

# Temperature Detection

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## Temperature Detection

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## I. Learning Objectives

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1. Understand basic ADC knowledge.
2. Learn basic ADC usage, printing collected internal temperature values through serial port.

### ADC Principle

ADC (analog to digital converter) is an analog-to-digital converter used to convert analog signals (such as voltage) into digital signals. Analog signals change continuously, while digital signals are discrete binary numbers. ADC converts analog signals into digital data through sampling and quantization, so that processors or microcontrollers can perform subsequent processing. According to their conversion principles, they are mainly divided into three types: successive approximation type, dual-slope integration type, and voltage-frequency conversion type.

MSPM0G3507 uses a successive approximation (SAR) ADC, which is a common ADC working principle. Its basic idea is to gradually approximate the digital representation of the input signal by comparing the magnitude relationship between the analog signal and the reference voltage. In successive approximation ADCs, the input signal and reference voltage are compared through a differential amplifier to produce a differential voltage. Then, this differential voltage is input to a successive approximation digital quantizer, which gradually compares it with a series of reference voltages. At each approximation stage, the quantizer compares the input signal with an intermediate voltage point and selects a higher or lower reference voltage as the reference for the next approximation stage based on the comparison result. This process continues until the quantizer finally approximates to a digital output value.

### ADC Basic Parameters

#### 1. Resolution:

- Resolution represents the precision of the ADC converter output, usually measured in bits, such as 8-bit, 10-bit, 12-bit, etc. The higher the resolution, the more discrete digital values the ADC can represent, thereby providing higher precision.

#### 2. Sampling Rate:

- Sampling rate (also called conversion rate) represents the rate at which the ADC samples the analog input signal, usually expressed in samples per second (SPS). It indicates how many analog-to-digital conversions the ADC can perform per second.
- **MSPM0G3507** has a sampling rate of 4Msps (4 million samples per second), suitable for high-frequency signal acquisition and real-time data processing.

#### 3. Voltage Reference:

- The ADC voltage reference is a reference voltage used to compare with the analog input signal to ultimately achieve analog-to-digital signal conversion. The accuracy and stability of the voltage reference are crucial to the ADC conversion precision.

- MSPM0G3507

supports three voltage reference configurations:

- Internal configurable reference voltage: 1.4V and 2.5V dedicated ADC reference voltage (VREF).
- MCU power supply voltage (VDD) as reference voltage.
- External reference voltage provided through VREF+ and VREF- pins. If no voltage reference is configured, the MCU's power supply voltage (VDD) is used as the reference voltage by default.

#### 4. Sampling Range:

- Sampling range represents the voltage range of analog input signals that the ADC can collect, usually closely related to the reference voltage setting. The range is as follows:  
VREF- ≤ ADC ≤ VREF+
  - **VREF-:** Set reference voltage negative terminal, usually 0V.
  - **VREF+:** Set reference voltage positive terminal, determined according to software configuration.

These parameters together determine the ADC performance, including its precision, response speed, and input voltage range.

## II. Hardware Setup

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The data sheet feature description states that MSPM0 has an integrated temperature sensor that can roughly feedback chip temperature

- **High-performance analog peripherals**
  - Two simultaneous sampling 12-bit 4-MspS analog-to-digital converters (ADCs) with up to 17 external channels
    - 14-bit effective resolution at 250-ksps with hardware averaging
  - One 12-bit 1-MSPS digital-to-analog converter with integrated output buffer (DAC)
  - Two zero-drift zero-crossover chopper op-amps (OPA)
    - 0.5- $\mu$ V/ $^{\circ}$ C drift with chopping
    - Integrated programmable gain stage, up to 32x
  - One general-purpose amplifier (GPAMP)
  - Three high-speed comparators (COMP) with 8-bit reference DACs
    - 32-ns propagation delay in high-speed mode
    - Support low-power mode operation down to 0.7  $\mu$ A
  - Programmable analog connections between ADC, OPAs, COMP and DAC
  - Configurable 1.4-V or 2.5-V internal shared voltage reference (VREF)
    - Integrated temperature sensor
    - Integrated supply monitor

