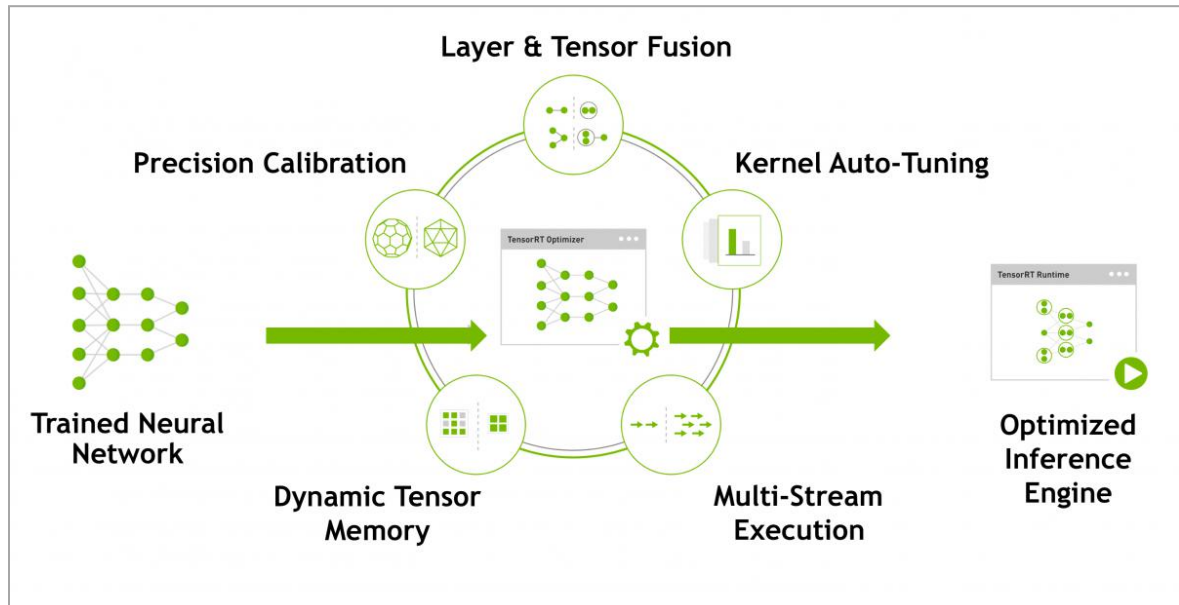


## 5.TensorRT Environmental construction (jetson-inference)



### 1. Preparation:

Because the model required for this example is about 1G, most of this example is not stored on the SD card (the SD card only has TensorRT required to run this model).

We need to remotely transfer the previously downloaded package to the corresponding directory.

First, if you don't have git and cmake, you need to install them.

```
sudo apt-get install libpython3-dev python3-numpy
sudo apt-get install git cmake
```

Clone the jetson-inference library

```
git clone https://github.com/dusty-nv/jetson-inference
```

Note:

If the system prompts, "error: RPC failed; curl 56 GnuTLS recv error (-54): Error in the pull function."

This reason is due to insufficient git default cache size.

We can increase the cache size using the following command

```
git config --global http.postBuffer 5242880000
```

If it still didn't work, it may be that the network speed is slow, configure the minimum speed and minimum speed time of git.

```
git config --global http.lowSpeedLimit 0
```

```
git config --global http.lowSpeedTime 999999
```

If it still does not work, it is a network problem in my own experience, and it is

recommended to do it when the network condition is better.

```
cd jetson-inference
git submodule update --init
```

```
mkdir build      # Create build folder
cd build         # Enter build
cmake ../        # Run cmake, it will automatically execute CMakePrebuild.sh in the
upper directory
```

**!!!Note:**

During this period, the system may prompt whether you need to install pytorch, please choose according to your personal needs.

Proceed as follows:

Edit `jetson-inference/CMakePrebuild.sh`.

