Docker hardware interaction and data processing

4.1. Hardware mounting (port binding)

- 1. Create udev rules in the host machine (/etc/udev/rules.d/), see [VI. Linux operating system --- 6. Binding device ID] section
- 2. Then when starting the container, mount the devices with the rules set into the docker container through parameters such as --device=/dev/myserial --device=/dev/rplidar

```
docker run -it --device=/dev/myserial --device=/dev/rplidar ubuntu:latest
/bin/bash
```

3. The device can be found in the docker container

```
jetson@ubuntu:~$ docker images
                                        IMAGE ID CREATED
REPOSITORY
                                                                            SIZE
                             1.0
                                      78ca7be949b6 About an hour ago
ubuntu
                                                                            69.2MB
pengan88/ubuntu
                             1.0
                                      78ca7be949b6 About an hour ago
                                                                            69.2MB
yahboomtechnology/ros-foxy 3.4.0 49581aa78b6b 6 hours ago
                                                                            24.3GB
yahboomtechnology/ros-foxy 3.3.9 cefb5ac2ca02 4 days ago yahboomtechnology/ros-foxy 3.3.8 49996806c64a 4 days ago yahboomtechnology/ros-foxy 3.3.7 8989b8860d17 5 days ago
                                                                            20.5GB
                                                                            20.5GB
                                                                            17.1GB
yahboomtechnology/ros-foxy 3.3.6
                                      326531363d6e 5 days ago
                                                                            16.1GB
mysq1
                             latest 5371f8c3b63e 6 days ago
                                                                            592MB
ubuntu
                             latest bab8ce5c00ca 6 weeks ago
                                                                            69.2MB
                              latest 46331d942d63 13 months ago
hello-world
                                                                            9.14kB
jetson@ubuntu:~$ 11 /dev | grep ttyUSB*
                              7 Apr 23 18:07 myse....
7 Apr 23 18:07 rplidar -> ttyUSB1
lrwxrwxrwx 1 root root
                                    7 Apr 23 18:07 myserial -> ttyUSB0
lrwxrwxrwx 1 root root
crwxrwxrwx 1 root dialout 188, 0 Apr 23 18:07 ttyUSBO
crwxrwxrwx 1 root dialout 188, 1 Apr 23 18:07 ttyUSB1
jetson@ubuntu:~$ docker run -it --device=/dev/myserial --device=/dev/rplidar
ubuntu:latest /bin/bash
root@03522257ba30:/# ls /dev # myserial and rplidar are already in docker
console fd full mqueue myserial null ptmx pts random rplidar shm
stderr stdin stdout tty urandom zero
```

4.2. Display of GUI in docker

1. Install in the host machine:

```
sudo apt-get install tigervnc-standalone-server tigervnc-viewer sudo apt-get install x11-xserver-utils
```

2. Execute in the host machine: xhost +

After the following figure is displayed normally, perform 3 steps:

3. Execute the command in the host machine to enter the container, and pay attention to modify the corresponding version number:

```
docker run -it \
--privileged \
--net=host \
--ipc=bridge \
--ipc=host \
--pid=host \
--env="DISPLAY" \
--env="QT_X11_NO_MITSHM=1" \
-v /dev/bus/usb:/dev/bus/usb \
-v /tmp/.X11-unix:/tmp/.X11-unix \
-v ~/temp:/root/temp \
yahboomtechnology/jetcobot_noetic:3.1.3 /bin/bash
```

You can also edit the startup script, name it new_jetcobot_docker.sh, and run the following command to enter the container.

```
sh new_jetcobot_docker.sh

4. Testing

Execute in the container: rviz
```

4.3, Transfer files between docker container and host

4.3.1, Use cp naming

4.3.1.1, Copy files from container to host

```
# Command
docker cp container id: path in container destination host path
# Test
# Execute in container, create a file test
jetson@ubuntu:~$ docker ps -a
                     COMMAND CREATED
CONTAINER ID IMAGE
                                                     STATUS
 PORTS
         NAMES
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago Up 9 minutes
          funny_hugle
3b9c01839579 hello-world "/hello" 3 hours ago
                                                     Exited (0) 3 hours ago
          jovial_brown
jetson@ubuntu:~$ docker attach c5
```

```
root@c54bf9efae47:/# ls
bin boot dev etc home lib media mnt opt proc root run sbin srv sys
tmp usr var
root@c54bf9efae47:/# cd
root@c54bf9efae47:~# ls
root@c54bf9efae47:~# touch test.txt
root@c54bf9efae47:~# ls
test.txt
root@c54bf9efae47:~# pwd
/root
root@c54bf9efae47:/# read escape sequence #Press ctrl+P+Q to exit the
container without stopping
jetson@ubuntu:~$ docker cp c54bf9efae47:/root/test.txt ~/
jetson@ubuntu:~$ ls # The test.txt file has been copied in
Desktop Documents Downloads fishros Music openvino Pictures Public
rootOnNVMe run_docker.sh sensors snap temp Templates test.txt Videos
```

4.3.1.2. Copy files from the host to the container

```
# Command
docker cp host file path container id: path in container
# Test
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE
                          COMMAND CREATED
                                                    STATUS
 PORTS NAMES
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago Up 5 minutes
          funny_hugle
3b9c01839579 hello-world
                           "/hello" 3 hours ago Exited (0) 3 hours ago
          jovial_brown
jetson@ubuntu:~$ ls
Desktop Documents Downloads fishros Music openvino Pictures Public
rootOnNVMe run_docker.sh sensors snap temp Templates test.txt Videos
jetson@ubuntu:~$ touch 11.txt
jetson@ubuntu:~$ ls
11.txt Desktop Documents Downloads fishros Music openvino Pictures Public
rootOnNVMe run_docker.sh sensors snap temp Templates test.txt Videos
jetson@ubuntu:~$ docker cp 11.txt c54bf9efae47:/root/
jetson@ubuntu:~$ docker attach c5
root@c54bf9efae47:/# 1s
bin boot dev etc home lib media mnt opt proc root run sbin srv sys
tmp usr var
root@c54bf9efae47:/# cd /root/
root@c54bf9efae47:~# ls # 11.txt file has been copied in
11.txt test.txt
```

4.3.2. Using Data Volumes

4.3.2.1. Data Volume Overview

Package the application and the running environment into a container to run. The running can be accompanied by the container, but our requirement for data is that it can be persistent! For example, if you install a mysql, and then you delete the container, it is equivalent to deleting the library and running away. This is definitely not okay! So we hope that it is possible to share data between containers. If the data generated by the docker container is not generated through docker commit, so that the data is saved as part of the image, then when the container is deleted, the data will naturally disappear! This will not work!

In order to save data in docker, we can use volumes! Let the data be mounted locally! In this way, the data will not be lost due to container deletion!

Features:

share.

- 1. Data volumes can share or reuse data between containers
- 2. Changes in the volume can take effect directly
- 3. Changes in the data volume will not be included in the update of the image
- 4. The life cycle of the data volume lasts until no container uses it

4.3.2.2, Data volume usage

```
# Command
docker run -it -v host absolute path directory: container directory image name
# Test
docker run -it -v /home/jetson/temp:/root/temp yahboomtechnology/ros-foxy:3.4.0
/bin/bash
The /home/jetson/temp directory in the host and the /root/temp directory in the
```

container can share data, or you can change it to other directories you want to