Camera preview

1. Enter Docker

```
sh ~/ros_melodic.sh
```
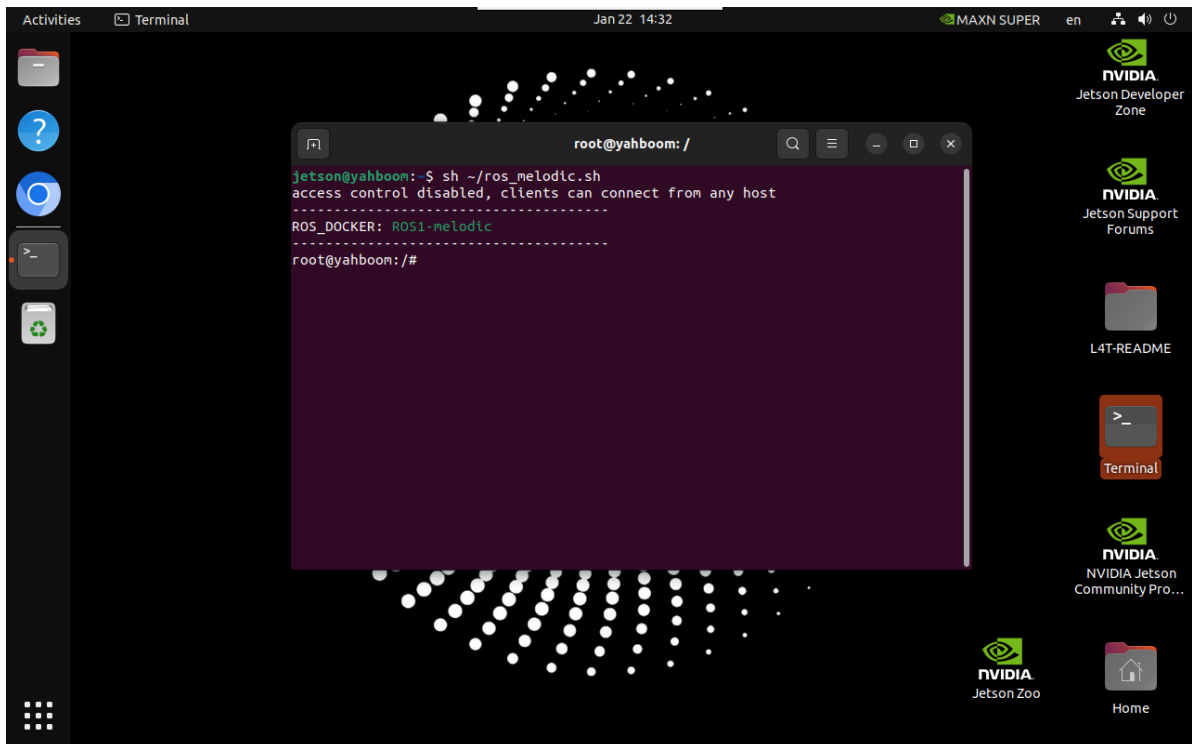

2. Camera preview

After entering Docker, we need to enter the user directory: just enter the cd command!

```
python3 ~/CameraPreview.py
```

root@yahboom: /

```
jetson@yahboom:~$ sh ~/ros_melodic.sh
access control disabled, clients can connect from any host
---------------------------------------
ROS_DOCKER: ROS1-melodic
---------------------------------------
root@yahboom:/# python3 ~/CameraPreview.py
```

CameraPreview

FPS:30.19

(x=108, y=194) ~ R:126 G:133 B:139

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