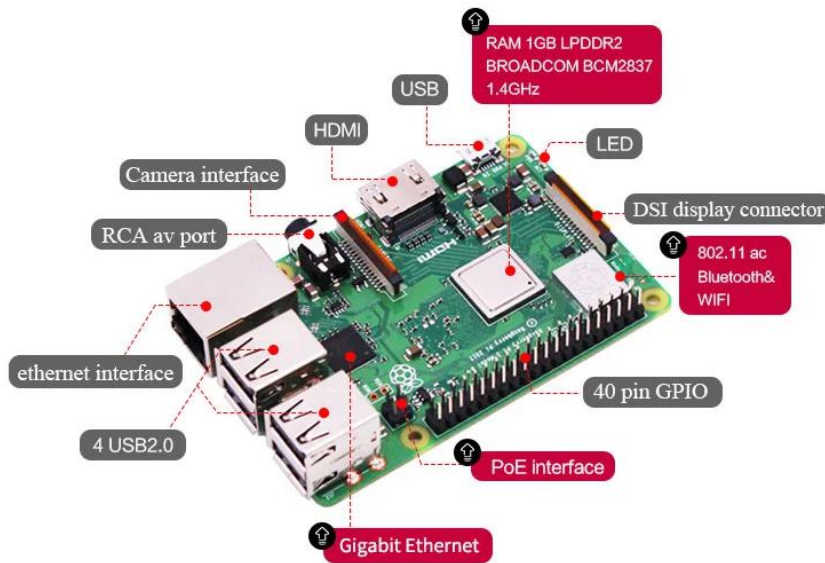


7.Raspberry Pi platform ----- infrared_follow

1)Preparation



1-1 Raspberry Pi board



1-2 Infrared obstacle avoidance module

2)Purpose of Experimental

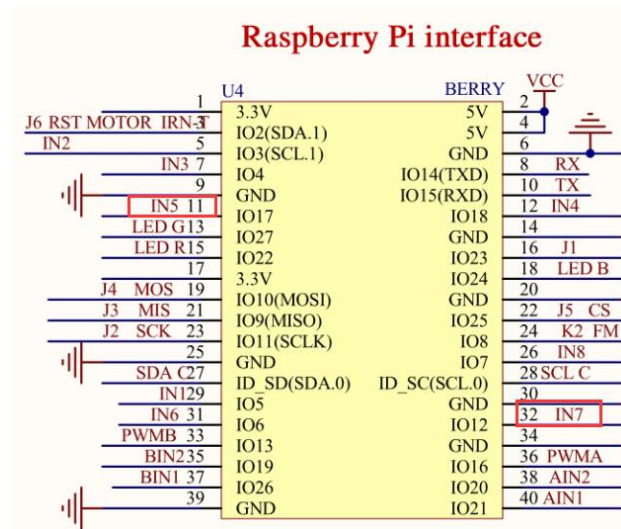
After running the infrared_follow executable in the Raspberry Pi system. You need to press the K2 to start the car, and the infrared follow function is started. When there is an obstacle in front, the car can follow the obstacle automatically.

3)Principle of experimental

The basic principle of the infrared sensor is to use the reflective nature of the object. Within a certain range, if there is an obstacle, the infrared rays will encounter obstacle and will be reflected to reach the sensor receiving pin. In this experiment, we used 2 infrared sensors connected to the Raspberry Pi board to detect the obstacles by detecting the electrical level of the two ports, and robot car will make corresponding follow actions.

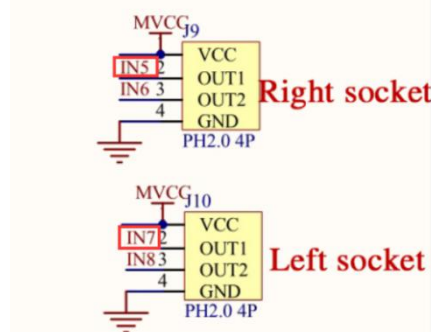
4)Experimental Steps

4-1 About the schematic



4-1 Raspberry Pi interface circuit diagram

Infrared obstacle avoidance seeks light



4-2 Left and right infrared sensor interface

wiringPi	BCM	Funtion	Physical pin	Funtion	BCM	wiringPi
		3.3V	1	2	5V	
8	2	SDA.1	3	4	5V	
9	3	SCL.1	5	6	GND	
7	4	GPIO.7	7	8	TXD	14
		GND	9	10	RXD	15
0	17	GPIO.0	11	12	GPIO.1	18
2	27	GPIO.2	13	14	GND	
3	22	GPIO.3	15	16	GPIO.4	23
		3.3V	17	18	GPIO.5	24
12	10	MOSI	19	20	GND	
13	9	MISO	21	22	GPIO.6	25
14	11	SCLK	23	24	CE0	8
		GND	25	26	CE1	7
30	0	SDA.0	27	28	SCL.0	1
21	5	GPIO.21	29	30	GND	
22	6	GPIO.22	31	32	GPIO.26	12
23	13	GPIO.23	33	34	GND	
24	19	GPIO.24	35	36	GPIO.27	16
25	26	GPIO.25	37	38	GPIO.28	20
		GND	39	40	GPIO.29	21

4-3 Raspberry Pi 40 pins comparison table

4-2 According to the circuit schematic:

Left infrared sensor-----32(Physical pin)----- 26(wiringPi)

Right infrared sensor-----11(Physical pin)----- 0(wiringPi)

(Note: We use the wiringPi library to write code.)

(Note: In this experiment, we can adjust the sensitivity of the infrared follow module by rotating the potentiometer on the infrared module to achieve better experimental results.)

4-3 About the code

(1) We need to compile this file in the Raspberry Pi system. (Note: we need to add -lwiringPi to the library file.)

We need to input: `gcc infrared_follow.c -o infrared_follow -lwiringPi`

(2) We need to run the compiled executable file in the Raspberry Pi system. We need to input: `./infrared_follow`

As shown in the figure below.

```
root@raspberrypi:/home/pi/SmartCar# gcc infrared_avoid.c -o infrared_avoid -lwiringPi
root@raspberrypi:/home/pi/SmartCar# ./infrared_avoid
^C
```

(3) We can input: `ctrl+c` to stop this process, which mean is send a signal to the linux kernel to terminate the current process, but the state of the relevant pin is uncertain at this time, we also need to run a script to initialize all pins.

(Note: The initpin.sh script file is included in the SmartCar directory.)

You need to input: `chmod 777 initpin.sh`
`./initpin.sh`

```
root@raspberrypi:/home/pi/SmartCar# chmod 777 initpin.sh
root@raspberrypi:/home/pi/SmartCar# ./initpin.sh
root@raspberrypi:/home/pi/SmartCar#
```

After completing the above steps, the experiment is over.