

First-time use instructions

1. The product is equipped with multiple power adapters with the same interface type but different voltages. In order to avoid burning the device due to wrong insertion, please check and confirm before powering on the device.
2. The robot arm will automatically stand up after it is turned on. Please place the robot arm in an area with sufficient space before turning it on.
3. The Moveit course for Jetson Nano needs to be run in a virtual machine.
4. If you do not need the APP control program to start automatically when the computer is turned on, you can enter the command `sudo systemctl disable yahboom_app.service` to permanently shut down the APP and handle control programs. The next time you turn on the computer, the APP and handle control programs will not be automatically started.