The temperature sensor is internally connected to ADC channel 11 and channel 12. Here we take ADC0 peripheral conversion channel 11 as an example

**Table 8-7. ADC Channel Mapping**

CHANNEL[0:7]	SIGNAL NAME <sup>(2)</sup>		CHANNEL[8:15]	SIGNAL NAME <sup>(1) (2)</sup>	
	ADC0	ADC1		ADC0	ADC1
0	A0_0	A1_0 / DAC_OUT <sup>(4)</sup>	8	A1_7 <sup>(3)</sup>	A0_7 <sup>(3)</sup>
1	A0_1	A1_1	9	-	-
2	A0_2	A1_2	10	-	-
3	A0_3	A1_3	11	Temperature Sensor	-
4	A0_4	A1_4	12	A0_12	Temperature Sensor
5	A0_5	A1_5	13	OPA0 output	OPA1 output
6	A0_6	A1_6	14	GPAMP output	GPAMP output
7	A0_7	A1_7	15	Supply/Battery Monitor	Supply/Battery Monitor

The following is the data sheet description of the temperature sensor

A unit-specific single-point trim value (TEMP\_SENSE0.DATA) is provided in each device's factory constant memory. This value represents the output voltage of the temperature sensor at the factory temperature (TSTRIM), expressed in ADC result code format. The ADC result code in TEMP\_SENSE0. Data is based on 12-bit sampling mode, and the temperature sensor outputs a voltage linearly related to temperature. The temperature coefficient (TSc) is the slope of the temperature-voltage relationship (in mV/C), given in the specifications section of the device-specific data sheet (as shown in the table below)

### 7.13 Temperature Sensor

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
TS <sub>TRIM</sub>	Factory trim temperature <sup>(1)</sup>	ADC and VREF configuration: RES=0 (12-bit mode), VRSEL=0h (VDDA=3.3V), ADC t <sub>sample</sub> =12.5μs	27	30	33	°C
TS <sub>c</sub>	Temperature coefficient	-40°C ≤ T <sub>j</sub> ≤ 130°C	-1.9	-1.8	-1.7	mV/°C
t <sub>SET, TS</sub>	Temperature sensor settling time <sup>(2)</sup>	ADC and VREF configuration: RES=0 (12-bit mode), VRSEL=0h (VDDA=3.3V), ADC CHANNEL=11			10	us

The approximate temperature of the device can be computed through the use of the following parameters:

- TS<sub>c</sub>, taken from the device data sheet
- TEMP\_SENSE0.DATA, taken from the unit-specific factory constants memory
- TS<sub>TRIM</sub>, taken from the device data sheet
- V<sub>SAMPLE</sub> (voltage sample of the temperature sensor at time of interest, taken with the ADC)

The temperature is computed through the linear relationship given in [Equation 17](#), where V<sub>SAMPLE</sub> is the current temperature sensor voltage, and V<sub>TRIM</sub> is the factory calibrated temperature sensor voltage at the TS<sub>TRIM</sub> temperature (derived from TEMP\_SENSE0.DATA):

$$T_{SAMPLE} = (1 / TS_c) * (V_{SAMPLE} - V_{TRIM}) + TS_{TRIM} \quad (17)$$

The ADC<sub>CODE</sub> raw result can be converted to a voltage equivalent (V<sub>SAMPLE</sub>) as shown in the relationship in [Equation 18](#), where RES is the ADC resolution in bits, and VREF is the ADC reference voltage.

