Jetson Nano I2C Communication Tutorial

The I2C pin of the Jetson nano is shown in the figure, and the I2C service needs to be enabled before use.

GPIO和BCM对照表

BCII编码	功能名	物理	引脚	功能名	BCM编码
	373	1	2	5V	
2	SDA	3	4	5V	
3	SCL	5	6	GND	
4	D4	7	8	D14(TXD)	14
	GND	9	10	D15(RXD)	15
17	D17	11	12	D18	18
27	D27	13	14	GND	
22	D22	15	16	D23	23
	373	17	18	D24	24
10	D10	19	20	GND	
9	D9	21	22	D25	25
11	D11	23	24	D8	8
	GND	25	26	D7	7
0	DO(ID_SD)	27	28	D1(ID_SC)	1
5	D5	29	30	GND	
6	D6	31	32	D12	12
13	D13	33	34	GND	
19	D19	35	36	D16	16
26	D26	37	38	D20	20
	GND	39	40	D21	21

Firstly, install I2Ctool, and input the terminal as follows:

```
sudo apt-get update
sudo apt-get install -y i2c-tools
```

Check the installation status, terminal input:

```
apt-cache policy i2c-tools
```

The following output indicates successful installation

```
i2c-tools:
was installed: 4.0-2
candidate: 4.0-2
Version List:
*** 4.0-2 500
500 http://ports.ubuntu.com/ubuntu-ports bionic/universe arm64 Packages
100 /var/lib/dpkg/status
```

Scan all i2c devices on a certain bus and print out the device i2c bus address. For example, if a device with address 0x0f is mounted on the I2C pin, the corresponding device I2C address will be displayed

```
sudo i2cdetect -y -r -a 1
```

Smbus is a Python library. If smbus is not installed, the terminal input is:

```
sudo apt-get update
sudo apt-get install -y python3-smbus
```

The Smbus protocol has many related library functions that can be used for I2C communication

function	description	parameters	return value			
SMBus Access						
write_quick (addr)	Quick transaction.	int addr	long			
read_byte (addr)	Read Byte transaction.	int addr	long			
write_byte (addr, val)	Write Byte transaction.	int addr, char val	long			
read_byte_data (addr, cmd)	Read Byte Data transaction.	int addr, char cmd	long			
write_byte_data (addr, cmd, val)	Write Byte Data transaction.	int addr, char cmd, char val	long			
read_word_data (addr, cmd)	Read Word Data transaction.	int addr, char cmd	long			
write_word_data (addr, cmd, val)	Write Word Data transaction.	int addr, char cmd, int val	long			
process_call (addr, cmd, val)	Process Call transaction.	int addr, char cmd, int val	long			
read_block_data (addr, cmd)	Read Block Data transaction.	int addr, char cmd	long[]			
write_block_data (addr, cmd, vals)	Write Block Data transaction.	int addr, char cmd, long []	None			
block_process_call (addr, cmd, vals)	Block Process Call transaction.	int addr, char cmd, long []	long []			
12C Access						
read_i2c_block_data (addr, cmd)	Block Read transaction.	int addr, char cmd	long []			
write_i2c_block_data (addr, cmd, vals)	Block Write transaction.	int addr, char cmd, long []	None			

The following is a program case of our store's OLED module. If testing is needed, the corresponding OLED module should be used (you can choose to change the OLED module in our store)

0.91寸OLED显示屏 显示屏无背光 中文/英文/图片都可显示

Wiring:

Jetson Nano pin 3 (SDA) →oled module SDA

Jetson Nano J pin 5 (SCL) →oled module SCL

Jetson Nano J pin 2 (5V) →oled module VCC

Jetson Nano J pin 6 (GND) →oled module GND

Import Adafruit_ SSD1306 library This is the OLED library, and you need to download this library when using your own image

pip install Adafruit_SSD1306

```
#!/usr/bin/env python3
# coding=utf-8
import time
import os
import Adafruit_SSD1306 as SSD
from PIL import Image
from PIL import ImageDraw
from PIL import ImageFont
import subprocess
# V1.0.1
class Yahboom_OLED:
   def __init__(self, i2c_bus=1, debug=False):
        self. debug = debug
        self.__i2c_bus = i2c_bus
       self.\_top = -2
        self._x = 0
        self.__total_last = 0
        self.__idle_last = 0
        self.__str_CPU = "CPU:0%"
   def __del__(self):
        if self.__debug:
           print("---OLED-DEL---")
   #初始化OLED,成功返回:True,失败返回:False
   # Initialize OLED, return True on success, False on failure
```

Initialize oled:

```
#初始化OLED,成功返回:True,失败返回:False
# Initialize OLED, return True on success, False on failure
def begin(self):
    try:
        self.__oled = SSD.SSD1306_128_32(
            rst=None, i2c_bus=self.__i2c_bus, gpio=1)
        self.__oled.begin()
        self. oled.clear()
       self. oled.display()
       self.__width = self.__oled.width
       self.__height = self.__oled.height
        self.__image = Image.new('1', (self.__width, self.__height))
       self. draw = ImageDraw.Draw(self. image)
       self. font = ImageFont.load default()
        if self.__debug:
            print("---OLED begin ok!---")
       return True
    except:
        if self.__debug:
           print("---OLED no found!---")
        return False
```

Afterwards, if you are interested in reading some basic information functions of nano, you can go to this py file to learn more, which includes obtaining local IP, tf card space usage, memory usage, system time, and other information.

Terminal input:

sudo python3 yahboom_oled.py

Experimental phenomenon:

