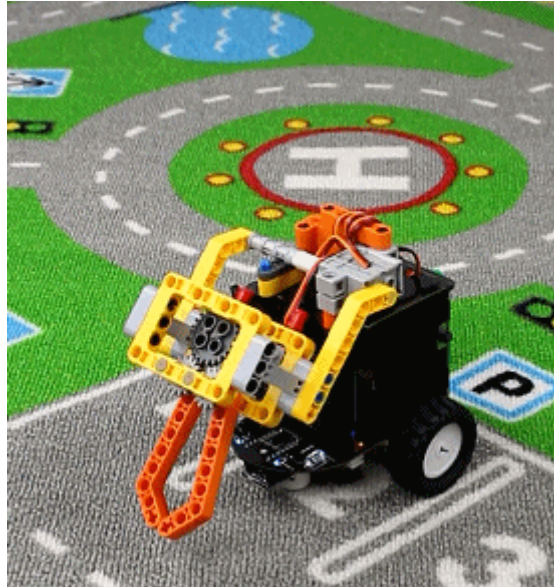


!!!Note:

When use servo in the first time,we need to remove the gear on the building block servo and download the program to micro:bit. Next, turn on the power of the robot, wait for the building block servo to turn to the initial position. Then ,turn off the power. Finally, we need to install the gear on the building block servo.

In initial status, clip is put down and close.As shown below.

**About wiring:**

Servo1 connect to S1 interface of PCB board.

Servo2 connect to S2 interface of PCB board.

