

# SDK manager writing system

1. Open NVIDIA's Jetpack download website :

<https://developer.nvidia.com/embedded/jetpack>

Using the virtual machine Ubuntu 18.04 (20.04 is also possible) system, click to download SDK Manager. Please register/log in to your NVIDIA account before using it.

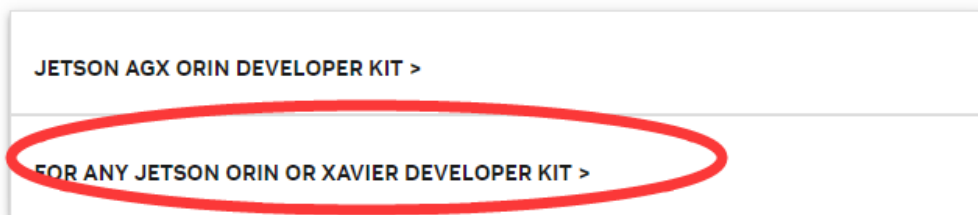
Jetson AGX Orin Developer Kit, Jetson Orin Nano Developer Kit, Jetson AGX Xavier Developer Kit and J

## Installing JetPack

### Debian Package Method

JetPack can be installed or upgraded using a Debian package management tool running on Jetson. NVI components. The runtime packages do not include samples and documentations while the developmen JetPack or only runtime JetPack components over Jetson Linux.

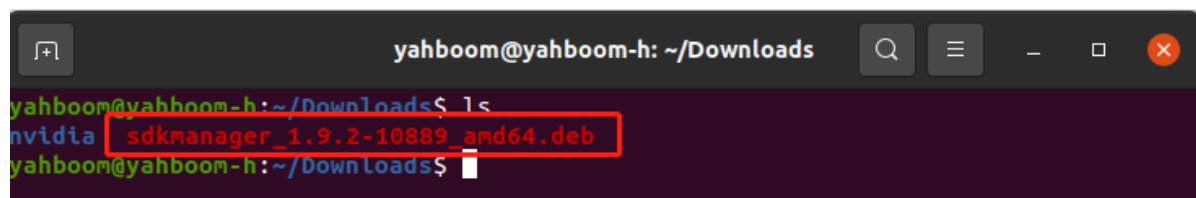
Please refer to [JetPack documentation for instructions](#) on the list of debian packages we host. Also Rei on top of Jetson Linux or upgrade JetPack.



2. Install SDK Manager.

First, enter the path of the .deb file you just downloaded, for example, download it here to the Downloads directory.

```
cd Downloads/
```



Enter the following command on the terminal to install SDK Manager.

```
sudo dpkg -i sdkmanager_1.9.2-10889_amd64.deb
```

```

yahboom@yahboom-vm:~/Downloads$ sudo dpkg -i sdkmanager_1.5.0-7774_amd64.deb
[sudo] password for yahboom:
Selecting previously unselected package sdkmanager.
(Reading database ... 114535 files and directories currently installed.)
Preparing to unpack sdkmanager_1.5.0-7774_amd64.deb ...
Unpacking sdkmanager (1.5.0-7774) ...
dpkg: dependency problems prevent configuration of sdkmanager:
 sdkmanager depends on libgconf-2-4; however:
  Package libgconf-2-4 is not installed.
 sdkmanager depends on libcanberra-gtk-module; however:
  Package libcanberra-gtk-module is not installed.

dpkg: error processing package sdkmanager (--install):
 dependency problems - leaving unconfigured
Processing triggers for gnome-menus (3.13.3-11ubuntu1.1) ...
Processing triggers for desktop-file-utils (0.23-1ubuntu3.18.04.2) ...
Processing triggers for mime-support (3.60ubuntu1) ...
Processing triggers for hicolor-icon-theme (0.17-2) ...
Errors were encountered while processing:
 sdkmanager

```

At this point, the system may report an error that the dependent file cannot be found. Enter the following command to solve this problem.

