47
    4
```

#### 4. Main source code analysis

```
while True:
    print(dog.read_battery())
    time.sleep(1)
```

Through the API interface, read the underlying IMU data and print it out.