- 1) Comment out `./download-models.sh` (with a `#` comment in front) as shown in Figure 1).
- 2) Transfer the jetson-inference package to the `data/networks` directory through WinSCP. As shown in Figure 2.

```

yahboom@yahboom-desktop: ~/yahboom/jetson-inference
#!/usr/bin/env bash
# this script is automatically run from CMakeLists.txt

BUILD_ROOT=$PWD

echo "[Pre-build] dependency installer script running..."
echo "[Pre-build] build root directory: $BUILD_ROOT"
echo ""

# Break on errors
set -e

# install packages
sudo apt-get update
sudo apt-get install -y dialog
sudo apt-get install -y libglew-dev glew-utils libgstreamer1.0-dev libgstreamer-plugins-base1.0-dev libglib2.0-dev
sudo apt-get install -y libopencv-calib3d-dev libopencv-dev
# libgstreamer0.10-0-dev libgstreamer-plugins-base0.10-dev libxnnlib-dev
sudo apt-get update

# run the model downloader
./download-models.sh

# run the pytorch installer
./install-pytorch.sh

echo "[Pre-build] Finished CMakePreBuild script"

```

Figure 1

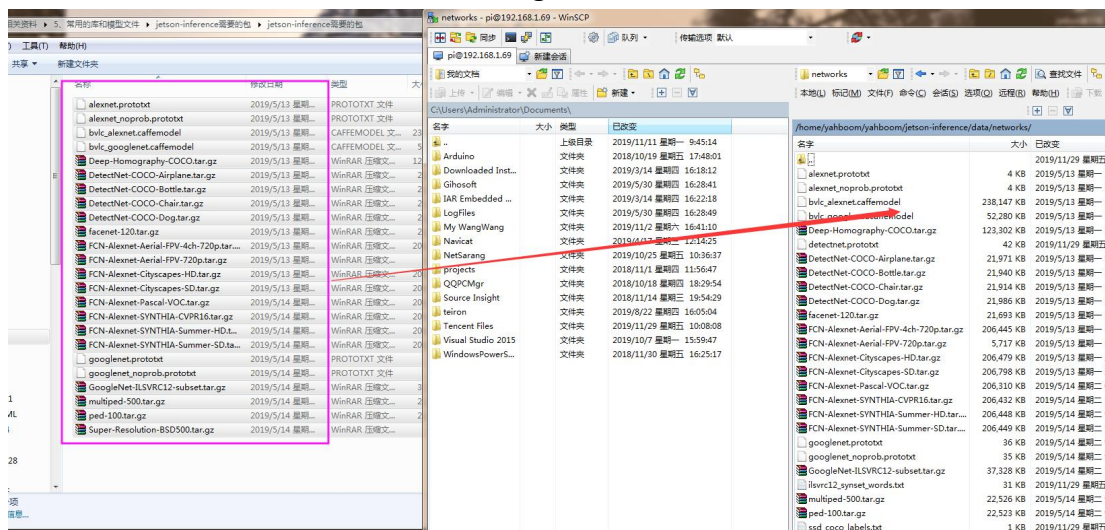


Figure 2

Input the following command to unzip .tar.gz files:

