

Precautions

ROS1 and ROS2 vision applications can only be used with USB cameras!

The script that enters the Docker container does not add the host video* device. If you run the ROS1/2 visual application, you need to add the host video device in the script yourself.

You can add the following line of code to the script file: the specific device number can be modified according to your own system

```
--device=/dev/video0 \
```