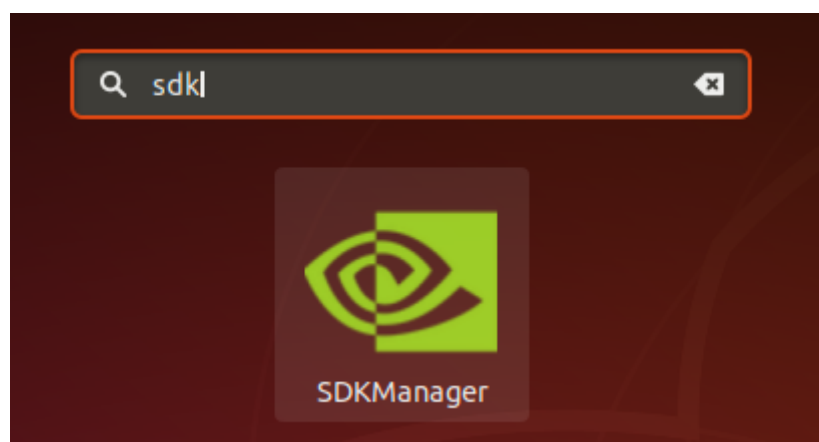
```
sudo apt --fix-broken install
```

```

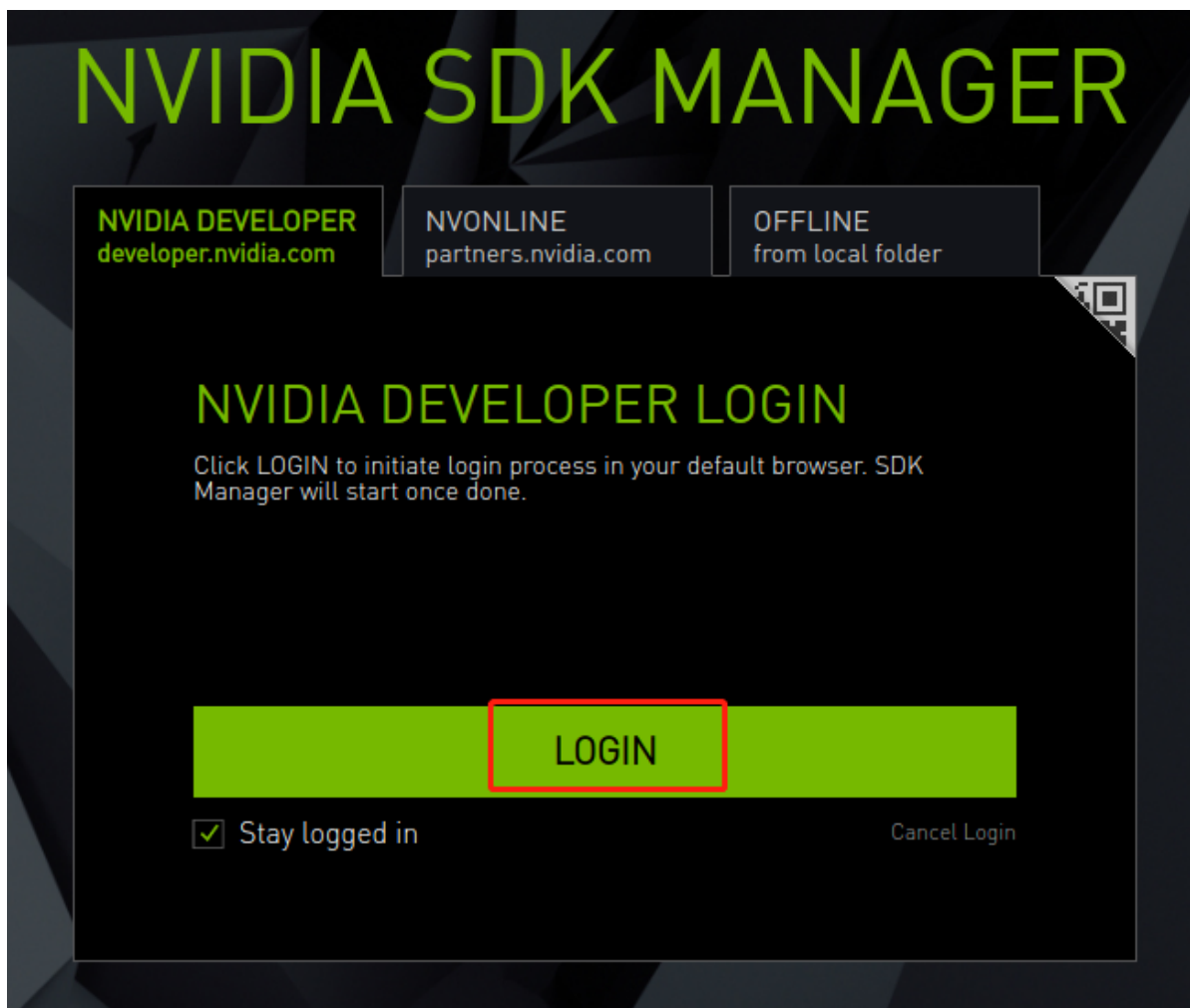
yahboom@yahboom-vm:~/Downloads$ sudo apt --fix-broken install
[sudo] password for yahboom:
Reading package lists... Done
Building dependency tree
Reading state information... Done
Correcting dependencies... Done
The following packages were automatically installed and are no longer required:
 fonts-liberation2 fonts-opensymbol gir1.2-gst-plugins-base-1.0 gir1.2-gstreamer-1.0 gir1.2-gudev-1.0 gir1.2-udisks-2.0 grilo-plugins-0.3-base gstreamer1.0-gtk3
 libboost-date-time1.65.1 libboost-filesystem1.65.1 libboost-iostreams1.65.1 libboost-locale1.65.1 libboost-1.65.1 libclucene-contribs1v5 libclucene-core1v5 libcms-0.5-sv5
 libcoland2 libdazzle-1.0-0 libe-book-0.1-1 libedataserverui-1.2-2 libeot0 libepubgen-0.1-1 libetonyek-0.1-1 libevent-2.1-6 libexiv2-14 libfreerdp-client2-2 libfreerdp2-2
 libgic2 libgee-0.8-2 libgexiv2-2 libgion-1.0-0 libgpgmepp6 libgpod-common libgpod4 liblangtag-common liblangtag1 liblirc-client0 liblua5.3-0 libmediart-2.0-0 libnsspub-0.1-1
 libodfgen-0.1-1 libqwing2v5 libraw16 librevenge-0.0-0 libsgutils2-2 libssh-4 libsuitesparseconfig5 libvncclient1 libwinpr2-2 libxapian3 libxlnsec1 libxlnsec1-nss lp-solve
 media-player-info python3-nako python3-markupsafe syslinux syslinux-common syslinux-legacy usb-creator-common
Use 'sudo apt autoremove' to remove them.
The following additional packages will be installed:
  gconf-service gconf-service-backend gconf2-common libcanberra-gtk-module libcanberra-gtk0 libgconf-2-4
The following NEW packages will be installed:
  gconf-service gconf-service-backend gconf2-common libcanberra-gtk-module libcanberra-gtk0 libgconf-2-4
0 upgraded, 6 newly installed, 0 to remove and 295 not upgraded.
1 not fully installed or removed.
Need to get 862 kB of archives.
After this operation, 0,134 kB of additional disk space will be used.
Do you want to continue? [Y/n] Y