for tar in \*.tar.gz; do tar xvf \$tar; done

```

nano@nano-desktop:~/jetson-inference/data/networks$ ls
alexnet_noprob.prototxt      FCN-Alexnet-Cityscapes-HD.tar.gz
alexnet.prototxt            FCN-Alexnet-Cityscapes-SD
bvlc_alexnet.caffemodel     FCN-Alexnet-Cityscapes-SD.tar.gz
bvlc_googlenet.caffemodel   FCN-Alexnet-Pascal-VOC
Deep-Homography-COCO        FCN-Alexnet-Pascal-VOC.tar.gz
Deep-Homography-COCO.tar.gz FCN-Alexnet-SYNTHIA-CVPR16
DetectNet-COCO-Airplane     FCN-Alexnet-SYNTHIA-CVPR16.tar.gz
DetectNet-COCO-Airplane.tar.gz FCN-Alexnet-SYNTHIA-Summer-HD
DetectNet-COCO-Bottle       FCN-Alexnet-SYNTHIA-Summer-HD.tar.gz
DetectNet-COCO-Bottle.tar.gz FCN-Alexnet-SYNTHIA-Summer-SD
DetectNet-COCO-Chair        FCN-Alexnet-SYNTHIA-Summer-SD.tar.gz
DetectNet-COCO-Chair.tar.gz GoogleNet-ILSVRC12-subset
DetectNet-COCO-Dog          GoogleNet-ILSVRC12-subset.tar.gz
DetectNet-COCO-Dog.tar.gz  googlenet_noprob.prototxt
detectnet.prototxt         googlenet.prototxt
facenet-120                ilsvrc12_synset_words.txt
facenet-120.tar.gz         multyped-500
FCN-Alexnet-Aerial-FPV-4ch-720p multyped-500.tar.gz
FCN-Alexnet-Aerial-FPV-4ch-720p.tar.gz ped-100
FCN-Alexnet-Aerial-FPV-720p  ped-100.tar.gz
FCN-Alexnet-Aerial-FPV-720p.tar.gz Super-Resolution-BSD500
FCN-Alexnet-Cityscapes-HD   Super-Resolution-BSD500.tar.gz
nano@nano-desktop:~/jetson-inference/data/networks$

```

Input the following command to unzip .tar.gz files:

```
for gz in *.gz; do gunzip $gz; done
```

Input the following command to unzip multiple .tar.gz files:

```
for tar in *.tar.gz; do tar xvf $tar; done
```

After cmake is successful, we need to compile

```
cd jetson-inference/build
```

# Make here without sudo

# Back -j4 uses 4 CPU cores to compile at the same time, reducing time

```
make (or make -j4)
```

Note: (In the build directory)

```
sudo make install
```

Note: (In the build directory)

If the compilation is successful, the following folder structure will be generated.

| -build

\aarch64	(64-bit)
\bin	where the sample binaries are built to
\include	where the headers reside
\lib	where the libraries are built to
\armhf	(32-bit)
\bin	where the sample binaries are built to
\include	where the headers reside
\lib	where the libraries are built to

### 3. Testing

We need to input the following command:

```
cd jetson-inference/build/aarch64/bin
./imagenet-console orange_0.jpg output_0.jpg
```

