**Experimental content:** When ultrasonic module detect different distance, the buzzer play different tone(do rui mi fa sol la si).

Tip: Reference tone do(C4), rui(D4), mi(E4,) fa(F4), sol(G4), la(A4), si(B4).

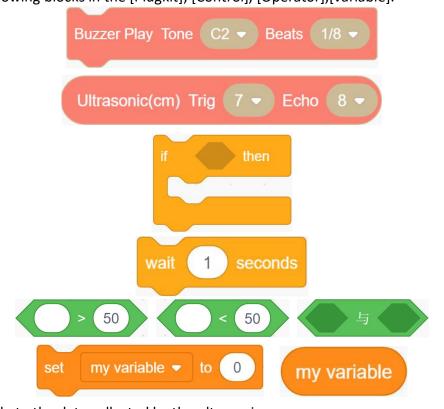
**Experiment preparation:** UNO board \*1, Plugkit sensor expansion board \*1, 4pin cable (PH2.0) \* 1, USB data cable \*1, Ultrasonic sensor module \*1.

## **Experimental wiring:**



## **Experimental steps:**

1. Select the following blocks in the [Plugkit], [Control], [Operator], [variable].



2.Set my variable to the data collected by the ultrasonic sensor.



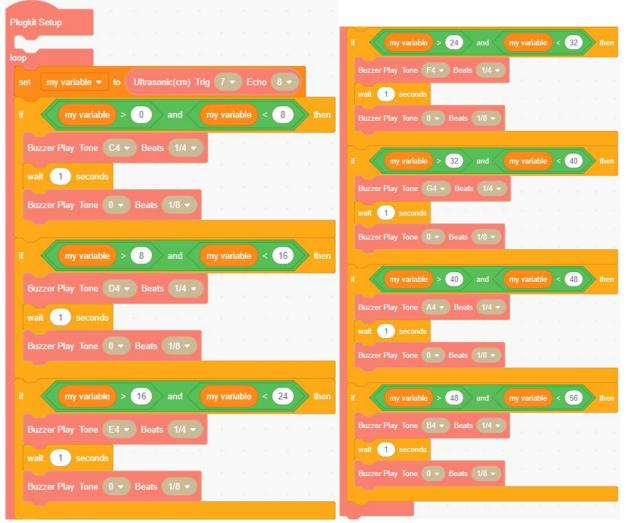
3.If the value of my variable is greater than 0 and my variable is less than 8 at the same time, the buzzer module makes a sound. We use a "logic and(&)" block. The function of this block, when the left and right conditions is satisfied at the same time, it is true, otherwise it is false.



4.We take a distance of 8cm and output a different tone every 8cm. It can be modified by duplicating the block combination of step 3.

Distance	Tone
0~8cm	do(C4)
8cm~16cm	rui(D4)
16cm~24cm	mi(E4)
24cm~32cm	fa(F4)
32cm~40cm	sol(G4)
40cm~48cm	la(A4)
48cm~56cm	si(B4)

5.Put the combination of the blocks in step 2 and the combination of blocks in steps 3 and 4 into the loop. Because the overall program is long, only the segmented program is provided here, combine the blocks from left to right as shown below



6.Compiling and uploading programs.

**Experimental phenomena:** When ultrasonic module detect different distance, the buzzer play different tone(do, rui, mi, fa, sol, la, si).