$$V_{SAMPLE} = (VREF / 2^{RES}) * (ADC_{CODE} - 0.5) \quad (18)$$

## III. Experiment Steps

### Import Project

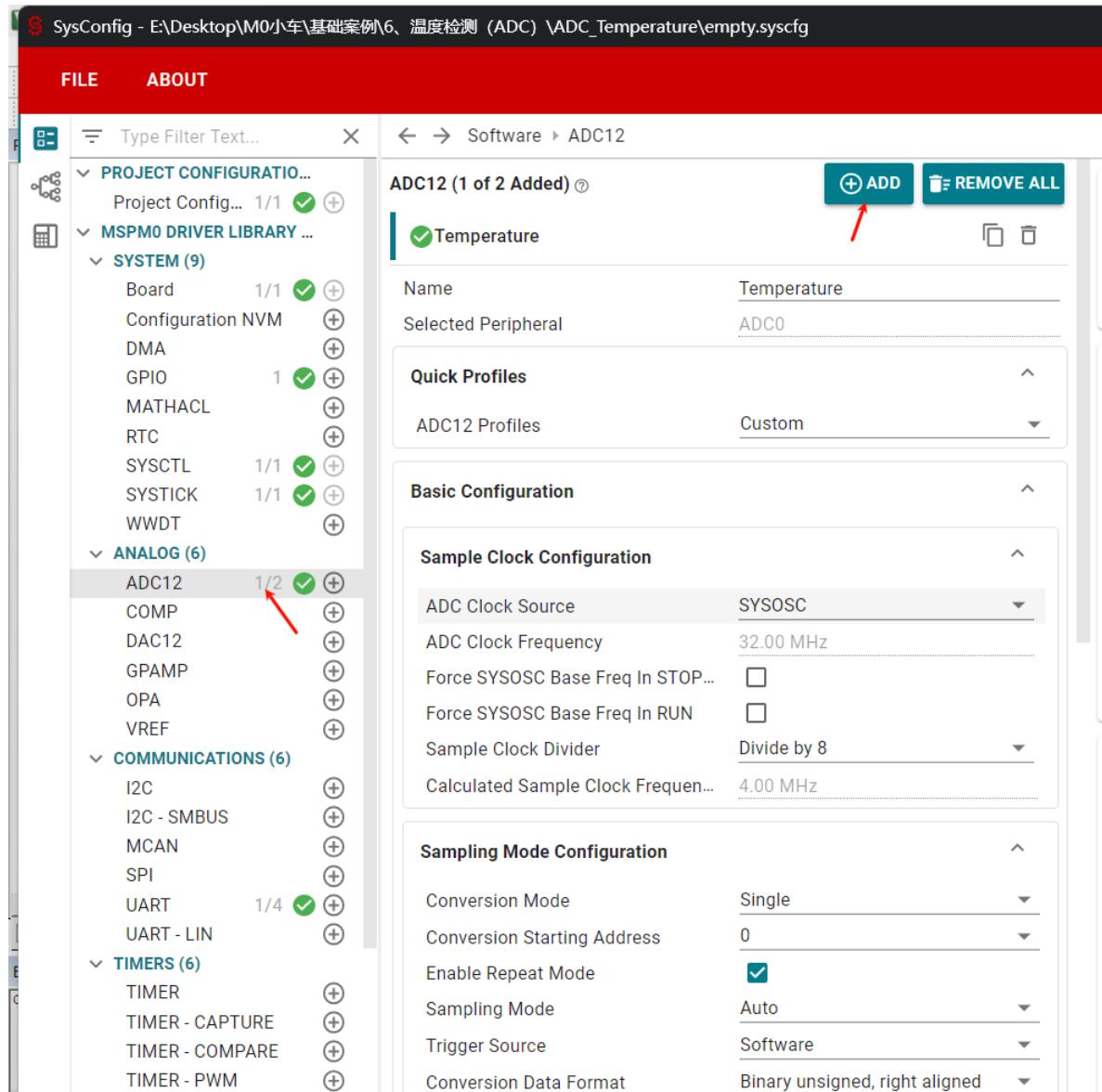
In KEIL, open our serial communication project from the previous section, or you can use the project template from the 80MHz clock frequency configuration chapter or the empty project from the SDK.

After selecting and opening, in the KEIL interface, open the empty.syscfg file. **With the empty.syscfg file open**, select Open SYSCONFIG GUI interface from the Tools menu.

### Add ADC Peripheral Configuration

The source code for this tutorial is based on the source code from tutorial 4 Serial Communication.

