The dog performs a preset action

1. Purpose

Learn to control the preset actions of the robot dog

If you want to climb stairs, you need to use firmware V4.3.2 or above, otherwise it will not work.

2. Experimental path source code

Enter the robot dog system, end the robot dog program, enter "ip (ip is the robot dog's ip): 8888" in the browser, and enter the password "yahboom"

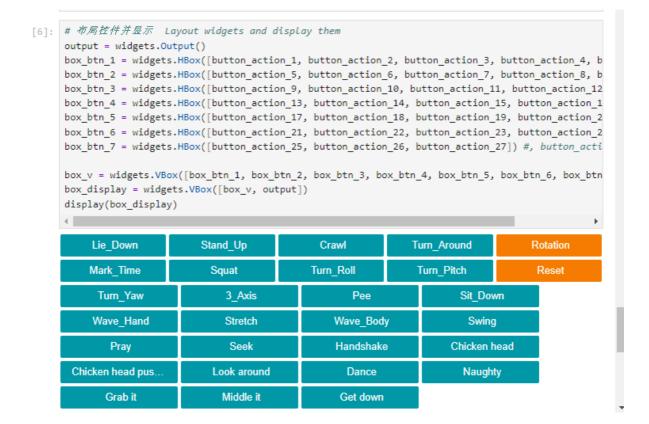


Then log in and go to cd ~/DOGZILLA_Lite_class/3.Dog Base Control/06.Execute preset actions and run contorl action.ipynb.

3. Experimental Phenomenon

After running the source code, run it to the end, and then control the preset actions according to the buttons at the bottom, and the robot dog will execute the corresponding action group. If you want the button prompt to be in Chinese, change False to True here. The default is English

```
# 中文开关,默认为英文 Chinese switch. The default value is English
g_ENABLE_CHINESE = False True
```



4. Main source code analysis

- 1. g_dog.action(num)
- Incoming parameter: num The action group number corresponding to the action group is as follows

ID	Actions	Duration/s	ID	Actions	Duration/s	ID	Actions	Duration/s
1	Lie down	3	2	Stand up	3	3	Crawl	5
4	Turn in a circle	5	5	Mini is stepping	4	6	Squat	4
7	Roll	4	8	Turn Pitch	4	9	Yaw	4
10	Three-axis rotation	7	11	Pee	7	12	Sit	5
13	Wave	7	14	Stretch	10	15	Wave	6
16	Sway	6	17	Beg	6	18	Find food	6
19	Shake hands	10	20	Chicken head	9	21	Push-ups	8
22	Look around	8	23	Dance	6	24	Playful	7
128	Grab up	10	129	Catch	10	130	Grab	10