```

3. Open the program for Ubuntu 18.04 system, search for SDK, you can find SDKManager, and open the file.



Log in to the NVIDIA account and a link will pop up in the browser, where you can enter your username and password to log in.



#### 4. Virtual Machine Ubuntu 18.04 Connection Jetson Orin nano

At this point, it is necessary to put the Jetson Orin nano into the system REC flash mode.

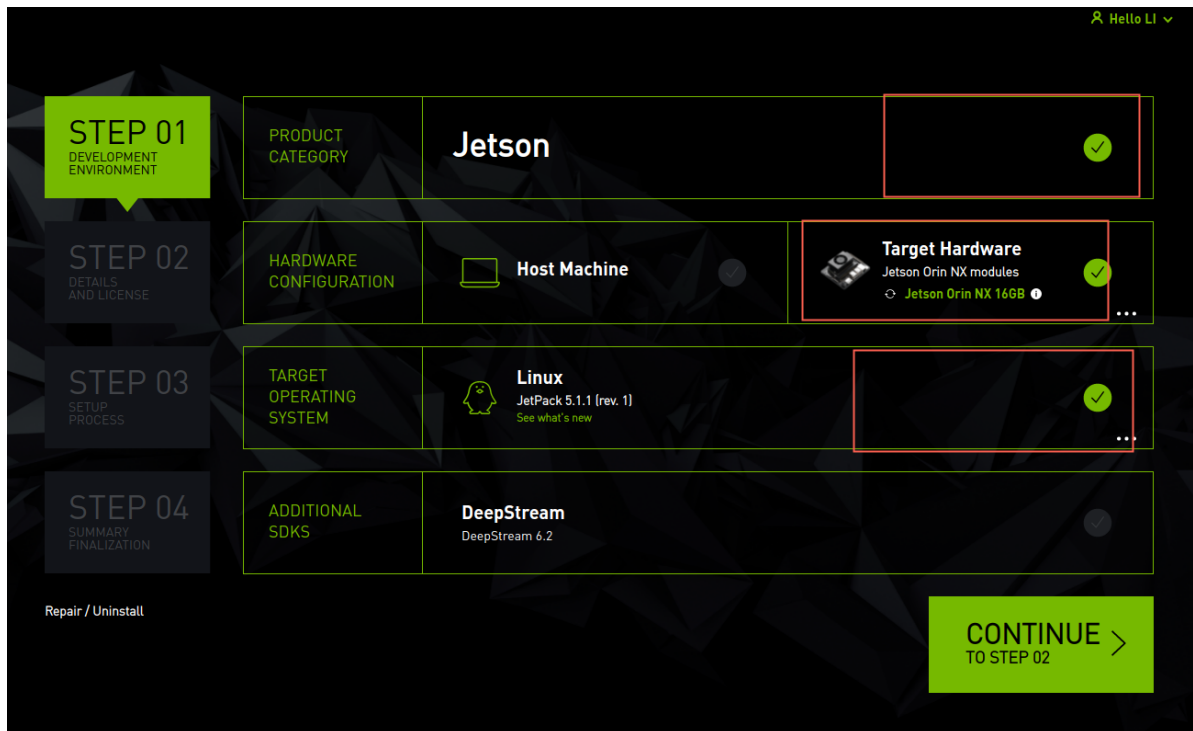
Connect the jumper cap to the FC REC and GND pins, that is, to the second and third pins of the carrier board below the core board, as shown in the following figure:



Connect the line, connect the HDMI display screen, mouse, keyboard, and microUSB data cable to the Jetson Orin nano, and finally connect to the power supply. Since the jumper cap was already connected to the FC REC and GND pins in the previous step, it will automatically enter the REC flash mode after powering on.



5. In the SDK Manager software of virtual machine Ubuntu 18.04, select Target Hardware as Jetson Orin nano modules, JetPack version, taking version 5.1.1 as an example.



If the target hardware displays an unconnected status, please confirm whether nano has entered REC flash mode and connected to the virtual machine, and then click refresh to refresh. Please note that using a virtual machine requires setting the device to connect to the virtual machine.

