# **Object detection**

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References

Using Python to demonstrate **Ultralytics**: Object Detection in images, videos, and real-time detection.

## 1. Enable optimal performance of the motherboard

### 1.1. Enable MAX power mode

Enabling MAX Power Mode on Jetson will ensure that all CPU and GPU cores are turned on:

sudo nvpmodel -m 2

### 1.2. Enable Jetson Clocks

Enabling Jetson Clocks will ensure that all CPU and GPU cores run at maximum frequency:

sudo jetson\_clocks

## 2. Target prediction: image

Use yolo11n.pt to predict the images provided by the ultralytics project.

Enter the code folder:

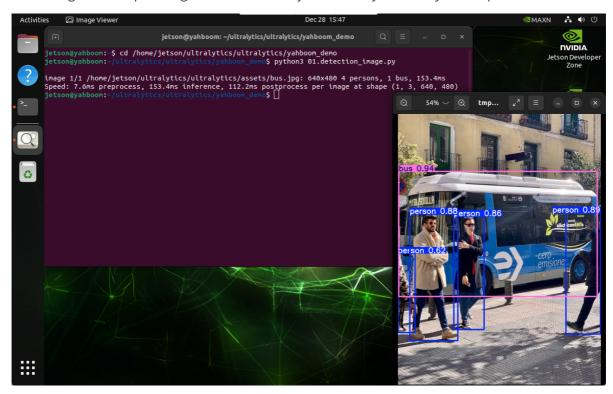
cd /home/jetson/ultralytics/ultralytics/yahboom\_demo

Run the code:

python3 01.detection\_image.py

#### **Effect preview**

Yolo recognition output image location: /home/jetson/ultralytics/ultralytics/output/



Sample code:

```
from ultralytics import YOLO
# Load a model
model = YOLO("/home/jetson/ultralytics/ultralytics/yolo11n.pt")
# Run batched inference on a list of images
results = model("/home/jetson/ultralytics/ultralytics/assets/bus.jpg") # return
a list of Results objects
# Process results list
for result in results:
   boxes = result.boxes # Boxes object for bounding box outputs
   # masks = result.masks # Masks object for segmentation masks outputs
   # keypoints = result.keypoints # Keypoints object for pose outputs
   # probs = result.probs # Probs object for classification outputs
    # obb = result.obb # Oriented boxes object for OBB outputs
    result.show() # display to screen
 result.save(filename="/home/jetson/ultralytics/ultralytics/output/bus_output.jp
g") # save to disk
```

### 3. Target prediction: video

Use yolo11n.pt to predict videos under the ultralytics project (not the videos that come with ultralytics).

Enter the code folder:

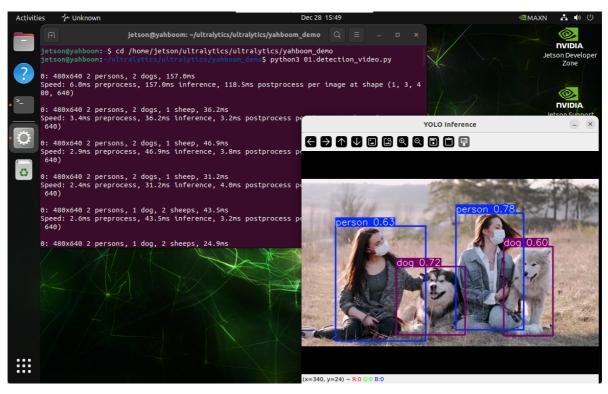
```
cd /home/jetson/ultralytics/ultralytics/yahboom_demo
```

Run the code:

```
python3 01.detection_video.py
```

#### **Effect preview**

Video location of yolo recognition output: /home/jetson/ultralytics/ultralytics/output/



Sample code:

```
import cv2
from ultralytics import YOLO
# Load the YOLO model
model = YOLO("/home/jetson/ultralytics/ultralytics/yolo11n.pt")
# Open the video file
video_path = "/home/jetson/ultralytics/ultralytics/videos/people_animals.mp4"
cap = cv2.VideoCapture(video_path)
# Get the video frame size and frame rate
frame_width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
frame_height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))
fps = int(cap.get(cv2.CAP_PROP_FPS))
# Define the codec and create a VideoWriter object to output the processed video
output_path =
"/home/jetson/ultralytics/ultralytics/output/01.people_animals_output.mp4"
fourcc = cv2.VideoWriter_fourcc(*'mp4v') # You can use 'XVID' or 'mp4v'
depending on your platform
out = cv2.videoWriter(output_path, fourcc, fps, (frame_width, frame_height))
# Loop through the video frames
while cap.isOpened():
    # Read a frame from the video
    success, frame = cap.read()
```

```
if success:
        # Run YOLO inference on the frame
        results = model(frame)
        # Visualize the results on the frame
        annotated_frame = results[0].plot()
        # Write the annotated frame to the output video file
        out.write(annotated_frame)
        # Display the annotated frame
        cv2.imshow("YOLO Inference", annotated_frame)
        # Break the loop if 'q' is pressed
        if cv2.waitKey(1) & 0xFF == ord("q"):
           break
    else:
        # Break the loop if the end of the video is reached
# Release the video capture and writer objects, and close the display window
cap.release()
out.release()
cv2.destroyAllWindows()
```

# 4. Target prediction: real-time detection

#### 4.1. USB camera

Use yolo11n.pt to predict the USB camera image.

