

## 3. USB wireless handle + mobile phone screen remote control tutorial

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#### 3.1. Open steps

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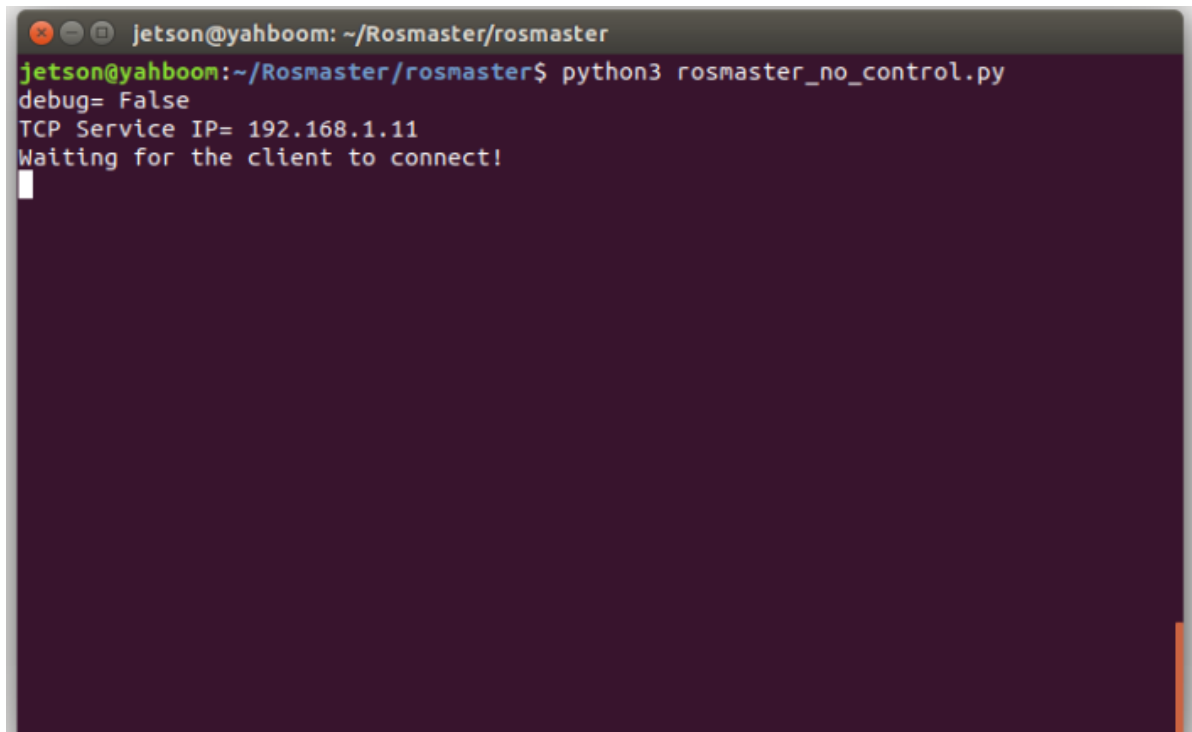
- After booting into the program, first close the large program, you can refer to the second section of "05. ROSMASTER Basic Control Tutorial" "2. Turn off the self-starting large program".
- Open a terminal, type,

```
roslaunch yahboomcar_bringup bringup.launch #launch chassis + remote control
```

- Open another terminal and enter

```
cd ~/Rosmaster/rosmaster
```

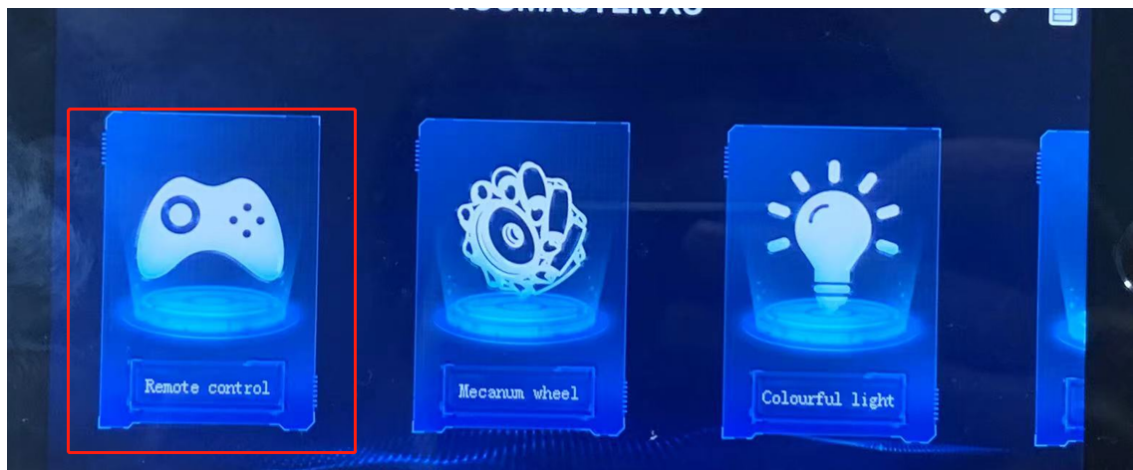
```
python3 rosmaster_no_control.py
```



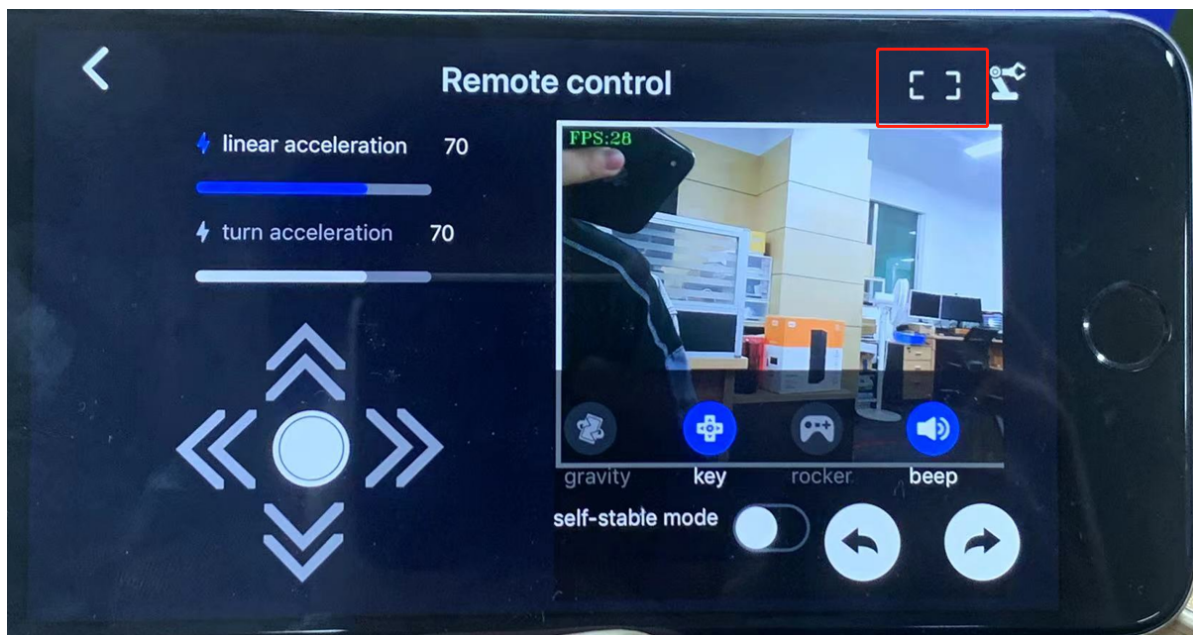
```
jetson@yahboom: ~/Rosmaster/rosmaster
jetson@yahboom:~/Rosmaster/rosmaster$ python3 rosmaster_no_control.py
debug= False
TCP Service IP= 192.168.1.11
Waiting for the client to connect!
█
```

- Refer to the "Mobile APP Remote Control Tutorial" in "03. Mobile Phone Remote Control Tutorial", connect the mobile phone to the rosmaster, and then you can see the screen transmitted by the rosmaster on the mobile phone screen.

[Click here to enter the control screen](#)



Click [here](#) for full screen viewing,



- Fix the phone on the handle, press the start button on the handle, and you can control it after you hear a beep.