4. Read pin high and low levels

1. Create and open the readgpio.py file

```
nano readgpio.py
```

2. Write program

```
import wiringpi
GPIO_Output_Pin = 0 #Define GPIO_Output_Pin as pin 0
GPIO_Intput_Pin = 1  #Define GPIO_Intput_Pin as 1 pin
OUTPUT = 1
                   #Define OUTPUT to be 1, that is, output
                    #Define INPUT to be 0, that is, input
INPUT = 0
HIGH = 1
                    #Define HIGH as 1, that is, the high point is flat
LOW = 0
                     #Define HIGH as 1, that is, the high point is flat
wiringpi.wiringPiSetup()
                                                #Set the GPIO number to wPi
mode
wiringpi.pinMode(GPIO_Output_Pin,OUTPUT) #Set GPIO_Output_Pin to OUTPUT
output mode
wiringpi.pinMode(GPIO_Intput_Pin,INPUT)
                                               #Set GPIO_Intput_Pin to INPUT
input mode
while 1:
   wiringpi.digitalWrite(GPIO_Output_Pin,HIGH) #Set GPIO_Output_Pin to output
high level
   print('GPIO_Output_Pin OUTPUT =>HIGH')
    print('GPIO_Intput_Pin INPUT <=',wiringpi.digitalRead(GPIO_Intput_Pin))</pre>
#Print the data read from GPIO_Intput_Pin
   wiringpi.delay(1000)
                              #Delay 1000ms
   print()
   wiringpi.digitalWrite(GPIO_Output_Pin,LOW)
                                                   #Set GPIO_Output_Pin output
low level
    print('GPIO_Output_Pin OUTPUT =>LOW')
    print('GPIO_Intput_Pin INPUT <=',wiringpi.digitalRead(GPIO_Intput_Pin))</pre>
#Print the data read from GPIO_Intput_Pin
   wiringpi.delay(1000)
                              #Delay 1000ms
    print()
```

After writing is completed, press the shortcut key to exit

```
"Ctrl+X"
```

"Y"

The system will prompt you whether you need to save, press Y and press Enter to save and exit.

3. Use Dupont cable to connect GPIO0 and GPIO1 of Raspberry Pi



4. Run python code

readgpio.py

```
pi@raspberrypi:~/work/example/Python $ python3 readgpio.py
GPIO_Output_Pin OUTPUT =>HIGH
GPIO_Intput_Pin INPUT <= 1

GPIO_Output_Pin OUTPUT =>LOW
GPIO_Intput_Pin INPUT <= 0

GPIO_Output_Pin OUTPUT =>HIGH
GPIO_Intput_Pin INPUT <= 1

GPIO_Output_Pin OUTPUT =>LOW
GPIO_Intput_Pin INPUT <= 0

GPIO_Output_Pin OUTPUT =>HIGH
GPIO_Intput_Pin INPUT <= 0</pre>
```

The GPIO_Input_Pin pin changes as the GPIO_Output_Pin output changes

• Appendix: GPIO pin reference diagram

pi@raspberrypi:~ \$ gpio readall +++												
ı	BCM	wPi	Name						Mode	Name	wPi	BCM
ı			3.3v			1	2			5v		
	2	8	SDA.1	IN	1	3	4		į i	5v	į į	i
	3	9	SCL.1	IN	1	5	6		į i	0v	į i	i i
	4	7	GPI0. 7	IN	1	7	8	1	IN	TxD	15	14
	į į	į i	0v			9	10	1	IN	RxD	16	15
	17	Θ	GPIO. 0	IN	1	11	12	1	OUT	GPIO. 1	1	18
	27	2	GPIO. 2	IN		13	14			0v	İ	İ
	22	3	GPIO. 3	IN		15	16	Θ	IN	GPIO. 4	4	23
	İ	į i	3.3v			17	18	0	IN	GPIO. 5	5	24
	10	12	MOSI	IN		19	20			Θv	İ	j
	9	13	MISO	IN		21	22	0	IN	GPIO. 6	6	25
	11	14	SCLK	IN		23	24	1	IN	CE0	10	8
			0v			25	26	1	IN	CE1	11	7
	0	30	SDA.0	IN	1	27	28	1	IN	SCL.0	31	1
	5	21	GPI0.21	IN	1	29	30			0v	İ	
	6	22	GPI0.22	IN	1	31	32	0	IN	GPI0.26	26	12
	13	23	GPI0.23	IN		33	34			0v		
	19	24	GPI0.24	IN		35	36	0	IN	GPI0.27	27	16
	26	25	GPI0.25	IN		37	38	0	IN	GPI0.28	28	20
			ΘV			39	40	Θ	IN	GPI0.29	29	21
++												
I	BCM	wPi	Name	Mode	V	Phys	sical	V	Mode	Name	wPi	BCM
	+	+	++			+Pj	i 4B	+	+	+	++	+