Enter the code folder:

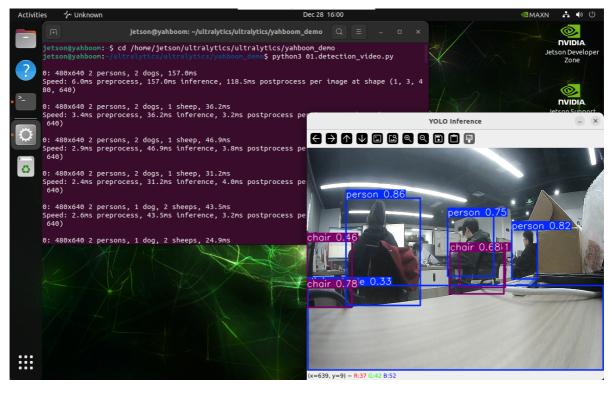
```
cd /home/jetson/ultralytics/ultralytics/yahboom_demo
```

Run the code: Click the preview screen and press the q key to terminate the program!

```
python3 01.detection_camera_usb.py
```

### **Effect preview**

Video location of yolo recognition output: /home/jetson/ultralytics/ultralytics/output/



#### Sample code:

```
import cv2
from ultralytics import YOLO
# Load the YOLO model
model = YOLO("/home/jetson/ultralytics/ultralytics/yolo11n.pt")
# Open the cammera
cap = cv2.VideoCapture(0)
# Get the video frame size and frame rate
frame_width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
frame_height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))
fps = int(cap.get(cv2.CAP_PROP_FPS))
# Define the codec and create a VideoWriter object to output the processed video
output_path =
"/home/jetson/ultralytics/ultralytics/output/01.detection_camera_usb.mp4"
fourcc = cv2.VideoWriter_fourcc(*'mp4v') # You can use 'XVID' or 'mp4v'
depending on your platform
out = cv2.VideoWriter(output_path, fourcc, fps, (frame_width, frame_height))
# Loop through the video frames
while cap.isOpened():
    # Read a frame from the video
    success, frame = cap.read()
    if success:
        # Run YOLO inference on the frame
        results = model(frame)
        # Visualize the results on the frame
        annotated_frame = results[0].plot()
        # Write the annotated frame to the output video file
```

### 4.2, CSI camera

Use yolo11n.pt to predict the CSI camera image.

Enter the code folder:

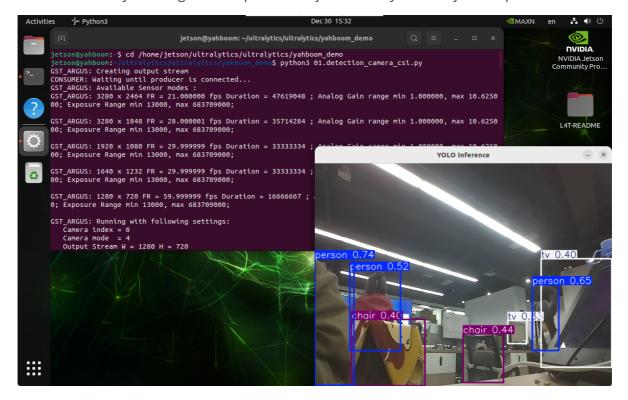
```
cd /home/jetson/ultralytics/ultralytics/yahboom_demo
```

Run the code: Click the preview screen and press the q key to terminate the program!

```
python3 01.detection_camera_csi.py
```

### **Effect preview**

Video location of yolo recognition output: /home/jetson/ultralytics/ultralytics/output/



Sample code:

```
from ultralytics import YOLO
from jetcam.csi_camera import CSICamera
# Load the YOLO model
model = YOLO("/home/jetson/ultralytics/ultralytics/yolo11n.pt")
# Open the camera (CSI Camera)
cap = CSICamera(capture_device=0, width=640, height=480)
# Get the video frame size and frame rate
frame_width = 640
frame_height = 480
fps = 30
# Define the codec and create a Videowriter object to output the processed video
output_path =
"/home/jetson/ultralytics/ultralytics/output/01.detection_camera_csi.mp4"
fourcc = cv2.videoWriter_fourcc(*'mp4v') # You can use 'XVID' or 'mp4v'
depending on your platform
out = cv2.VideoWriter(output_path, fourcc, fps, (frame_width, frame_height))
# Loop through the video frames
while True:
    # Read a frame from the camera
    frame = cap.read()
    if frame is not None:
        # Run YOLO inference on the frame
        results = model(frame)
        # Visualize the results on the frame
        annotated_frame = results[0].plot()
        # Write the annotated frame to the output video file
        out.write(annotated_frame)
        # Display the annotated frame
        cv2.imshow("YOLO Inference", cv2.resize(annotated_frame, (640, 480)))
        # Break the loop if 'q' is pressed
        if cv2.waitKey(1) & 0xFF == ord("q"):
            break
        # Break the loop if no frame is received (camera error or end of stream)
        print("No frame received, breaking the loop.")
# Release the video capture and writer objects, and close the display window
cap.release()
out.release()
cv2.destroyAllWindows()
```

### References