# 2. Common commands

## 2. Common commands

- 2.1, do not use the sudo command
- 2.2, help commands
- 2.3, mirror command
- 2.4, container commands
- 2.5, common other commands
- 2.6、Command Summary

## 2.1, do not use the sudo command

Usually, to operate docker commands, you need to add the prefix sudo, as follows:

```
sudo docker version
```

But after adding the docker user group, you don't need to add the sudo prefix. How to add a docker user group (run commands in the host running docker):

```
sudo groupadd docker # Add docker user group
sudo gpasswd -a $USER docker # Add the current user to the docker user group, where
$USER can automatically resolve to the currently logged in user
Newgrp Docker# Update the docker user group
```

After adding the above command, use the [docker images] command to test, if there is no error, it means that you can already use the sudo command. If the following error is reported:

```
pi@ubuntu:~$ docker images
WARNING: Error loading config file: /home/pi/.docker/config.json: open
/home/pi/.docker/config.json: permission denied
```

Run the following command on the host to solve the problem:

```
sudo chown "$USER":"$USER" /home/"$USER"/.docker -R
sudo chmod g+rwx "/home/$USER/.docker" -R
```

# 2.2、help commands

```
docker info # Displays Docker system information, including the number of images and containers.

docker --help # Help
```

# 2.3、mirror command

1. Docker pull download image

```
# Download the image
jetson@ubuntu:~$ docker pull ubuntu
Using default tag: latest # Do not write tag, default is latest
latest: Pulling from library/ubuntu
cd741b12a7ea: Pull complete # Layered download
Digest: sha256:67211c14fa74f070d27cc59d69a7fa9aeff8e28ea118ef3babc295a0428a6d21
Status: Downloaded newer image for ubuntu:latest
docker.io/library/ubuntu:latest # Real Location
```

### 2. Docker images lists the images

```
# Lists the images on the local host
jetson@ubuntu:~$ docker images
REPOSITORY
                           TAG
                                    IMAGE ID
                                                   CREATED
                                                                      SIZE
yahboomtechnology/ros-foxy
                           3.4.0
                                    49581aa78b6b About an hour ago
                                                                      24.3GB
yahboomtechnology/ros-foxy 3.3.9
                                    cefb5ac2ca02
                                                   3 days ago
                                                                      20.5GB
yahboomtechnology/ros-foxy 3.3.8
                                    49996806c64a 4 days ago
                                                                      20.5GB
yahboomtechnology/ros-foxy 3.3.7
                                    8989b8860d17 4 days ago
                                                                     17.1GB
                                    326531363d6e
yahboomtechnology/ros-foxy 3.3.6
                                                   5 days ago
                                                                      16.1GB
hello-world
                           latest
                                    9.14kB
# interpretation
REPOSITORY: The repository source of the mirror
TAG: The label of the image
IMAGE: ID The ID of the image
CREATED: Image creation time
SIZE: Image size
# The same repository source can have multiple tags, representing different versions
of this repository source, we use REPOSITORY: TAG to define different images, if you
do not define the tag version of the image, docker will use lastest images by
default!
# Optional
-a: Lists all local images
-q: Only the image ID is displayed
--digests: Displays the summary information of the image
```

#### 3. docker search

```
# Search for mirrors
jetson@ubuntu:~$ docker search ros2
NAME
                                               DESCRIPTION
            STARS
                     OFFICIAL AUTOMATED
osrf/ros2
                                               **Experimental** Docker Images for
ROS2 deve...
            60
                                  [OK]
tiryoh/ros2-desktop-vnc
                                               A Docker image to provide HTML5 VNC
interfac... 11
althack/ros2
                                               An assortment of development
containers for ... 7
```

```
tiryoh/ros2 unofficial ROS2 image

6
athackst/ros2 [Deprecated-> use althack/ros2]

5
uobflightlabstarling/starling-mavros2 ROS2 version of MAVROS

2
theosakamg7/ros2_java_docker Image base

1 [OK]

# docker search The name of an image corresponds to the image in the DockerHub repository

# Optional
--filter=stars=50 : Lists images with a collection of no less than the specified value.
```

4、docker rmi delete the image

```
# Delete the image
docker rmi -f image id # deletes a single
docker rmi -f image name: tag image name: tag # Delete multiple
docker rmi -f $(docker images -qa) # deletes all
```

# 2.4, container commands

To create a container with an image, we use the image of ubuntu here to test and download the image:

```
docker pull ubuntu
```