In SYSCONFIG, select MCU peripherals on the left, find ADC12 option and click to enter. In ADC12, click ADD to add ADC peripheral. Here we name it Temperature



The configuration selected here is to use 32MHz ADC frequency, sampling frequency of 4MHz, single repeat conversion mode, ADC sampling is triggered by software, data format is binary right-aligned. We set the sampling time to 10ms

Enable channel 0 result load interrupt

Total Conversion Frequency	AUTO, ADC wakeup time may need to be considered in each sample window. Refer to the device window.	<a href="#">Generated File</a>
Conversion Resolution		
Enable FIFO Mode		
Power Down Mode		
Desired Sample Time 0		
Actual Sample Time 0		
Desired Sample Time 1		
Actual Sample Time 1		
<b>Interrupt Configuration</b>		
Enable Interrupts		
Interrupt Priority	MEM0 result loaded interrupt	X ▾
	Default	▼

Configure as ADC0 as conversion peripheral

Disable Channel 12 Pin	<input type="checkbox"/>
PinMux Peripheral and Pin Configuration	
ADC12 Peripheral	Any(ADC0) <span style="float: right;">▼ </span>

Parameter description:

**ADC Clock Source:** ADC clock source. Set to `SYSOSC(32MHz)`.

**ADC Clock Frequency:** Shows the current ADC clock frequency.

**Sample Clock Divider:** Sampling divider. Configured as divide by 8

**Calculated Sample clock Frequency:** Shows the sampling frequency after division.

**Conversion Mode:** Conversion mode. Configured as `single`, `single`.

**Conversion Starting Address:** Conversion start address. Configured to start sampling

0th (related to the storage register below).

**Sampling Mode:** Sampling method. Set to **Auto**, automatic.

**Enable Repeat Mode:** Whether to enable repeat conversion. Checked here, enabled.

**Sampling Mode:** Sampling method. Set to `Auto`, automatic.

**Trigger Source:** ADC trigger method. Configured as `Software` software trigger method.

**Conversion Data Format:** ADC data conversion format. Configured as `Binary unsigned, right aligned` binary format right-aligned method

MSPM0G3507's ADC supports multiple data alignment methods to adapt to different application scenarios. Common data alignment methods include **left-aligned** and **right-aligned**.

- **Right-aligned mode:** In right-aligned mode, the ADC data is right-aligned to the least significant bits after conversion, with insufficient bits filled with 0 in the high bits. Right-aligned mode allows for better dynamic range without precision loss.

Rule group data

0	0	0	0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
---	---	---	---	-----	-----	----	----	----	----	----	----	----	----	----	----

Injection group data

Sign	Sign	Sign	Sign	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
------	------	------	------	-----	-----	----	----	----	----	----	----	----	----	----	----

DAL=0

- **Left-aligned mode:** In left-aligned mode, the ADC data is left-aligned to the most significant bits, with insufficient bits filled with 0 in the low bits. Left-aligned mode can improve resolution but results in reduced dynamic range.

Rule group data

D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	0	0	0	0
-----	-----	----	----	----	----	----	----	----	----	----	----	---	---	---	---

Injection group data

Sign	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	0	0	0
------	-----	-----	----	----	----	----	----	----	----	----	----	----	---	---	---

DAL=1

We configure as right-aligned method, so we can directly perform calculations on the converted data.

ADC conversion channel configuration puts conversion results in memory 0

**ADC Conversion Memory Configurations**

Active Memory Control Blocks

ADC Conversion Memory

Select All  ADC Conversion Memory 0

**ADC Conversion Memory 0 Configuration**

Name	ADC_CH0
Input Channel	Channel 11
Device Pin Name	Temperature Sensor
Reference Voltage	VDDA
VDDA	3.30 V
Sample Period Source	Sampling Timer 0
ADC Conversion Period	52.25 $\mu$ s

**Optional Configuration**

Parameter description:

**Active Memory Control Blocks:** ADC data storage address. Store ADC conversion result in register 0.

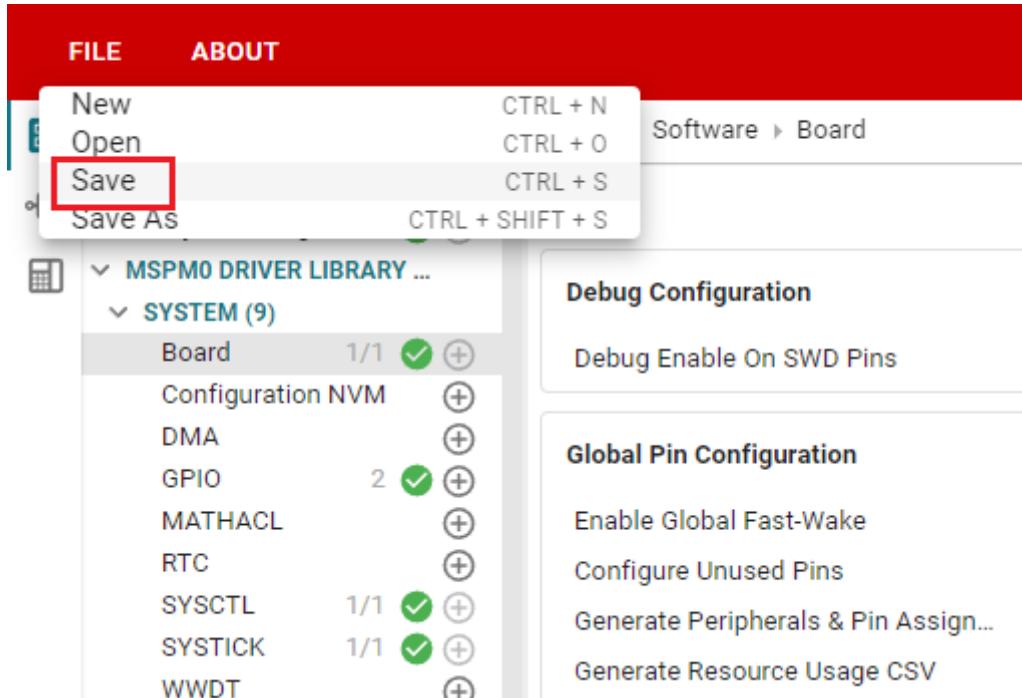
**Input Channel:** Input channel. Select channel 0 (each channel corresponds to different pins).

**Device Pin Name:** Pin automatically selected according to channel, channel 0 pin is PA27.

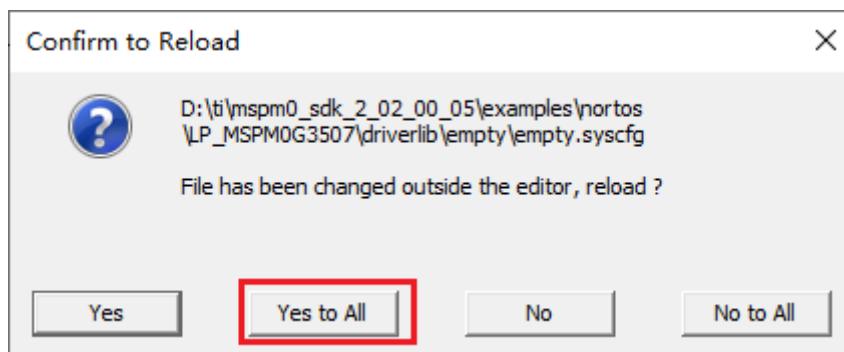
**Reference Voltage:** Voltage reference. Configured to use MCU power supply VDDA.

**ADC Conversion Period:** Shows the time for ADC to convert a single data

Click SAVE to save the configuration in SYS CONFIG, then close SYS CONFIG and return to keil.



Select Yes to All in the pop-up window



## IV. Program Analysis

Like the previous section, we create new bsp\_vol\_adc.c, bsp\_vol\_adc.h under the BSP file, configured as follows

temperature\_adc.h

```
#ifndef __BSP_TEMPRATURE_H__
#define __BSP_TEMPRATURE_H__

#include "ti_msp_d1_config.h"
```

```

#define TEMP_TS_TRIM_C ((uint32_t)30)
// (-1.75f)
#define TEMP_TS_COEF_mV_C (3.3f)
#define ADC_VREF_VOLTAGE

#define ADC_BIT_RESOLUTION ((uint32_t)(1)<<12)

extern volatile bool gCheckADC;
extern volatile float gTemperatureDegC;
extern volatile float gTemperatureDegF;

#endif

```

temperature\_adc.c

```

#include "temperature_adc.h"

volatile bool gCheckADC;
volatile float gTemperatureDegC;
volatile float gTemperatureDegF;

/**
 * @brief Temperature ADC interrupt service routine
 * @brief 温度ADC中断服务函数
 */
void Temperature_INST_IRQHandler(void)
{
    //Check and process ADC interrupt sources
    //检查并处理ADC中断源
    switch (DL_ADC12_getPendingInterrupt(Temperature_INST)) {

        //ADC MEMO result loaded interrupt
        //ADC MEMO结果加载中断
        case DL_ADC12_IIDX_MEMO_RESULT_LOADED:
            //Set ADC completion flag
            //设置ADC完成标志位
            gCheckADC = true;
            break;

        //Other interrupt cases
        //其他中断情况
        default:
            break;
    }
}

```

empty.c

```

#include "ti_msp_dl_config.h"
#include "temperature_adc.h"
#include "uart0.h"
#include <math.h>

```

```

int main(void)
{
    //ADC sampling result / ADC采样结果
    uint32_t adcResult;

    //tempDegC: Celsius temperature / 摄氏温度
    //tempDegF: Fahrenheit temperature / 华氏温度
    //vSample: Current voltage / 当前电压

    //vTrim: Output voltage of temperature sensor at factory calibration
    //temperature TEMP_TS_TRIM_C
    float vSample, vTrim, tempDegC, tempDegF;

    //System configuration initialization
    SYSCFG_DL_init();

    //Get factory calibration value and convert to voltage
    //DL_SYSCTL_getTempCalibrationConstant reads ADC value from TEMP_SENSE0.DATA
    vTrim = (DL_SYSCTL_getTempCalibrationConstant() - 0.5f) * ADC_VREF_VOLTAGE /
    ADC_BIT_RESOLUTION;
    //Enable temperature ADC interrupt
    NVIC_EnableIRQ(Temperature_INST_INT IRQN);

    gCheckADC = false;
    while (1) {
        //Start ADC conversion
        DL_ADC12_startConversion(Temperature_INST);

        //Wait for conversion to complete
        while (false == gCheckADC) {
            __WFE();
        }
        gCheckADC = false;

        //Stop ADC conversion
        DL_ADC12_stopConversion(Temperature_INST);

        //Collect ADC value of current temperature
        adcResult = DL_ADC12_getMemResult(Temperature_INST,
        Temperature_ADCMEM_ADC_CH0);

        //Convert ADC result to voltage value
        vSample = (adcResult - 0.5f) * ADC_VREF_VOLTAGE / ADC_BIT_RESOLUTION;

        //Calculate temperature (Celsius)
        //Formula: Temp = (V_sample - V_trim) * coeff + Trim_Temp
        tempDegC = (vSample - vTrim) * TEMP_TS_COEF_mV_C * 1000.0f +
        TEMP_TS_TRIM_C;

        //Note: Coefficient TEMP_TS_COEF_mV_C comes from data sheet

        //Multiply by 1000 above converts millivolts to volts, because vSample
        //and vTrim units are volts (V)
        //Calculate Fahrenheit temperature
        tempDegF = tempDegC * 9.0f / 5.0f + 32.0f;
        //Update global temperature variables
        gTemperatureDegC = tempDegC;
}

```

```

gTemperatureDegF = tempDegF;

//Print temperature value (retain 1 decimal place)
printf("%3.1f°C \r\n", gTemperatureDegC);
}
}

```

## V. Experiment Phenomenon

We connect Type-C to the computer and the car, then open the serial debugging assistant, baud rate 9600, eight data bits, one stop bit, no parity.

**Note that when using Type-C as debugging serial port output, it is not recommended to connect other sensors to serial port 0!**