After waiting patiently, we will see the interface shown below.  
(The first execution will take a long time)

```
yahboom@yahboom-desktop: ~/yahboom/jetson-inference/build/aarch64/bin$ ./imagenet-console ./images/bird_0.jpg output.jpg

imagenet -- loading classification network model from:
-- prototxt      networks/googlenet.prototxt
-- model         networks/bvlc_googlenet.caffemodel
-- class_labels  networks/ilsrvrc12_synset_words.txt
-- input_blob    'data'
-- output_blob   'prob'
-- batch_size    1

-- dim #0  3 (CHANNEL)
-- dim #1  224 (SPATIAL)
-- dim #2  224 (SPATIAL)
[TRT]  binding -- index  1
-- name    'prob'
-- type    FP32
-- in/out  OUTPUT
-- # dims  3
-- dim #0  1000 (CHANNEL)
-- dim #1  1 (SPATIAL)
-- dim #2  1 (SPATIAL)
[TRT]  binding to input 0 data binding index:  0
[TRT]  binding to input 0 data dims (b=1 c=3 h=224 w=224) size=602112
[TRT]  binding to output 0 prob binding index:  1
[TRT]  binding to output 0 prob dims (b=1 c=1000 h=1 w=1) size=4000
device GPU, networks/bvlc_googlenet.caffemodel initialized.
[TRT]  networks/bvlc_googlenet.caffemodel loaded
imagenet -- loaded 1000 class info entries
networks/bvlc_googlenet.caffemodel initialized.
[image] loaded './images/bird_0.jpg' (368 x 500, 3 channels)
class 0015 - 0.998702 (robin, American robin, Turdus migratorius)
imagenet-console: './images/bird_0.jpg' -> 99.87018% class #15 (robin, American robin, Turdus migratorius)

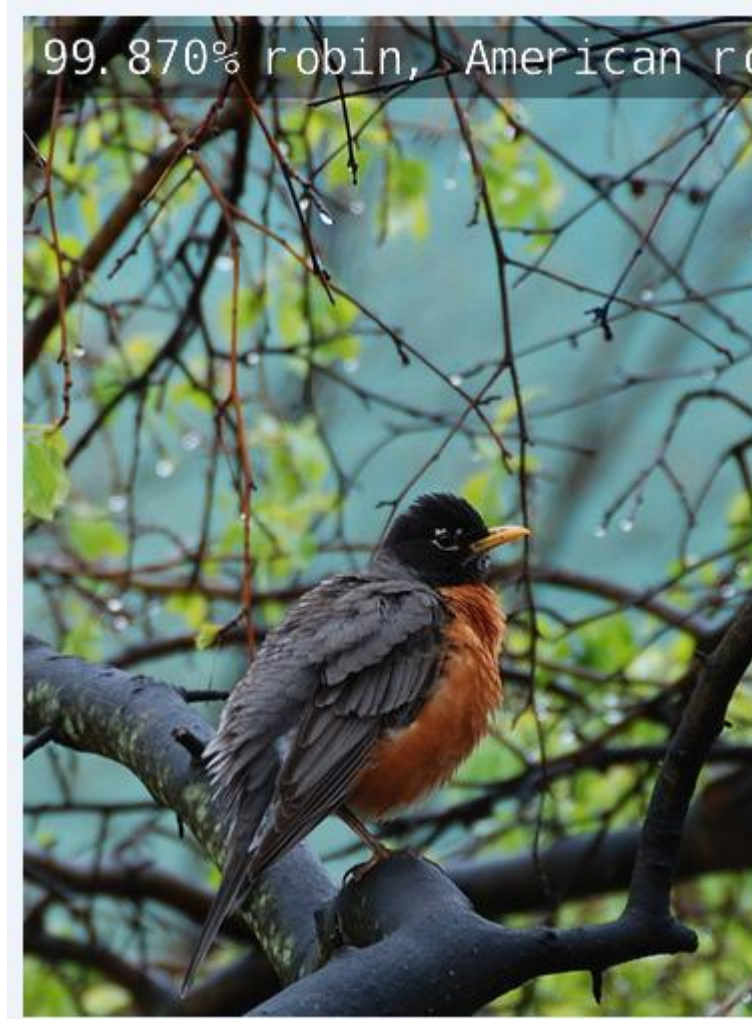
[TRT]  -----
[TRT]  Timing Report networks/bvlc_googlenet.caffemodel
[TRT]  -----
[TRT]  Pre-Process  CPU    0.08995ms  CUDA    0.64693ms
[TRT]  Network      CPU    72.14478ms  CUDA    71.47083ms
[TRT]  Post-Process  CPU    0.97890ms  CUDA    1.06088ms
[TRT]  Total        CPU    73.21364ms  CUDA    73.17864ms
[TRT]  -----

[TRT]  note -- when processing a single image, run 'sudo jetson_clocks' before
        to disable DVFS for more accurate profiling/timing measurements

imagenet-console: attempting to save output image to 'output.jpg'
imagenet-console: completed saving 'output.jpg'
imagenet-console: shutting down...
imagenet-console: shutdown complete
```

We need to find the corresponding directory to view **output\_0.jpg**, the recognition result will be displayed at the top of the picture, as shown below.





For more detail, please see the official documentation:

Official Demo:

<https://developer.nvidia.com/embedded/twodaystoademo>

Official TensorRT tutorial:

<https://docs.nvidia.com/deeplearning/sdk/tensorrt-sample-support-guide/index.html>