### New USB device detected

Select where you want to connect the NVIDIA APX

- ☐ Connect to host
- ☒ Connect to virtual machine

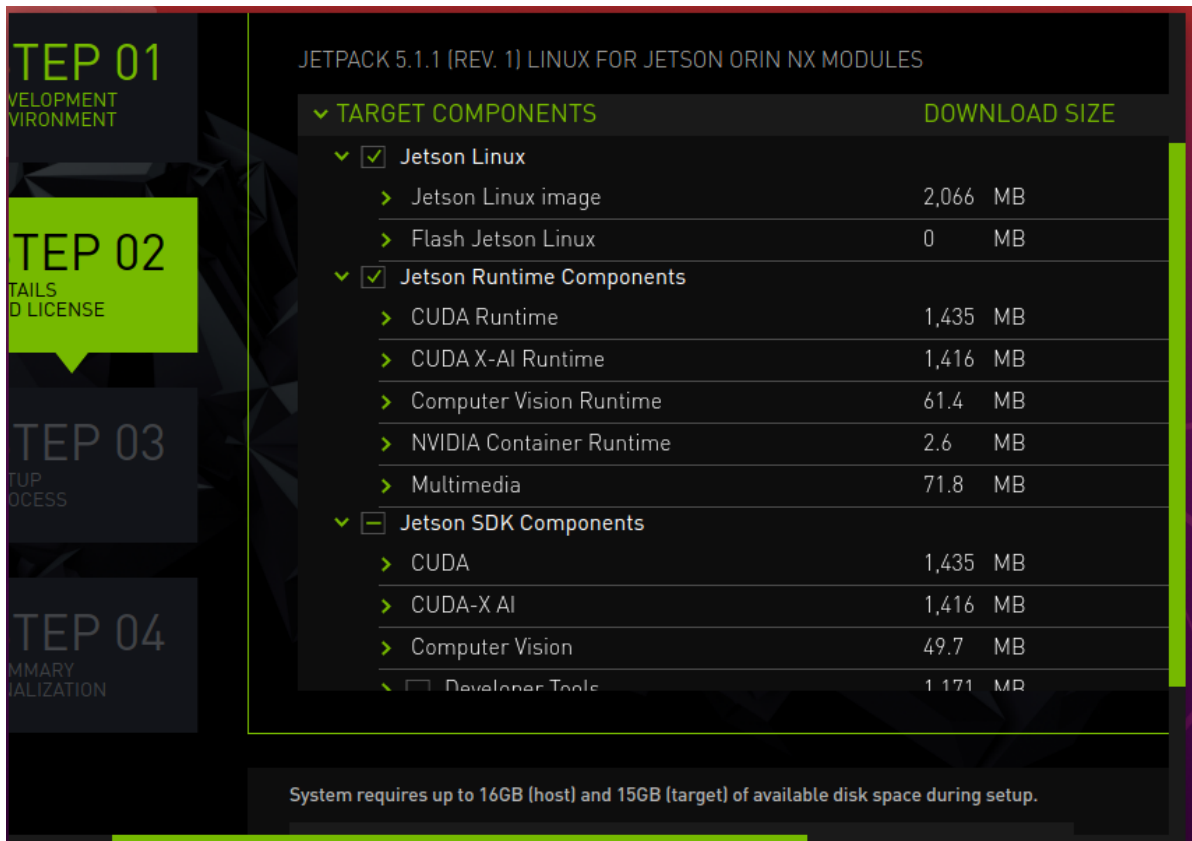
VM name

Ubuntu18

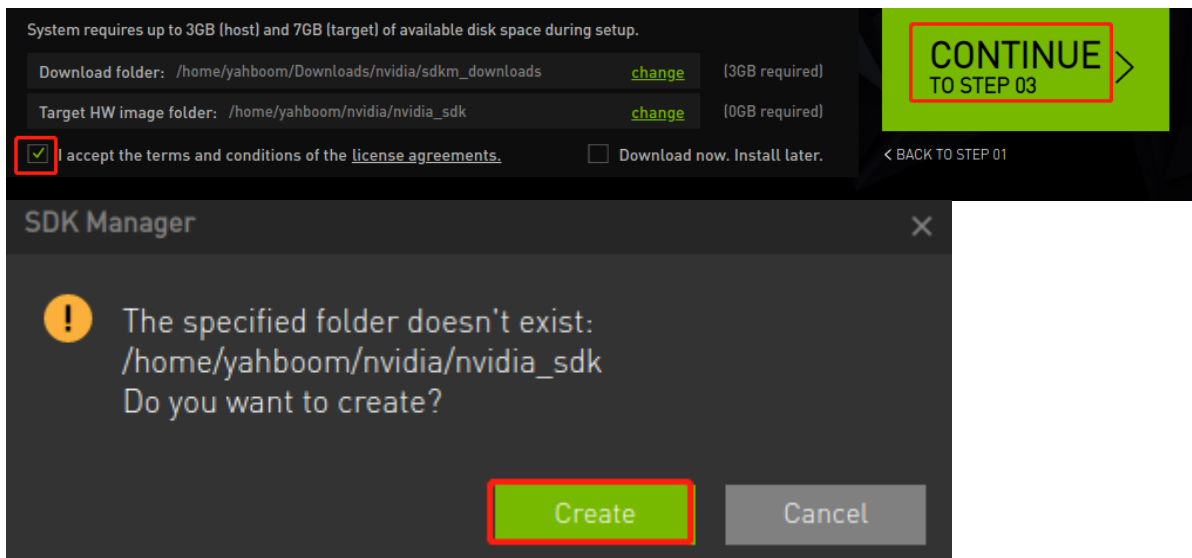
There are two versions of the Jetson Orin nano. Based on actual selection, choose an 8GB module for 8GB and a 16G module for 16GB. Generally, it will be automatically recognized when plugged in.

