

10. YOLOv3 environment building and camera real-time detection

Official Link: <https://pjreddie.com/darknet/yolo/>

In this course, we use the tiny version of YOLOv3. The official version and the tiny version are installed in the same way, except that the configuration file and the weight file are different.

1. Install CUDA, OpenCV, cuDNN

Please refer to tutorial 1 for details.

2. Download

git clone <https://github.com/AlexeyAB/darknet.git>

Note:

If this prompt appears “Error: RPC failed; curl 56 GnuTLS recv error (-54): Error in the pull function.”

This is due to insufficient git default cache size. Use the following command to increase the cache size

`git config --global http.postBuffer 524288000`

If it still doesn't work, it may be that the network speed is slow, configure the minimum speed and minimum speed time of git

`git config --global http.lowSpeedLimit 0`

`git config --global http.lowSpeedTime 999999`

If it still doesn't work, it's a network problem from my own experience.

You can also download the ZIP file to your computer by going to

<https://github.com/AlexeyAB/darknet.git>, and then unzip it.

3. Configuration

`cd darknet`

`sudo vim Makefile` #Modify Makefile

4. Modify the first three lines of the Makefile

`GPU=1`

`CUDNN=1`

`OPENCV=1`

5. Compile

`make -j4`

6. Download the weight file

We can directly copy yolov4.weights to the darknet directory. As shown below.

```

nx@nx-desktop: ~/darknet-master$ ls
3rdparty      darknet      json_mjpeg_streams.sh  scripts
backup        DarknetConfig.cmake.in LICENSE             src
build         darknet.py   Makefile            video_v2.sh
build.ps1     darknet_video.py net_cam_v3.sh       video_yolov3.sh
build.sh      data        obj                 yolov4.weights
cfg           image_yolov2.sh predictions.jpg
cmake         image_yolov3.sh README.md
CMakeLists.txt include     results

```

7. Testing

Picture detection

```
./darknet detect cfg/yolov4.cfg yolov4.weights data/dog.jpg # Simplified version
```

```
./darknet detector test cfg/coco.data cfg/yolov4.cfg yolov4.weights data/dog.jpg
```

#Full version

Change the detection threshold

By default, YOLO only displays objects detected with a confidence of .25 or higher.

You can change this setting by passing the -thresh <val> flag to the yolo command.

