

0.ReadMe before use

We provide some function package source codes.

yahboomcar_ws.zip: This is the function package for driving lidar and handheld lidar mapping

oradar_ws_src.tar.xz: This is the function package source code for Yahboom rosmaster car tutorial case, which needs to be used with the car. Here only for reference.

Generally, you only need to install the yahboomcar_ws function package on your RDK board.

yahboomcar_ws_src.tar.xz, which contains the ROS2 basic tutorial related code.

YDLidar-SDK-master.zip, which contains the SDK function package.