After confirming that there are no errors, click on 'Continue'

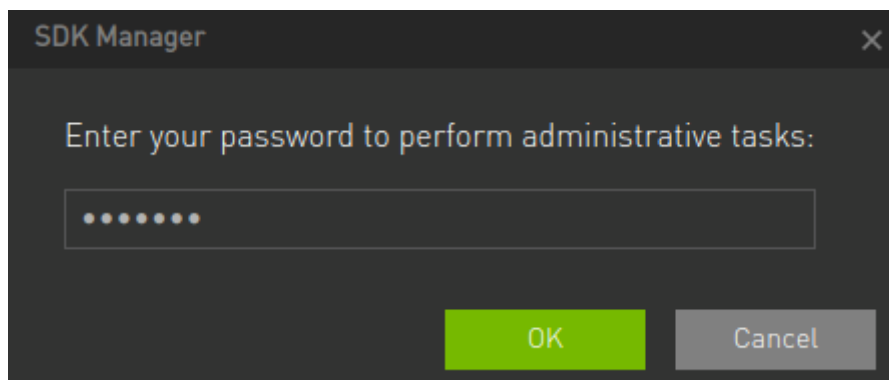
6. By default, Jetson OS and Jetson SDK Components will be checked, indicating that the system and SDK can be flushed in. You can select the system OS or software SDK separately, but before flushing in the software SDK separately, it is necessary to ensure that the system OS has been flushed in.



Just keep the default file download path, check the protocol, and click on 'Continue' to proceed to the next step.



Enter the password for the virtual machine.



At this point, the SDK Manager will first download the files that need to be burned, and wait for the download of the burned files to complete before starting to burn the system and SDK.



7. After waiting for the system OS to burn, the Jetson Orin nano will automatically restart and enter the system. At this time, it is necessary to set the basic functions of the system according to the system prompts, including setting a username and password, connecting to the same local area network as the virtual machine, and so on. Switch to the Jetson Orin nano system for settings. The settings here are relatively simple, so I won't take screenshots to explain them one by one. It is important to remember the username and password settings here, otherwise there may be issues with logging in to the system.

System Configuration

## Who are you?

Your name:  ✓

Your computer's name:  ✓  
The name it uses when it talks to other computers.