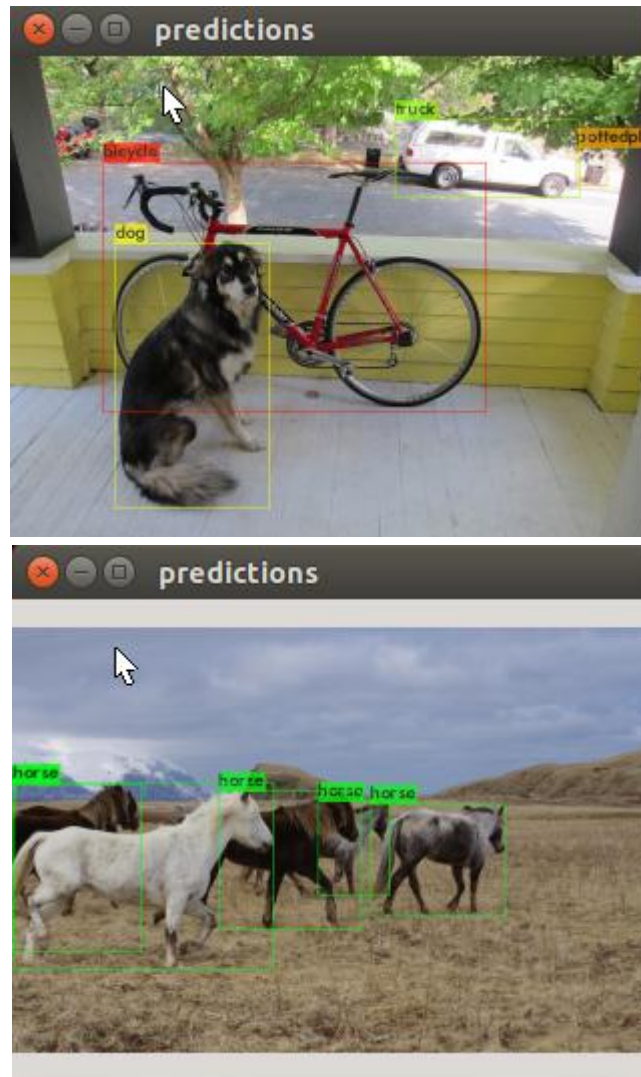
For example, to display all detections, you can set the threshold to 0.1:

```
./darknet detect cfg/yolov4.cfg yolov4.weights data/dog.jpg -thresh 0.1
```

```

nx@nx-desktop:~$ cd darknet-master/
nx@nx-desktop:~/darknet-master$ ./darknet detect cfg/yolov4.cfg yolov4.weights data/dog.jpg
  CUDA-version: 10020 (10020), cuDNN: 8.0.0, GPU count: 1
  OpenCV version: 4.1.1
  0 : compute_capability = 720, cudnn_half = 0, GPU: Xavier
  net.optimized_memory = 0
  mini_batch = 1, batch = 1, time_steps = 1, train = 0
  layer  filters  size/strd(dil)  input  output
  0 conv    32         3 x 3/ 1      608 x 608 x 3 -> 608 x 608 x 32 0.639 BF
  1 conv    64         3 x 3/ 2      608 x 608 x 32 -> 304 x 304 x 64 3.407 BF
  2 conv    64         1 x 1/ 1      304 x 304 x 64 -> 304 x 304 x 64 0.757 BF
  3 route    1                         -> 304 x 304 x 64
  4 conv    64         1 x 1/ 1      304 x 304 x 64 -> 304 x 304 x 64 0.757 BF
  5 conv    32         1 x 1/ 1      304 x 304 x 64 -> 304 x 304 x 32 0.379 BF
  6 conv    64         3 x 3/ 1      304 x 304 x 32 -> 304 x 304 x 64 3.407 BF
  7 Shortcut Layer: 4, wt = 0, wn = 0, outputs: 304 x 304 x 64 0.006 BF
  8 conv    64         1 x 1/ 1      304 x 304 x 64 -> 304 x 304 x 64 0.757 BF
  9 route    8 2                         -> 304 x 304 x 128
 10 conv    64         1 x 1/ 1      304 x 304 x 128 -> 304 x 304 x 64 1.514 BF
 11 conv   128         3 x 3/ 2      304 x 304 x 64 -> 152 x 152 x 128 3.407 BF
 12 conv    64         1 x 1/ 1      152 x 152 x 128 -> 152 x 152 x 64 0.379 BF
 13 route   11                         -> 152 x 152 x 128
 14 conv    64         1 x 1/ 1      152 x 152 x 128 -> 152 x 152 x 64 0.379 BF
 15 conv    64         1 x 1/ 1      152 x 152 x 64 -> 152 x 152 x 64 0.189 BF
 16 conv    64         3 x 3/ 1      152 x 152 x 64 -> 152 x 152 x 64 1.703 BF
 17 Shortcut Layer: 14, wt = 0, wn = 0, outputs: 152 x 152 x 64 0.001 BF
 18 conv    64         1 x 1/ 1      152 x 152 x 64 -> 152 x 152 x 64 0.189 BF
 19 conv    64         3 x 3/ 1      152 x 152 x 64 -> 152 x 152 x 64 1.703 BF
 20 Shortcut Layer: 17, wt = 0, wn = 0, outputs: 152 x 152 x 64 0.001 BF

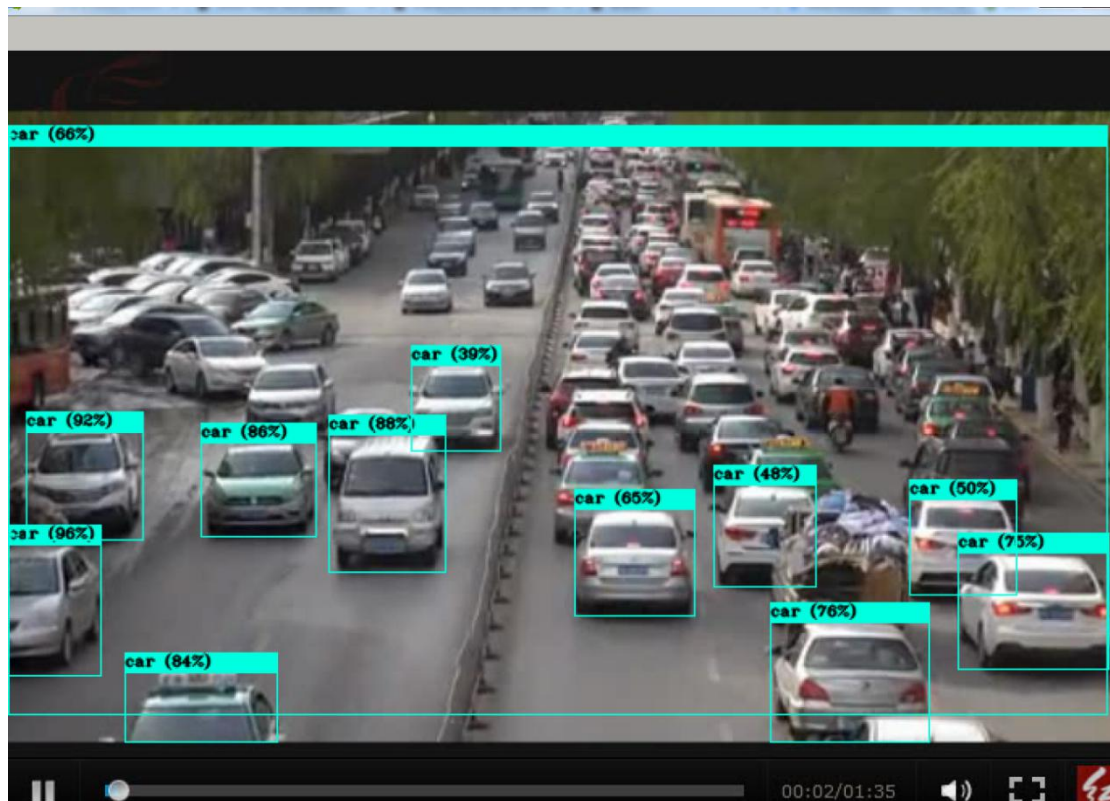
```



Video detection

`./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights data/123.mp4`

```
nx@nx-desktop:~/darknet-master$ ./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights data/123.mp4
CUDA-version: 10020 (10020), cuDNN: 8.0.0, GPU count: 1
OpenCV version: 4.1.1
Demo
0 : compute_capability = 720, cudnn_half = 0, GPU: Xavier
net.optimized_memory = 0
mini_batch = 1, batch = 1, time_steps = 1, train = 0
layer  filters  size/strd(dil)  input           output
0 conv    32          3 x 3/ 1       608 x 608 x 3 -> 608 x 608 x 32 0.639 BF
1 conv    64          3 x 3/ 2       608 x 608 x 32 -> 304 x 304 x 64 3.407 BF
2 conv    64          1 x 1/ 1       304 x 304 x 64 -> 304 x 304 x 64 0.757 BF
3 route    1           ->            304 x 304 x 64
4 conv    64          1 x 1/ 1       304 x 304 x 64 -> 304 x 304 x 64 0.757 BF
5 conv    32          1 x 1/ 1       304 x 304 x 64 -> 304 x 304 x 32 0.379 BF
6 conv    64          3 x 3/ 1       304 x 304 x 32 -> 304 x 304 x 64 3.407 BF
```



Camera real-time detect method

`./darknet detector demo cfg/coco.data cfg/yolov4.cfg yolov4.weights /dev/video1`

!Note:

Video needs to select the number corresponding to the current USB camera, such as video0, video1