1、docker run

```
# command
docker run [OPTIONS] IMAGE [COMMAND][ARG...]
# Description of common parameters
--name="Name" # Specify a name for the container
-d # runs the container in background mode and returns the ID of the container!
-i # runs the container in interactive mode by using it with -t
-t # reassigns a terminal to the container, usually used with -i
-P # random port mapping (uppercase)
-p # specifies the port mapping (summary), which can generally be written in four
ip:hostPort:containerPort
ip::containerPort
hostPort:containerPort (commonly used)
containerPort
# test
jetson@ubuntu:~$ docker images
REPOSITORY
                            TAG
                                      IMAGE ID
                                                                     SIZE
                                                     CREATED
yahboomtechnology/ros-foxy 3.4.0
                                                                     24.3GB
                                      49581aa78b6b 2 hours ago
```

```
yahboomtechnology/ros-foxy 3.3.9
                                    cefb5ac2ca02
                                                  3 days ago
                                                                 20.5GB
yahboomtechnology/ros-foxy 3.3.8
                                    49996806c64a 4 days ago
                                                                 20.5GB
                                    8989b8860d17 4 days ago
yahboomtechnology/ros-foxy 3.3.7
                                                                 17.1GB
yahboomtechnology/ros-foxy 3.3.6
                                    326531363d6e 5 days ago
                                                                 16.1GB
ubuntu
                           latest
                                    bab8ce5c00ca
                                                  6 weeks ago
                                                                 69.2MB
hello-world
                           latest
                                    46331d942d63 13 months ago
                                                                 9.14kB
# Use ubuntu to start the container in interactive mode and execute the /bin/bash
command inside the container!
jetson@ubuntu:~$ docker run -it ubuntu:latest /bin/bash
root@c54bf9efae47:/# ls
bin boot dev etc home lib media mnt opt proc root run sbin srv sys
tmp usr var
root@c54bf9efae47:/# exit # Use exit to exit the container back to the host
exit
jetson@ubuntu:~$
```

#### 2、docker ps

```
# command
docker ps [OPTIONS]
# Description of common parameters
-a # lists all currently running containers + historically run containers
-l # displays the most recently created container
-n=? # Displays the last n created containers
-q # silent mode, only the container number is displayed.
#test
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE COMMAND
                                           CREATED
                                                        STATUS
PORTS
         NAMES
              ubuntu:latest "/bin/bash"
c54bf9efae47
                                           2 hours ago
                                                       Up 4 seconds
         funny_hugle
3b9c01839579 hello-world
                             "/hello"
                                           3 hours ago
                                                       Exited (0) 3 hours ago
         jovial_brown
```

#### 3. Exit the container

```
exit # The container stops exiting ctrl+P+Q # container does not stop exiting
```

### 4、Multiple terminals enter a running container

```
# Command 1
docker exec -it docker_id bashShell

# test
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE COMMAND CREATED STATUS
PORTS NAMES
```

```
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago Up 4 seconds
         funny_hugle
3b9c01839579 hello-world
                             "/hello" 3 hours ago Exited (0) 3 hours ago
         jovial_brown
jetson@ubuntu:~$ docker exec -it c5 /bin/bash # The ID of the container can be
abbreviated, as long as it uniquely identifies the container
root@c54bf9efae47:/#
# Command 2
docker attach docker_id
# test
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE COMMAND
                                        CREATED
                                                      STATUS
PORTS
        NAMES
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago Up 35 seconds
        funny_hugle
                             "/hello"
3b9c01839579 hello-world
                                          3 hours ago Exited (0) 3 hours ago
         jovial_brown
jetson@ubuntu:~$ docker attach c5 # The ID of the container can be abbreviated,
as long as it uniquely identifies the container
root@c54bf9efae47:/#
# Difference
# exec is to open a new terminal in the container and a new process can be started
# attach goes directly to the terminal of the container startup command and does not
start a new process
```

### 5. Start and stop the container

```
docker start (container ID or container name) # Start the container
docker restart (container id or container name) # Restart the container
docker stop (container id or container name) # Stop the container
docker kill (container ID or container name) # Forces the container to stop
```

## 6. Delete the container

```
Docker rm docker_id # Deletes the specified container docker rm -f $(docker ps -a -q) # Delete all containers docker ps -a -q|xargs docker rm # Delete all containers
```

