Free Q&A

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Function Introduction

This case is about starting a large program. You need to complete the configuration of the API-KEY related to the large model before you can use it normally. This function is a talkback function for communicating with users.

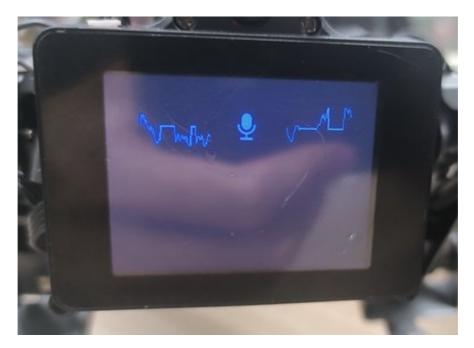
This function requires an Internet connection to work normally.

Functional Experience

1. Turn on the robot dog first, enter the sample mode by pressing the button on the upper right of the "dog head", and then select the free question and answer function.

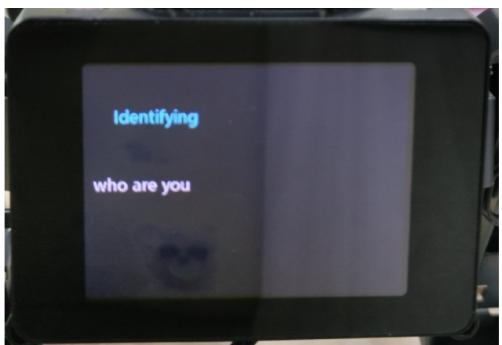


2. After entering the free question and answer function, wake it up with voice, "lulu".

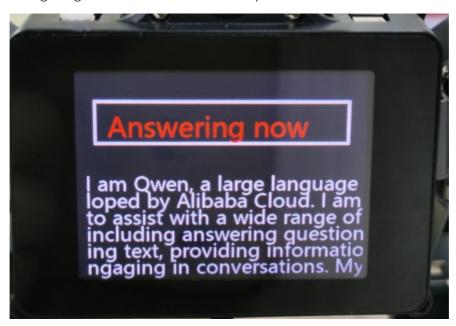


3. When you hear a ding, you can say the question you want to ask.





4. The robot dog will give an answer based on the question asked.



Program source code

- 1. First, log in to the robot dog's system through VNC
- 2. Then enter the terminal

cd /home/pi/RaspberryPi-CM4-main/demos/Free_QA/
tree

- 3. Directory structure description
 - answer.mp3 #Synthesized audio
 - audio.py #Recording file
 - auto_platform.py #Dependencies required for recording
 - chatgpt_main.py #Main program
 - language_recognize.py #Speech recognition
 - libnyumaya.py #Speech wake-up
 - xinghou_tts.py #Synthesized audio
 - ___ xinghou_UltraAPI.py #Large language model interface

How to replace the large model interface

- You can start with the Python version of the platform's corresponding interface program and fill in the necessary information according to the platform's interface and instructions.
- Then encapsulate the executable file into a function. You can refer to the method of "xinghou_UltraAPI.py" and put it in the directory of point 2. For example, the added file name is "mychatgpt.py"
- Open the **chatgpt_main.py** file and replace from xinghou_UltraAPI import * with the newly added from mychatgpt import * at the top.