Pick a username:  ✓

Choose a password:  Weak password

Confirm your password:  ✓

☐ Log in automatically

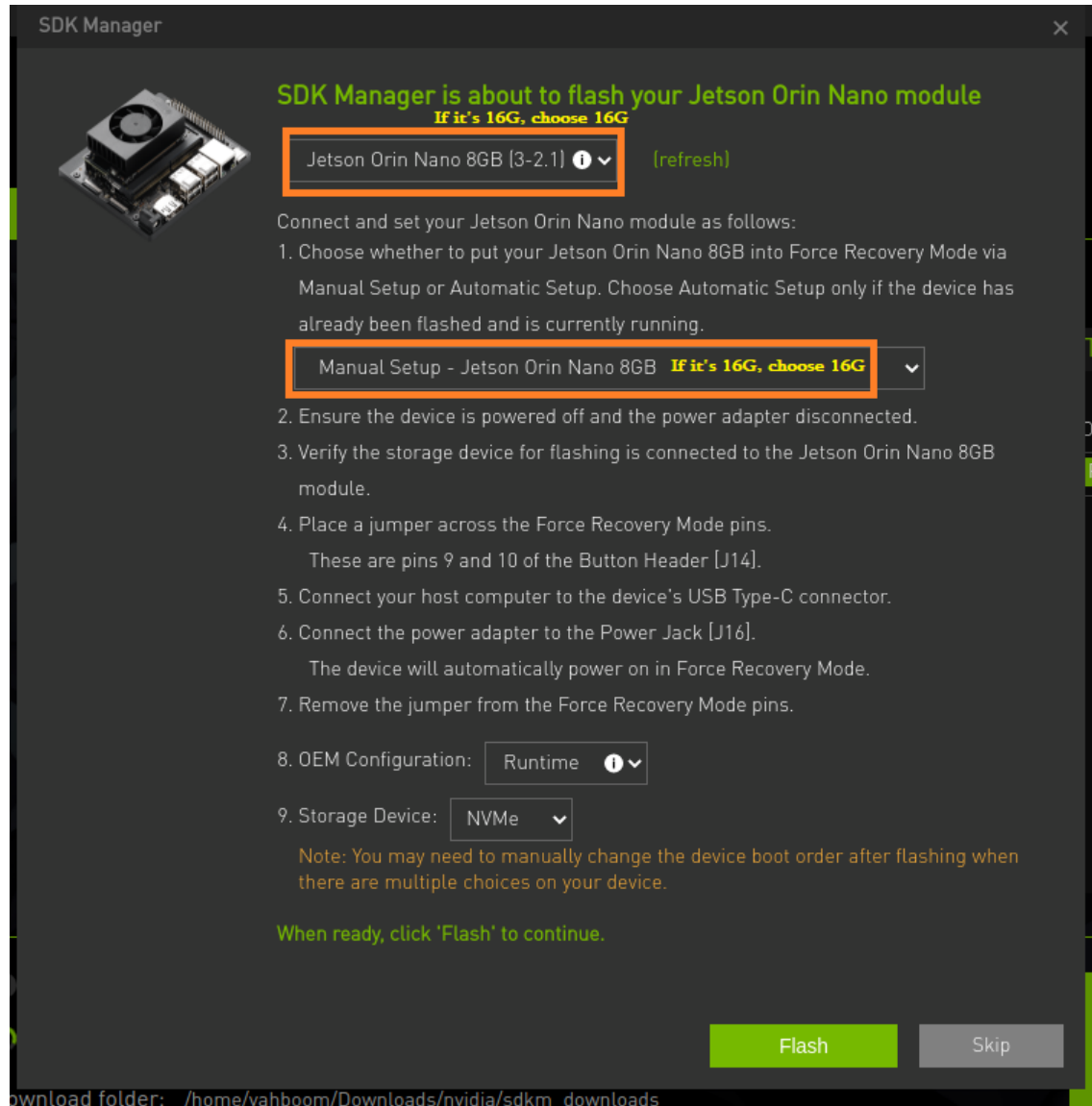
☒ Require my password to log in

Back Continue

Progress bar: 7 steps, last step completed.

8. After the system setup is completed, the Jetson Orin nano will restart again, and it will be disconnected from the virtual machine. You can plug and unplug the USB data cable again to connect to the virtual machine. Enter the username and password of the Jetson Orin nano that you just set up. Click Install to install the software SDK.

The following image is an 8GB



Note: Due to the need to use the network within the local area network to transmit data when swiping into the SDK, please insert a network cable for stable transmission.

After completion, it will prompt that all installations have been successful, and click FINISH. If there has been a software installation failure during the installation process, please click on 'reinstall'.



STEP 01  
DEVELOPMENT  
ENVIRONMENT

STEP 02  
DETAILS  
AND LICENSE

STEP 03  
SETUP  
PROCESS

STEP 04  
SUMMARY  
FINALIZATION

DETAILS

TERMINAL

JETPACK 4.6 LINUX FOR JETSON XAVIER NX

Expand all

TARGET COMPONENTS	VERSION	DOWNLOAD & INSTALL SIZE	STATUS
> Flash Jetson OS	0	MB	Skipped
> Jetson SDK Components			
> CUDA	1,027	MB	Installed
> CUDA-X AI	1,115	MB	Installed
With TensorRT, you can deliver fast inference using INT8 or FP16 optimized precision that significantly reduces latency. The NVIDIA CUDA Deep Neural Network (cuDNN) library provides high-performance GPU acceleration for your application.			
• cuDNN on Target	8.2	526.9 MB 1,595 MB (T)	Installed
• TensorRT on Target	8.0	588.2 MB 1,100 MB (T)	Installed
> Computer Vision	164.6	MB	Installed
> NVIDIA Container Runtime	1.1	MB	Installed
> Multimedia	71.7	MB	Installed
> Developer Tools	48.8	MB	Installed

✓

INSTALLATION COMPLETED SUCCESSFULLY.

Flash of target hardware was skipped.

EXPORT LOGS

FINISH  
AND EXIT

×

< BACK TO STEP 01

9. Note: After burning the system and SDK, please remove the jumper cap between FC REC and GND.