# 2.5 common other commands

1. View the process information running in the container and support ps command parameters.

```
# command
docker top docker_id
# Test
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE
                            COMMAND
                                        CREATED
                                                      STATUS
PORTS
        NAMES
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago
                                                     Up 2 minutes
         funny_hugle
3b9c01839579 hello-world
                            "/hello" 3 hours ago Exited (0) 3 hours ago
        jovial_brown
jetson@ubuntu:~$ docker top c5
                  PID
                                    PPID
                                                       C
UID
STIME
                  TTY
                                                       CMD
                                    TIME
root
                  9667
                                    9647
14:20
                                    00:00:00
                                                       /bin/bash
                  pts/0
```

### 2、View the metadata of the container/image

```
# Command
docker inspect docker_id
# Test viewing container metadata
jetson@ubuntu:~$ docker ps -a
CONTAINER ID IMAGE
                      COMMAND
                                         CREATED
                                                       STATUS
PORTS
         NAMES
c54bf9efae47 ubuntu:latest "/bin/bash" 2 hours ago Up 4 minutes
         funny_hugle
3b9c01839579 hello-world
                            "/hello" 3 hours ago Exited (0) 3 hours ago
         jovial_brown
jetson@ubuntu:~$ docker inspect c54bf9efae47
# The complete id, the container ID above here, is the first few digits of
this ID that were intercepted
       "Id": "c54bf9efae471071391202a8718b346d9af76cb1ff17741e206280603d6f0056",
       "Created": "2023-04-24T04:19:46.232822024Z",
       "Path": "/bin/bash",
       "Args": [],
       "State": {
           "Status": "running",
           "Running": true,
           "Paused": false,
           "Restarting": false,
           "OOMKilled": false.
           "Dead": false,
           "Pid": 9667,
           "ExitCode": 0,
           "Error": "",
```

```
"StartedAt": "2023-04-24T06:20:58.508213216Z",
            "FinishedAt": "2023-04-24T06:19:45.096483592Z"
        },
# Test viewing image metadata
jetson@ubuntu:~$ docker images
REPOSITORY
                             TAG IMAGE ID CREATED
                                                                       SIZE
                             latest bab8ce5c00ca 6 weeks ago
ubuntu
                                                                       69.2MB
hello-world
                             latest 46331d942d63 13 months ago 9.14kB
jetson@ubuntu:~$ docker inspect bab8ce5c00ca
Γ
    {
        "Id":
"sha256:bab8ce5c00ca3ef91e0d3eb4c6e6d6ec7cffa9574c447fd8d54a8d96e7c1c80e",
        "RepoTags": [
            "ubuntu:latest"
        ],
        "RepoDigests": [
"ubuntu@sha256:67211c14fa74f070d27cc59d69a7fa9aeff8e28ea118ef3babc295a0428a6d21"
        ٦,
        "Parent": "",
        "Comment": "",
        "Created": "2023-03-08T04:32:41.063980445Z",
        "Container":
"094fd0c521be8c84d81524e4a5e814e88a2839899c56f654484d32d171c7195b",
        "ContainerConfig": {
            "Hostname": "094fd0c521be",
            . . . . . . . . . . . . .
            "Labels": {
                "org.opencontainers.image.ref.name": "ubuntu",
                "org.opencontainers.image.version": "22.04"
            }
        },
        "DockerVersion": "20.10.12",
        "Author": "",
        "Config": {
            "Hostname": "",
            . . . . . . . . .
            "Labels": {
                "org.opencontainers.image.ref.name": "ubuntu",
                "org.opencontainers.image.version": "22.04"
            }
        },
        "Architecture": "arm64",
        "Variant": "v8",
        "Os": "linux",
        "size": 69212233,
        "VirtualSize": 69212233,
        "GraphDriver": {
            "Data": {
```

```
"MergedDir":
"/var/lib/docker/overlay2/8418b919a02d38a64ab86060969b37b435977e9bbdeb6b0840d4eb6982
80e796/merged",
                "UpperDir":
"/var/lib/docker/overlay2/8418b919a02d38a64ab86060969b37b435977e9bbdeb6b0840d4eb6982
80e796/diff",
                "WorkDir":
"/var/lib/docker/overlay2/8418b919a02d38a64ab86060969b37b435977e9bbdeb6b0840d4eb6982
80e796/work"
            },
            "Name": "overlay2"
        },
        "RootFS": {
            "Type": "layers",
            "Layers": [
"sha256:874b048c963ab55b06939c39d59303fb975d323822a4ea48a02ac8dc635ea371"
        },
        "Metadata": {
            "LastTagTime": "0001-01-01T00:00:00Z"
    }
]
```

# 2.6、Command Summary