• Then find this place and replace it with your own encapsulated API function interface.

```
scale=font2,
mono_space=False
             display.ShowImage(splash)
             lines = len(display_text.split("\n"))
             tick = 0.3
if lines > 6:
    scroll_text_on_lcd(display_text, 10, 111, 6, tick)
             #big model
sctext = "正在识别" if la == 'cn' else "Identifying"
lcd_draw_string(draw, 30, 40, sctext, color=(0, 255, 255), scale=font2, mono_space=False)
display.ShowImage(splash)
          re = Ultra_gpt(content) You can change the desired large model interface by yourself
             \label{local_control} $$ \operatorname{lcd_rect}(0,40,320,290,\operatorname{splash\_theme\_color,-1})$ $$ \operatorname{draw.rectangle}((20,30,300,80), \operatorname{splash\_theme\_color,-white-width=3}) $$
             ananan = "正在回答" if la == 'cn' else "Answering now" lcd_draw_string(draw,35,40, ananan, color=(255,0,0), scale=font3, mono_space=False)
             lcd_draw_string(
             draw, 10, 11, 11, 11, re_text, color=(255, 255, 255), scale=font2, mono_space=False,
             display.ShowImage(splash)
             relines = len(re_text.split("\n"))
tick = 0.3
            tick = 0.3
if relines > 6:
    scroll_text_on_lcd(re_text, 10, 111, 6, tick)
            try:
Xinghou_speaktts(re)#播放音频 play
     except:
pass
if content == 0:
break
time.sleep(0.1)
```

1. Then restart the car and enter this function again, you can run the model platform you replaced. If it cannot run, it means there is an error, and you need to check the syntax and logic of the newly added file yourself.

How to run this example in terminal

- 1. End the large program first to prevent screen distortion. For details on how to end the large program, please refer to the tutorial on ending the large program in Chapter 1. This will not be described here.
- 2. Enter the following command in the terminal

```
cd ~/RaspberryPi-CM4-main
sudo python3 demos/Free_QA/chatgpt_main.py
```

3. When "waiting for keyword" appears, wake up the robot dog by saying "lu lu". After a few seconds, a scrolling prompt "current volume, boot threshold, end threshold" will appear. You can then start voice input to the robot dog.

```
File Edit Tabs Help
    from DAgent_en import * #动作编排 choreography
  File "/home/pi/RaspberryPi-CM4-main/demos/dog_agent/DAgent_en.py", line 1, in
    from dog_API_en import *
  File "/home/pi/RaspberryPi-CM4-main/demos/dog_agent/dog_API_en.py", line 23
    messages=[
SyntaxError: invalid syntax
pi@raspberrypi:~/RaspberryPi-CM4-main $ python3 demos/dog_agent/AIMain_en.py
System:Linux
Release:6.1.21-v8+
Machine:aarch64
Uname:uname_result(system='Linux', node='raspberrypi', release='6.1.21-v8+', ver
sion='#1642 SMP PREEMPT Mon Apr 3 17:24:16 BST 2023', machine='aarch64')
en
en
start
Loading Library
Initialize Functions
Waiting for keyword...
```

Note:

1. If the terminal reports an error timeout, the reason may be that the large model interface is blocked or the network is affected. Just restart the program.

```
pi@raspberrypi:~/RaspberryPi-CM4-main $ python3 demos/dog_agent/Almain_en.py
System:Linux
Release:6.1.21-v8+
Machine:aarch64
Uname:uname_result(system='Linux', node='raspberrypi', release='6.1.21-v8+', ver
sion='#1642 SMP PREEMPT Mon Apr 3 17:24:16 BST 2023', machine='aarch64')
LITE
en
en
la is en
Network check failed: HTTPConnectionPool(host='www.baidu.com', port=80): Read ti
med out. (read timeout=2)
```

How to change the length of recording time

1. Terminal Input

```
nano ~/RaspberryPi-CM4-main/demos/Free_QA/audio.py
```

2. Find this place and change the place as shown in the figure below, then you can adjust the recording duration according to your own environment.

```
□def start_recording(timel = 3, save_file=SAVE_FILE):
232
             global automark, quitmark
233
             start_threshold = 1200<u>0</u>0
             end_threshold = 40000| The sound threshold for stopping talking can endlast = 15 be adjusted according to your environment.
234
235
             max_record_time = 20
236
237
                                Maximum recording time
238
             CHUNK = 1024
239
             FORMAT = pyaudio.paInt16
240
             CHANNELS = 1
241
             RATE = 16000
             WAVE_OUTPUT_FILENAME = save_file
242
243
```

Note: start_threshold>end_threshold , the adjustment of these two values needs to be adjusted according to your own environment.

Functional principle

The specific flow chart is as follows:

